

NAG Library Routine Document

G05PMF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

G05PMF simulates from an exponential smoothing model, where the model uses either single exponential, double exponential or a Holt–Winters method.

2 Specification

SUBROUTINE G05PMF (MODE, N, ITYPE, P, PARAM, INIT, VAR, R, STATE, E, EN, &
X, IFAIL)

INTEGER MODE, N, ITYPE, P, STATE(*), EN, IFAIL
REAL (KIND=nag_wp) PARAM(*), INIT(*), VAR, R(*), E(EN), X(N)

3 Description

G05PMF returns $\{x_t : t = 1, 2, \dots, n\}$, a realization of a time series from an exponential smoothing model defined by one of five smoothing functions:

Single Exponential Smoothing

$$\begin{aligned}x_t &= m_{t-1} + \epsilon_t \\m_t &= \alpha x_t + (1 - \alpha)m_{t-1}\end{aligned}$$

Brown Double Exponential Smoothing

$$\begin{aligned}x_t &= m_{t-1} + \frac{r_{t-1}}{\alpha} + \epsilon_t \\m_t &= \alpha x_t + (1 - \alpha)m_{t-1} \\r_t &= \alpha(m_t - m_{t-1}) + (1 - \alpha)r_{t-1}\end{aligned}$$

Linear Holt Exponential Smoothing

$$\begin{aligned}x_t &= m_{t-1} + \phi r_{t-1} + \epsilon_t \\m_t &= \alpha x_t + (1 - \alpha)(m_{t-1} + \phi r_{t-1}) \\r_t &= \gamma(m_t - m_{t-1}) + (1 - \gamma)\phi r_{t-1}\end{aligned}$$

Additive Holt–Winters Smoothing

$$\begin{aligned}x_t &= m_{t-1} + \phi r_{t-1} + s_{t-1-p} + \epsilon_t \\m_t &= \alpha(x_t - s_{t-p}) + (1 - \alpha)(m_{t-1} + \phi r_{t-1}) \\r_t &= \gamma(m_t - m_{t-1}) + (1 - \gamma)\phi r_{t-1} \\s_t &= \beta(x_t - m_t) + (1 - \beta)s_{t-p}\end{aligned}$$

Multiplicative Holt–Winters Smoothing

$$\begin{aligned}x_t &= (m_{t-1} + \phi r_{t-1}) \times s_{t-1-p} + \epsilon_t \\m_t &= \alpha x_t / s_{t-p} + (1 - \alpha)(m_{t-1} + \phi r_{t-1}) \\r_t &= \gamma(m_t - m_{t-1}) + (1 - \gamma)\phi r_{t-1} \\s_t &= \beta x_t / m_t + (1 - \beta)s_{t-p}\end{aligned}$$

where m_t is the mean, r_t is the trend and s_t is the seasonal component at time t with p being the seasonal order. The errors, ϵ_t are either drawn from a normal distribution with mean zero and variance σ^2 or randomly sampled, with replacement, from a user-supplied vector.

4 References

Chatfield C (1980) *The Analysis of Time Series* Chapman and Hall

5 Parameters

- 1: MODE – INTEGER *Input*
- On entry:* indicates if G05PMF is continuing from a previous call or, if not, how the initial values are computed.
- MODE = 0
Values for m_0 , r_0 and s_{-j} , for $j = 0, 1, \dots, p - 1$, are supplied in INIT.
- MODE = 1
G05PMF continues from a previous call using values that are supplied in R. R is not updated.
- MODE = 2
G05PMF continues from a previous call using values that are supplied in R. R is updated.
- Constraint:* MODE = 0, 1 or 2.
- 2: N – INTEGER *Input*
- On entry:* the number of terms of the time series being generated.
- Constraint:* $N \geq 0$.
- 3: ITYPE – INTEGER *Input*
- On entry:* the smoothing function.
- ITYPE = 1
Single exponential.
- ITYPE = 2
Brown's double exponential.
- ITYPE = 3
Linear Holt.
- ITYPE = 4
Additive Holt–Winters.
- ITYPE = 5
Multiplicative Holt–Winters.
- Constraint:* ITYPE = 1, 2, 3, 4 or 5.
- 4: P – INTEGER *Input*
- On entry:* if ITYPE = 4 or 5, the seasonal order, p , otherwise P is not referenced.
- Constraint:* if ITYPE = 4 or 5, $P > 1$.
- 5: PARAM(*) – REAL (KIND=nag_wp) array *Input*
- Note:** the dimension of the array PARAM must be at least 1 if ITYPE = 1 or 2, 3 if ITYPE = 3 and at least 4 if ITYPE = 4 or 5.
- On entry:* the smoothing parameters.
- If ITYPE = 1 or 2, PARAM(1) = α and any remaining elements of PARAM are not referenced.
- If ITYPE = 3, PARAM(1) = α , PARAM(2) = γ , PARAM(3) = ϕ and any remaining elements of PARAM are not referenced.
- If ITYPE = 4 or 5, PARAM(1) = α , PARAM(2) = γ , PARAM(3) = β and PARAM(4) = ϕ and any remaining elements of PARAM are not referenced.

Constraints:

- if $ITYPE = 1$, $0.0 \leq \alpha \leq 1.0$;
- if $ITYPE = 2$, $0.0 < \alpha \leq 1.0$;
- if $ITYPE = 3$, $0.0 \leq \alpha \leq 1.0$ and $0.0 \leq \gamma \leq 1.0$ and $\phi \geq 0.0$;
- if $ITYPE = 4$ or 5 , $0.0 \leq \alpha \leq 1.0$ and $0.0 \leq \gamma \leq 1.0$ and $0.0 \leq \beta \leq 1.0$ and $\phi \geq 0.0$.

- 6: INIT(*) – REAL (KIND=nag_wp) array *Input*
Note: the dimension of the array INIT must be at least 1 if $ITYPE = 1$, 2 if $ITYPE = 2$ or 3 and at least $2 + P$ if $ITYPE = 4$ or 5.
On entry: if $MODE = 0$, the initial values for m_0 , r_0 and s_{-j} , for $j = 0, 1, \dots, p - 1$, used to initialize the smoothing.
 If $ITYPE = 1$, $INIT(1) = m_0$ and any remaining elements of INIT are not referenced.
 If $ITYPE = 2$ or 3, $INIT(1) = m_0$ and $INIT(2) = r_0$ and any remaining elements of INIT are not referenced.
 If $ITYPE = 4$ or 5, $INIT(1) = m_0$, $INIT(2) = r_0$ and $INIT(3)$ to $INIT(2 + p)$ hold the values for s_{-j} , for $j = 0, 1, \dots, p - 1$. Any remaining elements of INIT are not referenced.
- 7: VAR – REAL (KIND=nag_wp) *Input*
On entry: the variance, σ^2 of the Normal distribution used to generate the errors ϵ_i . If $VAR \leq 0.0$ then Normally distributed errors are not used.
- 8: R(*) – REAL (KIND=nag_wp) array *Input/Output*
Note: the dimension of the array R must be at least 13 if $ITYPE = 1, 2$ or 3 and at least $13 + P$ if $ITYPE = 4$ or 5.
On entry: if $MODE = 1$ or 2, R must contain the values as returned by a previous call to G05PMF, R need not be set otherwise.
On exit: if $MODE = 1$, R is unchanged. Otherwise, R contains the information on the current state of smoothing.
Constraint: if $MODE = 1$ or 2, R must have been initialized by at least one call to G05PMF or G13AMF with $MODE \neq 1$, and R must not have been changed since that call.
- 9: STATE(*) – INTEGER array *Communication Array*
Note: the actual argument supplied **must** be the array STATE supplied to the initialization routines G05KFF or G05KGF.
On entry: contains information on the selected base generator and its current state.
On exit: contains updated information on the state of the generator.
- 10: E(EN) – REAL (KIND=nag_wp) array *Input*
On entry: if $EN > 0$ and $VAR \leq 0.0$, a vector from which the errors, ϵ_t are randomly drawn, with replacement.
 If $EN \leq 0$, E is not referenced.
- 11: EN – INTEGER *Input*
On entry: if $EN > 0$, then the length of the vector E.
 If both $VAR \leq 0.0$ and $EN \leq 0$ then $\epsilon_t = 0.0$, for $t = 1, 2, \dots, n$.
- 12: X(N) – REAL (KIND=nag_wp) array *Output*
On exit: the generated time series, x_t , for $t = 1, 2, \dots, n$.

13: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, MODE = $\langle value \rangle$.
Constraint: MODE = 0, 1 or 2.

IFAIL = 2

On entry, N = $\langle value \rangle$.
Constraint: N \geq 0.

IFAIL = 3

On entry, ITYPE = $\langle value \rangle$.
Constraint: ITYPE = 1, 2, 3, 4 or 5.

IFAIL = 4

On entry, P = $\langle value \rangle$.
Constraint: if ITYPE = 4 or 5, P \geq 2.

IFAIL = 5

On entry, PARAM($\langle value \rangle$) = $\langle value \rangle$.
Constraint: $0 \leq$ PARAM(i) \leq 1.
On entry, PARAM($\langle value \rangle$) = $\langle value \rangle$.
Constraint: if ITYPE = 2, $0 <$ PARAM(i) \leq 1.
On entry, PARAM($\langle value \rangle$) = $\langle value \rangle$.
Constraint: PARAM(i) \geq 0.

IFAIL = 8

On entry, some of the elements of the array R have been corrupted or have not been initialized.

IFAIL = 9

On entry, STATE vector has been corrupted or not initialized.

IFAIL = 12

Model unsuitable for multiplicative Holt–Winter, try a different set of parameters.

IFAIL = -99

An unexpected error has been triggered by this routine. Please contact NAG.
See Section 3.8 in the Essential Introduction for further information.

IFAIL = -399

Your licence key may have expired or may not have been installed correctly.
See Section 3.7 in the Essential Introduction for further information.

IFAIL = -999

Dynamic memory allocation failed.
See Section 3.6 in the Essential Introduction for further information.

7 Accuracy

Not applicable.

8 Parallelism and Performance

G05PMF is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

None.

10 Example

This example reads 11 observations from a time series relating to the rate of the earth's rotation about its polar axis and fits an exponential smoothing model using G13AMF.

G05PMF is then called multiple times to obtain simulated forecast confidence intervals.

10.1 Program Text

```

Program g05pmfe

!      G05PMF Example Program Text

!      Mark 25 Release. NAG Copyright 2014.

!      .. Use Statements ..
Use nag_library, Only: g01amf, g01faf, g05kff, g05pmf, g13amf, nag_wp
!      .. Implicit None Statement ..
Implicit None
!      .. Parameters ..
Integer, Parameter          :: lseed = 1, nin = 5, nout = 6
!      .. Local Scalars ..
Real (Kind=nag_wp)         :: ad, alpha, dv, tmp, var, z
Integer                    :: en, genid, i, ifail, itype, k, le, &
                             linit, lparam, lr, lstate, mode, n, &
                             nf, nsim, p, smode, subid
!      .. Local Arrays ..
Real (Kind=nag_wp), Allocatable :: blim(:,,:), bsim(:,,:), e(:), fse(:), &
                                     fv(:), glim(:,,:), gsim(:,,:), &
                                     init(:), param(:), r(:), res(:), &

```

```

                                tsim1(:), tsim2(:), y(:), yhat(:)
Real (Kind=nag_wp)              :: q(2)
Integer                          :: seed(lseed)
Integer, Allocatable             :: state(:)
! .. Executable Statements ..
Write (nout,*) 'G05PMF Example Program Results'
Write (nout,*)

! Skip heading in data file
Read (nin,*)

! Read in the base generator information and seed
Read (nin,*) genid, subid, seed(1)

! Initial call to initialiser to get size of STATE array
lstate = 0
Allocate (state(lstate))
ifail = 0
Call g05kff(genid,subid,seed,lseed,state,lstate,ifail)

! Reallocate STATE
Deallocate (state)
Allocate (state(lstate))

! Initialize the generator to a repeatable sequence
ifail = 0
Call g05kff(genid,subid,seed,lseed,state,lstate,ifail)

! Read in the initial arguments and check array sizes
Read (nin,*) mode, itype, n, nf, nsim, alpha

Select Case (itype)
Case (1)
  lparam = 1
  p = 0
  linit = 1
Case (2)
  lparam = 2
  p = 0
  linit = 2
Case (3)
  lparam = 3
  p = 0
  linit = 2
Case Default
  lparam = 4

! Read in seasonal order
Read (nin,*) p

  linit = p + 2
End Select
lr = 13 + p
! Not using the E array for the bootstrap
le = 0
Allocate (param(lparam),init(linit),r(lr),e(le),fv(nf),fse(nf),yhat(n), &
  res(n),blim(2,nf),glim(2,nf),tsim1(nf),tsim2(nf),gsim(nsim,nf), &
  bsim(nsim,nf),y(n))

! Read in series to be smoothed
Read (nin,*) y(1:n)

! Read in parameters
Read (nin,*) param(1:lparam)

! Read in the MODE dependent arguments (skipping headings)
Select Case (mode)
Case (0)
! User supplied initial values
Read (nin,*) init(1:linit)
Case (1)

```

```

!      Continuing from a previously saved R
      Read (nin,*) r(1:(p+13))
Case (2)
!      Initial values calculated from first K observations
      Read (nin,*) k
End Select

!      Fit a smoothing model (parameter R in G05PMF and STATE in G13AMF
!      are in the same format)
      ifail = 0
      Call g13amf(mode,itype,p,param,n,y,k,init,nf,fv,fse,yhat,res,dv,ad,r, &
        ifail)

!      Simulate forecast values from the model, and don't update R
      smode = 2
      var = dv*dv

!      Simulate NSIM forecasts
      Do i = 1, nsim
!      Not using E array for gaussian errors
        en = 0

!      Simulations assuming gaussian errors
        ifail = 0
        Call g05pmf(smode,nf,itype,p,param,init,var,r,state,e,en,tsim1,ifail)

!      For bootstrapping error, we are using RES from call to G13AMF as the
!      errors, and length of RES is N
        en = n

!      Bootstrapping errors
        ifail = 0
        Call g05pmf(smode,nf,itype,p,param,init,0.0EO_nag_wp,r,state,res,en, &
          tsim2,ifail)

!      Copy and transpose the simulated values
        gsim(i,1:nf) = tsim1(1:nf)
        bsim(i,1:nf) = tsim2(1:nf)
      End Do

!      Calculate CI based on the quantiles for each simulated forecast
      q(1) = alpha/2.0EO_nag_wp
      q(2) = 1.0EO_nag_wp - q(1)
      Do i = 1, nf
        ifail = 0
        Call g01amf(nsim,gsim(1,i),2,q,glim(1,i),ifail)
        ifail = 0
        Call g01amf(nsim,bsim(1,i),2,q,blim(1,i),ifail)
      End Do

!      Display the forecast values and associated prediction intervals
      Write (nout,*) 'Initial values used:'
      Write (nout,99998) init(1:limit)
      Write (nout,*)
      Write (nout,99999) 'Mean Deviation      = ', dv
      Write (nout,99999) 'Absolute Deviation = ', ad
      Write (nout,*)
      Write (nout,*) '          Observed      1-Step'
      Write (nout,*) ' Period   Values      Forecast      Residual'
      Write (nout,*)
      Write (nout,99997)(i,y(i),yhat(i),res(i),i=1,n)
      Write (nout,*)
      Write (nout,*) '          '          ' // &
      Write (nout,*) '          Simulated CI      Simulated CI'
      Write (nout,*) 'Obs. Forecast      Estimated CI      ' // &
      Write (nout,*) '          (Gaussian Errors)      (Bootstrap Errors)'
      z = g01faf('L',q(2),ifail)
      Do i = 1, nf
        tmp = z*fse(i)
        Write (nout,99996) n + i, fv(i), fv(i) - tmp, fv(i) + tmp, glim(1,i), &
          glim(2,i), blim(1,i), blim(2,i)
      End Do

```

```

End Do
Write (nout,99995) 100.0E0_nag_wp*(1.0E0_nag_wp-alpha), &
  '% CIs were produced'

99999 Format (A,E12.4)
99998 Format (F12.3)
99997 Format (I4,1X,F12.3,1X,F12.3,1X,F12.3)
99996 Format (I3,7(1X,F10.3))
99995 Format (1X,F5.1,A)
End Program g05pmfe

```

10.2 Program Data

G05PMF Example Program Data

```

1 1 1762543          :: GENID,SUBID,SEED(1)
2 3 11 5 100 0.05   :: MODE,ITYPE,N,NF,NSIM,ALPHA
180 135 213 181 148 204 228 225 198 200 187 :: Y
0.01 1.0 1.0       :: PARAM
11                 :: K

```

10.3 Program Results

G05PMF Example Program Results

Initial values used:

```

168.018
3.800

```

```

Mean Deviation      = 0.2547E+02
Absolute Deviation  = 0.2123E+02

```

Period	Observed Values	1-Step Forecast	Residual
1	180.000	171.818	8.182
2	135.000	175.782	-40.782
3	213.000	178.848	34.152
4	181.000	183.005	-2.005
5	148.000	186.780	-38.780
6	204.000	189.800	14.200
7	228.000	193.492	34.508
8	225.000	197.732	27.268
9	198.000	202.172	-4.172
10	200.000	206.256	-6.256
11	187.000	210.256	-23.256

Obs.	Forecast	Estimated CI	Simulated CI		Simulated CI		
			(Gaussian Errors)		(Bootstrap Errors)		
12	213.854	163.928	263.781	161.431	258.001	173.073	248.363
13	217.685	167.748	267.622	172.660	262.100	177.311	252.638
14	221.516	171.556	271.475	169.259	263.107	179.344	256.921
15	225.346	175.347	275.345	180.721	272.776	183.672	260.804
16	229.177	179.115	279.238	184.790	263.591	186.398	264.173

95.0% CIs were produced

Example Program
Exponential Smoothing
(95% confidence intervals (CIs) are shown)

