

NAG Library Routine Document

F07HHF (DPBRFS)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F07HHF (DPBRFS) returns error bounds for the solution of a real symmetric positive definite band system of linear equations with multiple right-hand sides, $AX = B$. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```
SUBROUTINE F07HHF (UPLO, N, KD, NRHS, AB, LDAB, AFB, LDAFB, B, LDB, X, LDX,      &
                  FERR, BERR, WORK, IWORK, INFO)
INTEGER          N, KD, NRHS, LDAB, LDAFB, LDB, LDX, IWORK(N), INFO
REAL (KIND=nag_wp) AB(LDAB,*), AFB(LDAFB,*), B(LDB,*), X(LDX,*),      &
                  FERR(NRHS), BERR(NRHS), WORK(3*N)
CHARACTER(1)     UPLO
```

The routine may be called by its LAPACK name *dpbrfs*.

3 Description

F07HHF (DPBRFS) returns the backward errors and estimated bounds on the forward errors for the solution of a real symmetric positive definite band system of linear equations with multiple right-hand sides $AX = B$. The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of F07HHF (DPBRFS) in terms of a single right-hand side b and solution x .

Given a computed solution x , the routine computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$\begin{aligned}
 & (A + \delta A)x = b + \delta b \\
 & |\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.
 \end{aligned}$$

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where \hat{x} is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

- 1: UPLO – CHARACTER(1) *Input*
On entry: specifies whether the upper or lower triangular part of A is stored and how A is to be factorized.
 UPLO = 'U'
 The upper triangular part of A is stored and A is factorized as $U^T U$, where U is upper triangular.
 UPLO = 'L'
 The lower triangular part of A is stored and A is factorized as LL^T , where L is lower triangular.
Constraint: UPLO = 'U' or 'L'.
- 2: N – INTEGER *Input*
On entry: n , the order of the matrix A .
Constraint: $N \geq 0$.
- 3: KD – INTEGER *Input*
On entry: k_d , the number of superdiagonals or subdiagonals of the matrix A .
Constraint: $KD \geq 0$.
- 4: NRHS – INTEGER *Input*
On entry: r , the number of right-hand sides.
Constraint: $NRHS \geq 0$.
- 5: AB(LDAB,*) – REAL (KIND=nag_wp) array *Input*
Note: the second dimension of the array AB must be at least $\max(1, N)$.
On entry: the n by n original symmetric positive definite band matrix A as supplied to F07HDF (DPBTRF).
- 6: LDAB – INTEGER *Input*
On entry: the first dimension of the array AB as declared in the (sub)program from which F07HHF (DPBRFS) is called.
Constraint: $LDAB \geq KD + 1$.
- 7: AFB(LDAFB,*) – REAL (KIND=nag_wp) array *Input*
Note: the second dimension of the array AFB must be at least $\max(1, N)$.
On entry: the Cholesky factor of A , as returned by F07HDF (DPBTRF).
- 8: LDAFB – INTEGER *Input*
On entry: the first dimension of the array AFB as declared in the (sub)program from which F07HHF (DPBRFS) is called.
Constraint: $LDAFB \geq KD + 1$.
- 9: B(LDB,*) – REAL (KIND=nag_wp) array *Input*
Note: the second dimension of the array B must be at least $\max(1, NRHS)$.
On entry: the n by r right-hand side matrix B .

- 10: LDB – INTEGER *Input*
On entry: the first dimension of the array B as declared in the (sub)program from which F07HHF (DPBRFS) is called.
Constraint: $LDB \geq \max(1, N)$.
- 11: X(LDX,*) – REAL (KIND=nag_wp) array *Input/Output*
Note: the second dimension of the array X must be at least $\max(1, NRHS)$.
On entry: the n by r solution matrix X , as returned by F07HEF (DPBTRS).
On exit: the improved solution matrix X .
- 12: LDX – INTEGER *Input*
On entry: the first dimension of the array X as declared in the (sub)program from which F07HHF (DPBRFS) is called.
Constraint: $LDX \geq \max(1, N)$.
- 13: FERR(NRHS) – REAL (KIND=nag_wp) array *Output*
On exit: $FERR(j)$ contains an estimated error bound for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.
- 14: BERR(NRHS) – REAL (KIND=nag_wp) array *Output*
On exit: $BERR(j)$ contains the component-wise backward error bound β for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.
- 15: WORK($3 \times N$) – REAL (KIND=nag_wp) array *Workspace*
- 16: IWORK(N) – INTEGER array *Workspace*
- 17: INFO – INTEGER *Output*
On exit: $INFO = 0$ unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

$INFO < 0$

If $INFO = -i$, the i th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $8nk$ floating point operations. Each step of iterative refinement involves an additional $12nk$ operations. This assumes $n \gg k$. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form $Ax = b$; the number is usually 4 or 5 and never more than 11. Each solution involves approximately $4nk$ operations.

The complex analogue of this routine is F07HVF (ZPBRFS).

9 Example

This example solves the system of equations $AX = B$ using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 5.49 & 2.68 & 0.00 & 0.00 \\ 2.68 & 5.63 & -2.39 & 0.00 \\ 0.00 & -2.39 & 2.60 & -2.22 \\ 0.00 & 0.00 & -2.22 & 5.17 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 22.09 & 5.10 \\ 9.31 & 30.81 \\ -5.24 & -25.82 \\ 11.83 & 22.90 \end{pmatrix}.$$

Here A is symmetric and positive definite, and is treated as a band matrix, which must first be factorized by F07HDF (DPBTRF).

9.1 Program Text

```

Program f07hhfe

!      F07HHF Example Program Text

!      Mark 24 Release. NAG Copyright 2012.

!      .. Use Statements ..
Use nag_library, Only: dpbrfs, dpbtrf, dpbtrs, nag_wp, x04caf
!      .. Implicit None Statement ..
Implicit None
!      .. Parameters ..
Real (Kind=nag_wp), Parameter      :: zero = 0.0E0_nag_wp
Integer, Parameter                  :: nin = 5, nout = 6
!      .. Local Scalars ..
Integer                              :: i, ifail, info, j, kd, ldab, ldafb, &
                                     ldb, ldx, n, nrhs
Character (1)                        :: uplo
!      .. Local Arrays ..
Real (Kind=nag_wp), Allocatable     :: ab(:,,:), afb(:,,:), b(:,,:), berr(:), &
                                     ferr(:), work(:), x(:,,:)
Integer, Allocatable                 :: iwork(:)
!      .. Intrinsic Procedures ..
Intrinsic                            :: max, min
!      .. Executable Statements ..
Write (nout,*) 'F07HHF Example Program Results'
!      Skip heading in data file
Read (nin,*)
Read (nin,*) n, kd, nrhs
ldab = kd + 1
ldafb = kd + 1
ldb = n
ldx = n
Allocate (ab(ldab,n),afb(ldafb,n),b(ldb,nrhs),berr(nrhs),ferr(nrhs), &
         work(3*n),x(ldx,n),iwork(n))

!      Set A to zero to avoid referencing uninitialized elements

ab(1:kd+1,1:n) = zero

!      Read A and B from data file, and copy A to AFB and B to X

Read (nin,*) uplo
If (uplo=='U') Then
  Do i = 1, n
    Read (nin,*) (ab(kd+1+i-j,j),j=i,min(n,i+kd))
  End Do
Else If (uplo=='L') Then
  Do i = 1, n
    Read (nin,*) (ab(1+i-j,j),j=max(1,i-kd),i)
  End Do
End If

```

```

      Read (nin,*)(b(i,1:nrhs),i=1,n)

      afb(1:kd+1,1:n) = ab(1:kd+1,1:n)
      x(1:n,1:nrhs) = b(1:n,1:nrhs)

!      Factorize A in the array AFB
!      The NAG name equivalent of dpbtrf is f07hdf
!      Call dpbtrf(uplo,n,kd,afb,ldafb,info)

      Write (nout,*)
      Flush (nout)
      If (info==0) Then

!          Compute solution in the array X
!          The NAG name equivalent of dpbtrs is f07hef
!          Call dpbtrs(uplo,n,kd,nrhs,afb,ldafb,x,ldx,info)

!          Improve solution, and compute backward errors and
!          estimated bounds on the forward errors

!          The NAG name equivalent of dpbrfs is f07hhf
!          Call dpbrfs(uplo,n,kd,nrhs,ab,ldab,afb,ldafb,b,ldb,x,ldx,ferr,berr, &
!              work,iwork,info)

!          Print solution

!          ifail: behaviour on error exit
!          =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
      ifail = 0
      Call x04caf('General',' ',n,nrhs,x,ldx,'Solution(s)',ifail)

      Write (nout,*)
      Write (nout,*) 'Backward errors (machine-dependent)'
      Write (nout,99999) berr(1:nrhs)
      Write (nout,*) 'Estimated forward error bounds (machine-dependent)'
      Write (nout,99999) ferr(1:nrhs)
      Else
        Write (nout,*) 'A is not positive definite'
      End If

99999 Format ((3X,1P,7E11.1))
      End Program f07hhfe

```

9.2 Program Data

```

F07HHF Example Program Data
  4  1  2          :Values of N, KD and NRHS
  'L'            :Value of UPLO
  5.49
  2.68    5.63
          -2.39    2.60
          -2.22    5.17 :End of matrix A
  22.09    5.10
  9.31    30.81
  -5.24   -25.82
  11.83    22.90          :End of matrix B

```

9.3 Program Results

F07HHF Example Program Results

```

Solution(s)
      1          2
1      5.0000   -2.0000
2     -2.0000    6.0000
3     -3.0000   -1.0000
4      1.0000    4.0000

```

Backward errors (machine-dependent)

4.4E-17 9.2E-17

Estimated forward error bounds (machine-dependent)

2.0E-14 2.9E-14
