

# NAG Library Function Document

## nag\_zhsein (f08pxc)

### 1 Purpose

nag\_zhsein (f08pxc) computes selected left and/or right eigenvectors of a complex upper Hessenberg matrix corresponding to specified eigenvalues, by inverse iteration.

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_zhsein (Nag_OrderType order, Nag_SideType side,
  Nag_EigValsSourceType eig_source, Nag_InitVenumtype initv,
  const Nag_Boolean select[], Integer n, const Complex h[], Integer pdh,
  Complex w[], Complex vl[], Integer pdvl, Complex vr[], Integer pdvr,
  Integer mm, Integer *m, Integer ifaill[], Integer ifailr[],
  NagError *fail)
```

### 3 Description

nag\_zhsein (f08pxc) computes left and/or right eigenvectors of a complex upper Hessenberg matrix  $H$ , corresponding to selected eigenvalues.

The right eigenvector  $x$ , and the left eigenvector  $y$ , corresponding to an eigenvalue  $\lambda$ , are defined by:

$$Hx = \lambda x \quad \text{and} \quad y^H H = \lambda y^H \quad (\text{or } H^H y = \bar{\lambda} y).$$

The eigenvectors are computed by inverse iteration. They are scaled so that  $\max(|\operatorname{Re}(x_i)| + |\operatorname{Im}(x_i)|) = 1$ .

If  $H$  has been formed by reduction of a complex general matrix  $A$  to upper Hessenberg form, then the eigenvectors of  $H$  may be transformed to eigenvectors of  $A$  by a call to nag\_zunmhr (f08nuc).

### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **side** – Nag\_SideType *Input*

*On entry:* indicates whether left and/or right eigenvectors are to be computed.

**side** = Nag\_RightSide

Only right eigenvectors are computed.

**side** = Nag\_LeftSide

Only left eigenvectors are computed.

**side** = Nag\_BothSides

Both left and right eigenvectors are computed.

*Constraint:* **side** = Nag\_RightSide, Nag\_LeftSide or Nag\_BothSides.

3: **eig\_source** – Nag\_EigValsSourceType *Input*

*On entry:* indicates whether the eigenvalues of  $H$  (stored in **w**) were found using nag\_zhseqr (f08psc).

**eig\_source** = Nag\_HSEQRSource

The eigenvalues of  $H$  were found using nag\_zhseqr (f08psc); thus if  $H$  has any zero subdiagonal elements (and so is block triangular), then the  $j$ th eigenvalue can be assumed to be an eigenvalue of the block containing the  $j$ th row/column. This property allows the function to perform inverse iteration on just one diagonal block.

**eig\_source** = Nag\_NotKnown

No such assumption is made and the function performs inverse iteration using the whole matrix.

*Constraint:* **eig\_source** = Nag\_HSEQRSource or Nag\_NotKnown.

4: **initv** – Nag\_InitVenumtype *Input*

*On entry:* indicates whether you are supplying initial estimates for the selected eigenvectors.

**initv** = Nag\_NoVec

No initial estimates are supplied.

**initv** = Nag\_UserVec

Initial estimates are supplied in **vl** and/or **vr**.

*Constraint:* **initv** = Nag\_NoVec or Nag\_UserVec.

5: **select**[*dim*] – const Nag\_Boolean *Input*

**Note:** the dimension, *dim*, of the array **select** must be at least  $\max(1, \mathbf{n})$ .

*On entry:* specifies which eigenvectors are to be computed. To select the eigenvector corresponding to the eigenvalue  $\mathbf{w}[j - 1]$ , **select**[ $j - 1$ ] must be set to Nag\_TRUE.

6: **n** – Integer *Input*

*On entry:*  $n$ , the order of the matrix  $H$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

7: **h**[*dim*] – const Complex *Input*

**Note:** the dimension, *dim*, of the array **h** must be at least  $\max(1, \mathbf{pdh} \times \mathbf{n})$ .

The ( $i, j$ )th element of the matrix  $H$  is stored in

$\mathbf{h}[(j - 1) \times \mathbf{pdh} + i - 1]$  when **order** = Nag\_ColMajor;

$\mathbf{h}[(i - 1) \times \mathbf{pdh} + j - 1]$  when **order** = Nag\_RowMajor.

*On entry:* the  $n$  by  $n$  upper Hessenberg matrix  $H$ . If a NaN is detected in **h**, the function will return with **fail.code** = NE\_BAD\_PARAM.

*Constraint:* No element of **h** is equal to NaN.

8: **pdh** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **h**.

*Constraint:*  $\mathbf{pdh} \geq \max(1, \mathbf{n})$ .

9: **w**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **w** must be at least  $\max(1, \mathbf{n})$ .

*On entry:* the eigenvalues of the matrix *H*. If  **eig\_source** = Nag\_HSEQRSource, the array  **must** be exactly as returned by nag\_zhseqr (f08psc).

*On exit:* the real parts of some elements of **w** may be modified, as close eigenvalues are perturbed slightly in searching for independent eigenvectors.

10: **vl**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **vl** must be at least

$\max(1, \mathbf{pdvl} \times \mathbf{mm})$  when **side** = Nag\_LeftSide or Nag\_BothSides and **order** = Nag\_ColMajor;  
 $\max(1, \mathbf{n} \times \mathbf{pdvl})$  when **side** = Nag\_LeftSide or Nag\_BothSides and **order** = Nag\_RowMajor;  
 1 when **side** = Nag\_RightSide.

The (*i*, *j*)th element of the matrix is stored in

**vl**[(*j* – 1) × **pdvl** + *i* – 1] when **order** = Nag\_ColMajor;  
**vl**[(*i* – 1) × **pdvl** + *j* – 1] when **order** = Nag\_RowMajor.

*On entry:* if **initv** = Nag\_UserVec and **side** = Nag\_LeftSide or Nag\_BothSides, **vl** must contain starting vectors for inverse iteration for the left eigenvectors. Each starting vector must be stored in the same row or column as will be used to store the corresponding eigenvector (see below).

If **initv** = Nag\_NoVec, **vl** need not be set.

*On exit:* if **side** = Nag\_LeftSide or Nag\_BothSides, **vl** contains the computed left eigenvectors (as specified by **select**). The eigenvectors are stored consecutively in the rows or columns of the array (depending on the value of **order**), in the same order as their eigenvalues.

If **side** = Nag\_RightSide, **vl** is not referenced.

11: **pdvl** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **vl**.

*Constraints:*

if **order** = Nag\_ColMajor,  
     if **side** = Nag\_LeftSide or Nag\_BothSides, **pdvl** ≥ **n**;  
     if **side** = Nag\_RightSide, **pdvl** ≥ 1.;  
 if **order** = Nag\_RowMajor,  
     if **side** = Nag\_LeftSide or Nag\_BothSides, **pdvl** ≥  $\max(1, \mathbf{mm})$ ;  
     if **side** = Nag\_RightSide, **pdvl** ≥ 1.  
     if **side** = Nag\_LeftSide or Nag\_BothSides, **pdvl** ≥  $\max(1, \mathbf{m})$ ;  
     if **side** = Nag\_RightSide, **pdvl** ≥ 1..

12: **vr**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **vr** must be at least

$\max(1, \mathbf{pdvr} \times \mathbf{mm})$  when **side** = Nag\_RightSide or Nag\_BothSides and **order** = Nag\_ColMajor;  
 $\max(1, \mathbf{n} \times \mathbf{pdvr})$  when **side** = Nag\_RightSide or Nag\_BothSides and **order** = Nag\_RowMajor;  
 1 when **side** = Nag\_LeftSide.

The  $(i, j)$ th element of the matrix is stored in

$\mathbf{vr}[(j-1) \times \mathbf{pdvr} + i - 1]$  when **order** = Nag\_ColMajor;  
 $\mathbf{vr}[(i-1) \times \mathbf{pdvr} + j - 1]$  when **order** = Nag\_RowMajor.

*On entry:* if **initv** = Nag\_UserVec and **side** = Nag\_RightSide or Nag\_BothSides, **vr** must contain starting vectors for inverse iteration for the right eigenvectors. Each starting vector must be stored in the same row or column as will be used to store the corresponding eigenvector (see below).

If **initv** = Nag\_NoVec, **vr** need not be set.

*On exit:* if **side** = Nag\_RightSide or Nag\_BothSides, **vr** contains the computed right eigenvectors (as specified by **select**). The eigenvectors are stored consecutively in the rows or columns of the array (depending on the value of **order**), in the same order as their eigenvalues.

If **side** = Nag\_LeftSide, **vr** is not referenced.

13: **pdvr** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **vr**.

*Constraints:*

if **order** = Nag\_ColMajor,  
     if **side** = Nag\_RightSide or Nag\_BothSides, **pdvr**  $\geq$  **n**;  
     if **side** = Nag\_LeftSide, **pdvr**  $\geq$  1.;  
 if **order** = Nag\_RowMajor,  
     if **side** = Nag\_RightSide or Nag\_BothSides, **pdvr**  $\geq$  max(1, **mm**);  
     if **side** = Nag\_LeftSide, **pdvr**  $\geq$  1.  
     if **side** = Nag\_RightSide or Nag\_BothSides, **pdvr**  $\geq$  max(1, **m**);  
     if **side** = Nag\_LeftSide, **pdvr**  $\geq$  1..

14: **mm** – Integer *Input*

*On entry:* the number of columns in the arrays **vl** and/or **vr** if **order** = Nag\_ColMajor or the number of rows in the arrays if **order** = Nag\_RowMajor. The actual number of rows or columns required,  $required_{rowcol}$ , is obtained by counting 1 for each selected real eigenvector and 2 for each selected complex eigenvector (see **select**);  $0 \leq required_{rowcol} \leq n$ .

*Constraint:* **mm**  $\geq$   $required_{rowcol}$ .

15: **m** – Integer \* *Output*

*On exit:*  $required_{rowcol}$ , the number of selected eigenvectors.

16: **ifail**[*dim*] – Integer *Output*

**Note:** the dimension, *dim*, of the array **ifail** must be at least

max(1, **mm**) when **side** = Nag\_LeftSide or Nag\_BothSides;  
 1 when **side** = Nag\_RightSide.

*On exit:* if **side** = Nag\_LeftSide or Nag\_BothSides, then **ifail**[*i* - 1] = 0 if the selected left eigenvector converged and **ifail**[*i* - 1] = *j*  $\geq$  0 if the eigenvector stored in the *i*th row or column of **vl** (corresponding to the *j*th eigenvalue) failed to converge.

If **side** = Nag\_RightSide, **ifail** is not referenced.

17: **ifailr**[*dim*] – Integer

Output

**Note:** the dimension, *dim*, of the array **ifailr** must be at least

$\max(1, \mathbf{mm})$  when **side** = Nag\_RightSide or Nag\_BothSides;  
1 when **side** = Nag\_LeftSide.

*On exit:* if **side** = Nag\_RightSide or Nag\_BothSides, then **ifailr**[*i* – 1] = 0 if the selected right eigenvector converged and **ifailr**[*i* – 1] = *j* ≥ 0 if the eigenvector stored in the *i*th column of **vr** (corresponding to the *j*th eigenvalue) failed to converge.

If **side** = Nag\_LeftSide, **ifailr** is not referenced.

18: **fail** – NagError \*

Input/Output

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

Constraint: No element of **h** is equal to NaN.

On entry, argument *⟨value⟩* had an illegal value.

### NE\_CONVERGENCE

*⟨value⟩* eigenvectors (as indicated by arguments **ifailr** and/or **ifailr**) failed to converge. The corresponding columns of **vl** and/or **vr** contain no useful information.

### NE\_ENUM\_INT\_2

On entry, **side** = *⟨value⟩*, **pdvl** = *⟨value⟩*, **m** = *⟨value⟩*.

Constraint: if **side** = Nag\_LeftSide or Nag\_BothSides, **pdvl** ≥ max(1, **m**);  
if **side** = Nag\_RightSide, **pdvl** ≥ 1.

On entry, **side** = *⟨value⟩*, **pdvl** = *⟨value⟩*, **mm** = *⟨value⟩*.

Constraint: if **side** = Nag\_LeftSide or Nag\_BothSides, **pdvl** ≥ max(1, **mm**);  
if **side** = Nag\_RightSide, **pdvl** ≥ 1.

On entry, **side** = *⟨value⟩*, **pdvl** = *⟨value⟩* and **n** = *⟨value⟩*.

Constraint: if **side** = Nag\_LeftSide or Nag\_BothSides, **pdvl** ≥ **n**;  
if **side** = Nag\_RightSide, **pdvl** ≥ 1.

On entry, **side** = *⟨value⟩*, **pdvr** = *⟨value⟩*, **m** = *⟨value⟩*.

Constraint: if **side** = Nag\_RightSide or Nag\_BothSides, **pdvr** ≥ max(1, **m**);  
if **side** = Nag\_LeftSide, **pdvr** ≥ 1.

On entry, **side** = *⟨value⟩*, **pdvr** = *⟨value⟩*, **mm** = *⟨value⟩*.

Constraint: if **side** = Nag\_RightSide or Nag\_BothSides, **pdvr** ≥ max(1, **mm**);  
if **side** = Nag\_LeftSide, **pdvr** ≥ 1.

On entry, **side** = *⟨value⟩*, **pdvr** = *⟨value⟩* and **n** = *⟨value⟩*.

Constraint: if **side** = Nag\_RightSide or Nag\_BothSides, **pdvr** ≥ **n**;  
if **side** = Nag\_LeftSide, **pdvr** ≥ 1.

**NE\_INT**

On entry, **mm** =  $\langle value \rangle$ .

Constraint: **mm**  $\geq$  *required<sub>rowcol</sub>*, where *required<sub>rowcol</sub>* is the number of selected eigenvectors.

On entry, **n** =  $\langle value \rangle$ .

Constraint: **n**  $\geq$  0.

On entry, **pdh** =  $\langle value \rangle$ .

Constraint: **pdh**  $>$  0.

On entry, **pdvl** =  $\langle value \rangle$ .

Constraint: **pdvl**  $>$  0.

On entry, **pdvr** =  $\langle value \rangle$ .

Constraint: **pdvr**  $>$  0.

**NE\_INT\_2**

On entry, **pdh** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .

Constraint: **pdh**  $\geq$   $\max(1, \mathbf{n})$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

**7 Accuracy**

Each computed right eigenvector  $x_i$  is the exact eigenvector of a nearby matrix  $A + E_i$ , such that  $\|E_i\| = O(\epsilon)\|A\|$ . Hence the residual is small:

$$\|Ax_i - \lambda_i x_i\| = O(\epsilon)\|A\|.$$

However, eigenvectors corresponding to close or coincident eigenvalues may not accurately span the relevant subspaces.

Similar remarks apply to computed left eigenvectors.

**8 Parallelism and Performance**

nag\_zhsein (f08pxc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_zhsein (f08pxc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

**9 Further Comments**

The real analogue of this function is nag\_dhsein (f08pkc).

## **10 Example**

See Section 10 in nag\_zunmhr (f08nuc).

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