

# NAG Library Function Document

## nag\_zgges3 (f08xqc)

### 1 Purpose

nag\_zgges3 (f08xqc) computes the generalized eigenvalues, the generalized Schur form  $(S, T)$  and, optionally, the left and/or right generalized Schur vectors for a pair of  $n$  by  $n$  complex nonsymmetric matrices  $(A, B)$ .

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_zgges3 (Nag_OrderType order, Nag_LeftVecsType jobvsl,
                Nag_RightVecsType jobvsr, Nag_SortEigValsType sort,
                Nag_Boolean (*selctg)(Complex a, Complex b),
                Integer n, Complex a[], Integer pda, Complex b[], Integer pdb,
                Integer *sdim, Complex alpha[], Complex beta[], Complex vsl[],
                Integer pdvsl, Complex vsr[], Integer pdvsr, NagError *fail)
```

### 3 Description

The generalized Schur factorization for a pair of complex matrices  $(A, B)$  is given by

$$A = QSZ^H, \quad B = QTZ^H,$$

where  $Q$  and  $Z$  are unitary,  $T$  and  $S$  are upper triangular. The generalized eigenvalues,  $\lambda$ , of  $(A, B)$  are computed from the diagonals of  $T$  and  $S$  and satisfy

$$Az = \lambda Bz,$$

where  $z$  is the corresponding generalized eigenvector.  $\lambda$  is actually returned as the pair  $(\alpha, \beta)$  such that

$$\lambda = \alpha/\beta$$

since  $\beta$ , or even both  $\alpha$  and  $\beta$  can be zero. The columns of  $Q$  and  $Z$  are the left and right generalized Schur vectors of  $(A, B)$ .

Optionally, nag\_zgges3 (f08xqc) can order the generalized eigenvalues on the diagonals of  $(S, T)$  so that selected eigenvalues are at the top left. The leading columns of  $Q$  and  $Z$  then form an orthonormal basis for the corresponding eigenspaces, the deflating subspaces.

nag\_zgges3 (f08xqc) computes  $T$  to have real non-negative diagonal entries. The generalized Schur factorization, before reordering, is computed by the  $QZ$  algorithm.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (2012) *Matrix Computations* (4th Edition) Johns Hopkins University Press, Baltimore

## 5 Arguments

- 1: **order** – Nag\_OrderType *Input*  
*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.  
*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.
- 2: **jobvsl** – Nag\_LeftVecsType *Input*  
*On entry:* if **jobvsl** = Nag\_NotLeftVecs, do not compute the left Schur vectors.  
 If **jobvsl** = Nag\_LeftVecs, compute the left Schur vectors.  
*Constraint:* **jobvsl** = Nag\_NotLeftVecs or Nag\_LeftVecs.
- 3: **jobvsr** – Nag\_RightVecsType *Input*  
*On entry:* if **jobvsr** = Nag\_NotRightVecs, do not compute the right Schur vectors.  
 If **jobvsr** = Nag\_RightVecs, compute the right Schur vectors.  
*Constraint:* **jobvsr** = Nag\_NotRightVecs or Nag\_RightVecs.
- 4: **sort** – Nag\_SortEigValsType *Input*  
*On entry:* specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form.  
**sort** = Nag\_NoSortEigVals  
 Eigenvalues are not ordered.  
**sort** = Nag\_SortEigVals  
 Eigenvalues are ordered (see **selctg**).  
*Constraint:* **sort** = Nag\_NoSortEigVals or Nag\_SortEigVals.
- 5: **selctg** – function, supplied by the user *External Function*  
 If **sort** = Nag\_SortEigVals, **selctg** is used to select generalized eigenvalues to be moved to the top left of the generalized Schur form.  
 If **sort** = Nag\_NoSortEigVals, **selctg** is not referenced by nag\_zgges3 (f08xqc), and may be specified as NULLFN.

The specification of **selctg** is:

Nag\_Boolean selctg (Complex a, Complex b)

- 1: **a** – Complex *Input*  
 2: **b** – Complex *Input*

*On entry:* an eigenvalue  $\mathbf{a}[j-1]/\mathbf{b}[j-1]$  is selected if **selctg**( $\mathbf{a}[j-1], \mathbf{b}[j-1]$ ) is Nag\_TRUE.

Note that in the ill-conditioned case, a selected generalized eigenvalue may no longer satisfy **selctg**( $\mathbf{a}[j-1], \mathbf{b}[j-1]$ ) = Nag\_TRUE after ordering. **fail.code** = NE\_SCHUR\_REORDER\_SELECT in this case.

- 6: **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrices  $A$  and  $B$ .  
*Constraint:*  $\mathbf{n} \geq 0$ .

- 7: **a**[*dim*] – Complex *Input/Output*  
**Note:** the dimension, *dim*, of the array **a** must be at least  $\max(1, \mathbf{pda} \times \mathbf{n})$ .  
The (*i*, *j*)th element of the matrix *A* is stored in  
 $\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* the first of the pair of matrices, *A*.  
*On exit:* **a** has been overwritten by its generalized Schur form *S*.
- 8: **pda** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **a**.  
*Constraint:* **pda**  $\geq \max(1, \mathbf{n})$ .
- 9: **b**[*dim*] – Complex *Input/Output*  
**Note:** the dimension, *dim*, of the array **b** must be at least  $\max(1, \mathbf{pdb} \times \mathbf{n})$ .  
The (*i*, *j*)th element of the matrix *B* is stored in  
 $\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* the second of the pair of matrices, *B*.  
*On exit:* **b** has been overwritten by its generalized Schur form *T*.
- 10: **pdb** – Integer *Input*  
*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.  
*Constraint:* **pdb**  $\geq \max(1, \mathbf{n})$ .
- 11: **sdim** – Integer \* *Output*  
*On exit:* if **sort** = Nag\_NoSortEigVals, **sdim** = 0.  
If **sort** = Nag\_SortEigVals, **sdim** = number of eigenvalues (after sorting) for which **selectg** is Nag\_TRUE.
- 12: **alpha**[**n**] – Complex *Output*  
*On exit:* see the description of **beta**.
- 13: **beta**[**n**] – Complex *Output*  
*On exit:* **alpha**[*j* - 1]/**beta**[*j* - 1], for  $j = 1, 2, \dots, \mathbf{n}$ , will be the generalized eigenvalues. **alpha**[*j* - 1], for  $j = 1, 2, \dots, \mathbf{n}$  and **beta**[*j* - 1], for  $j = 1, 2, \dots, \mathbf{n}$ , are the diagonals of the complex Schur form (*A*, *B*) output by nag\_zgges3 (f08xqc). The **beta**[*j* - 1] will be non-negative real.  
**Note:** the quotients **alpha**[*j* - 1]/**beta**[*j* - 1] may easily overflow or underflow, and **beta**[*j* - 1] may even be zero. Thus, you should avoid naively computing the ratio  $\alpha/\beta$ . However, **alpha** will always be less than and usually comparable with  $\|A\|_2$  in magnitude, and **beta** will always be less than and usually comparable with  $\|B\|_2$ .

14: **vsl**[*dim*] – Complex *Output*

**Note:** the dimension, *dim*, of the array **vsl** must be at least

$\max(1, \mathbf{pdvsl} \times \mathbf{n})$  when **jobvsl** = Nag\_LeftVecs;  
1 otherwise.

The (*i*, *j*)th element of the matrix is stored in

**vsl**[(*j* – 1) × **pdvsl** + *i* – 1] when **order** = Nag\_ColMajor;  
**vsl**[(*i* – 1) × **pdvsl** + *j* – 1] when **order** = Nag\_RowMajor.

*On exit:* if **jobvsl** = Nag\_LeftVecs, **vsl** will contain the left Schur vectors, *Q*.

If **jobvsl** = Nag\_NotLeftVecs, **vsl** is not referenced.

15: **pdvsl** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **vsl**.

*Constraints:*

if **jobvsl** = Nag\_LeftVecs, **pdvsl** ≥  $\max(1, \mathbf{n})$ ;  
otherwise **pdvsl** ≥ 1.

16: **vsr**[*dim*] – Complex *Output*

**Note:** the dimension, *dim*, of the array **vsr** must be at least

$\max(1, \mathbf{pdvsr} \times \mathbf{n})$  when **jobvsr** = Nag\_RightVecs;  
1 otherwise.

The (*i*, *j*)th element of the matrix is stored in

**vsr**[(*j* – 1) × **pdvsr** + *i* – 1] when **order** = Nag\_ColMajor;  
**vsr**[(*i* – 1) × **pdvsr** + *j* – 1] when **order** = Nag\_RowMajor.

*On exit:* if **jobvsr** = Nag\_RightVecs, **vsr** will contain the right Schur vectors, *Z*.

If **jobvsr** = Nag\_NotRightVecs, **vsr** is not referenced.

17: **pdvsr** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **vsr**.

*Constraints:*

if **jobvsr** = Nag\_RightVecs, **pdvsr** ≥  $\max(1, \mathbf{n})$ ;  
otherwise **pdvsr** ≥ 1.

18: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument *value* had an illegal value.

**NE\_ENUM\_INT\_2**

On entry, **jobvsl** =  $\langle value \rangle$ , **pdvsl** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: if **jobvsl** = Nag\_LeftVecs, **pdvsl**  $\geq \max(1, \mathbf{n})$ ;  
 otherwise **pdvsl**  $\geq 1$ .

On entry, **jobvsr** =  $\langle value \rangle$ , **pdvsr** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: if **jobvsr** = Nag\_RightVecs, **pdvsr**  $\geq \max(1, \mathbf{n})$ ;  
 otherwise **pdvsr**  $\geq 1$ .

**NE\_INT**

On entry, **n** =  $\langle value \rangle$ .  
 Constraint: **n**  $\geq 0$ .

On entry, **pda** =  $\langle value \rangle$ .  
 Constraint: **pda**  $> 0$ .

On entry, **pdb** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $> 0$ .

On entry, **pdvsl** =  $\langle value \rangle$ .  
 Constraint: **pdvsl**  $> 0$ .

On entry, **pdvsr** =  $\langle value \rangle$ .  
 Constraint: **pdvsr**  $> 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pda**  $\geq \max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \mathbf{n})$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.  
 See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_ITERATION\_QZ**

The *QZ* iteration did not converge and the matrix pair  $(A, B)$  is not in the generalized Schur form. The computed  $\alpha_i$  and  $\beta_i$  should be correct for  $i = \langle value \rangle, \dots, \langle value \rangle$ .

The *QZ* iteration failed with an unexpected error, please contact NAG.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.  
 See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

**NE\_SCHUR\_REORDER**

The eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned).

**NE\_SCHUR\_REORDER\_SELECT**

After reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the generalized Schur form no longer satisfy **selectg** = Nag\_TRUE. This could also be caused by underflow due to scaling.

## 7 Accuracy

The computed generalized Schur factorization satisfies

$$A + E = QSZ^H, \quad B + F = QTZ^H,$$

where

$$\|(E, F)\|_F = O(\epsilon)\|(A, B)\|_F$$

and  $\epsilon$  is the *machine precision*. See Section 4.11 of Anderson *et al.* (1999) for further details.

## 8 Parallelism and Performance

nag\_zgges3 (f08xqc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_zgges3 (f08xqc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The total number of floating-point operations is proportional to  $n^3$ .

The real analogue of this function is nag\_dgges3 (f08xcc).

## 10 Example

This example finds the generalized Schur factorization of the matrix pair  $(A, B)$ , where

$$A = \begin{pmatrix} -21.10 - 22.50i & 53.50 - 50.50i & -34.50 + 127.50i & 7.50 + 0.50i \\ -0.46 - 7.78i & -3.50 - 37.50i & -15.50 + 58.50i & -10.50 - 1.50i \\ 4.30 - 5.50i & 39.70 - 17.10i & -68.50 + 12.50i & -7.50 - 3.50i \\ 5.50 + 4.40i & 14.40 + 43.30i & -32.50 - 46.00i & -19.00 - 32.50i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1.00 - 5.00i & 1.60 + 1.20i & -3.00 + 0.00i & 0.00 - 1.00i \\ 0.80 - 0.60i & 3.00 - 5.00i & -4.00 + 3.00i & -2.40 - 3.20i \\ 1.00 + 0.00i & 2.40 + 1.80i & -4.00 - 5.00i & 0.00 - 3.00i \\ 0.00 + 1.00i & -1.80 + 2.40i & 0.00 - 4.00i & 4.00 - 5.00i \end{pmatrix}.$$

### 10.1 Program Text

```

/* nag_zgges3 (f08xqc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <stdio.h>
#include <math.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <naga02.h>
#include <nagf08.h>
#include <nagf16.h>

```

```

#include <nagx02.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Complex alph, bet, z;
    double norma, normb, normd, norme, eps;
    Integer i, j, n, sdim, pda, pdb, pdc, pdd, pde, pdvsl, pdvsr;
    Integer exit_status = 0;

    /* Arrays */
    Complex *a = 0, *alpha = 0, *b = 0, *beta = 0, *c = 0;
    Complex *d = 0, *e = 0, *vsl = 0, *vsr = 0;
    Nag_LeftVecsType jobvsl;
    Nag_RightVecsType jobvsr;
    char nag_enum_arg[40];

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;

#ifdef NAG_COLUMN_MAJOR
#define A(I, J) a[(J-1)*pda + I - 1]
#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J) a[(I-1)*pda + J - 1]
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_zgges3 (f08xqc) Example Program Results\n\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%*[\n]", &n);
#else
    scanf("%" NAG_IFMT "%*[\n]", &n);
#endif
    if (n < 0) {
        printf("Invalid n\n");
        exit_status = 1;
        return exit_status;
    }
#ifdef _WIN32
    scanf_s(" %39s%*[\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf(" %39s%*[\n]", nag_enum_arg);
#endif
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    jobvsl = (Nag_LeftVecsType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
    scanf_s(" %39s%*[\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
    scanf(" %39s%*[\n]", nag_enum_arg);
#endif
    jobvsr = (Nag_RightVecsType) nag_enum_name_to_value(nag_enum_arg);

    pdvsl = (jobvsl == Nag_LeftVecs ? n : 1);
    pdvsr = (jobvsr == Nag_RightVecs ? n : 1);

```

```

pda = n;
pdb = n;
pdc = n;
pdd = n;
pde = n;
/* Allocate memory */
if (!(a = NAG_ALLOC(n * n, Complex)) ||
    !(b = NAG_ALLOC(n * n, Complex)) ||
    !(c = NAG_ALLOC(n * n, Complex)) ||
    !(d = NAG_ALLOC(n * n, Complex)) ||
    !(e = NAG_ALLOC(n * n, Complex)) ||
    !(alpha = NAG_ALLOC(n, Complex)) ||
    !(beta = NAG_ALLOC(n, Complex)) ||
    !(vsl = NAG_ALLOC(pdvs1 * pdvs1, Complex)) ||
    !(vsr = NAG_ALLOC(pdvsr * pdvsr, Complex)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Read in the matrices A and B */
for (i = 1; i <= n; ++i)
    for (j = 1; j <= n; ++j)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#else
        scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#endif
#ifdef _WIN32
        scanf_s("%*[\n]");
#else
        scanf("%*[\n]");
#endif

    for (i = 1; i <= n; ++i)
        for (j = 1; j <= n; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
            scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
            scanf_s("%*[\n]");
#else
            scanf("%*[\n]");
#endif

/* Copy A and B to D and E respectively: nag_zge_copy (f16tfc),
 * Complex valued general matrix copy.
 */
nag_zge_copy(order, Nag_NoTrans, n, n, a, pda, d, pdd, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_copy (f16tfc).\n%s\n", fail.message);
    exit_status = 2;
    goto END;
}
nag_zge_copy(order, Nag_NoTrans, n, n, b, pdb, e, pde, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_copy (f16tfc).\n%s\n", fail.message);
    exit_status = 3;
    goto END;
}
/* nag_zge_norm (f16uac): Find norms of input matrices A and B. */
nag_zge_norm(order, Nag_OneNorm, n, n, a, pda, &norma, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_norm (f16uac).\n%s\n", fail.message);
    exit_status = 4;
    goto END;
}
nag_zge_norm(order, Nag_OneNorm, n, n, b, pdb, &normb, &fail);

```

```

if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_norm (f16uac).\n%s\n", fail.message);
    exit_status = 5;
    goto END;
}

/* nag_gen_complx_mat_print_comp (x04dbc): Print matrices A and B. */
fflush(stdout);
nag_gen_complx_mat_print_comp(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                              n, a, pda, Nag_BracketForm, "%6.2f",
                              "Matrix A", Nag_IntegerLabels, 0,
                              Nag_IntegerLabels, 0, 80, 0, 0, &fail);

printf("\n");
if (fail.code != NE_NOERROR) {
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
          fail.message);
    exit_status = 6;
    goto END;
}
fflush(stdout);
nag_gen_complx_mat_print_comp(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                              n, b, pdb, Nag_BracketForm, "%6.2f",
                              "Matrix B", Nag_IntegerLabels, 0,
                              Nag_IntegerLabels, 0, 80, 0, 0, &fail);

printf("\n");
if (fail.code != NE_NOERROR) {
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
          fail.message);
    exit_status = 7;
    goto END;
}

/* Find the generalized Schur form using nag_zgges3 (f08xqc). */
nag_zgges3(order, jobvsl, jobvsr, Nag_NoSortEigVals, NULLFN, n, a, pda, b,
           pdb, &sdim, alpha, beta, vs1, pdvs1, vsr, pdvsr, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zgges3 (f08xqc).\n%s\n", fail.message);
    exit_status = 8;
    goto END;
}

/* Check generalized Schur Form by reconstruction of Schur vectors are
 * available.
 */
if (jobvsl == Nag_NotLeftVecs || jobvsr == Nag_NotRightVecs) {
    /* Cannot check factorization by reconstruction Schur vectors. */
    goto END;
}

/* Reconstruct A as Q*S*Z^H and subtract from original (D) using the steps
 * C = Q (Q in vs1) using nag_zge_copy (f16tfc).
 * C = C*S (S in a, upper triangular) using nag_ztrmm (f16zfc).
 * D = D - C*Z^H (Z in vsr) using nag_zgemm (f16zac).
 */
nag_zge_copy(order, Nag_NoTrans, n, n, vs1, pdvs1, c, pdc, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_copy (f16tfc).\n%s\n", fail.message);
    exit_status = 9;
    goto END;
}
alph = nag_complex(1.0, 0.0);
/* nag_ztrmm (f16zfc) Triangular complex matrix-matrix multiply. */
nag_ztrmm(order, Nag_RightSide, Nag_Upper, Nag_NoTrans, Nag_NonUnitDiag, n,
          n, alph, a, pda, c, pdc, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_ztrmm (f16zfc).\n%s\n", fail.message);
    exit_status = 10;
    goto END;
}
alph = nag_complex(-1.0, 0.0);
bet = nag_complex(1.0, 0.0);

```

```

nag_zgemm(order, Nag_NoTrans, Nag_ConjTrans, n, n, n, alph, c, pdc, vsr,
          pdvsr, bet, d, pdd, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zgemm (f16zac).\n%s\n", fail.message);
    exit_status = 11;
    goto END;
}

/* Reconstruct B as Q*T*Z^H and subtract from original (E) using the steps
 * Q = Q*T (Q in vsl, T in b, upper triangular) using nag_ztrmm (f16zfc).
 * E = E - Q*Z^H (Z in vsr) using nag_zgemm (f16zac).
 */
alph = nag_complex(1.0, 0.0);
nag_ztrmm(order, Nag_RightSide, Nag_Upper, Nag_NoTrans, Nag_NonUnitDiag, n,
          n, alph, b, pdb, vsl, pdvsl, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_ztrmm (f16zfc).\n%s\n", fail.message);
    exit_status = 12;
    goto END;
}
alph = nag_complex(-1.0, 0.0);
bet = nag_complex(1.0, 0.0);
nag_zgemm(order, Nag_NoTrans, Nag_ConjTrans, n, n, n, alph, vsl, pdvsl, vsr,
          pdvsr, bet, e, pde, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zgemm (f16zac).\n%s\n", fail.message);
    exit_status = 13;
    goto END;
}

/* nag_zge_norm (f16uac): Find norms of difference matrices D and E. */
nag_zge_norm(order, Nag_OneNorm, n, n, d, pdd, &normd, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_norm (f16uac).\n%s\n", fail.message);
    exit_status = 14;
    goto END;
}
nag_zge_norm(order, Nag_OneNorm, n, n, e, pde, &norme, &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_zge_norm (f16uac).\n%s\n", fail.message);
    exit_status = 15;
    goto END;
}

/* Get the machine precision, using nag_machine_precision (x02ajc) */
eps = nag_machine_precision;
if (MAX(normd, norme) > pow(eps, 0.8) * MAX(norma, normb)) {
    printf("The norm of the error in the reconstructed matrices is greater "
          "than expected.\nThe Schur factorization has failed.\n");
    exit_status = 16;
    goto END;
}

/* Print details on eigenvalues */
printf("Generalized eigenvalues are:\n");
for (i = 0; i < n; i++) {
    if (beta[i].re != 0.0 || beta[i].im != 0.0) {
        z = nag_complex_divide(alpha[i], beta[i]);
        printf("%3" NAG_IFMT " (%13.4e, %13.4e)\n", i + 1, z.re, z.im);
    }
    else
        printf("%3" NAG_IFMT " Eigenvalue is infinite\n", i + 1);
}

END:
NAG_FREE(a);
NAG_FREE(b);
NAG_FREE(c);
NAG_FREE(d);
NAG_FREE(e);
NAG_FREE(alpha);

```

```

NAG_FREE(beta);
NAG_FREE(vsl);
NAG_FREE(vsr);

return exit_status;
}

```

## 10.2 Program Data

nag\_zgges3 (f08xqc) Example Program Data

```

4 : n

Nag_LeftVecs : jobvsl
Nag_RightVecs : jobvsr

(-21.10,-22.50) ( 53.50,-50.50) (-34.50,127.50) ( 7.50, 0.50)
( -0.46, -7.78) ( -3.50,-37.50) (-15.50, 58.50) (-10.50, -1.50)
( 4.30, -5.50) ( 39.70,-17.10) (-68.50, 12.50) ( -7.50, -3.50)
( 5.50, 4.40) ( 14.40, 43.30) (-32.50,-46.00) (-19.00,-32.50) : A

( 1.00, -5.00) ( 1.60, 1.20) ( -3.00, 0.00) ( 0.00, -1.00)
( 0.80, -0.60) ( 3.00, -5.00) ( -4.00, 3.00) ( -2.40, -3.20)
( 1.00, 0.00) ( 2.40, 1.80) ( -4.00, -5.00) ( 0.00, -3.00)
( 0.00, 1.00) ( -1.80, 2.40) ( 0.00, -4.00) ( 4.00, -5.00) : B

```

## 10.3 Program Results

nag\_zgges3 (f08xqc) Example Program Results

Matrix A

```

1 2 3 4
1 (-21.10,-22.50) ( 53.50,-50.50) (-34.50,127.50) ( 7.50, 0.50)
2 ( -0.46, -7.78) ( -3.50,-37.50) (-15.50, 58.50) (-10.50, -1.50)
3 ( 4.30, -5.50) ( 39.70,-17.10) (-68.50, 12.50) ( -7.50, -3.50)
4 ( 5.50, 4.40) ( 14.40, 43.30) (-32.50,-46.00) (-19.00,-32.50)

```

Matrix B

```

1 2 3 4
1 ( 1.00, -5.00) ( 1.60, 1.20) ( -3.00, 0.00) ( 0.00, -1.00)
2 ( 0.80, -0.60) ( 3.00, -5.00) ( -4.00, 3.00) ( -2.40, -3.20)
3 ( 1.00, 0.00) ( 2.40, 1.80) ( -4.00, -5.00) ( 0.00, -3.00)
4 ( 0.00, 1.00) ( -1.80, 2.40) ( 0.00, -4.00) ( 4.00, -5.00)

```

Generalized eigenvalues are:

```

1 ( 3.0000e+00, -9.0000e+00)
2 ( 2.0000e+00, -5.0000e+00)
3 ( 3.0000e+00, -1.0000e+00)
4 ( 4.0000e+00, -5.0000e+00)

```

---