

NAG Library Function Document

nag_dorcsd (f08rac)

1 Purpose

nag_dorcsd (f08rac) computes the CS decomposition of a real m by m orthogonal matrix X , partitioned into a 2 by 2 array of submatrices.

2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_dorcsd (Nag_OrderType order, Nag_ComputeUType jobu1,
  Nag_ComputeUType jobu2, Nag_ComputeVType jobv1t,
  Nag_ComputeVType jobv2t, Nag_SignsType signs, Integer m, Integer p,
  Integer q, double x11[], Integer pdx11, double x12[], Integer pdx12,
  double x21[], Integer pdx21, double x22[], Integer pdx22,
  double theta[], double u1[], Integer pdu1, double u2[], Integer pdu2,
  double v1t[], Integer pdv1t, double v2t[], Integer pdv2t,
  NagError *fail)
```

3 Description

The m by m orthogonal matrix X is partitioned as

$$X = \begin{pmatrix} X_{11} & X_{12} \\ X_{21} & X_{22} \end{pmatrix}$$

where X_{11} is a p by q submatrix and the dimensions of the other submatrices X_{12} , X_{21} and X_{22} are such that X remains m by m .

The CS decomposition of X is $X = U\Sigma_p V^T$ where U , V and Σ_p are m by m matrices, such that

$$U = \begin{pmatrix} U_1 & \mathbf{0} \\ \mathbf{0} & U_2 \end{pmatrix}$$

is an orthogonal matrix containing the p by p orthogonal matrix U_1 and the $(m-p)$ by $(m-p)$ orthogonal matrix U_2 ;

$$V = \begin{pmatrix} V_1 & \mathbf{0} \\ \mathbf{0} & V_2 \end{pmatrix}$$

is an orthogonal matrix containing the q by q orthogonal matrix V_1 and the $(m-q)$ by $(m-q)$ orthogonal matrix V_2 ; and

$$\Sigma_p = \left(\begin{array}{cc|cc} I_{11} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ & C & \mathbf{0} & -S \\ \hline \mathbf{0} & \mathbf{0} & \mathbf{0} & -I_{12} \\ \hline & \mathbf{0} & \mathbf{0} & I_{22} \\ \hline \mathbf{0} & S & & C \\ \hline \mathbf{0} & & I_{21} & \mathbf{0} \end{array} \right)$$

contains the r by r non-negative diagonal submatrices C and S satisfying $C^2 + S^2 = I$, where $r = \min(p, m-p, q, m-q)$ and the top left partition is p by q .

The identity matrix I_{11} is of order $\min(p, q) - r$ and vanishes if $\min(p, q) = r$.

The identity matrix I_{12} is of order $\min(p, m-q) - r$ and vanishes if $\min(p, m-q) = r$.

The identity matrix I_{21} is of order $\min(m-p, q) - r$ and vanishes if $\min(m-p, q) = r$.

The identity matrix I_{22} is of order $\min(m-p, m-q) - r$ and vanishes if $\min(m-p, m-q) = r$.

In each of the four cases $r = p, q, m-p, m-q$ at least two of the identity matrices vanish.

The indicated zeros represent augmentations by additional rows or columns (but not both) to the square diagonal matrices formed by I_{ij} and C or S .

Σ_p does not need to be stored in full; it is sufficient to return only the values θ_i for $i = 1, 2, \dots, r$ where $C_{ii} = \cos(\theta_i)$ and $S_{ii} = \sin(\theta_i)$.

The algorithm used to perform the complete CS decomposition is described fully in Sutton (2009) including discussions of the stability and accuracy of the algorithm.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (2012) *Matrix Computations* (4th Edition) Johns Hopkins University Press, Baltimore

Sutton B D (2009) Computing the complete CS decomposition *Numerical Algorithms (Volume 50)* **1017–1398** Springer US 33–65 <http://dx.doi.org/10.1007/s11075-008-9215-6>

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **jobu1** – Nag_ComputeUType *Input*

On entry:

if **jobu1** = Nag_AllU, U_1 is computed;

if **jobu1** = Nag_NotU, U_1 is not computed.

Constraint: **jobu1** = Nag_AllU or Nag_NotU.

3: **jobu2** – Nag_ComputeUType *Input*

On entry:

if **jobu2** = Nag_AllU, U_2 is computed;

if **jobu2** = Nag_NotU, U_2 is not computed.

Constraint: **jobu2** = Nag_AllU or Nag_NotU.

4: **jobv1t** – Nag_ComputeVTType *Input*

On entry:

if **jobv1t** = Nag_AllVT, V_1^T is computed;

if **jobv1t** = Nag_NotVT, V_1^T is not computed.

Constraint: **jobv1t** = Nag_AllVT or Nag_NotVT.

- 5: **jobv2t** – Nag_ComputeVTType *Input*
On entry:
 if **jobv2t** = Nag_AllVT, V_2^T is computed;
 if **jobv2t** = Nag_NotVT, V_2^T is not computed.
Constraint: **jobv2t** = Nag_AllVT or Nag_NotVT.
- 6: **signs** – Nag_SignsType *Input*
On entry:
 if **signs** = Nag_LowerMinus, the lower-left block is made nonpositive (the other convention);
 if **signs** = Nag_UpperMinus, the upper-right block is made nonpositive (the default convention).
Constraint: **signs** = Nag_LowerMinus or Nag_UpperMinus.
- 7: **m** – Integer *Input*
On entry: m , the number of rows and columns in the orthogonal matrix X .
Constraint: $m \geq 0$.
- 8: **p** – Integer *Input*
On entry: p , the number of rows in X_{11} and X_{12} .
Constraint: $0 \leq p \leq m$.
- 9: **q** – Integer *Input*
On entry: q , the number of columns in X_{11} and X_{21} .
Constraint: $0 \leq q \leq m$.
- 10: **x11**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **x11** must be at least
 $\max(1, \mathbf{pdx11} \times \mathbf{p})$ when **order** = Nag_RowMajor;
 $\max(1, \mathbf{pdx11} \times \mathbf{q})$ when **order** = Nag_ColMajor.
 The (i, j)th element of the matrix is stored in
 $\mathbf{x11}[(j-1) \times \mathbf{pdx11} + i - 1]$ when **order** = Nag_ColMajor;
 $\mathbf{x11}[(i-1) \times \mathbf{pdx11} + j - 1]$ when **order** = Nag_RowMajor.
On entry: the upper left partition of the orthogonal matrix X whose CSD is desired.
On exit: contains details of the orthogonal matrix used in a simultaneous bidiagonalization process.
- 11: **pdx11** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) in the array **x11**.
Constraints:
 if **order** = Nag_RowMajor, $\mathbf{pdx11} \geq \max(1, \mathbf{q})$;
 if **order** = Nag_ColMajor, $\mathbf{pdx11} \geq \max(1, \mathbf{p})$.

- 12: **x12**[*dim*] – double *Input/Output*
- Note:** the dimension, *dim*, of the array **x12** must be at least
- $$\begin{aligned} & \max(1, \mathbf{pdx12} \times \mathbf{p}) \text{ when } \mathbf{order} = \text{Nag_RowMajor}; \\ & \max(1, \mathbf{pdx12} \times (\mathbf{m} - \mathbf{q})) \text{ when } \mathbf{order} = \text{Nag_ColMajor}. \end{aligned}$$
- The (*i*, *j*)th element of the matrix is stored in
- $$\begin{aligned} & \mathbf{x12}[(j - 1) \times \mathbf{pdx12} + i - 1] \text{ when } \mathbf{order} = \text{Nag_ColMajor}; \\ & \mathbf{x12}[(i - 1) \times \mathbf{pdx12} + j - 1] \text{ when } \mathbf{order} = \text{Nag_RowMajor}. \end{aligned}$$
- On entry:* the upper right partition of the orthogonal matrix *X* whose CSD is desired.
- On exit:* contains details of the orthogonal matrix used in a simultaneous bidiagonalization process.
- 13: **pdx12** – Integer *Input*
- On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **x12**.
- Constraints:*
- $$\begin{aligned} & \text{if } \mathbf{order} = \text{Nag_RowMajor}, \mathbf{pdx12} \geq \max(1, \mathbf{m} - \mathbf{q}); \\ & \text{if } \mathbf{order} = \text{Nag_ColMajor}, \mathbf{pdx12} \geq \max(1, \mathbf{p}). \end{aligned}$$
- 14: **x21**[*dim*] – double *Input/Output*
- Note:** the dimension, *dim*, of the array **x21** must be at least
- $$\begin{aligned} & \max(1, \mathbf{pdx21} \times (\mathbf{m} - \mathbf{p})) \text{ when } \mathbf{order} = \text{Nag_RowMajor}; \\ & \max(1, \mathbf{pdx21} \times \mathbf{q}) \text{ when } \mathbf{order} = \text{Nag_ColMajor}. \end{aligned}$$
- The (*i*, *j*)th element of the matrix is stored in
- $$\begin{aligned} & \mathbf{x21}[(j - 1) \times \mathbf{pdx21} + i - 1] \text{ when } \mathbf{order} = \text{Nag_ColMajor}; \\ & \mathbf{x21}[(i - 1) \times \mathbf{pdx21} + j - 1] \text{ when } \mathbf{order} = \text{Nag_RowMajor}. \end{aligned}$$
- On entry:* the lower left partition of the orthogonal matrix *X* whose CSD is desired.
- On exit:* contains details of the orthogonal matrix used in a simultaneous bidiagonalization process.
- 15: **pdx21** – Integer *Input*
- On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **x21**.
- Constraints:*
- $$\begin{aligned} & \text{if } \mathbf{order} = \text{Nag_RowMajor}, \mathbf{pdx21} \geq \max(1, \mathbf{q}); \\ & \text{if } \mathbf{order} = \text{Nag_ColMajor}, \mathbf{pdx21} \geq \max(1, \mathbf{m} - \mathbf{p}). \end{aligned}$$
- 16: **x22**[*dim*] – double *Input/Output*
- Note:** the dimension, *dim*, of the array **x22** must be at least
- $$\begin{aligned} & \max(1, \mathbf{pdx22} \times (\mathbf{m} - \mathbf{p})) \text{ when } \mathbf{order} = \text{Nag_RowMajor}; \\ & \max(1, \mathbf{pdx22} \times (\mathbf{m} - \mathbf{q})) \text{ when } \mathbf{order} = \text{Nag_ColMajor}. \end{aligned}$$
- The (*i*, *j*)th element of the matrix is stored in
- $$\begin{aligned} & \mathbf{x22}[(j - 1) \times \mathbf{pdx22} + i - 1] \text{ when } \mathbf{order} = \text{Nag_ColMajor}; \\ & \mathbf{x22}[(i - 1) \times \mathbf{pdx22} + j - 1] \text{ when } \mathbf{order} = \text{Nag_RowMajor}. \end{aligned}$$
- On entry:* the lower right partition of the orthogonal matrix *X* CSD is desired.
- On exit:* contains details of the orthogonal matrix used in a simultaneous bidiagonalization process.

- 17: **pdx22** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) in the array **x22**.
Constraints:
 if **order** = Nag_RowMajor, **pdx22** \geq $\max(1, \mathbf{m} - \mathbf{q})$;
 if **order** = Nag_ColMajor, **pdx22** \geq $\max(1, \mathbf{m} - \mathbf{p})$.
- 18: **theta**[*dim*] – double *Output*
Note: the dimension, *dim*, of the array **theta** must be at least $\min(\mathbf{p}, \mathbf{m} - \mathbf{p}, \mathbf{q}, \mathbf{m} - \mathbf{q})$.
On exit: the values θ_i for $i = 1, 2, \dots, r$ where $r = \min(p, m - p, q, m - q)$. The diagonal submatrices *C* and *S* of Σ_p are constructed from these values as

$$C = \text{diag}(\cos(\mathbf{theta}[0]), \dots, \cos(\mathbf{theta}[r - 1]))$$
 and

$$S = \text{diag}(\sin(\mathbf{theta}[0]), \dots, \sin(\mathbf{theta}[r - 1])).$$
- 19: **u1**[*dim*] – double *Output*
Note: the dimension, *dim*, of the array **u1** must be at least
 $\max(1, \mathbf{pdu1} \times \mathbf{p})$ when **jobu1** = Nag_AllU;
 otherwise **u1** may be **NULL**.
 The (*i*, *j*)th element of the matrix is stored in

$$\mathbf{u1}[(j - 1) \times \mathbf{pdu1} + i - 1]$$
 when **order** = Nag_ColMajor;

$$\mathbf{u1}[(i - 1) \times \mathbf{pdu1} + j - 1]$$
 when **order** = Nag_RowMajor.
On exit: if **jobu1** = Nag_AllU, **u1** contains the *p* by *p* orthogonal matrix U_1 .
- 20: **pdu1** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) in the array **u1**.
Constraint: if **jobu1** = Nag_AllU, **pdu1** \geq $\max(1, \mathbf{p})$
- 21: **u2**[*dim*] – double *Output*
Note: the dimension, *dim*, of the array **u2** must be at least
 $\max(1, \mathbf{pdu2} \times (\mathbf{m} - \mathbf{p}))$ when **jobu2** = Nag_AllU;
 otherwise **u2** may be **NULL**.
 The (*i*, *j*)th element of the matrix is stored in

$$\mathbf{u2}[(j - 1) \times \mathbf{pdu2} + i - 1]$$
 when **order** = Nag_ColMajor;

$$\mathbf{u2}[(i - 1) \times \mathbf{pdu2} + j - 1]$$
 when **order** = Nag_RowMajor.
On exit: if **jobu2** = Nag_AllU, **u2** contains the $m - p$ by $m - p$ orthogonal matrix U_2 .
- 22: **pdu2** – Integer *Input*
On entry: the stride separating row or column elements (depending on the value of **order**) in the array **u2**.
Constraint: if **jobu2** = Nag_AllU, **pdu2** \geq $\max(1, \mathbf{m} - \mathbf{p})$
- 23: **v1t**[*dim*] – double *Output*
Note: the dimension, *dim*, of the array **v1t** must be at least
 $\max(1, \mathbf{pdv1t} \times \mathbf{q})$ when **jobv1t** = Nag_AllVT;
 otherwise **v1t** may be **NULL**.

The (i, j) th element of the matrix is stored in

$$\begin{aligned} & \mathbf{v1t}[(j-1) \times \mathbf{pdv1t} + i - 1] \text{ when } \mathbf{order} = \text{Nag_ColMajor}; \\ & \mathbf{v1t}[(i-1) \times \mathbf{pdv1t} + j - 1] \text{ when } \mathbf{order} = \text{Nag_RowMajor}. \end{aligned}$$

On exit: if $\mathbf{jobv1t} = \text{Nag_AllVT}$, $\mathbf{v1t}$ contains the q by q orthogonal matrix V_1^T .

24: **pdv1t** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **v1t**.

Constraint: if $\mathbf{jobv1t} = \text{Nag_AllVT}$, $\mathbf{pdv1t} \geq \max(1, \mathbf{q})$

25: **v2t** $[\mathit{dim}]$ – double *Output*

Note: the dimension, dim , of the array **v2t** must be at least

$$\begin{aligned} & \max(1, \mathbf{pdv2t} \times (\mathbf{m} - \mathbf{q})) \text{ when } \mathbf{jobv2t} = \text{Nag_AllVT}; \\ & \text{otherwise } \mathbf{v2t} \text{ may be NULL.} \end{aligned}$$

The (i, j) th element of the matrix is stored in

$$\begin{aligned} & \mathbf{v2t}[(j-1) \times \mathbf{pdv2t} + i - 1] \text{ when } \mathbf{order} = \text{Nag_ColMajor}; \\ & \mathbf{v2t}[(i-1) \times \mathbf{pdv2t} + j - 1] \text{ when } \mathbf{order} = \text{Nag_RowMajor}. \end{aligned}$$

On exit: if $\mathbf{jobv2t} = \text{Nag_AllVT}$, **v2t** contains the $m - q$ by $m - q$ orthogonal matrix V_2^T .

26: **pdv2t** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **v2t**.

Constraint: if $\mathbf{jobv2t} = \text{Nag_AllVT}$, $\mathbf{pdv2t} \geq \max(1, \mathbf{m} - \mathbf{q})$

27: **fail** – NagError * *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_BAD_PARAM

On entry, argument $\langle \mathit{value} \rangle$ had an illegal value.

NE_CONVERGENCE

The Jacobi-type procedure failed to converge during an internal reduction to bidiagonal-block form. The process requires convergence to $\min(\mathbf{p}, \mathbf{m} - \mathbf{p}, \mathbf{q}, \mathbf{m} - \mathbf{q})$ values, the value of **fail.errnum** gives the number of converged values.

NE_ENUM_INT_2

On entry, $\mathbf{jobu1} = \langle \mathit{value} \rangle$, $\mathbf{pdu1} = \langle \mathit{value} \rangle$ and $\mathbf{p} = \langle \mathit{value} \rangle$.

Constraint: if $\mathbf{jobu1} = \text{Nag_AllU}$, $\mathbf{pdu1} \geq \max(1, \mathbf{p})$.

On entry, $\mathbf{jobv1t} = \langle \mathit{value} \rangle$, $\mathbf{pdv1t} = \langle \mathit{value} \rangle$ and $\mathbf{q} = \langle \mathit{value} \rangle$.

Constraint: if $\mathbf{jobv1t} = \text{Nag_AllVT}$, $\mathbf{pdv1t} \geq \max(1, \mathbf{q})$.

NE_ENUM_INT_3

On entry, **jobu2** = *⟨value⟩*, **pdu2** = *⟨value⟩*, **m** = *⟨value⟩* and **p** = *⟨value⟩*.
 Constraint: if **jobu2** = Nag_AllU, **pdu2** ≥ max(1, **m** – **p**).

On entry, **jobv2t** = *⟨value⟩*, **pdv2t** = *⟨value⟩*, **m** = *⟨value⟩* and **q** = *⟨value⟩*.
 Constraint: if **jobv2t** = Nag_AllVT, **pdv2t** ≥ max(1, **m** – **q**).

On entry, **pdx11** = *⟨value⟩*, **p** = *⟨value⟩*, **q** = *⟨value⟩* and **order** = *⟨value⟩*.
 Constraint: if **order** = Nag_RowMajor, **pdx11** ≥ max(1, **q**);
 if **order** = Nag_ColMajor, **pdx11** ≥ max(1, **p**).

NE_ENUM_INT_4

On entry, **pdx12** = *⟨value⟩*, **m** = *⟨value⟩*, **p** = *⟨value⟩*, **q** = *⟨value⟩* and **order** = *⟨value⟩*.
 Constraint: if **order** = Nag_RowMajor, **pdx12** ≥ max(1, **m** – **q**);
 if **order** = Nag_ColMajor, **pdx12** ≥ max(1, **p**).

On entry, **pdx21** = *⟨value⟩*, **m** = *⟨value⟩*, **p** = *⟨value⟩*, **q** = *⟨value⟩* and **order** = *⟨value⟩*.
 Constraint: if **order** = Nag_RowMajor, **pdx21** ≥ max(1, **q**);
 if **order** = Nag_ColMajor, **pdx21** ≥ max(1, **m** – **p**).

On entry, **pdx22** = *⟨value⟩*, **m** = *⟨value⟩*, **p** = *⟨value⟩*, **q** = *⟨value⟩* and **order** = *⟨value⟩*.
 Constraint: if **order** = Nag_RowMajor, **pdx22** ≥ max(1, **m** – **q**);
 if **order** = Nag_ColMajor, **pdx22** ≥ max(1, **m** – **p**).

NE_INT

On entry, **m** = *⟨value⟩*.
 Constraint: **m** ≥ 0.

NE_INT_2

On entry, **m** = *⟨value⟩* and **p** = *⟨value⟩*.
 Constraint: 0 ≤ **p** ≤ **m**.

On entry, **m** = *⟨value⟩* and **q** = *⟨value⟩*.
 Constraint: 0 ≤ **q** ≤ **m**.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

7 Accuracy

The computed *CS* decomposition is nearly the exact *CS* decomposition for the nearby matrix ($X + E$), where

$$\|E\|_2 = O(\epsilon),$$

and ϵ is the *machine precision*.

8 Parallelism and Performance

nag_dorcsd (f08rac) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_dorcsd (f08rac) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The total number of floating-point operations required to perform the full *CS* decomposition is approximately $2m^3$.

The complex analogue of this function is nag_zuncsd (f08rnc).

10 Example

This example finds the full CS decomposition of

$$X = \begin{pmatrix} -0.13484 & 0.52524 & -0.20924 & 0.81373 \\ 0.67420 & -0.52213 & -0.38886 & 0.34874 \\ 0.26968 & 0.52757 & -0.65782 & -0.46499 \\ 0.67420 & 0.41615 & 0.61014 & 0.00000 \end{pmatrix}$$

partitioned in 2 by 2 blocks.

The decomposition is performed both on submatrices of the orthogonal matrix *X* and on separated partition matrices. Code is also provided to perform a recombining check if required.

10.1 Program Text

```

/* nag_dorcsd (f08rac) Example Program.
 *
 * Copyright 2013, Numerical Algorithms Group.
 *
 * Mark 24, 2013.
 */

#include <stdio.h>
#include <math.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagf16.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    Integer    exit_status = 0;
    Integer    pdx, pdu, pdv, pdx11, pdx12, pdx21, pdx22, pdu1, pdu2, pdv1t;
    Integer    pdv2t, pdw;
    Integer    i, j, m, p, q, n11, n12, n21, n22, r;
    Integer    recombine = 1, reprint = 0;
    double     alpha, beta;
    /* Arrays */
    double     *theta = 0, *u = 0, *u1 = 0, *u2 = 0, *v = 0, *v1t = 0, *w = 0,
               *v2t = 0, *x = 0, *x11 = 0, *x12 = 0, *x21 = 0, *x22 = 0;
    /* Nag Types */
    Nag_OrderType order;
    NagError      fail;

#ifdef NAG_COLUMN_MAJOR
#define X(I,J) x[(J-1)*pdx + I-1]
#define U(I,J) u[(J-1)*pdu + I-1]
#define V(I,J) v[(J-1)*pdv + I-1]
#define W(I,J) w[(J-1)*pdw + I-1]
#define X11(I,J) x11[(J-1)*pdx11 + I-1]
#define X12(I,J) x12[(J-1)*pdx12 + I-1]
#define X21(I,J) x21[(J-1)*pdx21 + I-1]
#define X22(I,J) x22[(J-1)*pdx22 + I-1]
    order = Nag_ColMajor;
#else
#define X(I,J) x[(I-1)*pdx + J-1]
#define U(I,J) u[(I-1)*pdu + J-1]
#define V(I,J) v[(I-1)*pdv + J-1]

```



```

#define W(I,J) w[(I-1)*pdw + J-1]
#define X11(I,J) x11[(I-1)*pdx11 + J-1]
#define X12(I,J) x12[(I-1)*pdx12 + J-1]
#define X21(I,J) x21[(I-1)*pdx21 + J-1]
#define X22(I,J) x22[(I-1)*pdx22 + J-1]
    order = Nag_RowMajor;
#endifif

    INIT_FAIL(fail);

    printf("nag_dorcsd (f08rac) Example Program Results\n\n");

    /* Skip heading in data file*/
    scanf("%*[\n] ");
    scanf("%ld%ld%ld%*[\n] ", &m, &p, &q);

    r = MIN(MIN(p,q),MIN(m-p,m-q));

    if (!(x = NAG_ALLOC(m*m, double))||
        !(u = NAG_ALLOC(m*m, double))||
        !(v = NAG_ALLOC(m*m, double))||
        !(w = NAG_ALLOC(m*m, double))||
        !(theta = NAG_ALLOC(r, double))||
        !(x11 = NAG_ALLOC(p*q, double))||
        !(x12 = NAG_ALLOC(p*(m-q), double))||
        !(x21 = NAG_ALLOC((m-p)*q, double))||
        !(x22 = NAG_ALLOC((m-p)*(m-q), double))||
        !(u1 = NAG_ALLOC(p*p, double))||
        !(u2 = NAG_ALLOC((m-p)*(m-p), double))||
        !(v1t = NAG_ALLOC(q*q, double))||
        !(v2t = NAG_ALLOC((m-q)*(m-q), double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    pdx   = m; pdu   = m;   pdv   = m;   pdw   = m;
    pdu1  = p; pdu2  = m-p; pdv1t = q;   pdv2t = m-q;
#ifdef NAG_COLUMN_MAJOR
    pdx11 = p; pdx12 = p;   pdx21 = m-p; pdx22 = m-p;
#else
    pdx11 = q; pdx12 = m-q; pdx21 = q;   pdx22 = m-q;
#endifif
    /* Read and print orthogonal X from data file
     * (as, say, generated by a generalized singular value decomposition).
     */
    for ( i=1; i<=m; i++)
        for (j=1;j<=m; j++)
            scanf("%lf", &X(i, j));
    /* nag_gen_real_mat_print (x04cac).
     */
    nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, m, m,
                           &X(1,1), pdx, " Orthogonal matrix X", 0, &fail);
    if (fail.code != NE_NOERROR) {
        printf("Error from nag_gen_real_mat_print (x04cac).\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    printf("\n");

    /* nag_dorcsd (f08rac).
     * Compute the complete CS factorization of X:
     * X11 is stored in X(1:p, 1:q), X12 is stored in X(1:p, q+1:m)
     * X21 is stored in X(p+1:m, 1:q), X22 is stored in X(p+1:m, q+1:m)
     * U1 is stored in U(1:p, 1:p), U2 is stored in U(p+1:m, p+1:m)
     * V1 is stored in V(1:q, 1:q), V2 is stored in V(q+1:m, q+1:m)
     */
    for (j=1;j<=p; j++) {
        for (i=1;i<=q; i++) X11(j, i) = X(j, i);
        for (i=1;i<=m-q; i++) X12(j, i) = X(j, i + q);
    }

```

```

for (j=1;j<=m-p; j++) {
  for (i=1;i<=q; i++)    X21(j, i) = X(j + p, i);
  for (i=1;i<=m-q; i++)  X22(j, i) = X(j + p, i + q);
}
for ( i=1; i<=m; i++)
  for (j=1;j<=m; j++) {
    U(i,j) = 0.0;
    V(i,j) = 0.0;
  }

/* This is how you might pass partitions as sub-matrices */
nag_dorcsd(order, Nag_AllU, Nag_AllU, Nag_AllVT, Nag_AllVT, Nag_UpperMinus,
  m, p, q, &X(1,1), pdx, &X(1,q+1), pdx, &X(p+1,1), pdx, &X(p+1,q+1),
  pdx, theta, &U(1,1), pdu, &U(p+1,p+1), pdu, &V(1,1), pdv,
  &V(q+1,q+1), pdv, &fail);
if (fail.code != NE_NOERROR) {
  printf("Error from nag_dorcsd (f08rac).\n%s\n", fail.message);
  exit_status = 2;
  goto END;
}
/* Print Theta, U1, U2, V1T, V2T
 * using matrix printing routine nag_gen_real_mat_print (x04cac).
 */
printf("Components of CS factorization of X:\n");
nag_gen_real_mat_print(Nag_ColMajor, Nag_GeneralMatrix, Nag_NonUnitDiag,
  r, 1, theta, r, "  Theta", 0, &fail);
printf("\n");
nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
  p, p, &U(1,1), pdu, "  U1", 0, &fail);
printf("\n");
nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
  m-p, m-p, &U(p+1,p+1), pdu, "  U2", 0, &fail);
printf("\n");
nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
  q, q, &V(1,1), pdv, "  V1T", 0, &fail);
printf("\n");
nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
  m-q,m-q, &V(q+1,q+1), pdv, "  V2T", 0, &fail);
printf("\n");

/* And this is how you might pass partitions as separate matrices. */
nag_dorcsd(order, Nag_AllU, Nag_AllU, Nag_AllVT, Nag_AllVT, Nag_UpperMinus,
  m, p, q,
  x11, pdx11, x12, pdx12, x21, pdx21, x22, pdx22, theta,
  u1, pdu1, u2, pdu2, v1t, pdv1t, v2t, pdv2t, &fail);
if (fail.code != NE_NOERROR) {
  printf("Error second from nag_dorcsd (f08rac).\n%s\n", fail.message);
  exit_status = 3;
  goto END;
}
/* Print Theta, U1, U2, V1T, V2T
 * using matrix printing routine nag_gen_real_mat_print (x04cac).
 */
if (reprint != 0) {
  printf("Components of CS factorization of X:\n");
  nag_gen_real_mat_print(Nag_ColMajor, Nag_GeneralMatrix, Nag_NonUnitDiag,
    r, 1, theta, r, "  Theta", 0, &fail);
  nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
    p, p, u1, pdu1, "  U1", 0, &fail);
  nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
    m-p, m-p, u2, pdu2, "  U2", 0, &fail);
  nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
    q, q, v1t, pdv1t, "  V1T", 0, &fail);
  nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
    m-q, m-q, v2t, pdv2t, "  V2T", 0, &fail);
}
if ( recombine != 0) {
  /* Recombining should return the original matrix.
   Assemble Sigma_p into X
  */
}

```

```

    for ( i=1; i<=m; i++)
        for ( j=1; j<=m; j++)
X(i,j) = 0.0;
    n11 = MIN(p,q)-r;
    n12 = MIN(p,m-q)-r;
    n21 = MIN(m-p,q)-r;
    n22 = MIN(m-p,m-q)-r;

    /* top half */
    for ( j=1; j<=n11; j++) X(j,j) = 1.0;
    for ( j=1; j<=r; j++) {
        X(j+n11,j+n11) = cos(theta[j-1]);
        X(j+n11,j+n11+r+n21+n22) = -sin(theta[j-1]);
    }
    for ( j=1; j<=n12; j++) X(j+n11+r,j+n11+r+n21+n22+r) = -1.0;
    /* bottom half */
    for ( j=1; j<=n22; j++) X(p+j,q+j) = 1.0;
    for ( j=1; j<=r; j++) {
        X(p+n22+j,j+n11) = sin(theta[j-1]);
        X(p+n22+j,j+r+n21+n22) = cos(theta[j-1]);
    }
    for ( j=1; j<=n21; j++) X(p+n22+r+j,n11+r+j) = 1.0;

    alpha = 1.0;
    beta = 0.0;
    /* multiply U * Sigma_p into w */
    nag_dgemm(order, Nag_NoTrans, Nag_NoTrans, m, m, m, alpha,
        &U(1,1), pdu, &X(1,1), pdx, beta, &W(1,1), pdw, &fail);
    /* form U * Sigma_p * V^T into u */
    nag_dgemm(order, Nag_NoTrans, Nag_NoTrans, m, m, m, alpha,
        &W(1,1), pdw, &V(1,1), pdv, beta, &U(1,1), pdu, &fail);
    nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag,
m, m, &U(1,1), pdu, "    U * Sigma_p * V^T", 0, &fail);
}
END:
    NAG_FREE(x);
    NAG_FREE(u);
    NAG_FREE(v);
    NAG_FREE(w);
    NAG_FREE(theta);
    NAG_FREE(x11);
    NAG_FREE(x12);
    NAG_FREE(x21);
    NAG_FREE(x22);
    NAG_FREE(u1);
    NAG_FREE(u2);
    NAG_FREE(v1t);
    NAG_FREE(v2t);
    return exit_status;
}

```

10.2 Program Data

```

nag_dorcscd (f08rac) Example Program Data
  5      3      2      : m, p, q
-0.7576  0.3697  0.3838  0.2126 -0.3112
-0.4077 -0.1552 -0.1129  0.2676  0.8517
-0.0488  0.7240 -0.6730 -0.1301  0.0602
-0.2287  0.0088  0.2235 -0.9235  0.2120
  0.4530  0.5612  0.5806  0.1162  0.3595 : orthogonal matrix X

```

10.3 Program Results

nag_dorcscd (f08rac) Example Program Results

```

Orthogonal matrix X
      1      2      3      4      5
1 -0.7576  0.3697  0.3838  0.2126 -0.3112
2 -0.4077 -0.1552 -0.1129  0.2676  0.8517
3 -0.0488  0.7240 -0.6730 -0.1301  0.0602
4 -0.2287  0.0088  0.2235 -0.9235  0.2120
5  0.4530  0.5612  0.5806  0.1162  0.3595

Components of CS factorization of X:
Theta
      1
1  0.1811
2  0.8255

U1
      1      2      3
1 -0.8249 -0.3370 -0.4538
2 -0.2042 -0.5710  0.7952
3 -0.5271  0.7486  0.4022

U2
      1      2
1 -0.9802 -0.1982
2 -0.1982  0.9802

V1T
      1      2
1  0.7461 -0.6658
2  0.6658  0.7461

V2T
      1      2      3
1 -0.3397  0.8967 -0.2837
2  0.7738  0.4379  0.4576
3  0.5346 -0.0640 -0.8427

U * Sigma_p * V^T
      1      2      3      4      5
1 -0.7576  0.3697  0.3838  0.2126 -0.3112
2 -0.4077 -0.1551 -0.1129  0.2677  0.8517
3 -0.0488  0.7240 -0.6730 -0.1300  0.0602
4 -0.2287  0.0088  0.2235 -0.9234  0.2120
5  0.4530  0.5612  0.5806  0.1162  0.3595

```
