NAG Library Function Document

nag_tsa_inhom_ma (g13mgc)

1   Purpose

nag_tsa_inhom_ma (g13mgc) provides a moving average, moving norm, moving variance and moving standard deviation operator for an inhomogeneous time series.

2   Specification

```
#include <nag.h>
#include <nagg13.h>
```

```
void nag_tsa_inhom_ma (Integer nb, double ma[], const double t[], double tau,
    Integer m1, Integer m2, const double sinit[],
    const Nag_TS_Interpolation inter[], Nag_TS_Transform ftype, double *p,
    Integer *pn, double wma[], double rcomm[], NagError *fail)
```

3   Description

nag_tsa_inhom_ma (g13mgc) provides a number of operators for an inhomogeneous time series. The time series is represented by two vectors of length n; a vector of times, t; and a vector of values, z. Each element of the time series is therefore composed of the pair of scalar values (t_i, z_i), for $i = 1, 2, \ldots, n$. Time t can be measured in any arbitrary units, as long as all elements of t use the same units.

The main operator available, the moving average (MA), with parameter τ is defined as

$$\mathrm{MA}[\tau, m_1, m_2; y](t_i) = \frac{1}{m_2 - m_1 + 1} \sum_{j=m_1}^{m_2} \mathrm{EMA}[\tilde{\tau}, j; y](t_i) \tag{1}$$

where $\tilde{\tau} = \frac{2\tau}{m_2 + m_1}$, m_1 and m_2 are user-supplied integers controlling the amount of lag and smoothing respectively, with $m_2 \geq m_1$ and $\mathrm{EMA}[\cdot]$ is the iterated exponential moving average operator.

The iterated exponential moving average, $\mathrm{EMA}[\tilde{\tau}, m; y](t_i)$, is defined using the recursive formula:

$$\mathrm{EMA}[\tilde{\tau}, m; y](t_i) = \mathrm{EMA}[\tilde{\tau}; \mathrm{EMA}[\tilde{\tau}, m - 1; y](t_i)](t_i)$$

with

$$\mathrm{EMA}[\tilde{\tau}, 1; y](t_i) = \mathrm{EMA}[\tilde{\tau}; y](t_i)$$

and

$$\mathrm{EMA}[\tilde{\tau}; y](t_i) = \mu \mathrm{EMA}[\tilde{\tau}; y](t_{i-1}) + (\nu - \mu)y_{i-1} + (1 - \nu)y_i$$

where

$$\mu = e^{-\alpha} \quad \text{and} \quad \alpha = \frac{t_i - t_{i-1}}{\tilde{\tau}}.$$

The value of ν depends on the method of interpolation chosen and the relationship between y and the input series z depends on the transformation function chosen. nag_tsa_inhom_ma (g13mgc) gives the option of three interpolation methods:

    1.   Previous point: $\nu = 1$.
    2.   Linear: $\nu = (1 - \mu)/\alpha$.
    3.   Next point: $\nu = \mu$.

and three transformation functions:

1. Identity: $y_i = z_i^{[p]}$.
2. Absolute value: $y_i = |z_i|^p$.
3. Absolute difference: $y_i = |z_i - \mathrm{MA}[\tau, m_1, m_2; z](t_i)|^p$.

where the notation $[p]$ is used to denote the integer nearest to p. In addition, if either the absolute value or absolute difference transformation are used then the resulting moving average can be scaled by p^{-1}.

The various parameter options allow a number of different operators to be applied by nag_tsa_inhom_ma (g13mgc), a few of which are:

(i) **Moving Average (MA)**, as defined in (1) (obtained by setting **ftype** = Nag_Identity and **p** = 1).

(ii) **Moving Norm (MNorm)**, defined as

$$\mathrm{MNorm}(\tau, m, p; z) = \mathrm{MA}[\tau, 1, m; |z|^p]^{1/p}$$

(obtained by setting **ftype** = Nag_AbsValScaled, **m1** = 1 and **m2** = m).

(iii) **Moving Variance (MVar)**, defined as

$$\mathrm{MVar}(\tau, m, p; z) = \mathrm{MA}[\tau, 1, m; |z - \mathrm{MA}[\tau, 1, m; z]|^p]$$

(obtained by setting **ftype** = Nag_AbsDiff, **m1** = 1 and **m2** = m).

(iv) **Moving Standard Deviation (MSD)**, defined as

$$\mathrm{MSD}(\tau, m, p; z) = \mathrm{MA}[\tau, 1, m; |z - \mathrm{MA}[\tau, 1, m; z]|^p]^{1/p}$$

(obtained by setting **ftype** = Nag_AbsDiffScaled, **m1** = 1 and **m2** = m).

For large datasets or where all the data is not available at the same time, z and t can be split into arbitrary sized blocks and nag_tsa_inhom_ma (g13mgc) called multiple times.

4   References

Dacorogna M M, Gencay R, Müller U, Olsen R B and Pictet O V (2001) _An Introduction to High-frequency Finance_ Academic Press

Zumbach G O and Müller U A (2001) Operators on inhomogeneous time series _International Journal of Theoretical and Applied Finance_ **4(1)** 147–178

5   Arguments

1:    **nb** – Integer   _Input_

On entry: b, the number of observations in the current block of data. At each call the size of the block of data supplied in **ma** and **t** can vary; therefore **nb** can change between calls to nag_tsa_inhom_ma (g13mgc).

Constraint: **nb** ≥ 0.

2:    **ma**[**nb**] – double   _Input/Output_

On entry: z_i, the current block of observations, for $i = k+1, \ldots, k+b$, where k is the number of observations processed so far, i.e., the value supplied in **pn** on entry.

On exit: the moving average:

if **ftype** = Nag_AbsValScaled or Nag_AbsDiffScaled
$\qquad$ **ma**[$i-1$] = $\{\mathrm{MA}[\tau, m_1, m_2; y](t_i)\}^{1/p}$,

otherwise
$\qquad$ **ma**[$i-1$] = $\mathrm{MA}[\tau, m_1, m_2; y](t_i)$.

3:     **t**[**nb**] – const double   *Input*

   On entry: t_i, the times for the current block of observations, for $i = k+1, \ldots, k+b$, where k is the number of observations processed so far, i.e., the value supplied in **pn** on entry.

   If $t_i \leq t_{i-1}$, **fail.code** = NE_NOT_STRICTLY_INCREASING will be returned, but nag_tsa_inhom_ma (g13mgc) will continue as if t was strictly increasing by using the absolute value. The lagged difference, $t_i - t_{i-1}$ must be sufficiently small that $e^{-\alpha}$, $\alpha = (t_i - t_{i-1})/\tilde{\tau}$ can be calculated without overflowing, for all i.

4:     **tau** – double   *Input*

   On entry: τ, the parameter controlling the rate of decay. τ must be sufficiently large that $e^{-\alpha}$, $\alpha = (t_i - t_{i-1})/\tilde{\tau}$ can be calculated without overflowing, for all i, where $\tilde{\tau} = \frac{2\tau}{m_2 + m_1}$.

   Constraint: **tau** > 0.0.

5:     **m1** – Integer   *Input*

   On entry: m_1, the iteration of the EMA operator at which the sum is started.

   Constraint: **m1** ≥ 1.

6:     **m2** – Integer   *Input*

   On entry: m_2, the iteration of the EMA operator at which the sum is ended.

   Constraint: **m2** $\geq$ **m1**.

7:     **sinit**[*dim*] – const double   *Input*

   Note: the dimension, *dim*, of the array **sinit** must be at least

   > $2 \times$ **m2** + 3 when **ftype** = Nag_AbsDiff or Nag_AbsDiffScaled;
   > **m2** + 2 when **ftype** = Nag_Identity, Nag_AbsVal or Nag_AbsValScaled;
   > **sinit** may be **NULL** when **pn** $\neq 0$.

   On entry: if **pn** = 0, the values used to start the iterative process, with

   > **sinit**[0] = t_0,
   >
   > **sinit**[1] = y_0,
   >
   > **sinit**[$j + 1$] = EMA[$\tau, j; y$](t_0), for $i = 1, 2, \ldots,$ **m2**.

   In addition, if **ftype** = Nag_AbsDiff or Nag_AbsDiffScaled then

   > **sinit**[**m2** + 2] = z_0,
   >
   > **sinit**[**m2** + j + 1] = EMA[$\tau, j; z$](t_0), for $j = 1, 2, \ldots,$ **m2**.

   i.e., initial values based on the original data z as opposed to the transformed data y.

   If **pn** $\neq 0$, **sinit** is not referenced and may be **NULL**.

   Constraint: if **ftype** $\neq$ Nag_Identity, **sinit**[$j - 1$] ≥ 0, for $j = 2, 3, \ldots,$ **m2** + 2.

8:     **inter**[**2**] – const Nag_TS_Interpolation   *Input*

   On entry: the type of interpolation used with **inter**[0] indicating the interpolation method to use when calculating EMA[$\tau, 1; z$] and **inter**[1] the interpolation method to use when calculating EMA[$\tau, j; z$], $j > 1$.

   Three types of interpolation are possible:

   inter[i] = Nag_PreviousPoint
   > Previous point, with $\nu = 1$.

   inter[i] = Nag_Linear
   > Linear, with $\nu = (1 - \mu)/\alpha$.

inter$[i]$ = Nag_NextPoint
> Next point, $\nu = \mu$.

Zumbach and Müller (2001) recommend that linear interpolation is used in second and subsequent iterations, i.e., **inter**$[1]$ = Nag_Linear, irrespective of the interpolation method used at the first iteration, i.e., the value of **inter**$[0]$.

Constraint: **inter**$[i - 1]$ = Nag_PreviousPoint, Nag_Linear or Nag_NextPoint, for $i = 1, 2$.

9:    **ftype** – Nag_TS_Transform   *Input*

On entry: the function type used to define the relationship between y and z when calculating $EMA[\tau, 1; y]$. Three functions are provided:

ftype = Nag_Identity
> The identity function, with $y_i = z_i^{[p]}$.

ftype = Nag_AbsVal or Nag_AbsValScaled
> The absolute value, with $y_i = |z_i|^p$.

ftype = Nag_AbsDiff or Nag_AbsDiffScaled
> The absolute difference, with $y_i = |z_i - MA[\tau, m; y](t_i)|^p$.

If **ftype** = Nag_AbsValScaled or Nag_AbsDiffScaled then the resulting vector of averages is scaled by p^{-1} as described in **ma**.

Constraint: **ftype** = Nag_Identity, Nag_AbsVal, Nag_AbsDiff, Nag_AbsValScaled or Nag_AbsDiffScaled.

10:   **p** – double *   *Input/Output*

On entry: p, the power used in the transformation function.

On exit: if **ftype** = Nag_Identity, then $[p]$, the actual power used in the transformation function is returned, otherwise **p** is unchanged.

Constraint: **p** $\neq 0$.

11:   **pn** – Integer *   *Input/Output*

On entry: k, the number of observations processed so far. On the first call to nag_tsa_inhom_ma (g13mgc), or when starting to summarise a new dataset, **pn** must be set to 0. On subsequent calls it must be the same value as returned by the last call to nag_tsa_inhom_ma (g13mgc).

On exit: $k + b$, the updated number of observations processed so far.

Constraint: **pn** ≥ 0.

12:   **wma**$[$**nb**$]$ – double   *Output*

On exit: either the moving average or exponential moving average, depending on the value of **ftype**.

if **ftype** = Nag_AbsDiff or Nag_AbsDiffScaled
> **wma**$[i - 1]$ = $MA[\tau; y](t_i)$

otherwise
> **wma**$[i - 1]$ = $EMA[\tilde{\tau}; y](t_i)$.

13:   **rcomm**$[$**2** $\times$ **m2** $+$ **20**$]$ – double   *Communication Array*

On entry: communication array, used to store information between calls to nag_tsa_inhom_ma (g13mgc). If **rcomm** is **NULL** then **pn** must be set to zero and all the data must be supplied in one go.

14:    **fail** – NagError *   *Input/Output*

   The NAG error argument (see Section 3.6 in the Essential Introduction).

6   Error Indicators and Warnings

NE_ALLOC_FAIL

   Dynamic memory allocation failed.

NE_BAD_PARAM

   On entry, argument $\langle value \rangle$ had an illegal value.

NE_ILLEGAL_COMM

   rcomm has been corrupted between calls.

NE_INT

   On entry, $\mathbf{m1} = \langle value \rangle$.
   Constraint: $\mathbf{m1} \geq 1$.

   On entry, $\mathbf{nb} = \langle value \rangle$.
   Constraint: $\mathbf{nb} \geq 0$.

   On entry, $\mathbf{pn} = \langle value \rangle$.
   Constraint: $\mathbf{pn} \geq 0$.

NE_INT_2

   On entry, $\mathbf{m1} = \langle value \rangle$ and $\mathbf{m2} = \langle value \rangle$.
   Constraint: $\mathbf{m2} \geq \mathbf{m1}$.

NE_INTERNAL_ERROR

   An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

NE_NOT_STRICTLY_INCREASING

   On entry, $i = \langle value \rangle$, $\mathbf{t}[i-2] = \langle value \rangle$ and $\mathbf{t}[i-1] = \langle value \rangle$.
   Constraint: **t** should be strictly increasing.

NE_PREV_CALL

   If $\mathbf{pn} > 0$ then **ftype** must be unchanged since previous call.

   If $\mathbf{pn} > 0$ then **inter** must be unchanged since previous call.

   On entry, $\mathbf{m1} = \langle value \rangle$.
   On entry at previous call, $\mathbf{m1} = \langle value \rangle$.
   Constraint: if $\mathbf{pn} > 0$ then $\mathbf{m1}$ must be unchanged since previous call.

   On entry, $\mathbf{m2} = \langle value \rangle$.
   On entry at previous call, $\mathbf{m2} = \langle value \rangle$.
   Constraint: if $\mathbf{pn} > 0$ then $\mathbf{m2}$ must be unchanged since previous call.

   On entry, $\mathbf{p} = \langle value \rangle$.
   On exit from previous call, $\mathbf{p} = \langle value \rangle$.
   Constraint: if $\mathbf{pn} > 0$ then $\mathbf{p}$ must be unchanged since previous call.

   On entry, $\mathbf{pn} = \langle value \rangle$.
   On exit from previous call, $\mathbf{pn} = \langle value \rangle$.
   Constraint: if $\mathbf{pn} > 0$ then $\mathbf{pn}$ must be unchanged since previous call.

On entry, **tau** = ⟨*value*⟩.
On entry at previous call, **tau** = ⟨*value*⟩.
Constraint: if **pn** > 0 then **tau** must be unchanged since previous call.

NE_REAL

On entry, i = ⟨*value*⟩, **ma**$[i-1]$ = ⟨*value*⟩ and **p** = ⟨*value*⟩.
Constraint: if **ftype** = Nag_Identity, Nag_AbsVal or Nag_AbsValScaled and **ma**$[i-1]$ = 0 for any i then **p** > 0.0.

On entry, i = ⟨*value*⟩, **ma**$[i-1]$ = ⟨*value*⟩, **wma**$[i-1]$ = ⟨*value*⟩ and **p** = ⟨*value*⟩.
Constraint: if **p** < 0.0, **ma**$[i-1]$ − **wma**$[i-1]$ ≠ 0.0, for any i.

On entry, **p** = ⟨*value*⟩.
Constraint: absolute value of **p** must be representable as an integer.

On entry, **p** = ⟨*value*⟩.
Constraint: if **ftype** ≠ Nag_Identity, **p** ≠ 0.0. If **ftype** = Nag_Identity, the nearest integer to **p** must not be 0.

On entry, **tau** = ⟨*value*⟩.
Constraint: **tau** > 0.0.

NE_REAL_ARRAY

On entry, **ftype** ≠ Nag_Identity, j = ⟨*value*⟩ and **sinit**$[j-1]$ = ⟨*value*⟩.
Constraint: if **ftype** ≠ Nag_Identity, **sinit**$[j-1]$ ≥ 0.0, for $j = 2, 3, \ldots, \mathbf{m2} + 2$.

On entry, i = ⟨*value*⟩, **t**$[i-2]$ = ⟨*value*⟩ and **t**$[i-1]$ = ⟨*value*⟩.
Constraint: **t**$[i-1]$ ≠ **t**$[i-2]$ if linear interpolation is being used.

NW_OVERFLOW_WARN

Truncation occurred to avoid overflow, check for extreme values in **t**, **ma** or for **tau**. Results are returned using the truncated values.

7 Accuracy

Not applicable.

8 Parallelism and Performance

nag_tsa_inhom_ma (g13mgc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_tsa_inhom_ma (g13mgc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

Approximately $4m_2$ real elements are internally allocated by nag_tsa_inhom_ma (g13mgc). If **ftype** = Nag_AbsDiff or Nag_AbsDiffScaled then a further **nb** real elements are also allocated.

The more data you supply to nag_tsa_inhom_ma (g13mgc) in one call, i.e., the larger **nb** is, the more efficient the function will be.

Checks are made during the calculation of α and y_i to avoid overflow. If a potential overflow is detected the offending value is replaced with a large positive or negative value, as appropriate, and the calculations performed based on the replacement values. In such cases **fail.code** =

NW_OVERFLOW_WARN is returned. This should not occur in standard usage and will only occur if extreme values of **ma**, **t** or **tau** are supplied.

10 Example

The example reads in a simulated time series, (t, z) and calculates the moving average. The data is supplied in three blocks of differing sizes.

10.1 Program Text

```
/* nag_tsa_inhom_ma (g13mgc) Example Program.
 *
 * Copyright 2011, Numerical Algorithms Group.
 *
 * Mark 23, 2011.
 */
/* Pre-processor includes */
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagg13.h>

int main(void)
{
  /* Integer scalar and array declarations */
  Integer i, m1, m2, nb, pn, ierr, lsinit;
  Integer exit_status = 0;

  /* NAG structures and types */
  NagError fail;
  Nag_TS_Interpolation inter[2];
  Nag_TS_Transform ftype;

  /* Double scalar and array declarations */
  double p, tau;
  double *ma = 0, *rcomm = 0, *sinit = 0, *t = 0, *wma = 0;

  /* Character scalar and array declarations */
  char cinter[40], cftype[40];

  /* Initialise the error structure */
  INIT_FAIL(fail);

  printf("nag_tsa_inhom_ma (g13mgc) Example Program Results\n\n");

  /* Skip heading in data file */
  scanf("%*[^\n] ");

  /* Read in the problem size */
  scanf("%ld%ld%*[^\n] ",&m1,&m2);

  /* Read in the transformation function and its parameter */
  scanf("%39s",cftype);
  ftype = (Nag_TS_Transform) nag_enum_name_to_value(cftype);
  scanf("%lf",&p);

  /* Read in the interpolation method to use */
  scanf("%39s",cinter);
  inter[0] = (Nag_TS_Interpolation) nag_enum_name_to_value(cinter);
  scanf("%39s",cinter);
  inter[1] = (Nag_TS_Interpolation) nag_enum_name_to_value(cinter);

  /* Read in the decay parameter */
  scanf("%lf%*[^\n] ", &tau);

  /* Read in the initial values */
  if (ftype == Nag_AbsDiff || ftype == Nag_AbsDiffScaled) {
    lsinit = 2 * m2 + 3;
```

```
  } else {
    lsinit = m2 + 2;
  }
  if (!(sinit = NAG_ALLOC(lsinit, double)))
    {
      printf("Allocation failure\n");
      exit_status = -1;
      goto END;
    }
  for (i = 0; i < lsinit; i++)
    {
      scanf("%lf", &sinit[i]);
    }
  scanf("%*[^\n] ");

  /* Print some titles */
  printf("                  Time            MA\n");
  printf(" -----------------------------\n");

  if (!(rcomm = NAG_ALLOC(2*m2 + 20, double)))
    {
      printf("Allocation failure\n");
      exit_status = -1;
      goto END;
    }

  for (pn = 0;;)
    {
      /* Read in the number of observations in this block */
      ierr = scanf("%"NAG_IFMT, &nb);
      if (ierr == EOF || ierr < 1) break;
      scanf("%*[^\n] ");

      /* Allocate MA, T and WMA to the required size */
      NAG_FREE(ma);
      NAG_FREE(t);
      NAG_FREE(wma);
      if (!(ma = NAG_ALLOC(nb, double)) ||
          !(t = NAG_ALLOC(nb,double)) ||
          !(wma = NAG_ALLOC(nb,double)))
        {
          printf("Allocation failure\n");
          exit_status = -1;
          goto END;
        }

      /* Read in the data for this block */
      for (i = 0; i < nb; i++)
        {
          scanf("%lf%lf", &t[i], &ma[i]);
        }
      scanf("%*[^\n] ");

      /* Call nag_tsa_inhom_ma (g13mgc) to update the moving average
         operator for this block of data. The routine overwrites the
         input data */
      nag_tsa_inhom_ma(nb,ma,t,tau,m1,m2,sinit,inter,ftype,&p,&pn,wma,rcomm,
                       &fail);
      if (fail.code != NE_NOERROR)
        {
          printf("Error from nag_tsa_inhom_ma (g13mgc).\n%s\n",
                 fail.message);
          exit_status = -1;
          goto END;
        }

      /* Display the results for this block of data */
      for (i = 0; i < nb; i++)
        {
          printf(" %3ld    %10.1f    %10.3f\n", pn-nb+i+1,t[i],ma[i]);
        }
```

```
        printf("\n");
    }

 END:
  NAG_FREE(ma);
  NAG_FREE(wma);
  NAG_FREE(t);
  NAG_FREE(sinit);
  NAG_FREE(rcomm);

  return(exit_status);
}
```

10.2 Program Data

```
nag_tsa_inhom_ma (g13mgc) Example Program Data
1 2                                          :: m1,m2
Nag_Identity 1.0 Nag_NextPoint Nag_Linear 2.0 :: ftype,p,inter[0:1],tau
0.0 0.0 0.0 0.0                              :: sinit

5                                            :: nb
 7.5  0.6
 8.2  0.6
18.1  0.8
22.8  0.1
25.8  0.2                                    :: End of t, z 1st block

10                                           :: nb
26.8  0.2
31.1  0.5
38.4  0.7
45.9  0.1
48.2  0.4
48.9  0.7
57.9  0.8
58.5  0.3
63.9  0.2
65.2  0.5                                    :: End of t, z 2nd block

15                                           :: nb
66.6  0.2
67.4  0.3
69.3  0.8
69.9  0.6
73.0  0.1
75.6  0.7
77.0  0.9
84.7  0.6
86.8  0.3
88.0  0.1
88.5  0.1
91.0  0.4
93.0  1.0
93.7  1.0
94.0  0.1                                    :: End of t, z 3rd block
```

10.3 Program Results

```
nag_tsa_inhom_ma (g13mgc) Example Program Results

            Time          MA
  ------------------------------
    1        7.5        0.545
    2        8.2        0.567
    3       18.1        0.786
    4       22.8        0.214
    5       25.8        0.187

    6       26.8        0.192
    7       31.1        0.444
    8       38.4        0.680
    9       45.9        0.155
   10       48.2        0.298
   11       48.9        0.406
   12       57.9        0.777
   13       58.5        0.677
   14       63.9        0.258
   15       65.2        0.351

   16       66.6        0.291
   17       67.4        0.289
   18       69.3        0.572
   19       69.9        0.593
   20       73.0        0.244
   21       75.6        0.532
   22       77.0        0.715
   23       84.7        0.618
   24       86.8        0.426
   25       88.0        0.284
   26       88.5        0.240
   27       91.0        0.332
   28       93.0        0.723
   29       93.7        0.814
   30       94.0        0.744
```