NAG Library Function Document

nag_zgerfs (f07avc)

1 Purpose

nag_zgerfs (f07avc) returns error bounds for the solution of a complex system of linear equations with multiple right-hand sides, $AX = B$, $A^{\mathrm{T}}X = B$ or $A^{\mathrm{H}}X = B$. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Specification

```
#include <nag.h>
#include <nagf07.h>
void nag_zgerfs (Nag_OrderType order, Nag_TransType trans, Integer n,
     Integer nrhs, const Complex a[], Integer pda, const Complex af[],
     Integer pdaf, const Integer ipiv[], const Complex b[], Integer pdb,
     Complex x[], Integer pdx, double ferr[], double berr[], NagError *fail)
```

3 Description

nag_zgerfs (f07avc) returns the backward errors and estimated bounds on the forward errors for the solution of a complex system of linear equations with multiple right-hand sides $AX = B$, $A^{\mathrm{T}}X = B$ or $A^{\mathrm{H}}X = B$. The function handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of nag_zgerfs (f07avc) in terms of a single right-hand side b and solution x.

Given a computed solution x, the function computes the *component-wise backward error* β. This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$
$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where $\hat{x}$ is the true solution.

For details of the method, see the f07 Chapter Introduction.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **trans** – Nag_TransType *Input*

On entry: indicates the form of the linear equations for which X is the computed solution as follows:

trans = Nag_NoTrans
The linear equations are of the form $AX = B$.

trans = Nag_Trans
The linear equations are of the form $A^{\mathrm{T}}X = B$.

trans = Nag_ConjTrans
The linear equations are of the form $A^{\mathrm{H}}X = B$.

Constraint: **trans** = Nag_NoTrans, Nag_Trans or Nag_ConjTrans.

3: **n** – Integer *Input*

On entry: n, the order of the matrix A.

Constraint: $\mathbf{n} \geq 0$.

4: **nrhs** – Integer *Input*

On entry: r, the number of right-hand sides.

Constraint: $\mathbf{nrhs} \geq 0$.

5: **a**[dim] – const Complex *Input*

Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.

The (i, j)th element of the matrix A is stored in

a$[(j-1) \times \mathbf{pda} + i - 1]$ when **order** = Nag_ColMajor;
a$[(i-1) \times \mathbf{pda} + j - 1]$ when **order** = Nag_RowMajor.

On entry: the n by n original matrix A as supplied to nag_zgetrf (f07arc).

6: **pda** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **a**.

Constraint: $\mathbf{pda} \geq \max(1, \mathbf{n})$.

7: **af**[dim] – const Complex *Input*

Note: the dimension, *dim*, of the array **af** must be at least $\max(1, \mathbf{pdaf} \times \mathbf{n})$.

The (i, j)th element of the matrix is stored in

af$[(j-1) \times \mathbf{pdaf} + i - 1]$ when **order** = Nag_ColMajor;
af$[(i-1) \times \mathbf{pdaf} + j - 1]$ when **order** = Nag_RowMajor.

On entry: the LU factorization of A, as returned by nag_zgetrf (f07arc).

8: **pdaf** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **af**.

Constraint: $\mathbf{pdaf} \geq \max(1, \mathbf{n})$.

9: **ipiv**[dim] – const Integer *Input*

Note: the dimension, *dim*, of the array **ipiv** must be at least $\max(1, \mathbf{n})$.

On entry: the pivot indices, as returned by nag_zgetrf (f07arc).

10: **b**[dim] – const Complex *Input*

Note: the dimension, *dim*, of the array **b** must be at least

max(1, **pdb** × **nrhs**) when **order** = Nag_ColMajor;
max(1, **n** × **pdb**) when **order** = Nag_RowMajor.

The (i, j)th element of the matrix B is stored in

b[$(j-1) \times$ **pdb** $+ i - 1$] when **order** = Nag_ColMajor;
b[$(i-1) \times$ **pdb** $+ j - 1$] when **order** = Nag_RowMajor.

On entry: the n by r right-hand side matrix B.

11: **pdb** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.

Constraints:

if **order** = Nag_ColMajor, **pdb** $\geq$ max(1, **n**);
if **order** = Nag_RowMajor, **pdb** $\geq$ max(1, **nrhs**).

12: **x**[dim] – Complex *Input/Output*

Note: the dimension, *dim*, of the array **x** must be at least

max(1, **pdx** × **nrhs**) when **order** = Nag_ColMajor;
max(1, **n** × **pdx**) when **order** = Nag_RowMajor.

The (i, j)th element of the matrix X is stored in

x[$(j-1) \times$ **pdx** $+ i - 1$] when **order** = Nag_ColMajor;
x[$(i-1) \times$ **pdx** $+ j - 1$] when **order** = Nag_RowMajor.

On entry: the n by r solution matrix X, as returned by nag_zgetrs (f07asc).

On exit: the improved solution matrix X.

13: **pdx** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **x**.

Constraints:

if **order** = Nag_ColMajor, **pdx** $\geq$ max(1, **n**);
if **order** = Nag_RowMajor, **pdx** $\geq$ max(1, **nrhs**).

14: **ferr**[**nrhs**] – double *Output*

On exit: **ferr**[$j-1$] contains an estimated error bound for the jth solution vector, that is, the jth column of X, for $j = 1, 2, \ldots, r$.

15: **berr**[**nrhs**] – double *Output*

On exit: **berr**[$j-1$] contains the component-wise backward error bound β for the jth solution vector, that is, the jth column of X, for $j = 1, 2, \ldots, r$.

16: **fail** – NagError * *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_BAD_PARAM

On entry, argument ⟨*value*⟩ had an illegal value.

NE_INT

On entry, **n** = ⟨*value*⟩.
Constraint: **n** ≥ 0.

On entry, **nrhs** = ⟨*value*⟩.
Constraint: **nrhs** ≥ 0.

On entry, **pda** = ⟨*value*⟩.
Constraint: **pda** > 0.

On entry, **pdaf** = ⟨*value*⟩.
Constraint: **pdaf** > 0.

On entry, **pdb** = ⟨*value*⟩.
Constraint: **pdb** > 0.

On entry, **pdx** = ⟨*value*⟩.
Constraint: **pdx** > 0.

NE_INT_2

On entry, **pda** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pda** $\geq \max(1, \mathbf{n})$.

On entry, **pdaf** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pdaf** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = ⟨*value*⟩ and **nrhs** = ⟨*value*⟩.
Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

On entry, **pdx** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pdx** $\geq \max(1, \mathbf{n})$.

On entry, **pdx** = ⟨*value*⟩ and **nrhs** = ⟨*value*⟩.
Constraint: **pdx** $\geq \max(1, \mathbf{nrhs})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Parallelism and Performance

nag_zgerfs (f07avc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_zgerfs (f07avc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $16n^2$ real floating-point operations. Each step of iterative refinement involves an additional $24n^2$ real operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form $Ax = b$ or $A^{\mathrm{H}}x = b$; the number is usually 5 and never more than 11. Each solution involves approximately $8n^2$ real operations.

The real analogue of this function is nag_dgerfs (f07ahc).

10 Example

This example solves the system of equations $AX = B$ using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} -1.34 + 2.55i & 0.28 + 3.17i & -6.39 - 2.20i & 0.72 - 0.92i \\ -0.17 - 1.41i & 3.31 - 0.15i & -0.15 + 1.34i & 1.29 + 1.38i \\ -3.29 - 2.39i & -1.91 + 4.42i & -0.14 - 1.35i & 1.72 + 1.35i \\ 2.41 + 0.39i & -0.56 + 1.47i & -0.83 - 0.69i & -1.96 + 0.67i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 26.26 + 51.78i & 31.32 - 6.70i \\ 6.43 - 8.68i & 15.86 - 1.42i \\ -5.75 + 25.31i & -2.15 + 30.19i \\ 1.16 + 2.57i & -2.56 + 7.55i \end{pmatrix}.$$

Here A is nonsymmetric and must first be factorized by nag_zgetrf (f07arc).

10.1 Program Text

```
/* nag_zgerfs (f07avc) Example Program.
 *
 * Copyright 2001 Numerical Algorithms Group.
 *
 * Mark 7, 2001.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf07.h>
#include <nagx04.h>

int main(void)
{
  /* Scalars */
  Integer       berr_len, i, ferr_len, ipiv_len, j, n, nrhs;
  Integer       pda, pdaf, pdb, pdx;
  Integer       exit_status = 0;
  NagError      fail;
  Nag_OrderType order;
  /* Arrays */
  Complex       *a = 0, *af = 0, *b = 0, *x = 0;
  double        *berr = 0, *ferr = 0;
  Integer       *ipiv = 0;
```

```
#ifdef NAG_COLUMN_MAJOR
#define A(I, J)  a[(J-1)*pda + I - 1]
#define AF(I, J) af[(J-1)*pdaf + I - 1]
#define B(I, J)  b[(J-1)*pdb + I - 1]
#define X(I, J)  x[(J-1)*pdx + I - 1]
  order = Nag_ColMajor;
#else
#define A(I, J)  a[(I-1)*pda + J - 1]
#define AF(I, J) af[(I-1)*pdaf + J - 1]
#define B(I, J)  b[(I-1)*pdb + J - 1]
#define X(I, J)  x[(I-1)*pdx + J - 1]
  order = Nag_RowMajor;
#endif

  INIT_FAIL(fail);

  printf("nag_zgerfs (f07avc) Example Program Results\n\n");

  /* Skip heading in data file */
  scanf("%*[^\n] ");
  scanf("%ld%ld%*[^\n] ", &n, &nrhs);
#ifdef NAG_COLUMN_MAJOR
  pda = n;
  pdaf = n;
  pdb = n;
  pdx = n;
#else
  pda = n;
  pdaf = n;
  pdb = nrhs;
  pdx = nrhs;
#endif
  ipiv_len = n;
  ferr_len = n;
  berr_len = nrhs;

  /* Allocate memory */
  if (!(a = NAG_ALLOC(n * n, Complex)) ||
      !(af = NAG_ALLOC(n * n, Complex)) ||
      !(b = NAG_ALLOC(n * nrhs, Complex)) ||
      !(x = NAG_ALLOC(n * n, Complex)) ||
      !(berr = NAG_ALLOC(berr_len, double)) ||
      !(ferr = NAG_ALLOC(ferr_len, double)) ||
      !(ipiv = NAG_ALLOC(ipiv_len, Integer)))
    {
      printf("Allocation failure\n");
      exit_status = -1;
      goto END;
    }

  /* Read A and B from data file, and copy A to AF and B to X */
  for (i = 1; i <= n; ++i)
    {
      for (j = 1; j <= n; ++j)
        scanf(" ( %lf , %lf )", &A(i, j).re, &A(i, j).im);
    }
  scanf("%*[^\n] ");
  for (i = 1; i <= n; ++i)
    {
      for (j = 1; j <= nrhs; ++j)
        scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
    }
  scanf("%*[^\n] ");

  for (i = 1; i <= n; ++i)
    {
      for (j = 1; j <= n; ++j)
        {
          AF(i, j).re = A(i, j).re;
          AF(i, j).im = A(i, j).im;
        }
```

```
  }
for (i = 1; i <= n; ++i)
  {
    for (j = 1; j <= nrhs; ++j)
      {
        X(i, j).re = B(i, j).re;
        X(i, j).im = B(i, j).im;
      }
  }
/* Factorize A in the array AF */
/* nag_zgetrf (f07arc).
 * LU factorization of complex m by n matrix
 */
nag_zgetrf(order, n, n, af, pdaf, ipiv, &fail);
if (fail.code != NE_NOERROR)
  {
    printf("Error from nag_zgetrf (f07arc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
  }
/* Compute solution in the array X */
/* nag_zgetrs (f07asc).
 * Solution of complex system of linear equations, multiple
 * right-hand sides, matrix already factorized by nag_zgetrf
 * (f07arc)
 */
nag_zgetrs(order, Nag_NoTrans, n, nrhs, af, pdaf, ipiv, x, pdx, &fail);
if (fail.code != NE_NOERROR)
  {
    printf("Error from nag_zgetrs (f07asc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
  }
/* Improve solution, and compute backward errors and */
/* estimated bounds on the forward errors */
/* nag_zgerfs (f07avc).
 * Refined solution with error bounds of complex system of
 * linear equations, multiple right-hand sides
 */
nag_zgerfs(order, Nag_NoTrans, n, nrhs, a, pda, af, pdaf, ipiv, b, pdb, x,
           pdx, ferr, berr, &fail);
if (fail.code != NE_NOERROR)
  {
    printf("Error from nag_zgerfs (f07avc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
  }

/* Print solution */
/* nag_gen_complx_mat_print_comp (x04dbc).
 * Print complex general matrix (comprehensive)
 */
fflush(stdout);
nag_gen_complx_mat_print_comp(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                              nrhs, x, pdx, Nag_BracketForm, "%7.4f",
                              "Solution(s)", Nag_IntegerLabels,
                              0, Nag_IntegerLabels, 0, 80, 0, 0, &fail);
if (fail.code != NE_NOERROR)
  {
    printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
  }

printf("\nBackward errors (machine-dependent)\n");

for (j = 1; j <= nrhs; ++j)
  printf("%11.1e%s", berr[j-1], j%4 == 0?"\n":" ");
printf("\nEstimated forward error bounds (machine-dependent)\n");
for (j = 1; j <= nrhs; ++j)
```

```
    printf("%11.1e%s", ferr[j-1], j%4 == 0 || j == nrhs?"\n":" ");
 END:
  NAG_FREE(a);
  NAG_FREE(af);
  NAG_FREE(b);
  NAG_FREE(x);
  NAG_FREE(berr);
  NAG_FREE(ferr);
  NAG_FREE(ipiv);
  return exit_status;
}
```

10.2 Program Data

```
nag_zgerfs (f07avc) Example Program Data
  4  2                                                        :Values of N and NRHS
 (-1.34, 2.55) ( 0.28, 3.17) (-6.39,-2.20) ( 0.72,-0.92)
 (-0.17,-1.41) ( 3.31,-0.15) (-0.15, 1.34) ( 1.29, 1.38)
 (-3.29,-2.39) (-1.91, 4.42) (-0.14,-1.35) ( 1.72, 1.35)
 ( 2.41, 0.39) (-0.56, 1.47) (-0.83,-0.69) (-1.96, 0.67)  :End of matrix A
 (26.26, 51.78) (31.32, -6.70)
 ( 6.43, -8.68) (15.86, -1.42)
 (-5.75, 25.31) (-2.15, 30.19)
 ( 1.16,  2.57) (-2.56,  7.55)                            :End of matrix B
```

10.3 Program Results

```
nag_zgerfs (f07avc) Example Program Results

 Solution(s)
                     1                   2
 1  ( 1.0000, 1.0000)  (-1.0000,-2.0000)
 2  ( 2.0000,-3.0000)  ( 5.0000, 1.0000)
 3  (-4.0000,-5.0000)  (-3.0000, 4.0000)
 4  ( 0.0000, 6.0000)  ( 2.0000,-3.0000)

Backward errors (machine-dependent)
    4.1e-17     8.7e-17
Estimated forward error bounds (machine-dependent)
    5.8e-14     7.8e-14
```