

## NAG Library Function Document

### nag\_robust\_m\_regsn\_estim (g02hac)

#### 1 Purpose

nag\_robust\_m\_regsn\_estim (g02hac) performs bounded influence regression (M-estimates). Several standard methods are available.

#### 2 Specification

```
#include <nag.h>
#include <nagg02.h>

void nag_robust_m_regsn_estim (Nag_RegType regtype, Nag_PsiFun psifun,
    Nag_SigmaEst sigma_est, Nag_CovMatrixEst covmat_est, Integer n,
    Integer m, double x[], Integer tdx, double y[], double cpsi,
    const double hpsi[], double cucv, double dchi, double theta[],
    double *sigma, double c[], Integer tdc, double rs[], double wt[],
    double tol, Integer max_iter, Integer print_iter, const char *outfile,
    double info[], NagError *fail)
```

#### 3 Description

For the linear regression model

$$y = X\theta + \epsilon$$

where  $y$  is a vector of length  $n$  of the dependent variable,

$X$  is a  $n$  by  $m$  matrix of independent variables of column rank  $k$ ,

$\theta$  is a vector of length  $m$  of unknown arguments,

and  $\epsilon$  is a vector of length  $n$  of unknown errors with  $\text{var}(\epsilon_i) = \sigma^2$ :

nag\_robust\_m\_regsn\_estim (g02hac) calculates the M-estimates given by the solution,  $\hat{\theta}$ , to the equation

$$\sum_{i=1}^n \psi(r_i/(\sigma w_i)) w_i x_{ij} = 0, \quad j = 1, 2, \dots, m \quad (1)$$

where  $r_i$  is the  $i$ th residual, i.e., the  $i$ th element of  $r = y - X\hat{\theta}$ ,

$\psi$  is a suitable weight function,

$w_i$  are suitable weights,

and  $\sigma$  may be estimated at each iteration by the median absolute deviation of the residuals:

$$\hat{\sigma} = \text{med}_i [|r_i|] / \beta_1$$

or as the solution to:

$$\sum_{i=1}^n \chi(r_i/(\hat{\sigma} w_i)) w_i^2 = (n - k) \beta_2$$

for suitable weight function  $\chi$ , where  $\beta_1$  and  $\beta_2$  are constants, chosen so that the estimator of  $\sigma$  is asymptotically unbiased if the errors,  $\epsilon_i$ , have a Normal distribution. Alternatively  $\sigma$  may be held at a constant value.

The above describes the Schweppe type regression. If the  $w_i$  are assumed to equal 1 for all  $i$  then Huber type regression is obtained. A third type, due to Mallows, replaces (1) by

$$\sum_{i=1}^n \psi(r_i/\sigma) w_i x_{ij} = 0, \quad j = 1, 2, \dots, m.$$

This may be obtained by use of the transformations

$$w_i^* \leftarrow \sqrt{w_i}$$

$$y_i^* \leftarrow y_i \sqrt{w_i}$$

$$x_{ij}^* \leftarrow x_{ij} \sqrt{w_i}, \quad j = 1, 2, \dots, m$$

(see Marazzi (1987a)).

For Huber and Schweppe type regressions,  $\beta_1$  is the 75th percentile of the standard Normal distribution. For Mallows type regression  $\beta_1$  is the solution to

$$\frac{1}{n} \sum_{i=1}^n \Phi(\beta_1/\sqrt{w_i}) = .75$$

where  $\Phi$  is the standard Normal cumulative distribution function.

$\beta_2$  is given by:

$$\beta_2 = \int_{-\infty}^{\infty} \chi(z) \phi(z) dz, \quad \text{in Huber case;}$$

$$\beta_2 = \frac{1}{n} \sum_{i=1}^n w_i \int_{-\infty}^{\infty} \chi(z) \phi(z) dz, \quad \text{in Mallows case;}$$

$$\beta_2 = \frac{1}{n} \sum_{i=1}^n w_i^2 \int_{-\infty}^{\infty} \chi(z/w_i) \phi(z) dz, \quad \text{in Schweppe case;}$$

where  $\phi$  is the standard Normal density, i.e.,

$$\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}x^2\right).$$

The calculation of the estimates of  $\theta$  can be formulated as an iterative weighted least squares problem with a diagonal weight matrix  $G$  given by

$$G_{ii} = \begin{cases} \frac{\psi(r_i/(\sigma w_i))}{(r_i/(\sigma w_i))}, & r_i \neq 0 \\ \psi'(0), & r_i = 0 \end{cases}$$

where  $\psi'(t)$  is the derivative of  $\psi$  at the point  $t$ .

The value of  $\theta$  at each iteration is given by the weighted least squares regression of  $y$  on  $X$ . This is carried out by first transforming the  $y$  and  $X$  by

$$\tilde{y}_i = y_i \sqrt{G_{ii}}$$

$$\tilde{x}_{ij} = x_{ij} \sqrt{G_{ii}}, \quad j = 1, 2, \dots, m$$

and then obtaining the solution of the resulting least squares problem. If  $X$  is of full column rank then an orthogonal-triangular (QR) decomposition is used, if not, a singular value decomposition is used.

The following functions are available for  $\psi$  and  $\chi$  in nag\_robust\_m\_regsn\_estim (g02hac).

(a) **Unit Weights**

$$\psi(t) = t, \chi(t) = \frac{t^2}{2}$$

this gives least squares regression.

(b) **Huber's Function**

$$\psi(t) = \max(-c, \min(c, t)), \chi(t) = \begin{cases} \frac{t^2}{2}, & |t| \leq d \\ \frac{d^2}{2}, & |t| > d \end{cases}$$

**(c) Hampel's Piecewise Linear Function**

$$\psi_{h_1, h_2, h_3}(t) = -\psi_{h_1, h_2, h_3}(-t) = \begin{cases} t, & 0 \leq t \leq h_1 \\ h_1, & h_1 \leq t \leq h_2 \\ h_1(h_3 - t)/(h_3 - h_2), & h_2 \leq t \leq h_3 \\ 0, & h_3 < t \end{cases}$$

$$\chi(t) = \begin{cases} \frac{t^2}{2}, & |t| \leq d \\ \frac{d^2}{2}, & |t| > d \end{cases}$$

**(d) Andrew's Sine Wave Function**

$$\psi(t) = \begin{cases} \sin t, & -\pi \leq t \leq \pi \\ 0, & |t| > \pi \end{cases} \quad \chi(t) = \begin{cases} \frac{t^2}{2}, & |t| \leq d \\ \frac{d^2}{2}, & |t| > d \end{cases}$$

**(e) Tukey's Bi-weight**

$$\psi(t) = \begin{cases} t(1 - t^2)^2, & |t| \leq 1 \\ 0, & |t| > 1 \end{cases} \quad \chi(t) = \begin{cases} \frac{t^2}{2}, & |t| \leq d \\ \frac{d^2}{2}, & |t| > d \end{cases}$$

where  $c$ ,  $h_1$ ,  $h_2$ ,  $h_3$ , and  $d$  are given constants.

Several schemes for calculating weights have been proposed, see Hampel *et al.* (1986) and Marazzi (1987a). As the different independent variables may be measured on different scales, one group of proposed weights aims to bound a standardized measure of influence. To obtain such weights the matrix  $A$  has to be found such that:

$$\frac{1}{n} \sum_{i=1}^n u(\|z_i\|_2) z_i z_i^T = I$$

and

$$z_i = Ax_i$$

where

$x_i$  is a vector of length  $m$  containing the  $i$ th row of  $X$ ,

$A$  is a  $m$  by  $m$  lower triangular matrix,

and  $u$  is a suitable function.

The weights are then calculated as

$$w_i = f(\|z_i\|_2)$$

for a suitable function  $f$ .

nag\_robust\_m\_regsn\_estim (g02hac) finds  $A$  using the iterative procedure

$$A_k = (S_k + I)A_{k-1}$$

where  $S_k = (s_{jl})$ ,

$$s_{jl} = \begin{cases} -\min[\max(h_{jl}/n, -BL), BL] & j > \ell \\ -\min[\max(\frac{1}{2}(h_{jj}/n - 1), -BD), BD] & j = \ell \end{cases}$$

and

$$h_{jl} = \sum_{i=1}^n u(\|z_i\|_2) z_{ij} z_{il}$$

and  $BL$  and  $BD$  are bounds set at 0.9.

Two weights are available in nag\_robust\_m\_regsn\_estim (g02hac):

(i) Krasker–Welsch weights

$$u(t) = g_1\left(\frac{C}{t}\right)$$

where  $g_1(t) = t^2 + (1 - t^2)(2\Phi(t) - 1) - 2t\phi(t)$ ,  $\Phi(t)$  is the standard Normal cumulative distribution function,  $\phi(t)$  is the standard Normal probability density function, and  $f(t) = \frac{1}{t}$ .

These are for use with Schweppe type regression.

(ii) Maronna's proposed weights

$$u(t) = \begin{cases} c/t^2 & |t| > c \\ 1 & |t| \leq c \end{cases}$$

$$f(t) = \sqrt{u(t)}.$$

These are for use with Mallows type regression.

Finally the asymptotic variance-covariance matrix,  $C$ , of the estimates  $\theta$  is calculated.

For Huber type regression

$$C = f_H(X^T X)^{-1} \hat{\sigma}^2$$

where

$$f_H = \frac{1}{n - m} \frac{\sum_{i=1}^n \psi^2(r_i/\hat{\sigma})}{\left(\frac{1}{n} \sum_{i=1}^n \psi'(r_i/\hat{\sigma})\right)^2 \kappa^2}$$

$$\kappa^2 = 1 + \frac{m}{n} \frac{\frac{1}{n} \sum_{i=1}^n \left( \psi'(r_i/\hat{\sigma}) - \frac{1}{n} \sum_{i=1}^n \psi'(r_i/\hat{\sigma}) \right)^2}{\left(\frac{1}{n} \sum_{i=1}^n \psi'(r_i/\hat{\sigma})\right)^2}$$

See Huber (1981) and Marazzi (1987b).

For Mallows and Schweppe type regressions  $C$  is of the form

$$\frac{\hat{\sigma}^2}{n} S_1^{-1} S_2 S_1^{-1}$$

where  $S_1 = \frac{1}{n} X^T D X$  and  $S_2 = \frac{1}{n} X^T P X$ .

$D$  is a diagonal matrix such that the  $i$ th element approximates  $E(\psi'(r_i/(\sigma w_i)))$  in the Schweppe case and  $E(\psi'(r_i/\sigma)w_i)$  in the Mallows case.

$P$  is a diagonal matrix such that the  $i$ th element approximates  $E(\psi^2(r_i/(\sigma w_i))w_i^2)$  in the Schweppe case and  $E(\psi^2(r_i/\sigma)w_i^2)$  in the Mallows case.

Two approximations are available in `nag_robust_m_regsn_estim` (g02hac):

1. Average over the  $r_i$

$$\begin{array}{cc} \text{Schweppe} & \text{Mallows} \\ D_i = \left( \frac{1}{n} \sum_{j=1}^n \psi' \left( \frac{r_j}{\hat{\sigma} w_i} \right) \right) w_i & D_i = \left( \frac{1}{n} \sum_{j=1}^n \psi' \left( \frac{r_j}{\hat{\sigma}} \right) \right) w_i \end{array}$$

2. Replace expected value by observed

$$\begin{array}{cc} \text{Schweppe} & \text{Mallows} \\ D_i = \psi' \left( \frac{r_i}{\hat{\sigma} w_i} \right) w_i & D_i = \psi' \left( \frac{r_i}{\hat{\sigma}} \right) w_i \\ P_i = \psi^2 \left( \frac{r_i}{\hat{\sigma} w_i} \right) w_i^2 & P_i = \psi^2 \left( \frac{r_i}{\hat{\sigma}} \right) w_i^2 \end{array}$$

See Hampel *et al.* (1986) and Marazzi (1987b).

**Note:** There is no explicit provision in the function for a constant term in the regression model. However, the addition of a dummy variable whose value is 1.0 for all observations will produce a value of  $\hat{\theta}$  corresponding to the usual constant term.

nag\_robust\_m\_regn\_estim (g02hac) is based on routines in ROBETH, see Marazzi (1987a).

## 4 References

Hampel F R, Ronchetti E M, Rousseeuw P J and Stahel W A (1986) *Robust Statistics. The Approach Based on Influence Functions* Wiley

Huber P J (1981) *Robust Statistics* Wiley

Marazzi A (1987a) Weights for bounded influence regression in ROBETH *Cah. Rech. Doc. IUMSP, No. 3 ROB 3* Institut Universitaire de Médecine Sociale et Préventive, Lausanne

Marazzi A (1987b) Subroutines for robust and bounded influence regression in ROBETH *Cah. Rech. Doc. IUMSP, No. 3 ROB 2* Institut Universitaire de Médecine Sociale et Préventive, Lausanne

## 5 Arguments

- 1: **regtype** – Nag\_RegType *Input*

*On entry:* specifies the type of regression to be performed.

**regtype** = Nag\_HuberReg  
Huber type regression.

**regtype** = Nag\_MallowsReg  
Mallows type regression with Maronna's proposed weights.

**regtype** = Nag\_SchweppeReg  
Schweppe type regression with Krasker–Welsch weights.

*Constraint:* **regtype** = Nag\_HuberReg, Nag\_MallowsReg or Nag\_SchweppeReg.

- 2: **psifun** – Nag\_PsiFun *Input*

*On entry:* specifies which  $\psi$  function is to be used.

**psifun** = Nag\_Lsq  
 $\psi(t) = t$ , i.e., least squares.

**psifun** = Nag\_HuberFun  
Huber's function.

**psifun** = Nag\_HampelFun  
Hampel's piecewise linear function.

**psifun** = Nag\_AndrewFun  
Andrew's sine wave.

**psifun** = Nag\_TukeyFun  
Tukey's bi-weight.

*Constraint:* **psifun** = Nag\_Lsq, Nag\_HuberFun, Nag\_HampelFun, Nag\_AndrewFun or Nag\_TukeyFun.

3: **sigma\_est** – Nag\_SigmaEst *Input*

*On entry:* specifies how  $\sigma$  is to be estimated.

**sigma\_est** = Nag\_SigmaRes  
 $\sigma$  is estimated by median absolute deviation of residuals.

**sigma\_est** = Nag\_SigmaConst  
 $\sigma$  is held constant at its initial value.

**sigma\_est** = Nag\_SigmaChi  
 $\sigma$  is estimated using the  $\chi$  function.

*Constraint:* **sigma\_est** = Nag\_SigmaRes, Nag\_SigmaConst or Nag\_SigmaChi.

4: **covmat\_est** – Nag\_CovMatrixEst *Input*

*On entry:* if **regtype**  $\neq$  Nag\_HuberReg, **covmat\_est** specifies the approximations used in estimating the covariance matrix of  $\hat{\theta}$ . **covmat\_est** = Nag\_CovMatAve, averaging over residuals. **covmat\_est** = Nag\_CovMatObs, replacing expected by observed.

If **regtype** = Nag\_HuberReg then **covmat\_est** is not referenced.

*Constraint:* **covmat\_est** = Nag\_CovMatAve or Nag\_CovMatObs.

5: **n** – Integer *Input*

*On entry:* the number of observations,  $n$ .

*Constraint:*  $n > 1$ .

6: **m** – Integer *Input*

*On entry:* the number  $m$ , of independent variables.

*Constraint:*  $1 \leq m < n$ .

7: **x[n × tdx]** – double *Input/Output*

**Note:** the  $(i, j)$ th element of the matrix  $X$  is stored in  $x[(i - 1) \times tdx + j - 1]$ .

*On entry:* the values of the  $X$  matrix, i.e., the independent variables.  $x[i - 1][j - 1]$  must contain the  $ij$ th element of  $X$ , for  $i = 1, 2, \dots, n$  and  $j = 1, 2, \dots, m$ .

*On exit:* if **regtype** = Nag\_MallowsReg, then during calculations the elements of **x** will be transformed as described in Section 3. Before exit the inverse transformation will be applied. As a result there may be slight differences between the input **x** and the output **x**. Otherwise **x** is unchanged.

8: **tdx** – Integer *Input*

*On entry:* the stride separating matrix column elements in the array **x**.

*Constraint:*  $tdx \geq m$ .

9: **y[n]** – double *Input/Output*

*On entry:* the data values of the dependent variable.  $y[i - 1]$  must contain the value of  $y$  for the  $i$ th observation, for  $i = 1, 2, \dots, n$ .

*On exit:* if **regtype** = Nag\_MallowsReg, then during calculations the elements of **y** will be transformed as described in Section 3. Before exit the inverse transformation will be applied. As a

result there may be slight differences between the input  $\mathbf{y}$  and the output  $\mathbf{y}$ . Otherwise  $\mathbf{y}$  is unchanged.

10: **cpsi** – double *Input*

*On entry:* if **psifun** = Nag\_HuberFun, **cpsi** must specify the argument,  $c$ , of Huber's  $\psi$  function. Otherwise **cpsi** is not referenced.

*Constraint:* if **psifun** = Nag\_HuberFun then **cpsi** > 0.0.

11: **hpsi[3]** – const double *Input*

*On entry:* if **psifun** = Nag\_HampelFun then **hpsi[0]**, **hpsi[1]** and **hpsi[2]** must specify the arguments  $h_1$ ,  $h_2$ , and  $h_3$ , of Hampel's piecewise linear  $\psi$  function. Otherwise the elements of **hpsi** are not referenced.

*Constraint:* if **psifun** = Nag\_HampelFun,  $0.0 \leq \mathbf{hpsi}[0] \leq \mathbf{hpsi}[1] \leq \mathbf{hpsi}[2]$  and **hpsi[2]** > 0.0.

12: **cucv** – double *Input*

*On entry:* if **regtype** = Nag\_MallowsReg then **cucv** must specify the value of the constant,  $c$ , of the function  $u$  for Maronna's proposed weights.

If **regtype** = Nag\_SchweppeReg then **cucv** must specify the value of the function  $u$  for the Krasker–Welsch weights.

If **regtype** = Nag\_HuberReg then **cucv** is not referenced.

*Constraints:*

if **regtype** = Nag\_MallowsReg, **cucv**  $\geq \mathbf{m}$ ;  
if **regtype** = Nag\_SchweppeReg, **cucv**  $\geq \sqrt{\mathbf{m}}$ .

13: **dchi** – double *Input*

*On entry:* the constant,  $d$ , of the  $\chi$  function.

**dchi** is referenced only if **psifun**  $\neq$  Nag\_Lsq and **sigma\_est** = Nag\_SigmaChi.

*Constraint:* if **psifun**  $\neq$  Nag\_Lsq and **sigma\_est** = Nag\_SigmaChi, **dchi** > 0.0.

14: **theta[m]** – double *Input/Output*

*On entry:* starting values of the argument vector  $\theta$ . These may be obtained from least squares regression.

Alternatively if **sigma\_est** = Nag\_SigmaRes and **sigma** = 1 or if **sigma\_est** = Nag\_SigmaChi and **sigma** approximately equals the standard deviation of the dependent variable,  $y$ , then **theta**[ $i - 1$ ] = 0.0, for  $i = 1, 2, \dots, m$  may provide reasonable starting values.

*On exit:* **theta**[ $i - 1$ ] contains the M-estimate of  $\theta_i$ , for  $i = 1, 2, \dots, m$ .

15: **sigma** – double \* *Input/Output*

*On entry:* a starting value for the estimation of  $\sigma$ .

**sigma** should be approximately the standard deviation of the residuals from the model evaluated at the value of  $\theta$  given by **theta** on entry.

*On exit:* **sigma** contains the final estimate of  $\sigma$ , unless **sigma\_est** = Nag\_SigmaConst.

*Constraint:* **sigma** > 0.0.

16: **c[m × tdc]** – double *Output*

*On exit:* the diagonal elements of **c** contain the estimated asymptotic standard errors of the estimates of  $\theta$ , i.e., **c**[( $i - 1$ ) × **tdc** +  $i - 1$ ] contains the estimated asymptotic standard error of the estimate contained in **theta**[ $i - 1$ ], for  $i = 1, 2, \dots, m$ .

The elements above the diagonal contain the estimated asymptotic correlation between the estimates of  $\theta$ , i.e.,  $\mathbf{c}[(i-1) \times \mathbf{tdc} + j - 1]$ ,  $1 \leq i < j \leq m$  contains the asymptotic correlation between the estimates contained in  $\mathbf{theta}[i-1]$  and  $\mathbf{theta}[j-1]$ .

The elements below the diagonal contain the estimated asymptotic covariance between the estimates of  $\theta$ , i.e.,  $\mathbf{c}[(i-1) \times \mathbf{tdc} + j - 1]$ ,  $1 \leq j < i \leq m$  contains the estimated asymptotic covariance between the estimates contained in  $\mathbf{theta}[i-1]$  and  $\mathbf{theta}[j-1]$ .

17: **tdc** – Integer *Input*

*On entry:* the stride separating matrix column elements in the array **c**.

*Constraint:* **tdc**  $\geq$  **m**.

18: **rs[n]** – double *Output*

*On exit:* contains the residuals from the model evaluated at final value of **theta**, i.e.,  $\mathbf{rs}[i-1]$ , for  $i = 1, 2, \dots, n$ , contains the vector  $(y - X\hat{\theta})$ .

19: **wt[n]** – double *Output*

*On exit:* contains the vector of weights.  $\mathbf{wt}[i-1]$  contains the weight for the  $i$ th observation, for  $i = 1, 2, \dots, n$ .

20: **tol** – double *Input*

*On entry:* the relative precision for the calculation of  $A$  (if **regtype**  $\neq$  Nag\_HuberReg), the estimates of  $\theta$  and the estimate of  $\sigma$  (if **sigma\_est**  $\neq$  Nag\_SigmaConst). Convergence is assumed when the relative change in all elements being considered is less than **tol**.

If **regtype** = Nag\_MallowsReg and **sigma\_est** = Nag\_SigmaRes, **tol** is also used to determine the precision of  $\beta_1$ .

It is advisable for **tol** to be greater than  $100 \times$  *machine precision*.

*Constraint:* **tol**  $>$  0.0.

21: **max\_iter** – Integer *Input*

*On entry:* the maximum number of iterations that should be used in the calculation of  $A$  (if **regtype**  $\neq$  Nag\_HuberReg), and of the estimates of  $\theta$  and  $\sigma$ , and of  $\beta_1$  (if **regtype** = Nag\_MallowsReg and **sigma\_est** = Nag\_SigmaRes)

*Suggested value:* A value of **max\_iter** = 50 should be adequate for most uses.

*Constraint:* **max\_iter**  $>$  0.

22: **print\_iter** – Integer *Input*

*On entry:* the amount of information that is printed on each iteration.

**print\_iter** = 0

No information is printed.

**print\_iter**  $\neq$  0

The current estimate of  $\theta$ , the change in  $\theta$  during the current iteration and the current value of  $\sigma$  are printed on the first and every  $\text{abs}(\mathbf{print\_iter})$  iterations.

Also, if **regtype**  $\neq$  Nag\_HuberReg and **print\_iter**  $>$  0 then information on the iterations to calculate  $A$  is printed. This is the current estimate of  $A$  and the maximum value of  $S_{ij}$  (see Section 3).



- 23: **outfile** – const char \* *Input*  
*On entry:* a null terminated character string giving the name of the file to which results should be printed. If **outfile** is **NULL** or an empty string then the `stdout` stream is used. Note that the file will be opened in the append mode.
- 24: **info[4]** – double *Output*  
*On exit:* elements of **info** contain the following values:  
**info[0]** =  $\beta_1$  if **sigma\_est** = Nag\_SigmaRes,  
or **info[0]** =  $\beta_2$  if **sigma\_est** = Nag\_SigmaChi,  
**info[1]** = number of iterations used to calculate *A*.  
**info[2]** = number of iterations used to calculate final estimates of  $\theta$  and  $\sigma$ .  
**info[3]** =  $k$ , the rank of the weighted least squares equations.
- 25: **fail** – NagError \* *Input/Output*  
The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_2\_INT\_ARG\_GE

On entry, **m** =  $\langle value \rangle$  while **n** =  $\langle value \rangle$ . These arguments must satisfy **m** < **n**.

### NE\_2\_INT\_ARG\_LT

On entry, **tdc** =  $\langle value \rangle$  while **m** =  $\langle value \rangle$ . These arguments must satisfy **tdc**  $\geq$  **m**.

On entry, **tdx** =  $\langle value \rangle$  while **m** =  $\langle value \rangle$ . These arguments must satisfy **tdx**  $\geq$  **m**.

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_HAMPEL\_PSI\_FUN

On entry, **psifun** = Nag\_HampelFun and **hpsi[0]** =  $\langle value \rangle$ , **hpsi[1]** =  $\langle value \rangle$  and **hpsi[2]** =  $\langle value \rangle$ . For this value of **psifun**, the elements of **hpsi** must satisfy the condition  $0.0 \leq \mathbf{hpsi}[0] \leq \mathbf{hpsi}[1] \leq \mathbf{hpsi}[2]$  and **hpsi[2]** > 0.0.

### NE\_BAD\_PARAM

On entry, argument **covmat\_est** had an illegal value.

On entry, argument **psifun** had an illegal value.

On entry, argument **regtype** had an illegal value.

On entry, argument **sigma\_est** had an illegal value.

### NE\_BETA1\_ITER\_EXCEEDED

The number of iterations required to calculate  $\beta_1$  exceeds **max\_iter**. This is only applicable if **regtype** = Nag\_MallowsReg and **sigma\_est** = Nag\_SigmaRes.

### NE\_COV\_MAT\_FACTOR\_ZERO

In calculating the correlation factor for the asymptotic variance-covariance matrix, the factor for covariance matrix = 0.

For this error, either the value of

$$\frac{1}{n} \sum_{i=1}^n \psi'(r_i/\hat{\sigma}) = 0,$$

or  $\kappa = 0$ ,

or  $\sum_{i=1}^n \psi^2(r_i/\hat{\sigma}) = 0$ .

See Section 9. In this case **c** is returned as  $(X^T X)^{-1}$ .  
(This is only applicable if **regtype** = Nag\_HuberReg).

#### NE\_ERR\_DOF\_LEQ\_ZERO

**n** = *value*, rank of **x** = *value*. The degrees of freedom for error, **n** – (rank of **x**) must be > 0.0.

#### NE\_ESTIM\_SIGMA\_ZERO

The estimated value of  $\sigma$  was 0.0 during an iteration.

#### NE\_INT\_ARG\_LE

On entry, **max\_iter** must not be less than or equal to 0: **max\_iter** = *value*.

#### NE\_INT\_ARG\_LT

On entry, **m** = *value*.

Constraint: **m** ≥ 1.

On entry, **n** = *value*.

Constraint: **n** ≥ 2.

#### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

#### NE\_INVALID\_DCHI\_FUN

On entry, **psifun** ≠ Nag\_Lsq, **sigma\_est** = Nag\_SigmaChi and **dchi** = *value*. For these values of **psifun** and **sigma\_est**, **dchi** must be > 0.0.

#### NE\_INVALID\_HUBER\_FUN

On entry, **psifun** = Nag\_HuberFun and **cpsi** = *value*. For this value of **psifun**, **cpsi** must be > 0.0.

#### NE\_INVALID\_MALLOWS\_REG\_C

On entry, **regtype** = Nag\_MallowsReg, **cuvc** = *value* and **m** = *value*. For this value of **regtype**, **cuvc** must be ≥ **m**.

#### NE\_INVALID\_SCHWEPPE\_REG\_C

On entry, **regtype** = Nag\_SchweppeReg, **cuvc** = *value* and **m** = *value*. For this value of **regtype**, **cuvc** must be ≥  $\sqrt{\mathbf{m}}$ .

#### NE\_LSQ\_FAIL\_CONV

The iterations to solve the weighted least squares equations failed to converge.

#### NE\_NOT\_APPEND\_FILE

Cannot open file *string* for appending.

**NE\_NOT\_CLOSE\_FILE**

Cannot close file  $\langle string \rangle$ .

**NE\_REAL\_ARG\_LE**

On entry, **sigma** must not be less than or equal to 0.0: **sigma** =  $\langle value \rangle$ .

On entry, **tol** must not be less than or equal to 0.0: **tol** =  $\langle value \rangle$ .

**NE\_REG\_MAT\_SINGULAR**

Failure to invert matrix while calculating covariance.

If **regtype** = Nag\_HuberReg, then  $(X^T X)$  is almost singular.

If **regtype**  $\neq$  Nag\_HuberReg, then  $S_1$  is singular or almost singular. This may be due to too many diagonal elements of the matrix being zero, see Section 9.

**NE\_THETA\_ITER\_EXCEEDED**

The number of iterations required to calculate  $\theta$  and  $\sigma$  exceeds **max\_iter**. In this case, **info**[2] = **max\_iter** on exit.

**NE\_VAR\_THETA\_LEQ\_ZERO**

The estimated variance for an element of  $\theta \leq 0$ . In this case the diagonal element of **c** will contain the negative variance and the above diagonal elements in the row and the column corresponding to the element will be returned as zero.

This error may be caused by rounding errors or too many of the diagonal elements of **p** being zero. See Section 9.

**NE\_WT\_ITER\_EXCEEDED**

The number of iterations required to calculate the weights exceeds **max\_iter**. This is only applicable if **regtype**  $\neq$  Nag\_HuberReg.

**NE\_WT\_LSQ\_NOT\_FULL\_RANK**

The weighted least squares equations are not of full rank.

## 7 Accuracy

The precision of the estimates is determined by **tol**, see Section 5. As a more stable method is used to calculate the estimates of  $\theta$  than is used to calculate the covariance matrix, it is possible for the least squares equations to be of full rank but the  $(X^T X)$  matrix to be too nearly singular to be inverted.

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

In cases when **sigma\_est**  $\neq$  Nag\_SigmaRes it is important for the value of **sigma** to be of a reasonable magnitude. Too small a value may cause too many of the winsorized residuals, i.e.,  $\psi(r_i/\sigma)$  to be zero or a value of  $\psi'(r_i/\sigma)$ , used to estimate the asymptotic covariance matrix, to be zero. This can lead to errors with **fail** set to one of the following values:

NE\_WT\_LSQ\_NOT\_FULL\_RANK,

NE\_REG\_MAT\_SINGULAR (if **regtype**  $\neq$  Nag\_HuberReg),

NE\_COV\_MAT\_FACTOR\_ZERO (if **regtype** = Nag\_HuberReg),

NE\_VAR\_THETA\_LEQ\_ZERO.

## 10 Example

The number of observations and the number of  $x$  variables are read in followed by the data. The option arguments are then read in (in this case giving: Schweppe type regression with Hampel's  $\psi$  function and Huber's  $\chi$  function and then using the 'replace expected by observed' option in calculating the covariances). Finally a set of values for the constants are read in. After a call to `nag_robust_m_regsn_estim` (g02hac),  $\hat{\theta}$ , its standard error and  $\hat{\sigma}$  are printed. In addition the weight and residual for each observation is printed.

### 10.1 Program Text

```

/* nag_robust_m_regsn_estim (g02hac) Example Program.
 *
 * Copyright 2014 Numerical Algorithms Group.
 *
 * Mark 4, 1996.
 * Mark 8 revised, 2004.
 *
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <ctype.h>
#include <nagg02.h>

#define C(I, J) c[(I) *tdc + J]
#define X(I, J) x[(I) *tdx + J]

int main(void)
{
    Integer          exit_status = 0, i, j, m, max_iter, n, print_iter, tdc, tdx;
    double           *c = 0, cpsi, cucv, dchi, *hpsi = 0, *info = 0, *rs = 0,
                    sigma, *theta = 0;
    double           tol, *wt = 0, *x = 0, *y = 0;
    char             nag_enum_arg[40];
    Nag_CovMatrixEst covmat_est;
    Nag_PsiFun       psifun;
    Nag_RegType      regtype;
    Nag_SigmaEst     sigma_est;
    NagError         fail;

    INIT_FAIL(fail);

    printf(
        "nag_robust_m_regsn_estim (g02hac) Example Program Results\n\n");
    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    scanf_s("%"NAG_IFMT" %"NAG_IFMT"", &n, &m);
#else
    scanf("%"NAG_IFMT" %"NAG_IFMT"", &n, &m);
#endif
    if (n > 1 && (m >= 1 && m <= n))
    {
        if (!(c = NAG_ALLOC(m*m, double)) ||
            !(theta = NAG_ALLOC(m, double)) ||
            !(x = NAG_ALLOC(n*m, double)) ||
            !(y = NAG_ALLOC(n, double)) ||
            !(rs = NAG_ALLOC(n, double)) ||
            !(wt = NAG_ALLOC(n, double)) ||
            !(info = NAG_ALLOC(4, double)) ||
            !(hpsi = NAG_ALLOC(3, double)))
        {

```

```

        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    tdc = m;
    tdx = m;
}
else
{
    printf("Invalid n or m.\n");
    exit_status = 1;
    return exit_status;
}
/* Read in x and y */
for (i = 0; i < n; i++)
{
    for (j = 0; j < m; j++)
#ifdef _WIN32
        scanf_s("%lf", &X(i, j));
#else
        scanf("%lf", &X(i, j));
#endif
#ifdef _WIN32
        scanf_s("%lf", &y[i]);
#else
        scanf("%lf", &y[i]);
#endif
    }
    /* Read in control parameters */
#ifdef _WIN32
    scanf_s(" %39s", nag_enum_arg, _countof(nag_enum_arg));
#else
    scanf(" %39s", nag_enum_arg);
#endif
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    regtype = (Nag_RegType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
    scanf_s(" %39s", nag_enum_arg, _countof(nag_enum_arg));
#else
    scanf(" %39s", nag_enum_arg);
#endif
    psifun = (Nag_PsiFun) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
    scanf_s(" %39s", nag_enum_arg, _countof(nag_enum_arg));
#else
    scanf(" %39s", nag_enum_arg);
#endif
    sigma_est = (Nag_SigmaEst) nag_enum_name_to_value(nag_enum_arg);

    /* Read in appropriate weight function parameters. */
    if (regtype != Nag_HuberReg)
    {
#ifdef _WIN32
        scanf_s(" %39s %lf", nag_enum_arg, _countof(nag_enum_arg), &cucv);
#else
        scanf(" %39s %lf", nag_enum_arg, &cucv);
#endif
    }
    covmat_est = (Nag_CovMatrixEst) nag_enum_name_to_value(nag_enum_arg);

    if (psifun != Nag_Lsq)
    {
        if (psifun == Nag_HuberFun)
#ifdef _WIN32
            scanf_s("%lf", &cpsi);
#else
            scanf("%lf", &cpsi);
#endif
        else

```

```

        cpsi = 0.0;
        if (psifun == Nag_HampelFun)
            for (j = 0; j < 3; j++)
#ifdef _WIN32
                scanf_s("%lf", &hpsi[j]);
#else
                scanf("%lf", &hpsi[j]);
#endif
        if (sigma_est == Nag_SigmaChi)
#ifdef _WIN32
            scanf_s("%lf", &dchi);
#else
            scanf("%lf", &dchi);
#endif
    }
    /* Set values of remaining parameters */
    tol = 5e-5;
    max_iter = 50;
    /* Change print_iter to a positive value if monitoring information
     * is required
     */
    print_iter = 1;
    sigma = 1.0e0;
    for (i = 0; i < m; ++i)
        theta[i] = 0.0e0;

    /* nag_robust_m_regsn_estim (g02hac).
     * Robust regression, standard M-estimates
     */
    fflush(stdout);
    nag_robust_m_regsn_estim(regtype, psifun, sigma_est, covmat_est, n, m, x,
                            tdx, y, cpsi, hpsi, cucv, dchi, theta, &sigma,
                            c, tdc, rs, wt, tol, max_iter, print_iter,
                            0, info, &fail);

    if ((fail.code == NE_NOERROR) || (fail.code == NE_THETA_ITER_EXCEEDED) ||
        (fail.code == NE_LSQ_FAIL_CONV) || (fail.code == NE_MAT_SINGULAR) ||
        (fail.code == NE_WT_LSQ_NOT_FULL_RANK) ||
        (fail.code == NE_REG_MAT_SINGULAR) ||
        (fail.code == NE_COV_MAT_FACTOR_ZERO) ||
        (fail.code == NE_VAR_THETA_LEQ_ZERO) ||
        (fail.code == NE_ERR_DOF_LEQ_ZERO) ||
        (fail.code == NE_ESTIM_SIGMA_ZERO))
    {
        if (fail.code != NE_NOERROR)
        {
            printf("Error from nag_robust_m_regsn_estim (g02hac).\n%s\n",
                   fail.message);
            printf(
                "    Some of the following results may be unreliable\n");
        }
        printf("Sigma = %10.4f\n\n", sigma);
        printf("    Theta      Standard errors\n\n");
        for (j = 0; j < m; ++j)
            printf("%12.4f %13.4f\n", theta[j], C(j, j));
        printf("\n    Weights      Residuals\n\n");
        for (i = 0; i < n; ++i)
            printf("%12.4f %13.4f\n", wt[i], rs[i]);
    }
    else
    {
        printf("Error from nag_robust_m_regsn_estim (g02hac).\n%s\n",
               fail.message);
        exit_status = 1;
        goto END;
    }

END:
    NAG_FREE(c);
    NAG_FREE(theta);
    NAG_FREE(x);

```

```

NAG_FREE(y);
NAG_FREE(rs);
NAG_FREE(wt);
NAG_FREE(info);
NAG_FREE(hpsi);

return exit_status;
}

```

## 10.2 Program Data

```

nag_robust_m_regsn_estim (g02hac) Example Program Data
8 3
1. -1. -1. 2.1
1. -1. 1. 3.6
1. 1. -1. 4.5
1. 1. 1. 6.1
1. -2. 0. 1.3
1. 0. -2. 1.9
1. 2. 0. 6.7
1. 0. 2. 5.5
Nag_SchweppeReg Nag_HampelFun Nag_SigmaChi
Nag_CovMatObs 3.0
1.5 3.0 4.5
1.5

```

## 10.3 Program Results

```

nag_robust_m_regsn_estim (g02hac) Example Program Results

```

```

** Iteration monitoring for weights **

```

```

Iteration      1  max(abs(s(i,j))) =  1.93661e-01
      A
Row
  1  1.04e+00
  2  8.73e-18  8.05e-01
  3  8.73e-18  5.26e-20  8.05e-01
Iteration      2  max(abs(s(i,j))) =  9.25129e-02
      A
Row
  1  1.08e+00
  2 -7.92e-18  8.80e-01
  3 -6.96e-18  1.97e-18  8.80e-01
Iteration      3  max(abs(s(i,j))) =  3.56059e-02
      A
Row
  1  1.10e+00
  2  2.34e-18  9.11e-01
  3  2.46e-18 -4.84e-19  9.11e-01
Iteration      4  max(abs(s(i,j))) =  1.29404e-02
      A
Row
  1  1.11e+00
  2  2.56e-18  9.23e-01
  3  2.94e-18  7.72e-18  9.23e-01
Iteration      5  max(abs(s(i,j))) =  4.81557e-03
      A
Row
  1  1.12e+00
  2  2.37e-18  9.27e-01
  3  3.04e-18 -9.20e-20  9.27e-01
Iteration      6  max(abs(s(i,j))) =  1.81167e-03
      A
Row
  1  1.12e+00
  2 -1.54e-17  9.29e-01
  3 -1.44e-17 -8.96e-18  9.29e-01
Iteration      7  max(abs(s(i,j))) =  6.81356e-04
      A

```

```

Row
  1  1.12e+00
  2  3.88e-18   9.29e-01
  3  3.07e-18  -4.35e-18   9.29e-01
Iteration      8  max(abs(s(i,j))) =   2.56005e-04
  A
Row
  1  1.12e+00
  2 -1.72e-17   9.30e-01
  3 -1.76e-17  -3.91e-18   9.30e-01
Iteration      9  max(abs(s(i,j))) =   9.61466e-05
  A
Row
  1  1.12e+00
  2 -7.77e-18   9.30e-01
  3 -1.01e-17   6.47e-18   9.30e-01
Iteration     10  max(abs(s(i,j))) =   3.61034e-05
  A
Row
  1  1.12e+00
  2 -1.29e-17   9.30e-01
  3 -1.61e-17  -4.62e-18   9.30e-01
      ** Iteration monitoring for theta **

```

| iteration | sigma       | j | theta       | rs           |
|-----------|-------------|---|-------------|--------------|
| 1         | 1.63136e+00 | 1 | 3.93035e+00 | -3.93035e+00 |
|           |             | 2 | 1.24942e+00 | -1.24942e+00 |
|           |             | 3 | 9.19080e-01 | -9.19080e-01 |
| 2         | 4.48276e-01 | 1 | 3.96250e+00 | -3.21549e-02 |
|           |             | 2 | 1.30833e+00 | -5.89084e-02 |
|           |             | 3 | 8.58333e-01 | 6.07465e-02  |
| 3         | 3.70260e-01 | 1 | 3.97530e+00 | -1.28013e-02 |
|           |             | 2 | 1.30833e+00 | 2.22045e-16  |
|           |             | 3 | 8.41265e-01 | 1.70684e-02  |
| 4         | 3.23188e-01 | 1 | 3.98577e+00 | -1.04731e-02 |
|           |             | 2 | 1.30833e+00 | -2.22045e-16 |
|           |             | 3 | 8.27301e-01 | 1.39642e-02  |
| 5         | 2.91377e-01 | 1 | 3.99829e+00 | -1.25129e-02 |
|           |             | 2 | 1.30833e+00 | 4.44089e-16  |
|           |             | 3 | 8.10617e-01 | 1.66839e-02  |
| 6         | 2.62746e-01 | 1 | 4.02376e+00 | -2.54714e-02 |
|           |             | 2 | 1.30833e+00 | -4.44089e-16 |
|           |             | 3 | 7.76655e-01 | 3.39618e-02  |
| 7         | 2.26353e-01 | 1 | 4.04231e+00 | -1.85490e-02 |
|           |             | 2 | 1.30833e+00 | -2.22045e-16 |
|           |             | 3 | 7.51923e-01 | 2.47320e-02  |
| 8         | 2.09006e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |
| 9         | 2.04291e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |
| 10        | 2.03057e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |
| 11        | 2.02737e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |
| 12        | 2.02654e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |
| 13        | 2.02633e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |
| 14        | 2.02627e-01 | 1 | 4.04231e+00 | 0.00000e+00  |
|           |             | 2 | 1.30833e+00 | 0.00000e+00  |
|           |             | 3 | 7.51923e-01 | 0.00000e+00  |

Sigma = 0.2026

Theta          Standard errors



|         |           |
|---------|-----------|
| 4.0423  | 0.0384    |
| 1.3083  | 0.0272    |
| 0.7519  | 0.0311    |
| Weights | Residuals |
| 0.5783  | 0.1179    |
| 0.5783  | 0.1141    |
| 0.5783  | -0.0987   |
| 0.5783  | -0.0026   |
| 0.4603  | -0.1256   |
| 0.4603  | -0.6385   |
| 0.4603  | 0.0410    |
| 0.4603  | -0.0462   |

---