

## NAG Library Function Document

### nag\_ztgexc (f08ytc)

## 1 Purpose

nag\_ztgexc (f08ytc) reorders the generalized Schur factorization of a complex matrix pair in generalized Schur form.

## 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_ztgexc (Nag_OrderType order, Nag_Boolean wantq, Nag_Boolean wantz,
                 Integer n, Complex a[], Integer pda, Complex b[], Integer pdb,
                 Complex q[], Integer pdq, Complex z[], Integer pdz, Integer ifst,
                 Integer *ilst, NagError *fail)
```

## 3 Description

nag\_ztgexc (f08ytc) reorders the generalized complex  $n$  by  $n$  matrix pair  $(S, T)$  in generalized Schur form, so that the diagonal element of  $(S, T)$  with row index  $i_1$  is moved to row  $i_2$ , using a unitary equivalence transformation. That is,  $S$  and  $T$  are factorized as

$$S = \hat{Q}\hat{S}\hat{Z}^H, \quad T = \hat{Q}\hat{T}\hat{Z}^H,$$

where  $(\hat{S}, \hat{T})$  are also in generalized Schur form.

The pair  $(S, T)$  are in generalized Schur form if  $S$  and  $T$  are upper triangular as returned, for example, by nag\_zgges (f08xnc), or nag\_zhgeqz (f08xsc) with **job** = Nag\_Schur.

If  $S$  and  $T$  are the result of a generalized Schur factorization of a matrix pair  $(A, B)$

$$A = QSZ^H, \quad B = QTZ^H$$

then, optionally, the matrices  $Q$  and  $Z$  can be updated as  $Q\hat{Q}$  and  $Z\hat{Z}$ .

## 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

## 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **wantq** – Nag\_Boolean *Input*

*On entry:* if **wantq** = Nag\_TRUE, update the left transformation matrix  $Q$ .

If **wantq** = Nag\_FALSE, do not update  $Q$ .

3:	<b>wantz</b> – Nag Boolean	<i>Input</i>
<i>On entry:</i> if <b>wantz</b> = Nag_TRUE, update the right transformation matrix $Z$ . If <b>wantz</b> = Nag_FALSE, do not update $Z$ .		
4:	<b>n</b> – Integer	<i>Input</i>
<i>On entry:</i> $n$ , the order of the matrices $S$ and $T$ . <i>Constraint:</i> $n \geq 0$ .		
5:	<b>a</b> [ <i>dim</i> ] – Complex	<i>Input/Output</i>
<b>Note:</b> the dimension, $dim$ , of the array <b>a</b> must be at least $\max(1, \mathbf{pda} \times n)$ . The $(i, j)$ th element of the matrix $A$ is stored in $\begin{aligned} \mathbf{a}[(j-1) \times \mathbf{pda} + i - 1] &\text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ \mathbf{a}[(i-1) \times \mathbf{pda} + j - 1] &\text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$ <i>On entry:</i> the matrix $S$ in the pair $(S, T)$ . <i>On exit:</i> the updated matrix $\hat{S}$ .		
6:	<b>pda</b> – Integer	<i>Input</i>
<i>On entry:</i> the stride separating row or column elements (depending on the value of <b>order</b> ) in the array <b>a</b> . <i>Constraint:</i> $\mathbf{pda} \geq \max(1, n)$ .		
7:	<b>b</b> [ <i>dim</i> ] – Complex	<i>Input/Output</i>
<b>Note:</b> the dimension, $dim$ , of the array <b>b</b> must be at least $\max(1, \mathbf{pdb} \times n)$ . The $(i, j)$ th element of the matrix $B$ is stored in $\begin{aligned} \mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1] &\text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ \mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1] &\text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$ <i>On entry:</i> the matrix $T$ , in the pair $(S, T)$ . <i>On exit:</i> the updated matrix $\hat{T}$		
8:	<b>pdb</b> – Integer	<i>Input</i>
<i>On entry:</i> the stride separating row or column elements (depending on the value of <b>order</b> ) in the array <b>b</b> . <i>Constraint:</i> $\mathbf{pdb} \geq \max(1, n)$ .		
9:	<b>q</b> [ <i>dim</i> ] – Complex	<i>Input/Output</i>
<b>Note:</b> the dimension, $dim$ , of the array <b>q</b> must be at least $\begin{aligned} \max(1, \mathbf{pdq} \times n) &\text{ when } \mathbf{wantq} = \text{Nag\_TRUE}; \\ 1 &\text{ otherwise.} \end{aligned}$ >The $(i, j)$ th element of the matrix $Q$ is stored in $\begin{aligned} \mathbf{q}[(j-1) \times \mathbf{pdq} + i - 1] &\text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ \mathbf{q}[(i-1) \times \mathbf{pdq} + j - 1] &\text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$ <i>On entry:</i> if <b>wantq</b> = Nag_TRUE, the unitary matrix $Q$ . <i>On exit:</i> if <b>wantq</b> = Nag_TRUE, the updated matrix $Q\hat{Q}$ . >If <b>wantq</b> = Nag_FALSE, <b>q</b> is not referenced.		

10: **pdq** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **q**.

*Constraints:*

if **wantq** = Nag\_TRUE, **pdq**  $\geq \max(1, n)$ ;  
 otherwise **pdq**  $\geq 1$ .

11: **z[dim]** – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **z** must be at least

$\max(1, \text{pdz} \times n)$  when **wantz** = Nag\_TRUE;  
 1 otherwise.

The  $(i, j)$ th element of the matrix  $Z$  is stored in

**z** $[(j - 1) \times \text{pdz} + i - 1]$  when **order** = Nag\_ColMajor;  
**z** $[(i - 1) \times \text{pdz} + j - 1]$  when **order** = Nag\_RowMajor.

*On entry:* if **wantz** = Nag\_TRUE, the unitary matrix  $Z$ .

*On exit:* if **wantz** = Nag\_TRUE, the updated matrix  $Z\hat{Z}$ .

If **wantz** = Nag\_FALSE, **z** is not referenced.

12: **pdz** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **z**.

*Constraints:*

if **wantz** = Nag\_TRUE, **pdz**  $\geq \max(1, n)$ ;  
 otherwise **pdz**  $\geq 1$ .

13: **ifst** – Integer *Input*

14: **ilst** – Integer \* *Input/Output*

*On entry:* the indices  $i_1$  and  $i_2$  that specify the reordering of the diagonal elements of  $(S, T)$ . The element with row index **ifst** is moved to row **ilst**, by a sequence of swapping between adjacent diagonal elements.

*On exit:* **ilst** points to the row in its final position.

*Constraint:*  $1 \leq \text{ifst} \leq n$  and  $1 \leq \text{ilst} \leq n$ .

15: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

On entry, argument  $\langle\text{value}\rangle$  had an illegal value.

**NE\_CONSTRAINT**

On entry, **wantq** =  $\langle\text{value}\rangle$ , **pdq** =  $\langle\text{value}\rangle$  and **n** =  $\langle\text{value}\rangle$ .  
 Constraint: if **wantq** = Nag\_TRUE, **pdq**  $\geq \max(1, \mathbf{n})$ ;  
 otherwise **pdq**  $\geq 1$ .

On entry, **wantz** =  $\langle\text{value}\rangle$ , **pdz** =  $\langle\text{value}\rangle$  and **n** =  $\langle\text{value}\rangle$ .  
 Constraint: if **wantz** = Nag\_TRUE, **pdz**  $\geq \max(1, \mathbf{n})$ ;  
 otherwise **pdz**  $\geq 1$ .

**NE\_INT**

On entry, **n** =  $\langle\text{value}\rangle$ .  
 Constraint: **n**  $\geq 0$ .

On entry, **pda** =  $\langle\text{value}\rangle$ .  
 Constraint: **pda**  $> 0$ .

On entry, **pdb** =  $\langle\text{value}\rangle$ .  
 Constraint: **pdb**  $> 0$ .

On entry, **pdq** =  $\langle\text{value}\rangle$ .  
 Constraint: **pdq**  $> 0$ .

On entry, **pdz** =  $\langle\text{value}\rangle$ .  
 Constraint: **pdz**  $> 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle\text{value}\rangle$  and **n** =  $\langle\text{value}\rangle$ .  
 Constraint: **pda**  $\geq \max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle\text{value}\rangle$  and **n** =  $\langle\text{value}\rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \mathbf{n})$ .

**NE\_INT\_3**

On entry, **ifst** =  $\langle\text{value}\rangle$ , **ilst** =  $\langle\text{value}\rangle$  and **n** =  $\langle\text{value}\rangle$ .  
 Constraint:  $1 \leq \mathbf{ifst} \leq \mathbf{n}$  and  $1 \leq \mathbf{ilst} \leq \mathbf{n}$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

**NE\_SCHUR**

The transformed matrix pair would be too far from generalized Schur form; the problem is ill-conditioned.  $(S, T)$  may have been partially reordered, and **ilst** points to the first row of the current position of the block being moved.

**7 Accuracy**

The computed generalized Schur form is nearly the exact generalized Schur form for nearby matrices  $(S + E)$  and  $(T + F)$ , where

$$\|E\|_2 = O\epsilon\|S\|_2 \quad \text{and} \quad \|F\|_2 = O\epsilon\|T\|_2,$$

and  $\epsilon$  is the **machine precision**. See Section 4.11 of Anderson *et al.* (1999) for further details of error bounds for the generalized nonsymmetric eigenproblem.

**8 Parallelism and Performance**

Not applicable.

## 9 Further Comments

The real analogue of this function is nag\_dtgexc (f08yfc).

## 10 Example

This example exchanges rows 4 and 1 of the matrix pair  $(S, T)$ , where

$$S = \begin{pmatrix} 4.0 + 4.0i & 1.0 + 1.0i & 1.0 + 1.0i & 2.0 - 1.0i \\ 0 & 2.0 + 1.0i & 1.0 + 1.0i & 1.0 + 1.0i \\ 0 & 0 & 2.0 - 1.0i & 1.0 + 1.0i \\ 0 & 0 & 0 & 6.0 - 2.0i \end{pmatrix}$$

and

$$T = \begin{pmatrix} 2.0 & 1.0 + 1.0i & 1.0 + 1.0i & 3.0 - 1.0i \\ 0 & 1.0 & 2.0 + 1.0i & 1.0 + 1.0i \\ 0 & 0 & 1.0 & 1.0 + 1.0i \\ 0 & 0 & 0 & 2.0 \end{pmatrix}.$$

### 10.1 Program Text

```
/* nag_ztgexc (f08ytc) Example Program.
*
* Copyright 2011 Numerical Algorithms Group.
*
* Mark 23, 2011.
*/
#include <stdio.h>
#include <nag.h>
#include <nagx04.h>
#include <nag_stdlib.h>
#include <nagf08.h>

int main(void)
{
    /* Scalars */
    Integer i, ifst, ilst, j, n, pdq, pds, pdt, pdz;
    Integer exit_status = 0;

    /* Arrays */
    Complex *q = 0, *s = 0, *t = 0, *z = 0;
    char nag_enum_arg[40];

    NagError fail;
    Nag_OrderType order;
    Nag_Boolean wantq, wantz;
    Nag_MatrixType upmat = Nag_UpperMatrix;
    Nag_DiagType diag = Nag_NonUnitDiag;
    Nag_LabelType intlab = Nag_IntegerLabels;
    Nag_ComplexFormType brac = Nag_BracketForm;

#define NAG_COLUMN_MAJOR
#define S(I, J) s[(J-1)*pds + I - 1]
#define T(I, J) t[(J-1)*pdt + I - 1]
    order = Nag_ColMajor;
#else
#define S(I, J) s[(I-1)*pds + J - 1]
#define T(I, J) t[(I-1)*pdt + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_ztgexc (f08ytc) Example Program Results\n\n");
    /* Skip heading in data file */
}
```

```

scanf("%*[^\n]");
scanf("%ld%*[^\n]", &n);
if (n < 0)
{
    printf("Invalid n\n");
    exit_status = 1;
    goto END;
}
scanf(" %39s%*[^\n]", nag_enum_arg);
/* nag_enum_name_to_value (x04nac).
 * Converts NAG enum member name to value
 */
wantq = (Nag_Boolean) nag_enum_name_to_value(nag_enum_arg);
scanf(" %39s%*[^\n]", nag_enum_arg);
wantz = (Nag_Boolean) nag_enum_name_to_value(nag_enum_arg);

pds = n;
pdt = n;
pdq = (wantq?n:1);
pdz = (wantz?n:1);

/* Allocate memory */
if (
    !(s = NAG_ALLOC(n*n, Complex)) ||
    !(t = NAG_ALLOC(n*n, Complex)) ||
    !(q = NAG_ALLOC(pdq*pdq, Complex)) ||
    !(z = NAG_ALLOC(pdz*pdz, Complex)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

/* Read S and T from data file */
for (i = 1; i <= n; ++i)
    for (j = 1; j <= n; ++j)
        scanf(" ( %lf , %lf )", &s(i, j).re, &s(i, j).im);
scanf("%*[^\n]");
for (i = 1; i <= n; ++i)
    for (j = 1; j <= n; ++j)
        scanf(" ( %lf , %lf )", &t(i, j).re, &t(i, j).im);
scanf("%*[^\n]");

/* Read the row indices */
scanf("%ld%ld%*[^\n]", &ifst, &ilst);

/* Reorder the S and T */
nag_ztgexc(order, wantq, wantz, n, s, pds, t, pdt, q, pdq, z, pdz, ifst,
            &ilst, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_ztgexc (f08ytc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print reordered generalized Schur form */
fflush(stdout);
nag_gen_complx_mat_print_comp(order, upmat, diag, n, n, s, pds, brac,
                               "%7.4f", "Reordered Schur matrix S",
                               intlab, NULL, intlab, NULL, 80, 0, NULL,
                               &fail);
if (fail.code != NE_NOERROR) goto PRERR;
printf("\n");
fflush(stdout);
nag_gen_complx_mat_print_comp(order, upmat, diag, n, n, t, pdt, brac,
                               "%7.4f", "Reordered Schur matrix T",
                               intlab, NULL, intlab, NULL, 80, 0, NULL,
                               &fail);
PRERR:
if (fail.code != NE_NOERROR)

```

```

{
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
           fail.message);
    exit_status = 1;
}

END:
NAG_FREE(q);
NAG_FREE(s);
NAG_FREE(t);
NAG_FREE(z);

return exit_status;
}

```

## 10.2 Program Data

nag\_ztgexc (f08ytc) Example Program Data

```

4 : n

Nag_FALSE : wantq
Nag_FALSE : wantz

( 4.0, 4.0) ( 1.0, 1.0) ( 1.0, 1.0) ( 2.0,-1.0)
( 0.0, 0.0) ( 2.0, 1.0) ( 1.0, 1.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 2.0,-1.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 0.0, 0.0) ( 6.0,-2.0) : matrix S

( 2.0, 0.0) ( 1.0, 1.0) ( 1.0, 1.0) ( 3.0,-1.0)
( 0.0, 0.0) ( 1.0, 0.0) ( 2.0, 1.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 1.0, 0.0) ( 1.0, 1.0)
( 0.0, 0.0) ( 0.0, 0.0) ( 0.0, 0.0) ( 2.0, 0.0) : matrix T

1        4 : ifst and ilst

```

## 10.3 Program Results

nag\_ztgexc (f08ytc) Example Program Results

```

Reordered Schur matrix S
      1          2          3          4
1  ( 3.7081, 3.7081) (-2.0834,-0.5688) ( 2.6374, 1.0772) ( 0.2845, 0.7991)
2                  ( 1.6097, 1.5656) (-0.0634, 1.9234) (-0.0301, 0.9720)
3                  ( 4.7029,-2.1187) ( 1.1379,-3.1199) ( 2.3085,-1.8289)
4

Reordered Schur matrix T
      1          2          3          4
1  ( 2.2249, 0.7416) (-1.1631, 1.5347) ( 2.2608, 2.0851) ( 1.1094,-0.3205)
2                  ( 0.3308, 0.9482) ( 0.3919, 1.8172) (-0.6305, 1.6053)
3                  ( 1.6227,-0.1653) ( 0.9966,-0.9074) ( 0.1199,-1.0343)
4

```

---