NAG Library Function Document

nag_zggevx (f08wpc)

1 Purpose

nag_zggevx (f08wpc) computes for a pair of n by n complex nonsymmetric matrices (A, B) the generalized eigenvalues and, optionally, the left and/or right generalized eigenvectors using the QZ algorithm.

Optionally it also computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors, reciprocal condition numbers for the eigenvalues, and reciprocal condition numbers for the right eigenvectors.

2 Specification

```
#include <nag.h>
#include <nagf08.h>
void nag_zggevx (Nag_OrderType order, Nag_BalanceType balanc,
     Nag_LeftVecsType jobvl, Nag_RightVecsType jobvr, Nag_RCondType sense,
     Integer n, Complex a[], Integer pda, Complex b[], Integer pdb,
     Complex alpha[], Complex beta[], Complex vl[], Integer pdvl,
     Complex vr[], Integer pdvr, Integer *ilo, Integer *ihi, double lscale[],
     double rscale[], double *abnrm, double *bbnrm, double rconde[],
     double rcondv[], NagError *fail)
```

3 Description

A generalized eigenvalue for a pair of matrices (A, B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β), as there is a reasonable interpretation for $\beta = 0$, and even for both being zero.

The right generalized eigenvector v_j corresponding to the generalized eigenvalue λ_j of (A, B) satisfies

$$Av_j = \lambda_j Bv_j.$$

The left generalized eigenvector u_j corresponding to the generalized eigenvalue λ_j of (A, B) satisfies

$$u_j^{\mathrm{H}} A = \lambda_j u_j^{\mathrm{H}} B,$$

where u_j^{H} is the conjugate-transpose of u_j.

All the eigenvalues and, if required, all the eigenvectors of the complex generalized eigenproblem $Ax = \lambda Bx$, where A and B are complex, square matrices, are determined using the QZ algorithm. The complex QZ algorithm consists of three stages:

1. A is reduced to upper Hessenberg form (with real, non-negative subdiagonal elements) and at the same time B is reduced to upper triangular form.
2. A is further reduced to triangular form while the triangular form of B is maintained and the diagonal elements of B are made real and non-negative. This is the generalized Schur form of the pair (A, B).

   This function does not actually produce the eigenvalues λ_j, but instead returns α_j and β_j such that

   $$\lambda_j = \alpha_j/\beta_j, \quad j = 1, 2, \ldots, n.$$

   The division by β_j becomes your responsibility, since β_j may be zero, indicating an infinite eigenvalue.
3. If the eigenvectors are required they are obtained from the triangular matrices and then transformed back into the original coordinate system.

For details of the balancing option, see Section 3 in nag_zggbal (f08wvc).

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Wilkinson J H (1979) Kronecker's canonical form and the QZ algorithm *Linear Algebra Appl.* **28** 285–303

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **balanc** – Nag_BalanceType *Input*

On entry: specifies the balance option to be performed.

balanc = Nag_NoBalancing
Do not diagonally scale or permute.

balanc = Nag_BalancePermute
Permute only.

balanc = Nag_BalanceScale
Scale only.

balanc = Nag_BalanceBoth
Both permute and scale.

Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does. In the absence of other information, **balanc** = Nag_BalanceBoth is recommended.

Constraint: **balanc** = Nag_NoBalancing, Nag_BalancePermute, Nag_BalanceScale or Nag_BalanceBoth.

3: **jobvl** – Nag_LeftVecsType *Input*

On entry: if **jobvl** = Nag_NotLeftVecs, do not compute the left generalized eigenvectors.

If **jobvl** = Nag_LeftVecs, compute the left generalized eigenvectors.

Constraint: **jobvl** = Nag_NotLeftVecs or Nag_LeftVecs.

4: **jobvr** – Nag_RightVecsType *Input*

On entry: if **jobvr** = Nag_NotRightVecs, do not compute the right generalized eigenvectors.

If **jobvr** = Nag_RightVecs, compute the right generalized eigenvectors.

Constraint: **jobvr** = Nag_NotRightVecs or Nag_RightVecs.

5: **sense** – Nag_RCondType *Input*

On entry: determines which reciprocal condition numbers are computed.

sense = Nag_NotRCond
None are computed.

sense = Nag_RCondEigVals
Computed for eigenvalues only.

sense = Nag_RCondEigVecs
Computed for eigenvectors only.

sense = Nag_RCondBoth
Computed for eigenvalues and eigenvectors.

Constraint: **sense** = Nag_NotRCond, Nag_RCondEigVals, Nag_RCondEigVecs or Nag_RCondBoth.

6: **n** – Integer *Input*

On entry: n, the order of the matrices A and B.

Constraint: $\mathbf{n} \geq 0$.

7: **a**$[dim]$ – Complex *Input/Output*

Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.

Where $\mathbf{A}(i, j)$ appears in this document, it refers to the array element

$\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1]$ when **order** = Nag_ColMajor;
$\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1]$ when **order** = Nag_RowMajor.

On entry: the matrix A in the pair (A, B).

On exit: **a** has been overwritten. If **jobvl** = Nag_LeftVecs or **jobvr** = Nag_RightVecs or both, then A contains the first part of the Schur form of the 'balanced' versions of the input A and B.

8: **pda** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **a**.

Constraint: $\mathbf{pda} \geq \max(1, \mathbf{n})$.

9: **b**$[dim]$ – Complex *Input/Output*

Note: the dimension, *dim*, of the array **b** must be at least $\max(1, \mathbf{pdb} \times \mathbf{n})$.

Where $\mathbf{B}(i, j)$ appears in this document, it refers to the array element

$\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1]$ when **order** = Nag_ColMajor;
$\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1]$ when **order** = Nag_RowMajor.

On entry: the matrix B in the pair (A, B).

On exit: **b** has been overwritten.

10: **pdb** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.

Constraint: $\mathbf{pdb} \geq \max(1, \mathbf{n})$.

11: **alpha**$[\mathbf{n}]$ – Complex *Output*

On exit: see the description of **beta**.

12: **beta**[**n**] – Complex *Output*

On exit: **alpha**$[j-1]$/**beta**$[j-1]$, for $j = 1, 2, \ldots,$ **n**, will be the generalized eigenvalues.

Note: the quotients **alpha**$[j-1]$/**beta**$[j-1]$ may easily overflow or underflow, and **beta**$[j-1]$ may even be zero. Thus, you should avoid naively computing the ratio α_j/β_j. However, $\max\left(\left|\alpha_j\right|\right)$ will always be less than and usually comparable with $\|\mathbf{a}\|_2$ in magnitude, and $\max\left(\left|\beta_j\right|\right)$ will always be less than and usually comparable with $\|\mathbf{b}\|_2$.

13: **vl**[*dim*] – Complex *Output*

Note: the dimension, *dim*, of the array **vl** must be at least

$\max(1, \textbf{pdvl} \times \textbf{n})$ when **jobvl** = Nag_LeftVecs;
1 otherwise.

The (i, j)th element of the matrix is stored in

vl$[(j-1) \times$ **pdvl** $+ i - 1]$ when **order** = Nag_ColMajor;
vl$[(i-1) \times$ **pdvl** $+ j - 1]$ when **order** = Nag_RowMajor.

On exit: if **jobvl** = Nag_LeftVecs, the left generalized eigenvectors u_j are stored one after another in the columns of **vl**, in the same order as the corresponding eigenvalues. Each eigenvector will be scaled so the largest component will have |real part| + |imag. part| = 1.

If **jobvl** = Nag_NotLeftVecs, **vl** is not referenced.

14: **pdvl** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **vl**.

Constraints:

if **jobvl** = Nag_LeftVecs, **pdvl** $\geq \max(1, \textbf{n})$;
otherwise **pdvl** ≥ 1.

15: **vr**[*dim*] – Complex *Output*

Note: the dimension, *dim*, of the array **vr** must be at least

$\max(1, \textbf{pdvr} \times \textbf{n})$ when **jobvr** = Nag_RightVecs;
1 otherwise.

The (i, j)th element of the matrix is stored in

vr$[(j-1) \times$ **pdvr** $+ i - 1]$ when **order** = Nag_ColMajor;
vr$[(i-1) \times$ **pdvr** $+ j - 1]$ when **order** = Nag_RowMajor.

On exit: if **jobvr** = Nag_RightVecs, the right generalized eigenvectors v_j are stored one after another in the columns of **vr**, in the same order as the corresponding eigenvalues. Each eigenvector will be scaled so the largest component will have |real part| + |imag. part| = 1.

If **jobvr** = Nag_NotRightVecs, **vr** is not referenced.

16: **pdvr** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **vr**.

Constraints:

if **jobvr** = Nag_RightVecs, **pdvr** $\geq \max(1, \textbf{n})$;
otherwise **pdvr** ≥ 1.

17: **ilo** – Integer * *Output*

18: **ihi** – Integer * *Output*

On exit: **ilo** and **ihi** are integer values such that $\mathbf{A}(i,j) = 0$ and $\mathbf{B}(i,j) = 0$ if $i > j$ and $j = 1, 2, \ldots, \mathbf{ilo} - 1$ or $i = \mathbf{ihi} + 1, \ldots, \mathbf{n}$.

If **balanc** = Nag_NoBalancing or Nag_BalanceScale, **ilo** $= 1$ and **ihi** $= \mathbf{n}$.

19: **lscale**[**n**] – double *Output*

On exit: details of the permutations and scaling factors applied to the left side of A and B.

If pl_j is the index of the row interchanged with row j, and dl_j is the scaling factor applied to row j, then:

lscale$[j-1] = pl_j$, for $j = 1, 2, \ldots, \mathbf{ilo} - 1$;

lscale $= dl_j$, for $j = \mathbf{ilo}, \ldots, \mathbf{ihi}$;

lscale $= pl_j$, for $j = \mathbf{ihi} + 1, \ldots, \mathbf{n}$.

The order in which the interchanges are made is **n** to **ihi** $+ 1$, then 1 to **ilo** $- 1$.

20: **rscale**[**n**] – double *Output*

On exit: details of the permutations and scaling factors applied to the right side of A and B.

If pr_j is the index of the column interchanged with column j, and dr_j is the scaling factor applied to column j, then:

rscale$[j-1] = pr_j$, for $j = 1, 2, \ldots, \mathbf{ilo} - 1$;

if **rscale** $= dr_j$, for $j = \mathbf{ilo}, \ldots, \mathbf{ihi}$;

if **rscale** $= pr_j$, for $j = \mathbf{ihi} + 1, \ldots, \mathbf{n}$.

The order in which the interchanges are made is **n** to **ihi** $+ 1$, then 1 to **ilo** $- 1$.

21: **abnrm** – double * *Output*

On exit: the 1-norm of the balanced matrix A.

22: **bbnrm** – double * *Output*

On exit: the 1-norm of the balanced matrix B.

23: **rconde**[dim] – double *Output*

Note: the dimension, *dim*, of the array **rconde** must be at least $\max(1, \mathbf{n})$.

On exit: if **sense** = Nag_RCondEigVals or Nag_RCondBoth, the reciprocal condition numbers of the eigenvalues, stored in consecutive elements of the array.

If **sense** = Nag_NotRCond or Nag_RCondEigVecs, **rconde** is not referenced.

24: **rcondv**[dim] – double *Output*

Note: the dimension, *dim*, of the array **rcondv** must be at least $\max(1, \mathbf{n})$.

On exit: if **sense** = Nag_RCondEigVecs or Nag_RCondBoth, the estimated reciprocal condition numbers of the selected eigenvectors, stored in consecutive elements of the array.

If **sense** = Nag_NotRCond or Nag_RCondEigVals, **rcondv** is not referenced.

25: **fail** – NagError * *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.
See Section 3.2.1.2 in the Essential Introduction for further information.

NE_BAD_PARAM

On entry, argument ⟨*value*⟩ had an illegal value.

NE_EIGENVECTORS

A failure occurred in nag_dtgevc (f08ykc) while computing generalized eigenvectors.

NE_ENUM_INT_2

On entry, **jobvl** = ⟨*value*⟩, **pdvl** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: if **jobvl** = Nag_LeftVecs, **pdvl** $\geq \max(1, \mathbf{n})$;
otherwise **pdvl** ≥ 1.

On entry, **jobvr** = ⟨*value*⟩, **pdvr** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: if **jobvr** = Nag_RightVecs, **pdvr** $\geq \max(1, \mathbf{n})$;
otherwise **pdvr** ≥ 1.

NE_INT

On entry, **n** = ⟨*value*⟩.
Constraint: **n** ≥ 0.

On entry, **pda** = ⟨*value*⟩.
Constraint: **pda** > 0.

On entry, **pdb** = ⟨*value*⟩.
Constraint: **pdb** > 0.

On entry, **pdvl** = ⟨*value*⟩.
Constraint: **pdvl** > 0.

On entry, **pdvr** = ⟨*value*⟩.
Constraint: **pdvr** > 0.

NE_INT_2

On entry, **pda** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pda** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.
See Section 3.6.6 in the Essential Introduction for further information.

NE_ITERATION_QZ

The QZ iteration failed. No eigenvectors have been calculated but **alpha** and **beta** should be correct from element ⟨*value*⟩.

The QZ iteration failed with an unexpected error, please contact NAG.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly.
See Section 3.6.5 in the Essential Introduction for further information.

7 Accuracy

The computed eigenvalues and eigenvectors are exact for a nearby matrices $(A+E)$ and $(B+F)$, where

$$\|(E,F)\|_F = O(\epsilon)\|(A,B)\|_F,$$

and ϵ is the ***machine precision***.

An approximate error bound on the chordal distance between the ith computed generalized eigenvalue w and the corresponding exact eigenvalue λ is

$$\epsilon \times \|\mathbf{abnrm}, \mathbf{bbnrm}\|_2 / \mathbf{rconde}[i-1].$$

An approximate error bound for the angle between the ith computed eigenvector u_j or v_j is given by

$$\epsilon \times \|\mathbf{abnrm}, \mathbf{bbnrm}\|_2 / \mathbf{rcondv}[i-1].$$

For further explanation of the reciprocal condition numbers **rconde** and **rcondv**, see Section 4.11 of Anderson *et al.* (1999).

Note: interpretation of results obtained with the QZ algorithm often requires a clear understanding of the effects of small changes in the original data. These effects are reviewed in Wilkinson (1979), in relation to the significance of small values of α_j and β_j. It should be noted that if α_j and β_j are **both** small for any j, it may be that no reliance can be placed on **any** of the computed eigenvalues $\lambda_i = \alpha_i/\beta_i$. You are recommended to study Wilkinson (1979) and, if in difficulty, to seek expert advice on determining the sensitivity of the eigenvalues to perturbations in the data.

8 Parallelism and Performance

nag_zggevx (f08wpc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_zggevx (f08wpc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The total number of floating-point operations is proportional to n^3.

The real analogue of this function is nag_dggevx (f08wbc).

10 Example

This example finds all the eigenvalues and right eigenvectors of the matrix pair (A,B), where

$$A = \begin{pmatrix} -21.10-22.50i & 53.50-50.50i & -34.50+127.50i & 7.50+0.50i \\ -0.46-7.78i & -3.50-37.50i & -15.50+58.50i & -10.50-1.50i \\ 4.30-5.50i & 39.70-17.10i & -68.50+12.50i & -7.50-3.50i \\ 5.50+4.40i & 14.40+43.30i & -32.50-46.00i & -19.00-32.50i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1.00 - 5.00i & 1.60 + 1.20i & -3.00 + 0.00i & 0.00 - 1.00i \\ 0.80 - 0.60i & 3.00 - 5.00i & -4.00 + 3.00i & -2.40 - 3.20i \\ 1.00 + 0.00i & 2.40 + 1.80i & -4.00 - 5.00i & 0.00 - 3.00i \\ 0.00 + 1.00i & -1.80 + 2.40i & 0.00 - 4.00i & 4.00 - 5.00i \end{pmatrix},$$

together with estimates of the condition number and forward error bounds for each eigenvalue and eigenvector. The option to balance the matrix pair is used.

10.1 Program Text

```
/* nag_zggevx (f08wpc) Example Program.
 *
 * Copyright 2014 Numerical Algorithms Group.
 *
 * Mark 23, 2011.
 */

#include <stdio.h>
#include <math.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <naga02.h>
#include <nagf08.h>
#include <nagx02.h>

int main(void)
{
  /* Scalars */
  Complex           z;
  double            abnorm, abnrm, bbnrm, eps, small, tol;
  Integer           i, ihi, ilo, j, n, pda, pdb, pdvl, pdvr;
  Integer           exit_status = 0;

  /* Arrays */
  Complex           *a = 0, *alpha = 0, *b = 0, *beta = 0, *vl = 0, *vr = 0;
  double            *lscale = 0, *rconde = 0, *rcondv = 0, *rscale = 0;
  char              nag_enum_arg[40];

  /* Nag Types */
  NagError          fail;
  Nag_OrderType     order;
  Nag_LeftVecsType  jobvl;
  Nag_RightVecsType jobvr;
  Nag_RCondType     sense;


#ifdef NAG_COLUMN_MAJOR
#define A(I, J)  a[(J-1)*pda + I - 1]
#define B(I, J)  b[(J-1)*pdb + I - 1]
  order = Nag_ColMajor;
#else
#define A(I, J)  a[(I-1)*pda + J - 1]
#define B(I, J)  b[(I-1)*pdb + J - 1]
  order = Nag_RowMajor;
#endif

  INIT_FAIL(fail);

  printf("nag_zggevx (f08wpc) Example Program Results\n");

  /* Skip heading in data file */
#ifdef _WIN32
  scanf_s("%*[^\n]");
#else
  scanf("%*[^\n]");
#endif
#ifdef _WIN32
  scanf_s("%"NAG_IFMT"%*[^\n]", &n);
```

```
#else
  scanf("%"NAG_IFMT"%*[^\n]", &n);
#endif
  if (n < 0)
    {
      printf("Invalid n\n");
      exit_status = 1;
      goto END;
    }
#ifdef _WIN32
  scanf_s(" %39s%*[^\n]", nag_enum_arg, _countof(nag_enum_arg));
#else
  scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
  /* nag_enum_name_to_value (x04nac).
   * Converts NAG enum member name to value
   */
  jobvl = (Nag_LeftVecsType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
  scanf_s(" %39s%*[^\n]", nag_enum_arg, _countof(nag_enum_arg));
#else
  scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
  jobvr = (Nag_RightVecsType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
  scanf_s(" %39s%*[^\n]", nag_enum_arg, _countof(nag_enum_arg));
#else
  scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
  sense = (Nag_RCondType) nag_enum_name_to_value(nag_enum_arg);

  pda = n;
  pdb = n;
  pdvl = (jobvl==Nag_LeftVecs?n:1);
  pdvr = (jobvr==Nag_RightVecs?n:1);

  /* Allocate memory */
  if (!(a      = NAG_ALLOC(n*n, Complex)) ||
      !(b      = NAG_ALLOC(n*n, Complex)) ||
      !(alpha  = NAG_ALLOC(n, Complex)) ||
      !(beta   = NAG_ALLOC(n, Complex)) ||
      !(vl     = NAG_ALLOC(pdvl*pdvl, Complex)) ||
      !(vr     = NAG_ALLOC(pdvr*pdvr, Complex)) ||
      !(lscale = NAG_ALLOC(n, double)) ||
      !(rconde = NAG_ALLOC(n, double)) ||
      !(rcondv = NAG_ALLOC(n, double)) ||
      !(rscale = NAG_ALLOC(n, double)))
    {
      printf("Allocation failure\n");
      exit_status = -1;
      goto END;
    }

  /* Read in the matrices A and B */
  for (i = 1; i <= n; ++i)
    for (j = 1; j <= n; ++j)
#ifdef _WIN32
      scanf_s(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#else
      scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
#endif
#ifdef _WIN32
  scanf_s("%*[^\n]");
#else
  scanf("%*[^\n]");
#endif
  for (i = 1; i <= n; ++i)
    for (j = 1; j <= n; ++j)
#ifdef _WIN32
      scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
```

```
      scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
  scanf_s("%*[^\n]");
#else
  scanf("%*[^\n]");
#endif

  /* Solve the generalized eigenvalue problem using nag_zggevx (f08wpc). */
  nag_zggevx(order, Nag_BalanceBoth, jobvl, jobvr, sense, n, a, pda, b, pdb,
             alpha, beta, vl, pdvl, vr, pdvr, &ilo, &ihi, lscale, rscale,
             &abnrm, &bbnrm, rconde, rcondv, &fail);
  if (fail.code != NE_NOERROR)
    {
      printf("Error from nag_zggevx (f08wpc).\n%s\n", fail.message);
      exit_status = 1;
      goto END;
    }

  /* nag_real_safe_small_number (x02amc), nag_machine_precision (x02ajc) */
  eps = nag_machine_precision;
  small = nag_real_safe_small_number;
  if (abnrm == 0.0)
    abnorm = ABS(bbnrm);
  else if (bbnrm == 0.0)
    abnorm = ABS(abnrm);
  else if (ABS(abnrm) >= ABS(bbnrm))
    abnorm = ABS(abnrm)*sqrt(1.0+(bbnrm/abnrm)*(bbnrm/abnrm));
  else
    abnorm = ABS(bbnrm)*sqrt(1.0+(abnrm/bbnrm)*(abnrm/bbnrm));

  tol = eps * abnorm;

  /* Print out eigenvalues and associated condition number and bounds */
  if (sense!=Nag_NotRCond)
    printf("\n R = Reciprocal condition number, E = Error bound\n\n");
  printf("%22s","Eigenvalues");
  if (sense==Nag_RCondEigVals || sense==Nag_RCondBoth)
    printf("%15s%10s","R","E");
  printf("\n");
  for (j = 0; j < n; ++j)
    {
      /* Print out information on the jth eigenvalue */
      if (nag_complex_abs(alpha[j])*small >= nag_complex_abs(beta[j]))
        {
          printf("%2"NAG_IFMT" is numerically infinite or undetermined\n", j+1);
          printf("   alpha = (%9.4f, %9.4f), beta = (%9.4f, %9.4f)\n",
                 alpha[j].re, alpha[j].im, beta[j].re, beta[j].im);
        }
      else
        {
          z = nag_complex_divide(alpha[j], beta[j]);
          printf("%2"NAG_IFMT" (%13.4e, %13.4e)", j+1, z.re, z.im);
          if (sense==Nag_RCondEigVals || sense==Nag_RCondBoth)
            {
              printf(" %10.1e", rconde[j]);
              if (rconde[j] > 0.0)
                printf(" %9.1e", tol/rconde[j]);
              else
                printf(" infinite");
            }
          printf("\n");
        }
    }

  /* Print out information on the eigenvectors as requested */
  if (jobvl==Nag_LeftVecs) {
    printf("\n");
    /* Print left eigenvectors using nag_gen_complx_mat_print (x04dac). */
    fflush(stdout);
    nag_gen_complx_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
```

```
                            n, vl, pdvl, "    Left eigenvectors (columns)",
                            0, &fail);
  }
  if ( jobvr==Nag_RightVecs && fail.code == NE_NOERROR) {
    printf("\n");
    /* Print rightt eigenvectors using nag_gen_complx_mat_print (x04dac). */
    fflush(stdout);
    nag_gen_complx_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                            n, vr, pdvr, "    Right eigenvectors (columns)",
                            0, &fail);
  }
  if (fail.code != NE_NOERROR)
    {
      printf("Error from nag_gen_complx_mat_print (x04dac).\n%s\n",
             fail.message);
      exit_status = 1;
      goto END;
    }
  if (sense==Nag_RCondEigVecs || sense==Nag_RCondBoth)
    {
      printf("%2s","R");
      for (j = 0; j < n; ++j) printf(" %8.1e", rcondv[j]);
      printf("\n%2s","E");
      for (j = 0; j < n; ++j)
        {
          if (rcondv[j] > 0.0)
            printf(" %8.1e", tol/rcondv[j]);
          else
            printf(" infinite");
        }
      printf("\n");
    }

 END:
  NAG_FREE(a);
  NAG_FREE(b);
  NAG_FREE(alpha);
  NAG_FREE(beta);
  NAG_FREE(vl);
  NAG_FREE(vr);
  NAG_FREE(lscale);
  NAG_FREE(rconde);
  NAG_FREE(rcondv);
  NAG_FREE(rscale);

  return exit_status;
}
```

10.2 Program Data

```
nag_zggevx (f08wpc) Example Program Data

    4                                                                 : n

   Nag_NotLeftVecs                                                    : jobvl
   Nag_RightVecs                                                      : jobvr
   Nag_RCondBoth                                                      : sense

  (-21.10,-22.50) ( 53.50,-50.50) (-34.50,127.50) (  7.50,  0.50)
  ( -0.46, -7.78) ( -3.50,-37.50) (-15.50, 58.50) (-10.50, -1.50)
  (  4.30, -5.50) ( 39.70,-17.10) (-68.50, 12.50) ( -7.50, -3.50)
  (  5.50,  4.40) ( 14.40, 43.30) (-32.50,-46.00) (-19.00,-32.50) : A

  (  1.00, -5.00) (  1.60,  1.20) ( -3.00,  0.00) (  0.00, -1.00)
  (  0.80, -0.60) (  3.00, -5.00) ( -4.00,  3.00) ( -2.40, -3.20)
  (  1.00,  0.00) (  2.40,  1.80) ( -4.00, -5.00) (  0.00, -3.00)
  (  0.00,  1.00) ( -1.80,  2.40) (  0.00, -4.00) (  4.00, -5.00) : B
```

10.3 Program Results

```
nag_zggevx (f08wpc) Example Program Results

 R = Reciprocal condition number, E = Error bound

          Eigenvalues              R         E
 1 (   3.0000e+00,   -9.0000e+00)    5.1e-01   3.1e-15
 2 (   2.0000e+00,   -5.0000e+00)    3.8e-01   4.3e-15
 3 (   3.0000e+00,   -1.0000e+00)    1.3e-01   1.2e-14
 4 (   4.0000e+00,   -5.0000e+00)    6.2e-01   2.6e-15

     Right eigenvectors (columns)
          1        2        3        4
 1  -0.7396   0.6237   0.4880  -0.3660
    -0.2604   0.3763   0.5120   0.6340

 2  -0.1496   0.0041   0.1395   0.0010
     0.0471  -0.0004   0.0233   0.0081

 3  -0.0471   0.0392   0.1405   0.0122
    -0.1496   0.0237  -0.0167  -0.0211

 4   0.1496  -0.0237   0.0167  -0.0986
    -0.0471   0.0392   0.1405  -0.0569

 R  4.7e-02  6.6e-02  1.7e-01  3.5e-02
 E  3.4e-14  2.4e-14  9.3e-15  4.6e-14
```