NAG Library Function Document

nag specfun 1f1 real scaled (s22bbc)

1 Purpose

nag_specfun_1f1_real_scaled (s22bbc) returns a value for the confluent hypergeometric function $_1F_1(a;b;x)$, with real parameters a and b and real argument x. The solution is returned in the scaled form $_1F_1(a;b;x)=m_f\times 2^{m_s}$. This function is sometimes also known as Kummer's function M(a,b,x).

2 Specification

3 Description

nag_specfun_1f1_real_scaled (s22bbc) returns a value for the confluent hypergeometric function $_1F_1(a;b;x)$, with real parameters a and b and real argument x, in the scaled form $_1F_1(a;b;x)=m_f\times 2^{m_s}$, where m_f is the real scaled component and m_s is the integer power of two scaling. This function is unbounded or not uniquely defined for b equal to zero or a negative integer.

The confluent hypergeometric function is defined by the confluent series,

$$_{1}F_{1}(a;b;x) = M(a,b,x) = \sum_{s=0}^{\infty} \frac{(a)_{s}x^{s}}{(b)_{s}s!} = 1 + \frac{a}{b}x + \frac{a(a+1)}{b(b+1)2!}x^{2} + \cdots$$

where $(a)_s = 1(a)(a+1)(a+2)\dots(a+s-1)$ is the rising factorial of a. M(a,b,x) is a solution to the second order ODE (Kummer's Equation):

$$x\frac{d^{2}M}{dx^{2}} + (b-x)\frac{dM}{dx} - aM = 0.$$
 (1)

Given the parameters and argument (a,b,x), this function determines a set of safe values $\{(\alpha_i,\beta_i,\zeta_i)\mid i\leq 2\}$ and selects an appropriate algorithm to accurately evaluate the functions $M_i(\alpha_i,\beta_i,\zeta_i)$. The result is then used to construct the solution to the original problem M(a,b,x) using, where necessary, recurrence relations and/or continuation.

For improved precision in the final result, this function accepts a and b split into an integral and a decimal fractional component. Specifically $a = a_i + a_r$, where $|a_r| \le 0.5$ and $a_i = a - a_r$ is integral. b is similarly deconstructed.

Additionally, an artificial bound, arbnd is placed on the magnitudes of a_i , b_i and x to minimize the occurrence of overflow in internal calculations. $arbnd = 0.0001 \times I_{\rm max}$, where $I_{\rm max} = {\rm X02BBC}$. It should, however, not be assumed that this function will produce an accurate result for all values of a_i , b_i and x satisfying this criterion.

Please consult the NIST Digital Library of Mathematical Functions or the companion (2010) for a detailed discussion of the confluent hypergeometric function including special cases, transformations, relations and asymptotic approximations.

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4 References

NIST Handbook of Mathematical Functions (2010) (eds F W J Olver, D W Lozier, R F Boisvert, C W Clark) Cambridge University Press

Pearson J (2009) Computation of hypergeometric functions MSc Dissertation, Mathematical Institute, University of Oxford

5 Arguments

1: **ani** – double *Input*

On entry: a_i , the nearest integer to a_i , satisfying $a_i = a - a_r$.

Constraints:

$$\mathbf{ani} = \lfloor \mathbf{ani} \rfloor;$$

 $|\mathbf{ani}| \le arbnd.$

2: **adr** – double *Input*

On entry: a_r , the signed decimal remainder satisfying $a_r = a - a_i$ and $|a_r| \le 0.5$.

Constraint: |adr| < 0.5.

Note: if $|\mathbf{adr}| < 100.0\epsilon$, $a_r = 0.0$ will be used, where ϵ is the *machine precision* as returned by nag machine precision (X02AJC).

3: **bni** – double *Input*

On entry: b_i , the nearest integer to b, satisfying $b_i = b - b_r$.

Constraints:

```
\begin{aligned} \mathbf{bni} &= \lfloor \mathbf{bni} \rfloor; \\ |\mathbf{bni}| &\leq arbnd; \\ \text{if } \mathbf{bdr} &= 0.0, \ \mathbf{bni} > 0. \end{aligned}
```

4: **bdr** – double *Input*

On entry: b_r , the signed decimal remainder satisfying $b_r = b - b_i$ and $|b_r| \le 0.5$.

Constraint: $|\mathbf{bdr}| < 0.5$.

Note: if $|\mathbf{bdr} - \mathbf{adr}| < 100.0\epsilon$, $a_r = b_r$ will be used, where ϵ is the *machine precision* as returned by nag_machine_precision (X02AJC).

5: \mathbf{x} - double Input

On entry: the argument x of the function.

Constraint: $|\mathbf{x}| < arbnd$.

6: **frm** – double * Output

On exit: m_f , the scaled real component of the solution satisfying $m_f = M(a, b, x) \times 2^{-m_s}$.

Note: if overflow occurs upon completion, as indicated by **fail.code** = NW_OVERFLOW_WARN, the value of m_f returned may still be correct. If overflow occurs in a subcalculation, as indicated by **fail.code** = NE_OVERFLOW, this should not be assumed.

7: scm – Integer * Output

On exit: m_s , the scaling power of two, satisfying $m_s = \log_2\left(\frac{M(a,b,x)}{m_f}\right)$.

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Note: if overflow occurs upon completion, as indicated by **fail.code** = NW_OVERFLOW_WARN, then $m_s \geq I_{\max}$, where I_{\max} is the largest representable integer (see nag_max_integer (X02BBC)). If overflow occurs during a subcalculation, as indicated by **fail.code** = NE_OVERFLOW, m_s may or may not be greater than I_{\max} . In either case, $\mathbf{scm} = \text{nag_max_integer}$ will have been returned.

8: fail – NagError * Input/Output

The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE ALLOC FAIL

Dynamic memory allocation failed.

See Section 3.2.1.2 in the Essential Introduction for further information.

NE BAD PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG. See Section 3.6.6 in the Essential Introduction for further information.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly. See Section 3.6.5 in the Essential Introduction for further information.

NE_OVERFLOW

Overflow occurred in a subcalculation of M(a, b, x). The answer may be completely incorrect.

NE REAL

```
On entry, \mathbf{adr} = \langle value \rangle.
Constraint: |\mathbf{adr}| \leq 0.5.
On entry, \mathbf{bdr} = \langle value \rangle.
Constraint: |\mathbf{bdr}| \leq 0.5.
```

NE_REAL_2

```
On entry, b = \mathbf{bni} + \mathbf{bdr} = \langle value \rangle. M(a, b, x) is undefined when b is zero or a negative integer.
```

NE REAL ARG NON INTEGRAL

```
ani is non-integral.
On entry, ani = \langle value \rangle.
Constraint: ani = \lfloor ani \rfloor.
bni is non-integral.
On entry, bni = \langle value \rangle.
Constraint: bni = \lfloor bni \rfloor.
```

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NE REAL RANGE CONS

On entry, $\mathbf{ani} = \langle value \rangle$.

Constraint: $|\mathbf{ani}| \leq arbnd = \langle value \rangle$.

On entry, **bni** = $\langle value \rangle$.

Constraint: $|\mathbf{bni}| \leq arbnd = \langle value \rangle$.

On entry, $\mathbf{x} = \langle value \rangle$.

Constraint: $|\mathbf{x}| \leq arbnd = \langle value \rangle$.

NE TOTAL PRECISION LOSS

All approximations have completed, and the final residual estimate indicates no accuracy can be guaranteed.

Relative residual $= \langle value \rangle$.

NW OVERFLOW WARN

On completion, overflow occurred in the evaluation of M(a, b, x).

NW SOME PRECISION LOSS

All approximations have completed, and the final residual estimate indicates some precision may have been lost.

Relative residual = $\langle value \rangle$.

NW UNDERFLOW WARN

Underflow occurred during the evaluation of M(a, b, x).

The returned value may be inaccurate.

7 Accuracy

In general, if $fail.code = NE_NOERROR$, the value of M may be assumed accurate, with the possible loss of one or two decimal places. Assuming the result does not under or overflow, an error estimate res is made internally using equation (1). If the magnitude of res is sufficiently large a different fail.code will be returned. Specifically,

 $\begin{array}{ll} \textbf{fail.code} = \text{NE_NOERROR} & res \leq 1000\epsilon \\ \textbf{fail.code} = \text{NW_SOME_PRECISION_LOSS} & 1000\epsilon < res \leq 0.1 \\ \textbf{fail.code} = \text{NE_TOTAL_PRECISION_LOSS} & res > 0.1 \\ \end{array}$

A further estimate of the residual can be constructed using equation (1), and the differential identity,

$$\frac{dM(a,b,x)}{dx} = \frac{a}{b}M(a+1,b+1,x),$$

$$\frac{d^2M(a,b,x)}{dx^2} = \frac{a(a+1)}{b(b+1)}M(a+2,b+2,x).$$

This estimate is however dependent upon the error involved in approximating M(a+1,b+1,x) and M(a+2,b+2,x).

8 Parallelism and Performance

 $nag_specfun_1f1_real_scaled \ (s22bbc) \ is \ threaded \ by \ NAG \ for \ parallel \ execution \ in \ multithreaded implementations of the NAG \ Library.$

nag_specfun_1f1_real_scaled (s22bbc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

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Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The values of m_f and m_s are implementation dependent. In most cases, if ${}_1F_1(a;b;x)=0$, $m_f=0$ and $m_s=0$ will be returned, and if ${}_1F_1(a;b;x)=0$ is finite, the fractional component will be bound by $0.5 \le |m_f| < 1$, with m_s chosen accordingly.

The values returned in **frm** (m_f) and **scm** (m_s) may be used to explicitly evaluate M(a, b, x), and may also be used to evaluate products and ratios of multiple values of M as follows,

$$\begin{array}{lcl} M(a,b,x) & = & m_f \times 2^{m_s} \\ \\ M(a_1,b_1,x_1) \times M(a_2,b_2,x_2) & = & \left(m_{f1} \times m_{f2}\right) \times 2^{(m_{s1}+m_{s2})} \\ \\ \frac{M(a_1,b_1,x_1)}{M(a_2,b_2,x_2)} & = & \frac{m_{f1}}{m_{f2}} \times 2^{(m_{s1}-m_{s2})} \\ \\ \ln |M(a,b,x)| & = & \ln |m_f| + m_s \times \ln(2) \end{array}$$

10 Example

This example evaluates the confluent hypergeometric function at two points in scaled form using nag_specfun_1f1_real_scaled (s22bbc), and subsequently calculates their product and ratio without having to explicitly construct M.

10.1 Program Text

```
/* nag_specfun_1f1_real_scaled (s22bbc) Example Program.
 * Copyright 2014 Numerical Algorithms Group.
 * Mark 24, 2013.
#include <stdio.h>
#include <string.h>
#include <math.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nags.h>
#include <nagx02.h>
int main(void)
  /* Scalars */
  Integer exit_status = 0;
Integer k, maxexponent, scm;
double and adv bai bdv
  double
           ani, adr, bni, bdr, delta, frm, x;
  /* Arrays */
  double frmv[2];
Integer scmv[2];
  /* Nag Types */
  NagError fail;
  maxexponent = X02BLC;
  printf("nag_specfun_1f1_real_scaled (s22bbc) Example Program Results\n\n");
  ani = -10.0;
  bni = 30.0;
  delta = 1.0E-4;
  adr = delta;
  bdr = -delta;
  x = 25.0;
```

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```
printf("%9s%10s%10s%12s%9s%12s\n", "a", "b", "x", "frm", "scm", "M(a,b,x)");
 for (k = 0; k < 2; k++)
   {
     INIT_FAIL(fail);
     /* Compute the real confluent hypergeometric function M(a,b,x) in scaled
      * form using nag_specfun_1f1_real_scaled (s22bbc).
     nag_specfun_1f1_real_scaled(ani, adr, bni, bdr, x, &frm, &scm, &fail);
     switch (fail.code) {
     case NE_NOERROR:
     case NW_UNDERFLOW_WARN:
     case NW_SOME_PRECISION_LOSS:
         if (scm < maxexponent)</pre>
           printf(" %9.4f %9.4f %9.4f %13.4e %5"NAG_IFMT" %13.4e\n",
                  ani+adr, bni+bdr, x, frm, scm, frm*pow(2.0, scm));
           printf(" %9.4f %9.4f %9.4f %13.4e %5"NAG_IFMT" %17s\n",
                 ani+adr, bni+bdr, x, frm, scm, "Not Representable");
         frmv[k] = frm;
         scmv[k] = scm;
         break;
     default:
       {
         /* Either the result has overflowed, no accuracy may be assumed,
          * or an input error has been detected.
         printf(" %9.4f %9.4f %9.4f %17s\n", ani+adr, bni+bdr, x, "FAILED");
         exit_status = 1;
         goto END;
     }
     adr = -adr;
     bdr = -bdr;
 /* Calculate the product M1*M2*/
 frm = frmv[0] * frmv[1];
 scm = scmv[0] + scmv[1];
 printf("\n");
 if (scm < maxexponent)</pre>
   printf("%-30s%12.4e%6"NAG_IFMT"%12.4e\n",
          "Solution product", frm, scm, frm*pow(2.0, scm));
 else
   printf("%-30s%12.4e%6"NAG_IFMT"%17s\n",
          "Solution product", frm, scm, "Not Representable");
 /* Calculate the ratio M1/M2*/
 if (frmv[1] != 0.0)
     frm = frmv[0]/frmv[1];
     scm = scmv[0] - scmv[1];
     printf("\n");
     if (scm < maxexponent)</pre>
      printf("%-30s%12.4e%6"NAG_IFMT"%12.4e\n",
              "Solution ratio", frm, scm, frm*pow(2.0, scm));
       printf("%-30s%12.4e%6"NAG_IFMT"%17s\n",
              "Solution ratio", frm, scm, "Not Representable");
   }
END:
 return exit_status;
```

10.2 Program Data

None.

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10.3 Program Results

 ${\tt nag_specfun_1f1_real_scaled~(s22bbc)~Example~Program~Results}$

a b x frm scm M(a,b,x) -9.9999 29.9999 25.0000 -7.7329e-01 -15 -2.3599e-05 -10.0001 30.0001 25.0000 -7.7318e-01 -15 -2.3596e-05Solution product 5.9789e-01 -30 5.5683e-10 Solution ratio 1.0001e+00 0 1.0001e+00

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