

NAG Library Function Document

nag_dsygst (f08sec)

1 Purpose

nag_dsygst (f08sec) reduces a real symmetric-definite generalized eigenproblem $Az = \lambda Bz$, $ABz = \lambda z$ or $BAz = \lambda z$ to the standard form $Cy = \lambda y$, where A is a real symmetric matrix and B has been factorized by nag_dpotrf (f07fdc).

2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_dsygst (Nag_OrderType order, Nag_ComputeType comp_type,
                 Nag_UploType uplo, Integer n, double a[], Integer pda, const double b[],
                 Integer pdb, NagError *fail)
```

3 Description

To reduce the real symmetric-definite generalized eigenproblem $Az = \lambda Bz$, $ABz = \lambda z$ or $BAz = \lambda z$ to the standard form $Cy = \lambda y$, nag_dsygst (f08sec) must be preceded by a call to nag_dpotrf (f07fdc) which computes the Cholesky factorization of B ; B must be positive definite.

The different problem types are specified by the argument **comp_type**, as indicated in the table below. The table shows how C is computed by the function, and also how the eigenvectors z of the original problem can be recovered from the eigenvectors of the standard form.

			order = Nag_ColMajor			order = Nag_RowMajor		
comp_type	Problem	uplo	B	C	z	B	C	z
1	$Az = \lambda Bz$	Nag_Upper Nag_Lower	$U^T U$ LL^T	$U^{-T} A U^{-1}$ $L^{-1} A L^{-T}$	$U^{-1} y$ $L^{-T} y$	$U U^T$ $L^T L$	$U^{-1} A U^{-T}$ $L^{-T} A L^{-1}$	$U^{-T} y$ $L^{-1} y$
2	$ABz = \lambda z$	Nag_Upper Nag_Lower	$U^T U$ LL^T	$U A U^T$ $L^T A L$	$U^{-1} y$ $L^{-T} y$	$U U^T$ $L^T L$	$U^T A U$ $L A L^T$	$U^{-T} y$ $L^{-1} y$
3	$BAz = \lambda z$	Nag_Upper Nag_Lower	$U^T U$ LL^T	$U A U^T$ $L^T A L$	$U^T y$ $L y$	$U U^T$ $L^T L$	$U^T A U$ $L A L^T$	$U y$ $L^T y$

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by

order = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **comp_type** – Nag_ComputeType *Input*

On entry: indicates how the standard form is computed.

comp_type = Nag_Compute_1

if **uplo** = Nag_Upper, $C = U^{-T}AU^{-1}$ when **order** = Nag_ColMajor and $C = U^{-1}AU^{-T}$ when **order** = Nag_RowMajor;

if **uplo** = Nag_Lower, $C = L^{-1}AL^{-T}$ when **order** = Nag_ColMajor and $C = L^{-T}AL^{-1}$ when **order** = Nag_RowMajor.

comp_type = Nag_Compute_2 or Nag_Compute_3

if **uplo** = Nag_Upper, $C = UAU^T$ when **order** = Nag_ColMajor and $C = U^T AU$ when **order** = Nag_RowMajor;

if **uplo** = Nag_Lower, $C = L^T AL$ when **order** = Nag_ColMajor and $C = LAL^T$ when **order** = Nag_RowMajor.

Constraint: **comp_type** = Nag_Compute_1, Nag_Compute_2 or Nag_Compute_3.

3: **uplo** – Nag_UploType *Input*

On entry: indicates whether the upper or lower triangular part of A is stored and how B has been factorized.

uplo = Nag_Upper

The upper triangular part of A is stored and $B = U^T U$ when **order** = Nag_ColMajor and $B = U U^T$ when **order** = Nag_RowMajor.

uplo = Nag_Lower

The lower triangular part of A is stored and $B = L L^T$ when **order** = Nag_ColMajor and $B = L^T L$ when **order** = Nag_RowMajor.

Constraint: **uplo** = Nag_Upper or Nag_Lower.

4: **n** – Integer *Input*

On entry: n , the order of the matrices A and B .

Constraint: $n \geq 0$.

5: **a**[*dim*] – double *Input/Output*

Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.

On entry: the n by n symmetric matrix A .

If **order** = 'Nag_ColMajor', A_{ij} is stored in **a**[($j - 1$) \times **pda** + $i - 1$].

If **order** = 'Nag_RowMajor', A_{ij} is stored in **a**[($i - 1$) \times **pda** + $j - 1$].

If **uplo** = 'Nag_Upper', the upper triangular part of A must be stored and the elements of the array below the diagonal are not referenced.

If **uplo** = 'Nag_Lower', the lower triangular part of A must be stored and the elements of the array above the diagonal are not referenced.

On exit: the upper or lower triangle of **a** is overwritten by the corresponding upper or lower triangle of C as specified by **comp_type** and **uplo**.

- 6: **pda** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix A in the array **a**.
Constraint: **pda** \geq $\max(1, \mathbf{n})$.
- 7: **b**[*dim*] – const double *Input*
Note: the dimension, *dim*, of the array **b** must be at least $\max(1, \mathbf{pdb} \times \mathbf{n})$.
On entry: the Cholesky factor of B as specified by **uplo** and returned by nag_dpotr (f07fdc).
- 8: **pdb** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) of the matrix B in the array **b**.
Constraint: **pdb** \geq $\max(1, \mathbf{n})$.
- 9: **fail** – NagError * *Input/Output*
The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, **n** = $\langle value \rangle$.

Constraint: **n** \geq 0.

On entry, **pda** = $\langle value \rangle$.

Constraint: **pda** $>$ 0.

On entry, **pdb** = $\langle value \rangle$.

Constraint: **pdb** $>$ 0.

NE_INT_2

On entry, **pda** = $\langle value \rangle$ and **n** = $\langle value \rangle$.

Constraint: **pda** \geq $\max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$ and **n** = $\langle value \rangle$.

Constraint: **pdb** \geq $\max(1, \mathbf{n})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

7 Accuracy

Forming the reduced matrix C is a stable procedure. However it involves implicit multiplication by B^{-1} (if **comp_type** = Nag_Compute_1) or B (if **comp_type** = Nag_Compute_2 or Nag_Compute_3). When nag_dsygst (f08sec) is used as a step in the computation of eigenvalues and eigenvectors of the original problem, there may be a significant loss of accuracy if B is ill-conditioned with respect to inversion.

8 Parallelism and Performance

nag_dsygst (f08sec) is not threaded by NAG in any implementation.

nag_dsygst (f08sec) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The total number of floating-point operations is approximately n^3 .

The complex analogue of this function is nag_zhegst (f08ssc).

10 Example

This example computes all the eigenvalues of $Az = \lambda Bz$, where

$$A = \begin{pmatrix} 0.24 & 0.39 & 0.42 & -0.16 \\ 0.39 & -0.11 & 0.79 & 0.63 \\ 0.42 & 0.79 & -0.25 & 0.48 \\ -0.16 & 0.63 & 0.48 & -0.03 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 4.16 & -3.12 & 0.56 & -0.10 \\ -3.12 & 5.03 & -0.83 & 1.09 \\ 0.56 & -0.83 & 0.76 & 0.34 \\ -0.10 & 1.09 & 0.34 & 1.18 \end{pmatrix}.$$

Here B is symmetric positive definite and must first be factorized by nag_dpotrf (f07fdc). The program calls nag_dsygst (f08sec) to reduce the problem to the standard form $Cy = \lambda y$; then nag_dsytrd (f08fec) to reduce C to tridiagonal form, and nag_dsterf (f08jfc) to compute the eigenvalues.

10.1 Program Text

```

/* nag_dsygst (f08sec) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagf08.h>

int main(void)
{
    /* Scalars */
    Integer      i, j, n, pda, pdb, d_len, e_len, tau_len;
    Integer      exit_status = 0;
    NagError     fail;
    Nag_UploType uplo;
    Nag_OrderType order;
    /* Arrays */
    char         nag_enum_arg[40];
    double       *a = 0, *b = 0, *d = 0, *e = 0, *tau = 0;

#ifdef NAG_COLUMN_MAJOR
#define A(I, J) a[(J-1)*pda + I - 1]
#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I, J) a[(I-1)*pda + J - 1]
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif
    #endif

```

```

INIT_FAIL(fail);

printf("nag_dsygst (f08sec) Example Program Results\n\n");

/* Skip heading in data file */
scanf("%*[\n] ");
scanf("%ld%[\n] ", &n);
#ifdef NAG_COLUMN_MAJOR
    pda = n;
    pdb = n;
#else
    pda = n;
    pdb = n;
#endif
d_len = n;
e_len = n-1;
tau_len = n-1;

/* Allocate memory */
if (!(a = NAG_ALLOC(n * n, double)) ||
    !(b = NAG_ALLOC(n * n, double)) ||
    !(d = NAG_ALLOC(d_len, double)) ||
    !(e = NAG_ALLOC(e_len, double)) ||
    !(tau = NAG_ALLOC(tau_len, double)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}
/* Read A and B from data file */
scanf("%39s%[\n] ", nag_enum_arg);
/* nag_enum_name_to_value (x04nac).
 * Converts NAG enum member name to value
 */
uplo = (Nag_UploType) nag_enum_name_to_value(nag_enum_arg);
if (uplo == Nag_Upper)
{
    for (i = 1; i <= n; ++i)
    {
        for (j = i; j <= n; ++j)
            scanf("%lf", &A(i, j));
    }
    scanf("%*[\n] ");
    for (i = 1; i <= n; ++i)
    {
        for (j = i; j <= n; ++j)
            scanf("%lf", &B(i, j));
    }
    scanf("%*[\n] ");
}
else
{
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
            scanf("%lf", &A(i, j));
    }
    scanf("%*[\n] ");
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
            scanf("%lf", &B(i, j));
    }
    scanf("%*[\n] ");
}

/* Compute the Cholesky factorization of B */
/* nag_dpotrf (f07fdc).
 * Cholesky factorization of real symmetric
 * positive-definite matrix
 */

```

```

nag_dpotrf(order, uplo, n, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dpotrf (f07fdc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Reduce the problem to standard form C*y = lambda*y, storing */
/* the result in A */
/* nag_dsygst (f08sec).
 * Reduction to standard form of real symmetric-definite
 * generalized eigenproblem Ax = lambda Bx, ABx = lambda x
 * or BAx = lambda x, B factorized by nag_dpotrf (f07fdc)
 */
nag_dsygst(order, Nag_Compute_1, uplo, n, a, pda, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dsygst (f08sec).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Reduce C to tridiagonal form T = (Q**T)*C*Q */
/* nag_dsytrd (f08fec).
 * Orthogonal reduction of real symmetric matrix to
 * symmetric tridiagonal form
 */
nag_dsytrd(order, uplo, n, a, pda, d, e, tau, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dsytrd (f08fec).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Calculate the eigenvalues of T (same as C) */
/* nag_dsterf (f08jfc).
 * All eigenvalues of real symmetric tridiagonal matrix,
 * root-free variant of QL or QR
 */
nag_dsterf(n, d, e, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dsterf (f08jfc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
/* Print eigenvalues */
printf("Eigenvalues\n");
for (i = 1; i <= n; ++i)
    printf("%8.4f%s", d[i-1], i%9 == 0?"\n":" ");
printf("\n");
END:
NAG_FREE(a);
NAG_FREE(b);
NAG_FREE(d);
NAG_FREE(e);
NAG_FREE(tau);

return exit_status;
}

```

10.2 Program Data

```
nag_dsygst (f08sec) Example Program Data
  4                               :Value of n
  Nag_Lower                       :Value of uplo
  0.24
  0.39 -0.11
  0.42  0.79 -0.25
-0.16  0.63  0.48 -0.03   :End of matrix A
  4.16
-3.12  5.03
  0.56 -0.83  0.76
-0.10  1.09  0.34  1.18   :End of matrix B
```

10.3 Program Results

```
nag_dsygst (f08sec) Example Program Results
```

```
Eigenvalues
-2.2254 -0.4548  0.1001  1.1270
```
