

# NAG Library Function Document

## nag\_specfun\_2f1\_real\_scaled (s22bfc)

### 1 Purpose

nag\_specfun\_2f1\_real\_scaled (s22bfc) returns a value for the Gauss hypergeometric function  ${}_2F_1(a, b; c; x)$  for real parameters  $a, b$  and  $c$ , and real argument  $x$ . The result is returned in the scaled form  ${}_2F_1(a, b; c; x) = f_{\text{fr}} \times 2^{f_{\text{sc}}}$ .

### 2 Specification

```
#include <nag.h>
#include <nags.h>

void nag_specfun_2f1_real_scaled (double ani, double adr, double bni,
    double bdr, double cni, double cdr, double x, double *frf, Integer *scf,
    NagError *fail)
```

### 3 Description

nag\_specfun\_2f1\_real\_scaled (s22bfc) returns a value for the Gauss hypergeometric function  ${}_2F_1(a, b; c; x)$  for real parameters  $a, b$  and  $c$ , and for real argument  $x$ .

The Gauss hypergeometric function is a solution to the hypergeometric differential equation,

$$x(1-x)\frac{d^2f}{dx^2} + (c - (a+b+1)x)\frac{df}{dx} - abf = 0. \quad (1)$$

For  $|x| < 1$ , it may be defined by the Gauss series,

$${}_2F_1(a, b; c; x) = \sum_{s=0}^{\infty} \frac{(a)_s (b)_s}{(c)_s s!} x^s = 1 + \frac{ab}{c}x + \frac{a(a+1)b(b+1)}{c(c+1)2!}x^2 + \dots, \quad (2)$$

where  $(a)_s = 1(a)(a+1)(a+2)\dots(a+s-1)$  is the rising factorial of  $a$ .  ${}_2F_1(a, b; c; x)$  is undefined for  $c = 0$  or  $c$  a negative integer.

For  $|x| < 1$ , the series is absolutely convergent and  ${}_2F_1(a, b; c; x)$  is finite.

For  $x < 1$ , linear transformations of the form,

$${}_2F_1(a, b; c; x) = C_1(a_1, b_1, c_1, x_1) {}_2F_1(a_1, b_1; c_1; x_1) + C_2(a_2, b_2, c_2, x_2) {}_2F_1(a_2, b_2; c_2; x_2) \quad (3)$$

exist, where  $x_1, x_2 \in (0, 1]$ .  $C_1$  and  $C_2$  are real valued functions of the parameters and argument, typically involving products of gamma functions. When these are degenerate, finite limiting cases exist. Hence for  $x < 0$ ,  ${}_2F_1(a, b; c; x)$  is defined by analytic continuation, and for  $x < 1$ ,  ${}_2F_1(a, b; c; x)$  is real and finite.

For  $x = 1$ , the following apply:

If  $c > a + b$ ,  ${}_2F_1(a, b; c; 1) = \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)}$ , and hence is finite. Solutions also exist for the degenerate cases where  $c - a$  or  $c - b$  are negative integers or zero.

If  $c \leq a + b$ ,  ${}_2F_1(a, b; c; 1)$  is infinite, and the sign of  ${}_2F_1(a, b; c; 1)$  is determinable as  $x$  approaches 1 from below.

In the complex plane, the principal branch of  ${}_2F_1(a, b; c; z)$  is taken along the real axis from  $x = 1.0$  increasing.  ${}_2F_1(a, b; c; z)$  is multivalued along this branch, and for real parameters  $a, b$  and  $c$  is typically not real valued. As such, this function will not compute a solution when  $x > 1$ .

The solution strategy used by this function is primarily dependent upon the value of the argument  $x$ . Once trivial cases and the case  $x = 1.0$  are eliminated, this proceeds as follows.

For  $0 < x \leq 0.5$ , sets of safe parameters  $\{\alpha_{i,j}, \beta_{i,j}, \zeta_{i,j}, \chi_j | 1 \leq j \leq 2, 1 \leq i \leq 4\}$  are determined, such that the values of  ${}_2F_1(a_j, b_j; c_j; x_j)$  required for an appropriate transformation of the type (3) may be calculated either directly or using recurrence relations from the solutions of  ${}_2F_1(\alpha_{i,j}, \beta_{i,j}; \zeta_{i,j}; \chi_j)$ . If  $c$  is positive, then only transformations with  $C_2 = 0.0$  will be used, implying only  ${}_2F_1(a_1, b_1; c_1; x_1)$  will be required, with the transformed argument  $x_1 = x$ . If  $c$  is negative, in some cases a transformation with  $C_2 \neq 0.0$  will be used, with the argument  $x_2 = 1.0 - x$ . The function then cycles through these sets until acceptable solutions are generated. If no computation produces an accurate answer, the least inaccurate answer is selected to complete the computation. See Section 7.

For  $0.5 < x < 1.0$ , an identical approach is first used with the argument  $x$ . Should this fail, a linear transformation resulting in both transformed arguments satisfying  $x_j = 1.0 - x$  is employed, and the above strategy for  $0 < x \leq 0.5$  is utilized on both components. Further transformations in these sub-computations are however limited to single terms with no argument transformation.

For  $x < 0$ , a linear transformation mapping the argument  $x$  to the interval  $(0, 0.5]$  is first employed. The strategy for  $0 < x \leq 0.5$  is then used on each component, including possible further two term transforms. To avoid some degenerate cases, a transform mapping the argument  $x$  to  $[0.5, 1)$  may also be used.

For improved precision in the final result, this function accepts  $a, b$  and  $c$  split into an integral and a decimal fractional component. Specifically,  $a = a_i + a_r$ , where  $|a_r| \leq 0.5$  and  $a_i = a - a_r$  is integral. The other parameters  $b$  and  $c$  are similarly deconstructed.

In addition to the above restrictions on  $c$  and  $x$ , an artificial bound,  $arbnd$ , is placed on the magnitudes of  $a, b, c$  and  $x$  to minimize the occurrence of overflow in internal calculations, particularly those involving real to integer conversions.  $arbnd = 0.0001 \times I_{\max}$ , where  $I_{\max}$  is the largest machine integer (see `nag_max_integer (X02BBC)`). It should however not be assumed that this function will produce accurate answers for all values of  $a, b, c$  and  $x$  satisfying this criterion.

This function also tests for non-finite values of the parameters and argument on entry, and assigns non-finite values upon completion if appropriate. See Section 9 and Chapter x07.

Please consult the NIST Digital Library of Mathematical Functions or the companion (2010) for a detailed discussion of the Gauss hypergeometric function including special cases, transformations, relations and asymptotic approximations.

## 4 References

*NIST Handbook of Mathematical Functions* (2010) (eds F W J Olver, D W Lozier, R F Boisvert, C W Clark) Cambridge University Press

Pearson J (2009) Computation of hypergeometric functions *MSc Dissertation, Mathematical Institute, University of Oxford*

## 5 Arguments

1: **ani** – double *Input*

*On entry:*  $a_i$ , the nearest integer to  $a$ , satisfying  $a_i = a - a_r$ .

*Constraints:*

$$\begin{aligned} \mathbf{ani} &= \lfloor \mathbf{ani} \rfloor; \\ |\mathbf{ani}| &\leq arbnd. \end{aligned}$$

2: **adr** – double *Input*

*On entry:*  $a_r$ , the signed decimal remainder satisfying  $a_r = a - a_i$  and  $|a_r| \leq 0.5$ .

*Constraint:*  $|\mathbf{adr}| \leq 0.5$ .

- 3: **bni** – double *Input*  
*On entry:*  $b_i$ , the nearest integer to  $b$ , satisfying  $b_i = b - b_r$ .  
*Constraints:*  

$$\mathbf{bni} = \lfloor \mathbf{bni} \rfloor;$$

$$|\mathbf{bni}| \leq \mathit{arbnd}.$$
- 4: **bdr** – double *Input*  
*On entry:*  $b_r$ , the signed decimal remainder satisfying  $b_r = b - b_i$  and  $|b_r| \leq 0.5$ .  
*Constraint:*  $|\mathbf{bdr}| \leq 0.5$ .
- 5: **cni** – double *Input*  
*On entry:*  $c_i$ , the nearest integer to  $c$ , satisfying  $c_i = c - c_r$ .  
*Constraints:*  

$$\mathbf{cni} = \lfloor \mathbf{cni} \rfloor;$$

$$|\mathbf{cni}| \leq \mathit{arbnd};$$
 if  $|\mathbf{cdr}| < 16.0\epsilon$ ,  $\mathbf{cni} \geq 1.0$ .
- 6: **cdr** – double *Input*  
*On entry:*  $c_r$ , the signed decimal remainder satisfying  $c_r = c - c_i$  and  $|c_r| \leq 0.5$ .  
*Constraint:*  $|\mathbf{cdr}| \leq 0.5$ .
- 7: **x** – double *Input*  
*On entry:* the argument  $x$ .  
*Constraint:*  $-\mathit{arbnd} < \mathbf{x} \leq 1$ .
- 8: **frf** – double \* *Output*  
*On exit:*  $f_{\text{fr}}$ , the scaled real component of the solution satisfying  $f_{\text{fr}} = {}_2F_1(a, b; c; x) \times 2^{-f_{\text{sc}}}$ , i.e.,  ${}_2F_1(a, b; c; x) = f_{\text{fr}} \times 2^{f_{\text{sc}}}$ . See Section 9 for the behaviour of  $f_{\text{fr}}$  when a finite or non-finite answer is returned.
- 9: **scf** – Integer \* *Output*  
*On exit:*  $f_{\text{sc}}$ , the scaling power of two, satisfying  $f_{\text{sc}} = \log_2 \left( \frac{{}_2F_1(a, b; c; x)}{f_{\text{fr}}} \right)$ , i.e.,  ${}_2F_1(a, b; c; x) = f_{\text{fr}} \times 2^{f_{\text{sc}}}$ . See Section 9 for the behaviour of  $f_{\text{sc}}$  when a non-finite answer is returned.
- 10: **fail** – NagError \* *Input/Output*  
 The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.  
 See Section 3.2.1.2 in the Essential Introduction for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle \mathit{value} \rangle$  had an illegal value.

**NE\_CANNOT\_CALCULATE**

An internal calculation has resulted in an undefined result.

**NE\_COMPLEX**

On entry,  $\mathbf{x} = \langle value \rangle$ .

In general,  ${}_2F_1(a, b; c; x)$  is not real valued when  $x > 1$ .

**NE\_INFINITY**

On entry,  $\mathbf{x} = \langle value \rangle$ ,  $c = \langle value \rangle$ ,  $a + b = \langle value \rangle$ .

${}_2F_1(a, b; c; 1)$  is infinite in the case  $c \leq a + b$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.  
See Section 3.6.6 in the Essential Introduction for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.  
See Section 3.6.5 in the Essential Introduction for further information.

**NE\_OVERFLOW**

Overflow occurred in a subcalculation of  ${}_2F_1(a, b; c; x)$ . The answer may be completely incorrect.

**NE\_REAL**

On entry,  $\mathbf{adr}$  does not satisfy  $|\mathbf{adr}| \leq 0.5$ .

On entry,  $\mathbf{bdr}$  does not satisfy  $|\mathbf{bdr}| \leq 0.5$ .

On entry,  $\mathbf{cdr}$  does not satisfy  $|\mathbf{cdr}| \leq 0.5$ .

**NE\_REAL\_2**

On entry,  $c = \mathbf{cni} + \mathbf{cdr} = \langle value \rangle$ .

${}_2F_1(a, b; c; x)$  is undefined when  $c$  is zero or a negative integer.

**NE\_REAL\_ARG\_NON\_INTEGRAL**

$\mathbf{ANI}$  is non-integral.

On entry,  $\mathbf{ani} = \langle value \rangle$ .

Constraint:  $\mathbf{ani} = \lfloor \mathbf{ani} \rfloor$ .

$\mathbf{bni}$  is non-integral.

On entry,  $\mathbf{bni} = \langle value \rangle$ .

Constraint:  $\mathbf{bni} = \lfloor \mathbf{bni} \rfloor$ .

$\mathbf{cni}$  is non-integral.

On entry,  $\mathbf{cni} = \langle value \rangle$ .

Constraint:  $\mathbf{cni} = \lfloor \mathbf{cni} \rfloor$ .

**NE\_REAL\_RANGE\_CONS**

On entry,  $\mathbf{ani}$  does not satisfy  $|\mathbf{ani}| \leq \mathit{arbn}d = \langle value \rangle$ .

On entry,  $\mathbf{bni}$  does not satisfy  $|\mathbf{bni}| \leq \mathit{arbn}d = \langle value \rangle$ .

On entry,  $\mathbf{cni}$  does not satisfy  $|\mathbf{cni}| \leq \mathit{arbn}d = \langle value \rangle$ .

On entry,  $\mathbf{x}$  does not satisfy  $|\mathbf{x}| \leq \mathit{arbn}d = \langle value \rangle$ .

**NE\_TOTAL\_PRECISION\_LOSS**

All approximations have completed, and the final residual estimate indicates no accuracy can be guaranteed.

Relative residual =  $\langle value \rangle$ .

**NW\_OVERFLOW\_WARN**

On completion, overflow occurred in the evaluation of  ${}_2F_1(a, b; c; x)$ .

**NW\_SOME\_PRECISION\_LOSS**

All approximations have completed, and the final residual estimate indicates some precision may have been lost.

Relative residual =  $\langle value \rangle$ .

**NW\_UNDERFLOW\_WARN**

Underflow occurred during the evaluation of  ${}_2F_1(a, b; c; x)$ . The returned value may be inaccurate.

**7 Accuracy**

In general, if **fail.code** = NE\_NOERROR, the value of  ${}_2F_1(a, b; c; x)$  may be assumed accurate, with the possible loss of one or two decimal places. Assuming the result does not overflow, an error estimate *res* is made internally using equation (1). If the magnitude of this residual *res* is sufficiently large, a different **fail.code** will be returned. Specifically,

<b>fail.code</b> = NE_NOERROR or NW_UNDERFLOW_WARN	$res \leq 1000\epsilon$
<b>fail.code</b> = NW_SOME_PRECISION_LOSS	$1000\epsilon < res \leq 0.1$
<b>fail.code</b> = NE_TOTAL_PRECISION_LOSS	$res > 0.1$

where  $\epsilon$  is the *machine precision* as returned by nag\_machine\_precision (X02AJC). Note that underflow may also have occurred if **fail.code** = NE\_TOTAL\_PRECISION\_LOSS or NW\_SOME\_PRECISION\_LOSS.

A further estimate of the residual can be constructed using equation (1), and the differential identity,

$$\begin{aligned} \frac{d({}_2F_1(a, b; c; x))}{dx} &= \frac{ab}{c} {}_2F_1(a+1, b+1; c+1; x) \\ \frac{d^2({}_2F_1(a, b; c; x))}{dx^2} &= \frac{a(a+1)b(b+1)}{c(c+1)} {}_2F_1(a+2, b+2; c+2; x) \end{aligned} \quad (4)$$

This estimate is however dependent upon the error involved in approximating  ${}_2F_1(a+1, b+1; c+1; x)$  and  ${}_2F_1(a+2, b+2; c+2; x)$ .

**8 Parallelism and Performance**

Not applicable.

**9 Further Comments**

nag\_specfun\_2f1\_real\_scaled (s22bfc) returns non-finite values when appropriate. See Chapter x07 for more information on the definitions of non-finite values.

Should a non-finite value be returned, this will be indicated in the value of **fail**, as detailed in the following cases.

If **fail.code** = NE\_NOERROR or **fail.code** = NE\_TOTAL\_PRECISION\_LOSS, NW\_SOME\_PRECISION\_LOSS or NW\_UNDERFLOW\_WARN, a finite value will have been returned with approximate accuracy as detailed in Section 7.

The values of  $f_{fr}$  and  $f_{sc}$  are implementation dependent. In most cases, if  ${}_2F_1(a, b; c; x) = 0$ ,  $f_{fr} = 0$  and  $f_{sc} = 0$  will be returned, and if  ${}_2F_1(a, b; c; x)$  is finite, the fractional component will be bound by  $0.5 \leq |f_{fr}| < 1$ , with  $f_{sc}$  chosen accordingly.

The values returned in **frf** ( $f_{fr}$ ) and **scf** ( $f_{sc}$ ) may be used to explicitly evaluate  ${}_2F_1(a, b; c; x)$ , and may also be used to evaluate products and ratios of multiple values of  ${}_2F_1$  as follows,

$$\begin{aligned} {}_2F_1(a, b; c; x) &= f_{fr} \times 2^{f_{sc}} \\ {}_2F_1(a_1, b_1; c_1; x_1) \times {}_2F_1(a_2, b_2; c_2; x_2) &= (f_{fr1} \times f_{fr2}) \times 2^{(f_{sc1} + f_{sc2})} \\ \frac{{}_2F_1(a_1, b_1; c_1; x_1)}{{}_2F_1(a_2, b_2; c_2; x_2)} &= \frac{f_{fr1}}{f_{fr2}} \times 2^{(f_{sc1} - f_{sc2})} \\ \ln|{}_2F_1(a, b; c; x)| &= \ln|f_{fr}| + f_{sc} \times \ln(2). \end{aligned}$$

If **fail.code** = NE\_INFINITY then  ${}_2F_1(a, b; c; x)$  is infinite. A signed infinity will have been returned for **frf**, and **scf** = 0. The sign of **frf** should be correct when taking the limit as  $x$  approaches 1 from below.

If **fail.code** = NW\_OVERFLOW\_WARN then upon completion,  $|{}_2F_1(a, b; c; x)| > 2^{I_{\max}}$ , where  $I_{\max}$  is given by nag\_max\_integer (X02BBC), and hence is too large to be representable even in the scaled form. The scaled real component returned in **frf** may still be correct, whilst **scf** =  $I_{\max}$  will have been returned.

If **fail.code** = NE\_OVERFLOW then overflow occurred during a subcalculation of  ${}_2F_1(a, b; c; x)$ . The same result as for **fail.code** = NW\_OVERFLOW\_WARN will have been returned, however there is no guarantee that this is representative of either the magnitude of the scaling power  $f_{sc}$ , or the scaled component  $f_{fr}$  of  ${}_2F_1(a, b; c; x)$ .

If **fail.code** = NE\_NOERROR, **frf** and **scf** were inaccessible to nag\_specfun\_2f1\_real\_scaled (s22bfc), and as such it is not possible to determine what their values may be following the call to nag\_specfun\_2f1\_real\_scaled (s22bfc).

For all other error exits, **scf** = 0 will be returned and **frf** will be returned as a signalling NaN (see nag\_create\_nan (x07bbc)).

If **fail.code** = NE\_CANNOT\_CALCULATE an internal computation produced an undefined result. This may occur when two terms overflow with opposite signs, and the result is dependent upon their summation for example.

If **fail.code** = NE\_REAL\_2 then  $c$  is too close to a negative integer or zero on entry, and  ${}_2F_1(a, b; c; x)$  is undefined. Note, this will also be the case when  $c$  is a negative integer, and a (possibly trivial) linear transformation of the form (3) would result in either:

- (i) all  $c_j$  not being negative integers,
- (ii) for any  $c_j$  which remain as negative integers, one of the corresponding parameters  $a_j$  or  $b_j$  is a negative integer of magnitude less than  $c_j$ .

In the first case, the transformation coefficients  $C_j(a_j, b_j, c_j, x_j)$  are typically either infinite or undefined, preventing a solution being constructed. In the second case, the series (2) will terminate before the degenerate term, resulting in a polynomial of fixed degree, and hence potentially a finite solution.

If **fail.code** = NE\_REAL\_RANGE\_CONS then no computation will have been performed due to the risk of integer overflow. The actual solution may however be finite.

**fail.code** = NE\_COMPLEX indicates  $x > 1$ , and hence the requested solution is on the boundary of the principal branch of  ${}_2F_1(a, b; c; x)$ . Hence it is multivalued, typically with a non-zero imaginary component. It is however strictly finite.

## 10 Example

This example evaluates the Gauss hypergeometric function at two points in scaled form using nag\_specfun\_2f1\_real\_scaled (s22bfc), and subsequently calculates their product and ratio implicitly.

## 10.1 Program Text

```

/* nag_specfun_2f1_real_scaled (s22bfc) Example Program.
 *
 * Copyright 2014 Numerical Algorithms Group.
 *
 * Mark 24, 2013.
 */

#include <stdio.h>
#include <math.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nags.h>
#include <nagx02.h>

int main(void)
{
    /* Scalars */
    Integer  exit_status = 0;
    Integer  k, imax, scf;
    double   ani, adr, bni, bdr, cni, cdr, delta, frf, x;
    /* Arrays */
    double   frfv[2];
    Integer  scfv[2];
    /* Nag Types */
    Nag_Boolean finite_solutions;
    NagError fail;

    imax = X02BLC;
    printf("nag_specfun_2f1_real_scaled (s22bfc) Example Program Results\n\n");

    ani = -10.0;
    bni = 2.0;
    cni = -5.0;
    delta = 1.0E-4;
    adr = delta;
    bdr = -delta;
    cdr = delta;
    x = 0.45;
    finite_solutions = Nag_TRUE;
    printf("%11s%11s%11s%11s%14s%7s%14s\n",
           "a", "b", "c", "x", "frf", "scf", "2F1(a,b;c;x)");
    for (k = 0; k < 2; k++)
    {
        INIT_FAIL(fail);
        /* Compute the real Gauss hypergeometric function 2F1(a,b;c;x) in scaled
         * form using nag_specfun_2f1_real_scaled (s22bfc).
         */
        nag_specfun_2f1_real_scaled(ani, adr, bni, bdr, cni, cdr, x,
                                   &frf, &scf, &fail);

        switch (fail.code) {
        case NE_NOERROR:
        case NW_UNDERFLOW_WARN:
        case NW_SOME_PRECISION_LOSS:
            /* A finite result has been returned. */
            if (scf < imax)
                printf(" %10.4f %10.4f %10.4f %10.4f %13.5e %6"NAG_IFMT" %13.5e\n",
                       ani+adr, bni+bdr, cni+cdr, x, frf, scf, frf*pow(2.0, scf));
            else
                printf(" %10.4f %10.4f %10.4f %10.4f %13.5e %6"NAG_IFMT" %17s\n",
                       ani+adr, bni+bdr, cni+cdr, x, frf, scf, "Not Representable");
            frfv[k] = frf;
            scfv[k] = scf;
            break;
        case NE_INFINITE:
            /* The result is analytically infinite. */
            finite_solutions = Nag_FALSE;
            if (frf >= 0.0)
                printf(" %10.4f %10.4f %10.4f %10.4f %13s %6"NAG_IFMT" %13s\n",
                       ani+adr, bni+bdr, cni+cdr, x, "Inf", scf, "Inf");
        }
    }
}

```

```

else
    printf(" %10.4f %10.4f %10.4f %10.4f %13s %6"NAG_IFMT" %13s\n",
           ani+adr, bni+bdr, cni+cdr, x, "-Inf", scf, "-Inf");
break;
case NW_OVERFLOW_WARN:
case NE_OVERFLOW:
    /* The final result has overflowed. */
    finite_solutions = Nag_FALSE;
    if(frf>=0.0)
        printf(" %10.4f %10.4f %10.4f %10.4f %13.5e %6s %13s\n",
               ani+adr, bni+bdr, cni+cdr, x, frf, "imax", ">pow(2,imax)");
    else
        printf(" %10.4f %10.4f %10.4f %10.4f %13.5e %6s %13s\n",
               ani+adr, bni+bdr, cni+cdr, x, frf, "imax", "<-pow(2,imax)");
    break;
case NE_CANNOT_CALCULATE:
    /* An internal calculation resulted in an undefined result. */
    finite_solutions = Nag_FALSE;
    printf(" %10.4f %10.4f %10.4f %10.4f %13s %6"NAG_IFMT" %13s\n",
           ani+adr, bni+bdr, cni+cdr, x, "NaN", scf, "NaN");
    break;
default:
    /* An input error has been detected. */
    printf(" %10.4f %10.4f %10.4f %10.4f %17s\n",
           ani+adr, bni+bdr, cni+cdr, x, "FAILED");
    exit_status = 1;
    goto END;
    break;
}
adr = -adr;
bdr = -bdr;
cdr = -cdr;
}
if(finite_solutions)
{
    /* Calculate the product M1*M2. */
    frfv[0] = frfv[0] * frfv[1];
    scfv[0] = scfv[0] + scfv[1];
    printf("\n");
    if (scf < imax)
        printf("%-34s%13.5e %6"NAG_IFMT" %13.5e\n",
               " Solution product", frf, scf, frf*pow(2.0, scf));
    else
        printf("%-34s%13.5e %6"NAG_IFMT"%17s\n",
               " Solution product", frf, scf, "Not Representable");

    /* Calculate the ratio M1/M2. */
    if (frfv[1] != 0.0)
    {
        frfv[0] = frfv[0]/frfv[1];
        scfv[0] = scfv[0] - scfv[1];
        printf("\n");
        if (scf < imax)
            printf("%-34s%13.5e %6"NAG_IFMT" %13.5e\n",
                   " Solution ratio", frf, scf, frf*pow(2.0, scf));
        else
            printf("%-34s%13.5e %6"NAG_IFMT"%17s\n",
                   " Solution ratio", frf, scf, "Not Representable");
    }
}
END:
return exit_status;
}

```

## 10.2 Program Data

None.



**10.3 Program Results**

nag\_specfun\_2f1\_real\_scaled (s22bfc) Example Program Results

a	b	c	x	frf	scf	2F1(a,b;c;x)
-9.9999	1.9999	-4.9999	0.4500	-5.44477e-01	16	-3.56828e+04
-10.0001	2.0001	-5.0001	0.4500	5.44547e-01	16	3.56875e+04
Solution product			-2.96494e-01	32	-1.27343e+09	
Solution ratio			-9.99871e-01	0	-9.99871e-01	

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