

# NAG Library Function Document

## nag\_ztgexc (f08ytc)

### 1 Purpose

nag\_ztgexc (f08ytc) reorders the generalized Schur factorization of a complex matrix pair in generalized Schur form.

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_ztgexc (Nag_OrderType order, Nag_Boolean wantq, Nag_Boolean wantz,
                Integer n, Complex a[], Integer pda, Complex b[], Integer pdb,
                Complex q[], Integer pdq, Complex z[], Integer pdz, Integer ifst,
                Integer *ilst, NagError *fail)
```

### 3 Description

nag\_ztgexc (f08ytc) reorders the generalized complex  $n$  by  $n$  matrix pair  $(S, T)$  in generalized Schur form, so that the diagonal element of  $(S, T)$  with row index  $i_1$  is moved to row  $i_2$ , using a unitary equivalence transformation. That is,  $S$  and  $T$  are factorized as

$$S = \hat{Q}\hat{S}\hat{Z}^H, \quad T = \hat{Q}\hat{T}\hat{Z}^H,$$

where  $(\hat{S}, \hat{T})$  are also in generalized Schur form.

The pair  $(S, T)$  are in generalized Schur form if  $S$  and  $T$  are upper triangular as returned, for example, by nag\_zgges (f08xnc), or nag\_zhgeqz (f08xsc) with **job** = Nag\_Schur.

If  $S$  and  $T$  are the result of a generalized Schur factorization of a matrix pair  $(A, B)$

$$A = QSZ^H, \quad B = QTZ^H$$

then, optionally, the matrices  $Q$  and  $Z$  can be updated as  $Q\hat{Q}$  and  $Z\hat{Z}$ .

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

### 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **wantq** – Nag\_Boolean *Input*

*On entry:* if **wantq** = Nag\_TRUE, update the left transformation matrix  $Q$ .

If **wantq** = Nag\_FALSE, do not update  $Q$ .

- 3: **wantz** – Nag\_Boolean *Input*  
*On entry:* if **wantz** = Nag\_TRUE, update the right transformation matrix  $Z$ .  
 If **wantz** = Nag\_FALSE, do not update  $Z$ .
- 4: **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrices  $S$  and  $T$ .  
*Constraint:*  $n \geq 0$ .
- 5: **a**[ $dim$ ] – Complex *Input/Output*  
**Note:** the dimension,  $dim$ , of the array **a** must be at least  $\max(1, \mathbf{pda} \times \mathbf{n})$ .  
 The  $(i, j)$ th element of the matrix  $A$  is stored in  

$$\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor};$$

$$\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}.$$
*On entry:* the matrix  $S$  in the pair  $(S, T)$ .  
*On exit:* the updated matrix  $\hat{S}$ .
- 6: **pda** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **a**.  
*Constraint:*  $\mathbf{pda} \geq \max(1, \mathbf{n})$ .
- 7: **b**[ $dim$ ] – Complex *Input/Output*  
**Note:** the dimension,  $dim$ , of the array **b** must be at least  $\max(1, \mathbf{pdb} \times \mathbf{n})$ .  
 The  $(i, j)$ th element of the matrix  $B$  is stored in  

$$\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor};$$

$$\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}.$$
*On entry:* the matrix  $T$ , in the pair  $(S, T)$ .  
*On exit:* the updated matrix  $\hat{T}$ .
- 8: **pdb** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.  
*Constraint:*  $\mathbf{pdb} \geq \max(1, \mathbf{n})$ .
- 9: **q**[ $dim$ ] – Complex *Input/Output*  
**Note:** the dimension,  $dim$ , of the array **q** must be at least  

$$\max(1, \mathbf{pdq} \times \mathbf{n}) \text{ when } \mathbf{wantq} = \text{Nag\_TRUE};$$
 1 otherwise.  
 The  $(i, j)$ th element of the matrix  $Q$  is stored in  

$$\mathbf{q}[(j-1) \times \mathbf{pdq} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor};$$

$$\mathbf{q}[(i-1) \times \mathbf{pdq} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}.$$
*On entry:* if **wantq** = Nag\_TRUE, the unitary matrix  $Q$ .  
*On exit:* if **wantq** = Nag\_TRUE, the updated matrix  $Q\hat{Q}$ .  
 If **wantq** = Nag\_FALSE, **q** is not referenced.

- 10: **pdq** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **q**.  
*Constraints:*  
 if **wantq** = Nag\_TRUE, **pdq**  $\geq$  max(1, **n**);  
 otherwise **pdq**  $\geq$  1.
- 11: **z**[*dim*] – Complex *Input/Output*  
**Note:** the dimension, *dim*, of the array **z** must be at least  
 max(1, **pdz**  $\times$  **n**) when **wantz** = Nag\_TRUE;  
 1 otherwise.  
 The (*i*, *j*)th element of the matrix *Z* is stored in  
 $\mathbf{z}[(j-1) \times \mathbf{pdz} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{z}[(i-1) \times \mathbf{pdz} + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* if **wantz** = Nag\_TRUE, the unitary matrix *Z*.  
*On exit:* if **wantz** = Nag\_TRUE, the updated matrix  $Z\hat{Z}$ .  
 If **wantz** = Nag\_FALSE, **z** is not referenced.
- 12: **pdz** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **z**.  
*Constraints:*  
 if **wantz** = Nag\_TRUE, **pdz**  $\geq$  max(1, **n**);  
 otherwise **pdz**  $\geq$  1.
- 13: **ifst** – Integer *Input*  
 14: **ilst** – Integer \* *Input/Output*  
*On entry:* the indices  $i_1$  and  $i_2$  that specify the reordering of the diagonal elements of (*S*, *T*). The element with row index **ifst** is moved to row **ilst**, by a sequence of swapping between adjacent diagonal elements.  
*On exit:* **ilst** points to the row in its final position.  
*Constraint:*  $1 \leq \mathbf{ifst} \leq \mathbf{n}$  and  $1 \leq \mathbf{ilst} \leq \mathbf{n}$ .
- 15: **fail** – NagError \* *Input/Output*  
 The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 3.2.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument *value* had an illegal value.

**NE\_CONSTRAINT**

On entry, **wantq** =  $\langle value \rangle$ , **pdq** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: if **wantq** = Nag\_TRUE, **pdq**  $\geq \max(1, \mathbf{n})$ ;  
 otherwise **pdq**  $\geq 1$ .

On entry, **wantz** =  $\langle value \rangle$ , **pdz** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: if **wantz** = Nag\_TRUE, **pdz**  $\geq \max(1, \mathbf{n})$ ;  
 otherwise **pdz**  $\geq 1$ .

**NE\_INT**

On entry, **n** =  $\langle value \rangle$ .  
 Constraint: **n**  $\geq 0$ .

On entry, **pda** =  $\langle value \rangle$ .  
 Constraint: **pda**  $> 0$ .

On entry, **pdb** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $> 0$ .

On entry, **pdq** =  $\langle value \rangle$ .  
 Constraint: **pdq**  $> 0$ .

On entry, **pdz** =  $\langle value \rangle$ .  
 Constraint: **pdz**  $> 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pda**  $\geq \max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \mathbf{n})$ .

**NE\_INT\_3**

On entry, **ifst** =  $\langle value \rangle$ , **ilst** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint:  $1 \leq \mathbf{ifst} \leq \mathbf{n}$  and  $1 \leq \mathbf{ilst} \leq \mathbf{n}$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.  
 See Section 3.6.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.  
 See Section 3.6.5 in How to Use the NAG Library and its Documentation for further information.

**NE\_SCHUR**

The transformed matrix pair would be too far from generalized Schur form; the problem is ill-conditioned.  $(S, T)$  may have been partially reordered, and **ilst** points to the first row of the current position of the block being moved.

**7 Accuracy**

The computed generalized Schur form is nearly the exact generalized Schur form for nearby matrices  $(S + E)$  and  $(T + F)$ , where

$$\|E\|_2 = O\epsilon \|S\|_2 \quad \text{and} \quad \|F\|_2 = O\epsilon \|T\|_2,$$

and  $\epsilon$  is the *machine precision*. See Section 4.11 of Anderson *et al.* (1999) for further details of error bounds for the generalized nonsymmetric eigenproblem.

## 8 Parallelism and Performance

nag\_ztgexc (f08ytc) is not threaded in any implementation.

## 9 Further Comments

The real analogue of this function is nag\_dtgexc (f08yfc).

## 10 Example

This example exchanges rows 4 and 1 of the matrix pair  $(S, T)$ , where

$$S = \begin{pmatrix} 4.0 + 4.0i & 1.0 + 1.0i & 1.0 + 1.0i & 2.0 - 1.0i \\ 0 & 2.0 + 1.0i & 1.0 + 1.0i & 1.0 + 1.0i \\ 0 & 0 & 2.0 - 1.0i & 1.0 + 1.0i \\ 0 & 0 & 0 & 6.0 - 2.0i \end{pmatrix}$$

and

$$T = \begin{pmatrix} 2.0 & 1.0 + 1.0i & 1.0 + 1.0i & 3.0 - 1.0i \\ 0 & 1.0 & 2.0 + 1.0i & 1.0 + 1.0i \\ 0 & 0 & 1.0 & 1.0 + 1.0i \\ 0 & 0 & 0 & 2.0 \end{pmatrix}.$$

### 10.1 Program Text

```

/* nag_ztgexc (f08ytc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf08.h>

int main(void)
{
    /* Scalars */
    Integer i, ifst, ilst, j, n, pdq, pds, pdt, pdz;
    Integer exit_status = 0;

    /* Arrays */
    Complex *q = 0, *s = 0, *t = 0, *z = 0;
    char nag_enum_arg[40];

    NagError fail;
    Nag_OrderType order;
    Nag_Boolean wantq, wantz;
    Nag_MatrixType upmat = Nag_UpperMatrix;
    Nag_DiagType diag = Nag_NonUnitDiag;
    Nag_LabelType intlabeled = Nag_IntegerLabels;
    Nag_ComplexFormType brac = Nag_BracketForm;

#ifdef NAG_COLUMN_MAJOR
#define S(I, J) s[(J-1)*pds + I - 1]
#define T(I, J) t[(J-1)*pdt + I - 1]
    order = Nag_ColMajor;

```

```

#else
#define S(I, J) s[(I-1)*pds + J - 1]
#define T(I, J) t[(I-1)*pdt + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_ztgexc (f08ytc) Example Program Results\n\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%*[\n]", &n);
#else
    scanf("%" NAG_IFMT "%*[\n]", &n);
#endif
    if (n < 0) {
        printf("Invalid n\n");
        exit_status = 1;
        goto END;
    }
#ifdef _WIN32
    scanf_s(" %39s%*[\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf(" %39s%*[\n]", nag_enum_arg);
#endif
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    wantq = (Nag_Boolean) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
    scanf_s(" %39s%*[\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf(" %39s%*[\n]", nag_enum_arg);
#endif
    wantz = (Nag_Boolean) nag_enum_name_to_value(nag_enum_arg);

    pds = n;
    pdt = n;
    pdq = (wantq ? n : 1);
    pdz = (wanz ? n : 1);

    /* Allocate memory */
    if (!(s = NAG_ALLOC(n * n, Complex)) ||
        !(t = NAG_ALLOC(n * n, Complex)) ||
        !(q = NAG_ALLOC(pdq * pdq, Complex)) ||
        !(z = NAG_ALLOC(pdz * pdz, Complex)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    /* Read S and T from data file */
    for (i = 1; i <= n; ++i)
        for (j = 1; j <= n; ++j)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )", &S(i, j).re, &S(i, j).im);
#else
        scanf(" ( %lf , %lf )", &S(i, j).re, &S(i, j).im);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

```

```

    for (i = 1; i <= n; ++i)
        for (j = 1; j <= n; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &T(i, j).re, &T(i, j).im);
#else
            scanf(" ( %lf , %lf )", &T(i, j).re, &T(i, j).im);
#endif
#ifdef _WIN32
            scanf_s("%*[\n]");
#else
            scanf("%*[\n]");
#endif

    /* Read the row indices */
#ifdef _WIN32
            scanf_s("%" NAG_IFMT "%" NAG_IFMT "%*[\n]", &ifst, &ilst);
#else
            scanf("%" NAG_IFMT "%" NAG_IFMT "%*[\n]", &ifst, &ilst);
#endif

    /* Reorder the S and T */
    nag_ztgexc(order, wantq, wantz, n, s, pds, t, pdt, q, pdq, z, pdz, ifst,
              &ilst, &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_ztgexc (f08ytc).\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }

    /* Print reordered generalized Schur form */
    fflush(stdout);
    nag_gen_complx_mat_print_comp(order, upmat, diag, n, n, s, pds, brac,
                                  "%7.4f", "Reordered Schur matrix S",
                                  intlab, NULL, intlab, NULL, 80, 0, NULL,
                                  &fail);

    if (fail.code != NE_NOERROR)
        goto PRERR;
    printf("\n");
    fflush(stdout);
    nag_gen_complx_mat_print_comp(order, upmat, diag, n, n, t, pdt, brac,
                                  "%7.4f", "Reordered Schur matrix T",
                                  intlab, NULL, intlab, NULL, 80, 0, NULL,
                                  &fail);

PRERR:
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
              fail.message);
        exit_status = 1;
    }

END:
    NAG_FREE(q);
    NAG_FREE(s);
    NAG_FREE(t);
    NAG_FREE(z);

    return exit_status;
}

```

## 10.2 Program Data

nag\_ztgexc (f08ytc) Example Program Data

```

4                                     : n

Nag_FALSE                            : wantq
Nag_FALSE                            : wantz

( 4.0, 4.0) ( 1.0, 1.0) ( 1.0, 1.0) ( 2.0,-1.0)
( 0.0, 0.0) ( 2.0, 1.0) ( 1.0, 1.0) ( 1.0, 1.0)

```

```

( 0.0, 0.0) ( 0.0, 0.0) ( 2.0,-1.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 0.0, 0.0) ( 6.0,-2.0)   : matrix S

( 2.0, 0.0) ( 1.0, 1.0) ( 1.0, 1.0) ( 3.0,-1.0)
( 0.0, 0.0) ( 1.0, 0.0) ( 2.0, 1.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 1.0, 0.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 0.0, 0.0) ( 2.0, 0.0)   : matrix T

1           4           : ifst and ilst

```

### 10.3 Program Results

nag\_ztgexc (f08ytc) Example Program Results

```

Reordered Schur matrix S
      1           2           3           4
1 ( 3.7081, 3.7081) (-2.0834,-0.5688) ( 2.6374, 1.0772) ( 0.2845, 0.7991)
2           ( 1.6097, 1.5656) (-0.0634, 1.9234) (-0.0301, 0.9720)
3           ( 4.7029,-2.1187) ( 1.1379,-3.1199)
4           ( 2.3085,-1.8289)

Reordered Schur matrix T
      1           2           3           4
1 ( 2.2249, 0.7416) (-1.1631, 1.5347) ( 2.2608, 2.0851) ( 1.1094,-0.3205)
2           ( 0.3308, 0.9482) ( 0.3919, 1.8172) (-0.6305, 1.6053)
3           ( 1.6227,-0.1653) ( 0.9966,-0.9074)
4           ( 0.1199,-1.0343)

```

---