

# NAG Library Function Document

## nag\_dgtsv (f07cac)

### 1 Purpose

nag\_dgtsv (f07cac) computes the solution to a real system of linear equations

$$AX = B,$$

where  $A$  is an  $n$  by  $n$  tridiagonal matrix and  $X$  and  $B$  are  $n$  by  $r$  matrices.

### 2 Specification

```
#include <nag.h>
#include <nagf07.h>
void nag_dgtsv (Nag_OrderType order, Integer n, Integer nrhs, double dl[],
               double d[], double du[], double b[], Integer pdb, NagError *fail)
```

### 3 Description

nag\_dgtsv (f07cac) uses Gaussian elimination with partial pivoting and row interchanges to solve the equations  $AX = B$ . The matrix  $A$  is factorized as  $A = PLU$ , where  $P$  is a permutation matrix,  $L$  is unit lower triangular with at most one nonzero subdiagonal element per column, and  $U$  is an upper triangular band matrix, with two superdiagonals.

Note that the equations  $A^T X = B$  may be solved by interchanging the order of the arguments **du** and **dl**.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

### 5 Arguments

- 1: **order** – Nag\_OrderType *Input*  
*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.  
*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.
- 2: **n** – Integer *Input*  
*On entry:*  $n$ , the number of linear equations, i.e., the order of the matrix  $A$ .  
*Constraint:*  $n \geq 0$ .
- 3: **nrhs** – Integer *Input*  
*On entry:*  $r$ , the number of right-hand sides, i.e., the number of columns of the matrix  $B$ .  
*Constraint:* **nrhs**  $\geq 0$ .
- 4: **dl**[*dim*] – double *Input/Output*  
**Note:** the dimension, *dim*, of the array **dl** must be at least  $\max(1, n - 1)$ .

*On entry:* must contain the  $(n - 1)$  subdiagonal elements of the matrix  $A$ .

*On exit:* if no constraints are violated, **dl** is overwritten by the  $(n - 2)$  elements of the second superdiagonal of the upper triangular matrix  $U$  from the  $LU$  factorization of  $A$ , in **dl**[0], **dl**[1], ..., **dl**[ $n - 3$ ].

5: **d**[*dim*] – double *Input/Output*

**Note:** the dimension, *dim*, of the array **d** must be at least  $\max(1, \mathbf{n})$ .

*On entry:* must contain the  $n$  diagonal elements of the matrix  $A$ .

*On exit:* if no constraints are violated, **d** is overwritten by the  $n$  diagonal elements of the upper triangular matrix  $U$  from the  $LU$  factorization of  $A$ .

6: **du**[*dim*] – double *Input/Output*

**Note:** the dimension, *dim*, of the array **du** must be at least  $\max(1, \mathbf{n} - 1)$ .

*On entry:* must contain the  $(n - 1)$  superdiagonal elements of the matrix  $A$ .

*On exit:* if no constraints are violated, **du** is overwritten by the  $(n - 1)$  elements of the first superdiagonal of  $U$ .

7: **b**[*dim*] – double *Input/Output*

**Note:** the dimension, *dim*, of the array **b** must be at least

$\max(1, \mathbf{pdb} \times \mathbf{nrhs})$  when **order** = Nag\_ColMajor;  
 $\max(1, \mathbf{n} \times \mathbf{pdb})$  when **order** = Nag\_RowMajor.

The  $(i, j)$ th element of the matrix  $B$  is stored in

**b**[ $(j - 1) \times \mathbf{pdb} + i - 1$ ] when **order** = Nag\_ColMajor;  
**b**[ $(i - 1) \times \mathbf{pdb} + j - 1$ ] when **order** = Nag\_RowMajor.

*On entry:* the  $n$  by  $r$  right-hand side matrix  $B$ .

*On exit:* if **fail.code** = NE\_NOERROR, the  $n$  by  $r$  solution matrix  $X$ .

8: **pdb** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.

*Constraints:*

if **order** = Nag\_ColMajor, **pdb**  $\geq \max(1, \mathbf{n})$ ;  
 if **order** = Nag\_RowMajor, **pdb**  $\geq \max(1, \mathbf{nrhs})$ .

9: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

**NE\_INT**

On entry, **n** =  $\langle value \rangle$ .  
 Constraint: **n**  $\geq 0$ .

On entry, **nrhs** =  $\langle value \rangle$ .  
 Constraint: **nrhs**  $\geq 0$ .

On entry, **pdb** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $> 0$ .

**NE\_INT\_2**

On entry, **pdb** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$  and **nrhs** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq \max(1, \mathbf{nrhs})$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

**NE\_SINGULAR**

$U(\langle value \rangle, \langle value \rangle)$  is exactly zero, and the solution has not been computed. The factorization has not been completed unless **n** =  $\langle value \rangle$ .

**7 Accuracy**

The computed solution for a single right-hand side,  $\hat{x}$ , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and  $\epsilon$  is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where  $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$ , the condition number of  $A$  with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

Alternatives to nag\_dgtsv (f07cac), which return condition and error estimates are nag\_real\_tridiag\_lin\_solve (f04bcc) and nag\_dgtsvx (f07cbc).

**8 Parallelism and Performance**

Not applicable.

**9 Further Comments**

The total number of floating-point operations required to solve the equations  $AX = B$  is proportional to  $nr$ .

The complex analogue of this function is nag\_zgtsv (f07cnc).

## 10 Example

This example solves the equations

$$Ax = b,$$

where  $A$  is the tridiagonal matrix

$$A = \begin{pmatrix} 3.0 & 2.1 & 0 & 0 & 0 \\ 3.4 & 2.3 & -1.0 & 0 & 0 \\ 0 & 3.6 & -5.0 & 1.9 & 0 \\ 0 & 0 & 7.0 & -0.9 & 8.0 \\ 0 & 0 & 0 & -6.0 & 7.1 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 2.7 \\ -0.5 \\ 2.6 \\ 0.6 \\ 2.7 \end{pmatrix}.$$

### 10.1 Program Text

```

/* nag_dgtsv (f07cac) Example Program.
 *
 * Copyright 2004 Numerical Algorithms Group.
 *
 * Mark 23, 2011
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>

int main(void)
{
    /* Scalars */
    Integer      exit_status = 0, i, j, n, nrhs, pdb;

    /* Arrays */
    double       *b = 0, *d = 0, *dl = 0, *du = 0;

    /* Nag Types */
    NagError      fail;
    Nag_OrderType order;

#ifdef NAG_COLUMN_MAJOR
#define B(I, J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define B(I, J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    INIT_FAIL(fail);

    printf("nag_dgtsv (f07cac) Example Program Results\n\n");
    /* Skip heading in data file */
    scanf("%*[\n]");
    scanf("%ld%ld%*[\n]", &n, &nrhs);
    if (n < 0 || nrhs < 0)
    {
        printf("Invalid n or nrhs\n");
        exit_status = 1;
        goto END;
    }
    /* Allocate memory */
    if (!(b = NAG_ALLOC(n*nrhs, double)) ||
        !(d = NAG_ALLOC(n, double)) ||
        !(dl = NAG_ALLOC(n-1, double)) ||
        !(du = NAG_ALLOC(n-1, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
    }

```

```

        goto END;
    }

#ifdef NAG_COLUMN_MAJOR
    pdb = n;
#else
    pdb = nrhs;
#endif

/* Read the tridiagonal matrix A and the right hand side B from data file */
for (i = 0; i < n - 1; ++i) scanf("%lf", &du[i]);
scanf("%*[\n]");
for (i = 0; i < n; ++i) scanf("%lf", &d[i]);
scanf("%*[\n]");
for (i = 0; i < n - 1; ++i) scanf("%lf", &dl[i]);
scanf("%*[\n]");

for (i = 1; i <= n; ++i)
    for (j = 1; j <= nrhs; ++j) scanf("%lf", &B(i, j));
scanf("%*[\n]");

/* Solve the equations Ax = b for x using nag_dgtsv (f07cac). */
nag_dgtsv(order, n, nrhs, dl, d, du, b, pdb, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_dgtsv (f07cac).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print solution */
printf("Solution\n");
for (i = 1; i <= n; ++i) {
    for (j = 1; j <= nrhs; ++j) printf("%11.4f%s", B(i, j), j%7 == 0?"\n":" ");
}
END:
NAG_FREE(b);
NAG_FREE(d);
NAG_FREE(dl);
NAG_FREE(du);
return exit_status;
}

```

## 10.2 Program Data

nag\_dgtsv (f07cac) Example Program Data

```

5      1      : n, nrhs
2.1  -1.0   1.9   8.0 : superdiag of A
3.0   2.3  -5.0  -0.9   7.1 : main diag of A
3.4   3.6   7.0  -6.0      : subdiag of A

2.7
-0.5
2.6
0.6
2.7      : vector b

```

### 10.3 Program Results

nag\_dgtsv (f07cac) Example Program Results

Solution  
-4.0000  
7.0000  
3.0000  
-4.0000  
-3.0000

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