NAG Library Function Document

nag_zptsv (f07jnc)

1   Purpose

nag_zptsv (f07jnc) computes the solution to a complex system of linear equations

$$AX = B,$$

where A is an n by n Hermitian positive definite tridiagonal matrix, and X and B are n by r matrices.

2   Specification

```
#include <nag.h>
#include <nagf07.h>
```
```
void nag_zptsv (Nag_OrderType order, Integer n, Integer nrhs, double d[],
      Complex e[], Complex b[], Integer pdb, NagError *fail)
```

3   Description

nag_zptsv (f07jnc) factors A as $A = LDL^H$. The factored form of A is then used to solve the system of equations.

4   References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5   Arguments

1:    **order** – Nag_OrderType   *Input*

   On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

   Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2:    **n** – Integer   *Input*

   On entry: n, the order of the matrix A.

   Constraint: $\mathbf{n} \geq 0$.

3:    **nrhs** – Integer   *Input*

   On entry: r, the number of right-hand sides, i.e., the number of columns of the matrix B.

   Constraint: $\mathbf{nrhs} \geq 0$.

4:    **d**[*dim*] – double   *Input/Output*

   Note: the dimension, *dim*, of the array **d** must be at least $\max(1, \mathbf{n})$.

On entry: the n diagonal elements of the tridiagonal matrix A.

On exit: the n diagonal elements of the diagonal matrix D from the factorization $A = LDL^H$.

5:     **e**$[dim]$ – Complex   *Input/Output*

   Note: the dimension, *dim*, of the array **e** must be at least $\max(1, \mathbf{n} - 1)$.

   On entry: the $(n - 1)$ subdiagonal elements of the tridiagonal matrix A.

   On exit: the $(n - 1)$ subdiagonal elements of the unit bidiagonal factor L from the LDL^H factorization of A. (**e** can also be regarded as the superdiagonal of the unit bidiagonal factor U from the $U^H DU$ factorization of A.)

6:     **b**$[dim]$ – Complex   *Input/Output*

   Note: the dimension, *dim*, of the array **b** must be at least

   $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** $=$ Nag_ColMajor;
   $\max(1, \mathbf{n} \times \mathbf{pdb})$ when **order** $=$ Nag_RowMajor.

   The (i, j)th element of the matrix B is stored in

   $\mathbf{b}[(j - 1) \times \mathbf{pdb} + i - 1]$ when **order** $=$ Nag_ColMajor;
   $\mathbf{b}[(i - 1) \times \mathbf{pdb} + j - 1]$ when **order** $=$ Nag_RowMajor.

   On entry: the n by r right-hand side matrix B.

   On exit: if **fail.code** $=$ NE_NOERROR, the n by r solution matrix X.

7:     **pdb** – Integer   *Input*

   On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.

   Constraints:

   if **order** $=$ Nag_ColMajor, $\mathbf{pdb} \geq \max(1, \mathbf{n})$;
   if **order** $=$ Nag_RowMajor, $\mathbf{pdb} \geq \max(1, \mathbf{nrhs})$.

8:     **fail** – NagError *   *Input/Output*

   The NAG error argument (see Section 3.6 in the Essential Introduction).

6   Error Indicators and Warnings

NE_ALLOC_FAIL

   Dynamic memory allocation failed.

NE_BAD_PARAM

   On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

   On entry, $\mathbf{n} = \langle value \rangle$.
   Constraint: $\mathbf{n} \geq 0$.

   On entry, $\mathbf{nrhs} = \langle value \rangle$.
   Constraint: $\mathbf{nrhs} \geq 0$.

   On entry, $\mathbf{pdb} = \langle value \rangle$.
   Constraint: $\mathbf{pdb} > 0$.

NE_INT_2

> On entry, **pdb** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
> Constraint: **pdb** ≥ max(1, **n**).
>
> On entry, **pdb** = ⟨*value*⟩ and **nrhs** = ⟨*value*⟩.
> Constraint: **pdb** ≥ max(1, **nrhs**).

NE_INTERNAL_ERROR

> An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

NE_MAT_NOT_POS_DEF

> The leading minor of order ⟨*value*⟩ is not positive definite, and the solution has not been computed. The factorization has not been completed unless **n** = ⟨*value*⟩.

7 Accuracy

The computed solution for a single right-hand side, $\hat{x}$, satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and ϵ is the **machine precision**. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A)\frac{\|E\|_1}{\|A\|_1},$$

where $\kappa(A) = \left\|A^{-1}\right\|_1\|A\|_1$, the condition number of A with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

nag_zptsvx (f07jpc) is a comprehensive LAPACK driver that returns forward and backward error bounds and an estimate of the condition number. Alternatively, nag_herm_posdef_tridiag_lin_solve (f04cgc) solves $Ax = b$ and returns a forward error bound and condition estimate. nag_herm_posdef_tridiag_lin_solve (f04cgc) calls nag_zptsv (f07jnc) to solve the equations.

8 Parallelism and Performance

nag_zptsv (f07jnc) is not threaded by NAG in any implementation.

nag_zptsv (f07jnc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The number of floating-point operations required for the factorization of A is proportional to n, and the number of floating-point operations required for the solution of the equations is proportional to nr, where r is the number of right-hand sides.

The real analogue of this function is nag_dptsv (f07jac).

10   Example

This example solves the equations

$$Ax = b,$$

where A is the Hermitian positive definite tridiagonal matrix

$$A = \begin{pmatrix} 16.0 & 16.0 - 16.0i & 0 & 0 \\ 16.0 + 16.0i & 41.0 & 18.0 + 9.0i & 0 \\ 0 & 18.0 - 9.0i & 46.0 & 1.0 + 4.0i \\ 0 & 0 & 1.0 - 4.0i & 21.0 \end{pmatrix}$$

and

$$b = \begin{pmatrix} 64.0 + 16.0i \\ 93.0 + 62.0i \\ 78.0 - 80.0i \\ 14.0 - 27.0i \end{pmatrix}.$$

Details of the LDL^H factorization of A are also output.

10.1   Program Text

```c
/* nag_zptsv (f07jnc) Example Program.
 *
 * Copyright 2004 Numerical Algorithms Group.
 *
 * Mark 23, 2011.
 */
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>

int main(void)
{
  /* Scalars */
  Integer       exit_status = 0, i, j, n, nrhs, pdb;

  /* Arrays */
  Complex       *b = 0, *e = 0;
  double        *d = 0;

  /* Nag Types */
  NagError      fail;
  Nag_OrderType order;

#ifdef NAG_COLUMN_MAJOR
#define B(I, J) b[(J-1)*pdb + I - 1]
  order = Nag_ColMajor;
#else
#define B(I, J) b[(I-1)*pdb + J - 1]
  order = Nag_RowMajor;
#endif
  INIT_FAIL(fail);

  printf("nag_zptsv (f07jnc) Example Program Results\n\n");
  /* Skip heading in data file */
  scanf("%*[^\n]");
  scanf("%ld%ld%*[^\n]", &n, &nrhs);
  if (n < 0 || nrhs < 0)
    {
      printf("Invalid n or nrhs\n");
      exit_status = 1;
      goto END;
    }
  /* Allocate memory */
  if (!(b = NAG_ALLOC(n*nrhs, Complex)) ||
```

```
        !(e = NAG_ALLOC(n-1, Complex)) ||
        !(d = NAG_ALLOC(n, double)))
    {
      printf("Allocation failure\n");
      exit_status = -1;
      goto END;
    }

#ifdef NAG_COLUMN_MAJOR
      pdb = n;
#else
      pdb = nrhs;
#endif

  /* Read the lower bidiagonal part of the tridiagonal matrix A and */
  /* the right hand side b from data file */
  for (i = 0; i < n; ++i) scanf("%lf", &d[i]);
  scanf("%*[^\n]");
  for (i = 0; i < n - 1; ++i) scanf(" ( %lf , %lf )", &e[i].re, &e[i].im);
  scanf("%*[^\n]");

  for (i = 1; i <= n; ++i)
    for (j = 1; j <= nrhs; ++j)
      scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
  scanf("%*[^\n]");

  /* Solve the equations Ax = b for x using nag_zptsv (f07jnc). */
  nag_zptsv(order, n, nrhs, d, e, b, pdb, &fail);
  if (fail.code != NE_NOERROR)
    {
      printf("Error from nag_zptsv (f07jnc).\n%s\n", fail.message);
      exit_status = 1;
      goto END;
    }

  /* Print solution */
  printf("Solution\n");
  for (i = 1; i <= n; ++i)
    {
      for (j = 1; j <= nrhs; ++j)
        printf("(%8.4f, %8.4f)%s", B(i, j).re, B(i, j).im, j%4 == 0?"\n":" ");
      printf("\n");
    }

  /* Print details of factorization */
  printf("\nDiagonal elements of the diagonal matrix D\n");
  for (i = 0; i < n; ++i) printf("%7.4f%s", d[i], i%8 == 7?"\n":" ");

  printf("\n\nSub-diagonal elements of the Cholesky factor L\n");
  for (i = 0; i < n-1; ++i)
    printf("(%8.4f, %8.4f)%s", e[i].re, e[i].im, i%8 == 7?"\n":" ");

 END:
  NAG_FREE(b);
  NAG_FREE(e);
  NAG_FREE(d);

  return exit_status;
}
```

10.2 Program Data

```
nag_zptsv (f07jnc) Example Program Data
    4                 1                                        : n, nrhs
   16.0          41.0           46.0           21.0           : diagonal d
 ( 16.0, 16.0) ( 18.0, -9.0) (  1.0, -4.0)                    : sub-diagonal e
 ( 64.0, 16.0) ( 93.0, 62.0) ( 78.0,-80.0) ( 14.0,-27.0) : vector b
```

10.3 Program Results

```
nag_zptsv (f07jnc) Example Program Results

Solution
(  2.0000,   1.0000)
(  1.0000,   1.0000)
(  1.0000,  -2.0000)
(  1.0000,  -1.0000)

Diagonal elements of the diagonal matrix D
16.0000  9.0000  1.0000  4.0000

Sub-diagonal elements of the Cholesky factor L
(  1.0000,   1.0000) (  2.0000,  -1.0000) (  1.0000,  -4.0000)
```