

NAG Library Function Document

nag_dgtsv (f07cac)

1 Purpose

nag_dgtsv (f07cac) computes the solution to a real system of linear equations

$$AX = B,$$

where A is an n by n tridiagonal matrix and X and B are n by r matrices.

2 Specification

```
#include <nag.h>
#include <nagf07.h>
void nag_dgtsv (Nag_OrderType order, Integer n, Integer nrhs, double dl[],
               double d[], double du[], double b[], Integer pdb, NagError *fail)
```

3 Description

nag_dgtsv (f07cac) uses Gaussian elimination with partial pivoting and row interchanges to solve the equations $AX = B$. The matrix A is factorized as $A = PLU$, where P is a permutation matrix, L is unit lower triangular with at most one nonzero subdiagonal element per column, and U is an upper triangular band matrix, with two superdiagonals.

Note that the equations $A^T X = B$ may be solved by interchanging the order of the arguments **du** and **dl**.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

5 Arguments

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.
Constraint: **order** = Nag_RowMajor or Nag_ColMajor.
- 2: **n** – Integer *Input*
On entry: n , the number of linear equations, i.e., the order of the matrix A .
Constraint: $n \geq 0$.
- 3: **nrhs** – Integer *Input*
On entry: r , the number of right-hand sides, i.e., the number of columns of the matrix B .
Constraint: **nrhs** ≥ 0 .

- 4: **dl**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **dl** must be at least $\max(1, \mathbf{n} - 1)$.
On entry: must contain the $(n - 1)$ subdiagonal elements of the matrix *A*.
On exit: if no constraints are violated, **dl** is overwritten by the $(n - 2)$ elements of the second superdiagonal of the upper triangular matrix *U* from the *LU* factorization of *A*, in **dl**[0], **dl**[1], ..., **dl**[*n* - 3].
- 5: **d**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **d** must be at least $\max(1, \mathbf{n})$.
On entry: must contain the *n* diagonal elements of the matrix *A*.
On exit: if no constraints are violated, **d** is overwritten by the *n* diagonal elements of the upper triangular matrix *U* from the *LU* factorization of *A*.
- 6: **du**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **du** must be at least $\max(1, \mathbf{n} - 1)$.
On entry: must contain the $(n - 1)$ superdiagonal elements of the matrix *A*.
On exit: if no constraints are violated, **du** is overwritten by the $(n - 1)$ elements of the first superdiagonal of *U*.
- 7: **b**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **b** must be at least
 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** = Nag_ColMajor;
 $\max(1, \mathbf{n} \times \mathbf{pdb})$ when **order** = Nag_RowMajor.
The (*i*, *j*)th element of the matrix *B* is stored in
 $\mathbf{b}[(j - 1) \times \mathbf{pdb} + i - 1]$ when **order** = Nag_ColMajor;
 $\mathbf{b}[(i - 1) \times \mathbf{pdb} + j - 1]$ when **order** = Nag_RowMajor.
On entry: the *n* by *r* right-hand side matrix *B*.
On exit: if **fail.code** = NE_NOERROR, the *n* by *r* solution matrix *X*.
- 8: **pdb** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.
Constraints:
if **order** = Nag_ColMajor, **pdb** $\geq \max(1, \mathbf{n})$;
if **order** = Nag_RowMajor, **pdb** $\geq \max(1, \mathbf{nrhs})$.
- 9: **fail** – NagError * *Input/Output*
The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

See Section 3.2.1.2 in the Essential Introduction for further information.

NE_BAD_PARAM

On entry, argument *<value>* had an illegal value.

NE_INT

On entry, **n** = $\langle value \rangle$.
 Constraint: **n** ≥ 0 .

On entry, **nrhs** = $\langle value \rangle$.
 Constraint: **nrhs** ≥ 0 .

On entry, **pdb** = $\langle value \rangle$.
 Constraint: **pdb** > 0 .

NE_INT_2

On entry, **pdb** = $\langle value \rangle$ and **n** = $\langle value \rangle$.
 Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$ and **nrhs** = $\langle value \rangle$.
 Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.
 See Section 3.6.6 in the Essential Introduction for further information.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly.
 See Section 3.6.5 in the Essential Introduction for further information.

NE_SINGULAR

Element $\langle value \rangle$ of the diagonal is exactly zero, and the solution has not been computed. The factorization has not been completed unless **n** = $\langle value \rangle$.

7 Accuracy

The computed solution for a single right-hand side, \hat{x} , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and ϵ is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$, the condition number of A with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

Alternatives to nag_dgtsv (f07cac), which return condition and error estimates are nag_real_tridiag_lin_solve (f04bcc) and nag_dgtsvx (f07cbc).

8 Parallelism and Performance

Not applicable.

9 Further Comments

The total number of floating-point operations required to solve the equations $AX = B$ is proportional to nr .

The complex analogue of this function is nag_zgtsv (f07cnc).

10 Example

This example solves the equations

$$Ax = b,$$

where A is the tridiagonal matrix

$$A = \begin{pmatrix} 3.0 & 2.1 & 0 & 0 & 0 \\ 3.4 & 2.3 & -1.0 & 0 & 0 \\ 0 & 3.6 & -5.0 & 1.9 & 0 \\ 0 & 0 & 7.0 & -0.9 & 8.0 \\ 0 & 0 & 0 & -6.0 & 7.1 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 2.7 \\ -0.5 \\ 2.6 \\ 0.6 \\ 2.7 \end{pmatrix}.$$

10.1 Program Text

```

/* nag_dgtsv (f07cac) Example Program.
 *
 * Copyright 2014 Numerical Algorithms Group.
 *
 * Mark 23, 2011.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>

int main(void)
{
    /* Scalars */
    Integer      exit_status = 0, i, j, n, nrhs, pdb;

    /* Arrays */
    double       *b = 0, *d = 0, *dl = 0, *du = 0;

    /* Nag Types */
    NagError      fail;
    Nag_OrderType order;

#ifdef NAG_COLUMN_MAJOR
#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_dgtsv (f07cac) Example Program Results\n\n");
    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

#ifdef _WIN32
    scanf_s("%"NAG_IFMT%"NAG_IFMT"%*[\n]", &n, &nrhs);

```

```

#else
    scanf("%NAG_IFMT%"NAG_IFMT"%*[\n]", &n, &nrhs);
#endif
    if (n < 0 || nrhs < 0)
    {
        printf("Invalid n or nrhs\n");
        exit_status = 1;
        goto END;
    }
    /* Allocate memory */
    if (!(b = NAG_ALLOC(n*nrhs, double)) ||
        !(d = NAG_ALLOC(n, double)) ||
        !(dl = NAG_ALLOC(n-1, double)) ||
        !(du = NAG_ALLOC(n-1, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

#ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

    /* Read the tridiagonal matrix A and the right hand side B from data file */
#ifdef _WIN32
    for (i = 0; i < n - 1; ++i) scanf_s("%lf", &du[i]);
#else
    for (i = 0; i < n - 1; ++i) scanf("%lf", &du[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    for (i = 0; i < n; ++i) scanf_s("%lf", &d[i]);
#else
    for (i = 0; i < n; ++i) scanf("%lf", &d[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
#ifdef _WIN32
    for (i = 0; i < n - 1; ++i) scanf_s("%lf", &dl[i]);
#else
    for (i = 0; i < n - 1; ++i) scanf("%lf", &dl[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

    for (i = 1; i <= n; ++i)
#ifdef _WIN32
        for (j = 1; j <= nrhs; ++j) scanf_s("%lf", &B(i, j));
#else
        for (j = 1; j <= nrhs; ++j) scanf("%lf", &B(i, j));
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

    /* Solve the equations Ax = b for x using nag_dgtsv (f07cac). */

```

```

nag_dgtsv(order, n, nrhs, dl, d, du, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dgtsv (f07cac).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print solution */
printf("Solution\n");
for (i = 1; i <= n; ++i) {
    for (j = 1; j <= nrhs; ++j) printf("%11.4f%s", B(i, j), j%7 == 0?"\n":" ");
    printf("\n");
}
END:
NAG_FREE(b);
NAG_FREE(d);
NAG_FREE(dl);
NAG_FREE(du);
return exit_status;
}

```

10.2 Program Data

nag_dgtsv (f07cac) Example Program Data

```

5      1      : n, nrhs
      2.1 -1.0  1.9  8.0 : superdiag of A
3.0    2.3 -5.0 -0.9  7.1 : main diag of A
3.4    3.6  7.0 -6.0      : subdiag of A

2.7
-0.5
2.6
0.6
2.7      : vector b

```

10.3 Program Results

nag_dgtsv (f07cac) Example Program Results

```

Solution
-4.0000
 7.0000
 3.0000
-4.0000
-3.0000

```
