

# NAG Library Function Document

## nag\_zher2 (f16src)

### 1 Purpose

nag\_zher2 (f16src) performs a Hermitian rank-2 update on a complex Hermitian matrix.

### 2 Specification

```
#include <nag.h>
#include <nagf16.h>

void nag_zher2 (Nag_OrderType order, Nag_UptoType uplo, Integer n,
    Complex alpha, const Complex x[], Integer incx, const Complex y[],
    Integer incy, double beta, Complex a[], Integer pda, NagError *fail)
```

### 3 Description

nag\_zher2 (f16src) performs the Hermitian rank-2 update operation

$$A \leftarrow \alpha xy^H + \bar{\alpha} yx^H + \beta A$$

where  $A$  is an  $n$  by  $n$  complex Hermitian matrix,  $x$  and  $y$  are  $n$ -element complex vectors,  $\alpha$  is a complex scalar and  $\beta$  is a real scalar.

### 4 References

Basic Linear Algebra Subprograms Technical (BLAST) Forum (2001) *Basic Linear Algebra Subprograms Technical (BLAST) Forum Standard* University of Tennessee, Knoxville, Tennessee <http://www.netlib.org/blas/blast-forum/blas-report.pdf>

### 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **uplo** – Nag\_UptoType *Input*

*On entry:* specifies whether the upper or lower triangular part of  $A$  is stored.

**uplo** = Nag\_Upper

The upper triangular part of  $A$  is stored.

**uplo** = Nag\_Lower

The lower triangular part of  $A$  is stored.

*Constraint:* **uplo** = Nag\_Upper or Nag\_Lower.

3: **n** – Integer *Input*

*On entry:*  $n$ , the order of the matrix  $A$ .

*Constraint:* **n**  $\geq 0$ .

|   |                                |                     |
|---|--------------------------------|---------------------|
| 4:  | <b>alpha</b> – Complex         | <i>Input</i>        |
| <i>On entry:</i> the scalar $\alpha$ .  |                                |                     |
| 5:  | <b>x</b> [dim] – const Complex | <i>Input</i>        |
| <b>Note:</b> the dimension, $dim$ , of the array <b>x</b> must be at least $\max(1, 1 + (\mathbf{n} - 1) \mathbf{incx} )$ .                       |                                |                     |
| <i>On entry:</i> the vector $x$ .   |                                |                     |
| 6:  | <b>incx</b> – Integer          | <i>Input</i>        |
| <i>On entry:</i> the increment in the subscripts of <b>x</b> between successive elements of $x$ .   |                                |                     |
| <i>Constraint:</i> $\mathbf{incx} \neq 0$ .   |                                |                     |
| 7:  | <b>y</b> [dim] – const Complex | <i>Input</i>        |
| <b>Note:</b> the dimension, $dim$ , of the array <b>y</b> must be at least $\max(1, 1 + (\mathbf{n} - 1) \mathbf{incy} )$ .                       |                                |                     |
| <i>On entry:</i> the vector $y$ .   |                                |                     |
| 8:  | <b>incy</b> – Integer          | <i>Input</i>        |
| <i>On entry:</i> the increment in the subscripts of <b>y</b> between successive elements of $y$ .   |                                |                     |
| <i>Constraint:</i> $\mathbf{incy} \neq 0$ .   |                                |                     |
| 9:  | <b>beta</b> – double           | <i>Input</i>        |
| <i>On entry:</i> the scalar $\beta$ .   |                                |                     |
| 10:   | <b>a</b> [dim] – Complex       | <i>Input/Output</i> |
| <b>Note:</b> the dimension, $dim$ , of the array <b>a</b> must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$ .                            |                                |                     |
| <i>On entry:</i> the $n$ by $n$ Hermitian matrix $A$ .  |                                |                     |
| If <b>order</b> = Nag_ColMajor, $A_{ij}$ is stored in <b>a</b> [( $j - 1$ ) $\times$ <b>pda</b> + $i - 1$ ].                                      |                                |                     |
| If <b>order</b> = Nag_RowMajor, $A_{ij}$ is stored in <b>a</b> [( $i - 1$ ) $\times$ <b>pda</b> + $j - 1$ ].                                      |                                |                     |
| If <b>uplo</b> = Nag_Upper, the upper triangular part of $A$ must be stored and the elements of the array below the diagonal are not referenced.  |                                |                     |
| If <b>uplo</b> = Nag_Lower, the lower triangular part of $A$ must be stored and the elements of the array above the diagonal are not referenced.  |                                |                     |
| <i>On exit:</i> the updated matrix $A$ . The imaginary parts of the diagonal elements are set to zero.  |                                |                     |
| 11:   | <b>pda</b> – Integer           | <i>Input</i>        |
| <i>On entry:</i> the stride separating row or column elements (depending on the value of <b>order</b> ) of the matrix $A$ in the array <b>a</b> . |                                |                     |
| <i>Constraint:</i> $\mathbf{pda} \geq \max(1, \mathbf{n})$ .  |                                |                     |
| 12:   | <b>fail</b> – NagError *       | <i>Input/Output</i> |
| The NAG error argument (see Section 3.6 in the Essential Introduction).   |                                |                     |

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 3.2.1.2 in the Essential Introduction for further information.

**NE\_BAD\_PARAM**

On entry, argument  $\langle value \rangle$  had an illegal value.

**NE\_INT**

On entry, **incx** =  $\langle value \rangle$ .

Constraint: **incx**  $\neq 0$ .

On entry, **incy** =  $\langle value \rangle$ .

Constraint: **incy**  $\neq 0$ .

On entry, **n** =  $\langle value \rangle$ .

Constraint: **n**  $\geq 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ .

Constraint: **pda**  $\geq \max(1, n)$ .

**NE\_INTERNAL\_ERROR**

An unexpected error has been triggered by this function. Please contact NAG.

See Section 3.6.6 in the Essential Introduction for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.

See Section 3.6.5 in the Essential Introduction for further information.

## 7 Accuracy

The BLAS standard requires accurate implementations which avoid unnecessary over/underflow (see Section 2.7 of Basic Linear Algebra Subprograms Technical (BLAST) Forum (2001)).

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

None.

## 10 Example

Perform rank-2 update of complex Hermitian matrix  $A$  using vectors  $x$  and  $y$ :

$$A \leftarrow A - xy^H - yx^H,$$

where  $A$  is the 4 by 4 matrix given by

$$A = \begin{pmatrix} 23.0 + 0.0i & 10.0 - 17.0i & 13.0 + 14.2i & -19.0 + 8.0i \\ 10.0 + 17.0i & 1.0 + 0.0i & 0.3 + 1.2i & -4.7 + 2.1i \\ 13.0 - 14.2i & 0.3 - 1.2i & 1.0 + 0.0i & -5.9 + 0.1i \\ -19.0 - 8.0i & -4.7 + 2.1i & -5.9 + 0.1i & 1.0 + 0.0i \end{pmatrix},$$

and where

$$x = \begin{pmatrix} 2.0 + 1.0i \\ 2.0 + 3.0i \\ 0.2 - 1.0i \\ -1.0 - 2.0i \end{pmatrix}$$

and

$$y = \begin{pmatrix} 5.0 + 1.0i \\ -2.0 + 1.0i \\ 7.0 - 1.0i \\ -5.0 - 2.0i \end{pmatrix}.$$

The vector  $y$  is stored in every second element of array  $\mathbf{y}$  ( $\mathbf{incy} = 2$ ).

## 10.1 Program Text

```
/* nag_zher2 (f16src) Example Program.
*
* Copyright 2014 Numerical Algorithms Group.
*
* Mark 8, 2005.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stlib.h>
#include <nagf16.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Complex alpha;
    double beta;
    Integer exit_status, i, incx, incy, j, n, pda, xlen, ylen;

    /* Arrays */
    Complex *a = 0, *x = 0, *y = 0;
    char nag_enum_arg[40];

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;
    Nag_UptoType uplo;
    Nag_MatrixType matrix;

#define NAG_COLUMN_MAJOR
#define A(I, J) a[(J-1)*pda + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J) a[(I-1)*pda + J - 1]
    order = Nag_RowMajor;
#endif

    exit_status = 0;
    INIT_FAIL(fail);

    printf("nag_zher2 (f16src) Example Program Results\n\n");

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[^\n] ");
#else
    scanf("%*[^\n] ");
#endif

    /* Read the problem dimension */
#ifdef _WIN32
    scanf_s("%"NAG_IFMT"%*[^\n] ", &n);
#else
    scanf("%"NAG_IFMT"%*[^\n] ", &n);
#endif

    /* Read the uplo storage parameter */

```

```

#define _WIN32
    scanf_s("%39s%*[^\n] ", nag_enum_arg, _countof(nag_enum_arg));
#else
    scanf("%39s%*[^\n] ", nag_enum_arg);
#endif
/* nag_enum_name_to_value (x04nac).
 * Converts NAG enum member name to value
 */
uplo = (Nag_UptoType) nag_enum_name_to_value(nag_enum_arg);

/* Read scalar parameters */
#ifdef _WIN32
    scanf_s(" ( %lf , %lf )%*[^\n] ", &alpha.re, &alpha.im);
#else
    scanf(" ( %lf , %lf )%*[^\n] ", &alpha.re, &alpha.im);
#endif
#ifdef _WIN32
    scanf_s("%lf%*[^\n] ", &beta);
#else
    scanf("%lf%*[^\n] ", &beta);
#endif
/* Read increment parameters */
#ifdef _WIN32
    scanf_s("%"NAG_IFMT%"NAG_IFMT"%*[^\n] ", &incx, &incy);
#else
    scanf("%"NAG_IFMT%"NAG_IFMT"%*[^\n] ", &incx, &incy);
#endif

pda = n;

xlen = MAX(1, 1 + (n - 1)*ABS(incx));
ylen = MAX(1, 1 + (n - 1)*ABS(incy));

if (n > 0)
{
    /* Allocate memory */
    if (!(a = NAG_ALLOC(pda*n, Complex)) ||
        !(x = NAG_ALLOC(xlen, Complex)) ||
        !(y = NAG_ALLOC(ylen, Complex)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
}
else
{
    printf("Invalid n\n");
    exit_status = 1;
    return exit_status;
}

/* Input matrix A and vector x */

if (uplo == Nag_Upper)
{
    for (i = 1; i <= n; ++i)
    {
        for (j = i; j <= n; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#else
            scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#endif
#ifdef _WIN32
            scanf_s("%*[^\n] ");
#else
            scanf("%*[^\n] ");
#endif
    }
}

```

```

else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
#ifdef _WIN32
            scanf_s(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#else
            scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#endif
#ifdef _WIN32
            scanf_s("%*[^\n] ");
#else
            scanf("%*[^\n] ");
#endif
    }
    for (i = 0; i < xlen; ++i)
#ifdef _WIN32
    scanf_s(" ( %lf , %lf )%*[^\n] ", &x[i].re, &x[i].im);
#else
    scanf(" ( %lf , %lf )%*[^\n] ", &x[i].re, &x[i].im);
#endif
    for (i = 0; i < ylen; ++i)
#ifdef _WIN32
    scanf_s(" ( %lf , %lf )%*[^\n] ", &y[i].re, &y[i].im);
#else
    scanf(" ( %lf , %lf )%*[^\n] ", &y[i].re, &y[i].im);
#endif

/* nag_zher2 (f16src).
 * Rank two update of complex Hermitian matrix.
 */
nag_zher2(order, uplo, n, alpha, x, incx, y, incy, beta, a, pda,
          &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_zher2 (f16src).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

if (uplo == Nag_Upper)
{
    matrix = Nag_UpperMatrix;
}
else
{
    matrix = Nag_LowerMatrix;
}
/* Print updated matrix A */
/* nag_gen_complx_mat_print_comp (x04dbc).
 * Print complex general matrix (comprehensive)
 */
fflush(stdout);
nag_gen_complx_mat_print_comp(order, matrix, Nag_NonUnitDiag, n, n, a,
                               pda, Nag_BracketForm, "%5.1f",
                               "Updated Matrix A", Nag_IntegerLabels,
                               0, Nag_IntegerLabels, 0, 80, 0, 0,
                               &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s"
          "\n", fail.message);
    exit_status = 1;
    goto END;
}
END:
NAG_FREE(a);
NAG_FREE(x);

```

```
NAG_FREE(y);

return exit_status;
}
```

## 10.2 Program Data

```
nag_zher2 (f16src) Example Program Data
 4                               :Value of n
 Nag_Lower                      :Storage of A
 (-1.0, 0.0)                    :Value of alpha
 1.0                             :Value of beta
 1 2                            :Values of incx and incy
 ( 23.0, 0.0)
 ( 10.0, 17.0) ( 1.0, 0.0)
 ( 13.0,-14.2) ( 0.3,-1.2) ( 1.0, 0.0)
 (-19.0, -8.0) (-4.7, 2.1) (-5.9, 0.1) ( 1.0, 0.0) :End of matrix A
 ( 2.0, 1.0)
 ( 2.0, 3.0)
 ( 0.2,-1.0)
 (-1.0,-2.0)                   :End of vector x
 ( 5.0, 1.0)
 ( 0.0, 0.0)
 (-2.0, 1.0)
 ( 0.0, 0.0)
 ( 7.0,-1.0)
 ( 0.0, 0.0)
 (-5.0,-2.0)                   :End of vector y
```

## 10.3 Program Results

```
nag_zher2 (f16src) Example Program Results
```

| Updated Matrix A |             |               |               |               |
|------------------|-------------|---------------|---------------|---------------|
|                  | 1           | 2             | 3             | 4             |
| 1                | ( 1.0, 0.0) |               |               |               |
| 2                | ( 0.0, 0.0) | ( 3.0, 0.0)   |               |               |
| 3                | ( 0.0, 0.0) | ( -9.3, 20.0) | ( -3.8, 0.0)  |               |
| 4                | ( 0.0, 0.0) | ( 11.3,-13.9) | ( -1.9, 20.5) | ( -17.0, 0.0) |

---