

NAG Library Function Document

nag_zero_nonlin_eqns_expert (c05qcc)

1 Purpose

nag_zero_nonlin_eqns_expert (c05qcc) is a comprehensive function that finds a solution of a system of nonlinear equations by a modification of the Powell hybrid method.

2 Specification

```
#include <nag.h>
#include <nagc05.h>

void nag_zero_nonlin_eqns_expert (
    void (*fcn)(Integer n, const double x[], double fvec[], Nag_Comm *comm,
                Integer *iflag),
    Integer n, double x[], double fvec[], double xtol, Integer maxfev,
    Integer ml, Integer mu, double epsfcn, Nag_ScaleType scale_mode,
    double diag[], double factor, Integer nprint, Integer *nfev,
    double fjac[], double r[], double qtf[], Nag_Comm *comm, NagError *fail)
```

3 Description

The system of equations is defined as:

$$f_i(x_1, x_2, \dots, x_n) = 0, \quad i = 1, 2, \dots, n.$$

nag_zero_nonlin_eqns_expert (c05qcc) is based on the MINPACK routine HYBRD (see Moré *et al.* (1980)). It chooses the correction at each step as a convex combination of the Newton and scaled gradient directions. The Jacobian is updated by the rank-1 method of Broyden. At the starting point, the Jacobian is approximated by forward differences, but these are not used again until the rank-1 method fails to produce satisfactory progress. For more details see Powell (1970).

4 References

Moré J J, Garbow B S and Hillstom K E (1980) User guide for MINPACK-1 *Technical Report ANL-80-74* Argonne National Laboratory

Powell M J D (1970) A hybrid method for nonlinear algebraic equations *Numerical Methods for Nonlinear Algebraic Equations* (ed P Rabinowitz) Gordon and Breach

5 Arguments

- 1: **fcn** – function, supplied by the user *External Function*
fcn must return the values of the functions f_i at a point x , unless **iflag** = 0 on entry to nag_zero_nonlin_eqns_expert (c05qcc).

The specification of **fcn** is:

```
void fcn (Integer n, const double x[], double fvec[], Nag_Comm *comm,
         Integer *iflag)
```

1: **n** – Integer *Input*

On entry: n , the number of equations.

- | | | |
|----|---|--------------------------------|
| 2: | x[n] – const double | <i>Input</i> |
| | <i>On entry:</i> the components of the point x at which the functions must be evaluated. | |
| 3: | fvec[n] – double | <i>Input/Output</i> |
| | <i>On entry:</i> if iflag = 0, fvec contains the function values $f_i(x)$ and must not be changed. | |
| | <i>On exit:</i> if iflag > 0 on entry, fvec must contain the function values $f_i(x)$ (unless iflag is set to a negative value by fcn). | |
| 4: | comm – Nag_Comm * | <i>Communication Structure</i> |
| | Pointer to structure of type Nag_Comm; the following members are relevant to fcn . | |
| | user – double * | |
| | iuser – Integer * | |
| | p – Pointer | |
| | The type Pointer will be void *. Before calling nag_zero_nonlin_eqns_expert (c05qcc) you may allocate memory and initialize these pointers with various quantities for use by fcn when called from nag_zero_nonlin_eqns_expert (c05qcc) (see Section 3.2.1.1 in the Essential Introduction). | |
| 5: | iflag – Integer * | <i>Input/Output</i> |
| | <i>On entry:</i> iflag ≥ 0. | |
| | iflag = 0
x and fvec are available for printing (see nprint). | |
| | iflag > 0
fvec must be updated. | |
| | <i>On exit:</i> in general, iflag should not be reset by fcn . If, however, you wish to terminate execution (perhaps because some illegal point x has been reached), then iflag should be set to a negative integer. | |
-
- | | | |
|----|--|---------------------|
| 2: | n – Integer | <i>Input</i> |
| | <i>On entry:</i> n , the number of equations. | |
| | <i>Constraint:</i> n > 0. | |
| 3: | x[n] – double | <i>Input/Output</i> |
| | <i>On entry:</i> an initial guess at the solution vector. | |
| | <i>On exit:</i> the final estimate of the solution vector. | |
| 4: | fvec[n] – double | <i>Output</i> |
| | <i>On exit:</i> the function values at the final point returned in x . | |
| 5: | xtol – double | <i>Input</i> |
| | <i>On entry:</i> the accuracy in x to which the solution is required. | |
| | <i>Suggested value:</i> $\sqrt{\epsilon}$, where ϵ is the <i>machine precision</i> returned by nag_machine_precision (X02AJC). | |
| | <i>Constraint:</i> xtol ≥ 0.0. | |

- 6: **maxfev** – Integer *Input*
On entry: the maximum number of calls to **fcn** with **iflag** $\neq 0$. `nag_zero_nonlin_eqns_expert` (c05qcc) will exit with **fail.code** = NE_TOO_MANY_FEVALS, if, at the end of an iteration, the number of calls to **fcn** exceeds **maxfev**.
Suggested value: **maxfev** = $200 \times (n + 1)$.
Constraint: **maxfev** > 0.
- 7: **ml** – Integer *Input*
On entry: the number of subdiagonals within the band of the Jacobian matrix. (If the Jacobian is not banded, or you are unsure, set **ml** = $n - 1$.)
Constraint: **ml** ≥ 0 .
- 8: **mu** – Integer *Input*
On entry: the number of superdiagonals within the band of the Jacobian matrix. (If the Jacobian is not banded, or you are unsure, set **mu** = $n - 1$.)
Constraint: **mu** ≥ 0 .
- 9: **epsfcn** – double *Input*
On entry: a rough estimate of the largest relative error in the functions. It is used in determining a suitable step for a forward difference approximation to the Jacobian. If **epsfcn** is less than *machine precision* (returned by `nag_machine_precision` (X02AJC)) then *machine precision* is used. Consequently a value of 0.0 will often be suitable.
Suggested value: **epsfcn** = 0.0.
- 10: **scale_mode** – Nag_ScaleType *Input*
On entry: indicates whether or not you have provided scaling factors in **diag**.
If **scale_mode** = Nag_ScaleProvided the scaling must have been specified in **diag**.
Otherwise, if **scale_mode** = Nag_NoScaleProvided, the variables will be scaled internally.
Constraint: **scale_mode** = Nag_NoScaleProvided or Nag_ScaleProvided.
- 11: **diag[n]** – double *Input/Output*
On entry: if **scale_mode** = Nag_ScaleProvided, **diag** must contain multiplicative scale factors for the variables.
If **scale_mode** = Nag_NoScaleProvided, **diag** need not be set.
Constraint: if **scale_mode** = Nag_ScaleProvided, **diag**[$i - 1$] > 0.0, for $i = 1, 2, \dots, n$.
On exit: the scale factors actually used (computed internally if **scale_mode** = Nag_NoScaleProvided).
- 12: **factor** – double *Input*
On entry: a quantity to be used in determining the initial step bound. In most cases, **factor** should lie between 0.1 and 100.0. (The step bound is **factor** \times $\|\mathbf{diag} \times \mathbf{x}\|_2$ if this is nonzero; otherwise the bound is **factor**.)
Suggested value: **factor** = 100.0.
Constraint: **factor** > 0.0.

- 13: **nprint** – Integer *Input*
On entry: indicates whether (and how often) special calls to **fcn**, with **iflag** set to 0, are to be made for printing purposes.
nprint \leq 0
 No calls are made.
nprint $>$ 0
fcn is called at the beginning of the first iteration, every **nprint** iterations thereafter and immediately before the return from nag_zero_nonlin_eqns_expert (c05qcc).
- 14: **nfev** – Integer * *Output*
On exit: the number of calls made to **fcn** with **iflag** $>$ 0.
- 15: **fjac**[**n** \times **n**] – double *Output*
Note: the (*i*, *j*)th element of the matrix is stored in **fjac**[(*j* – 1) \times **n** + *i* – 1].
On exit: the orthogonal matrix *Q* produced by the *QR* factorisation of the final approximate Jacobian.
- 16: **r**[**n** \times (**n** + 1)/2] – double *Output*
On exit: the upper triangular matrix *R* produced by the *QR* factorization of the final approximate Jacobian, stored row-wise.
- 17: **qtf**[**n**] – double *Output*
On exit: the vector $Q^T f$.
- 18: **comm** – Nag_Comm * *Communication Structure*
 The NAG communication argument (see Section 3.2.1.1 in the Essential Introduction).
- 19: **fail** – NagError * *Input/Output*
 The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_DIAG_ELEMENTS

On entry, **scale_mode** = Nag_ScaleProvided and **diag** contained a non-positive element.

NE_INT

On entry, **maxfev** = $\langle value \rangle$.

Constraint: **maxfev** $>$ 0.

On entry, **m1** = $\langle value \rangle$.

Constraint: **m1** \geq 0.

On entry, **mu** = $\langle value \rangle$.

Constraint: **mu** \geq 0.

On entry, **n** = $\langle value \rangle$.
 Constraint: **n** > 0.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

NE_NO_IMPROVEMENT

The iteration is not making good progress, as measured by the improvement from the last $\langle value \rangle$ iterations.

The iteration is not making good progress, as measured by the improvement from the last $\langle value \rangle$ Jacobian evaluations.

NE_REAL

On entry, **factor** = $\langle value \rangle$.
 Constraint: **factor** > 0.0.

On entry, **xtol** = $\langle value \rangle$.
 Constraint: **xtol** \geq 0.0.

NE_TOO_MANY_FEVALS

There have been at least **maxfev** calls to **fcn**: **maxfev** = $\langle value \rangle$. Consider restarting the calculation from the final point held in **x**.

NE_TOO_SMALL

No further improvement in the solution is possible. **xtol** is too small: **xtol** = $\langle value \rangle$.

NE_USER_STOP

iflag was set negative in **fcn**. **iflag** = $\langle value \rangle$.

7 Accuracy

If \hat{x} is the true solution and D denotes the diagonal matrix whose entries are defined by the array **diag**, then `nag_zero_nonlin_eqns_expert` (c05qcc) tries to ensure that

$$\|D(x - \hat{x})\|_2 \leq \mathbf{xtol} \times \|D\hat{x}\|_2.$$

If this condition is satisfied with $\mathbf{xtol} = 10^{-k}$, then the larger components of Dx have k significant decimal digits. There is a danger that the smaller components of Dx may have large relative errors, but the fast rate of convergence of `nag_zero_nonlin_eqns_expert` (c05qcc) usually obviates this possibility.

If **xtol** is less than *machine precision* and the above test is satisfied with the *machine precision* in place of **xtol**, then the function exits with **fail.code** = NE_TOO_SMALL.

Note: this convergence test is based purely on relative error, and may not indicate convergence if the solution is very close to the origin.

The convergence test assumes that the functions are reasonably well behaved. If this condition is not satisfied, then `nag_zero_nonlin_eqns_expert` (c05qcc) may incorrectly indicate convergence. The validity of the answer can be checked, for example, by rerunning `nag_zero_nonlin_eqns_expert` (c05qcc) with a lower value for **xtol**.

8 Parallelism and Performance

`nag_zero_nonlin_eqns_expert` (c05qcc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_zero_nonlin_eqns_expert (c05qcc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

Local workspace arrays of fixed lengths are allocated internally by nag_zero_nonlin_eqns_expert (c05qcc). The total size of these arrays amounts to $4 \times n$ double elements.

The time required by nag_zero_nonlin_eqns_expert (c05qcc) to solve a given problem depends on n , the behaviour of the functions, the accuracy requested and the starting point. The number of arithmetic operations executed by nag_zero_nonlin_eqns_expert (c05qcc) to process each evaluation of the functions is approximately $11.5 \times n^2$. The timing of nag_zero_nonlin_eqns_expert (c05qcc) is strongly influenced by the time spent evaluating the functions.

Ideally the problem should be scaled so that, at the solution, the function values are of comparable magnitude.

The number of function evaluations required to evaluate the Jacobian may be reduced if you can specify **ml** and **mu** accurately.

10 Example

This example determines the values x_1, \dots, x_9 which satisfy the tridiagonal equations:

$$\begin{aligned} (3 - 2x_1)x_1 - 2x_2 &= -1, \\ -x_{i-1} + (3 - 2x_i)x_i - 2x_{i+1} &= -1, \quad i = 2, 3, \dots, 8 \\ -x_8 + (3 - 2x_9)x_9 &= -1. \end{aligned}$$

10.1 Program Text

```

/* nag_zero_nonlin_eqns_expert (c05qcc) Example Program.
 *
 * Copyright 2013 Numerical Algorithms Group.
 *
 * Mark 24, 2013.
 */

#include <nag.h>
#include <nagx04.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <math.h>
#include <nagc05.h>
#include <nagx02.h>

#ifdef __cplusplus
extern "C" {
#endif
static void NAG_CALL fcn(Integer n, const double x[], double fvec[],
                        Nag_Comm *comm, Integer *iflag);
#ifdef __cplusplus
}
#endif

static Integer nprint = 0;

int main(void)
{
    static double ruser[1] = {-1.0};
    Integer exit_status = 0, i, n = 9, maxfev, ml, mu, nfev;
    double *diag = 0, *fjac = 0, *fvec = 0, *qtf = 0, *r = 0, *x = 0;

```

```

double  epsfcn, factor, xtol;
/* Nag Types */
NagError fail;
Nag_Comm comm;
Nag_ScaleType scale_mode;

INIT_FAIL(fail);

printf("nag_zero_nonlin_eqns_expert (c05qcc) Example Program Results\n");

/* For communication with user-supplied functions: */
comm.user = ruser;

if (n > 0)
{
    if (!(diag = NAG_ALLOC(n, double)) ||
        !(fjac = NAG_ALLOC(n*n, double)) ||
        !(fvec = NAG_ALLOC(n, double)) ||
        !(qtf = NAG_ALLOC(n, double)) ||
        !(r = NAG_ALLOC(n*(n+1)/2, double)) ||
        !(x = NAG_ALLOC(n, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
}
else
{
    printf("Invalid n.\n");
    exit_status = 1;
    goto END;
}

/* The following starting values provide a rough solution. */
for (i = 0; i < n; i++)
    x[i] = -1.0;

/* nag_machine_precision (x02ajc).
 * The machine precision
 */
xtol = sqrt(nag_machine_precision);

for (i = 0; i < n; i++)
    diag[i] = 1.0;

maxfev = 2000;
ml = 1;
mu = 1;
epsfcn = 0.0;
scale_mode = Nag_ScaleProvided;
factor = 100.0;

/* nag_zero_nonlin_eqns_expert (c05qcc).
 * Solution of a system of nonlinear equations (function
 * values only)
 */
nag_zero_nonlin_eqns_expert(fcn, n, x, fvec, xtol, maxfev, ml, mu,
                           epsfcn, scale_mode, diag, factor, nprint, &nfev,
                           fjac, r, qtf, &comm, &fail);

if (fail.code != NE_NOERROR)
{
    printf("Error from nag_zero_nonlin_eqns_expert (c05qcc).\n%s\n",
          fail.message);
    exit_status = 1;
    if (fail.code != NE_TOO_MANY_FEVALS &&
        fail.code != NE_TOO_SMALL &&
        fail.code != NE_NO_IMPROVEMENT)
        goto END;
}
}

```

```

printf(fail.code == NE_NOERROR ? "Final approximate" : "Approximate");
printf(" solution\n\n");
for (i = 0; i < n; i++)
    printf("%12.4f%s", x[i], (i%3 == 2 || i == n-1)? "\n": " ");

if (fail.code != NE_NOERROR)
    exit_status = 2;

END:
NAG_FREE(diag);
NAG_FREE(fjac);
NAG_FREE(fvec);
NAG_FREE(qtf);
NAG_FREE(r);
NAG_FREE(x);
return exit_status;
}
static void NAG_CALL fcn(Integer n, const double x[], double fvec[],
                        Nag_Comm *comm, Integer *iflag)
{
    Integer k;

    if (comm->user[0] == -1.0)
    {
        printf("(User-supplied callback fcn, first invocation.)\n");
        comm->user[0] = 0.0;
    }
    if (*iflag==0)
    {
        if (nprint>0)
        {
            /* Insert print statements here if desired. */
        }
    }
    else
    {
        for (k = 0; k < n; ++k)
        {
            fvec[k] = (3.0-x[k]*2.0)*x[k]+1.0;
            if (k > 0)
                fvec[k] -= x[k-1];
            if (k < n-1)
                fvec[k] -= x[k+1]*2.0;
        }
    }
    /* Set iflag negative to terminate execution for any reason. */
    *iflag = 0;
}

```

10.2 Program Data

None.

10.3 Program Results

nag_zero_nonlin_eqns_expert (c05qcc) Example Program Results
 (User-supplied callback fcn, first invocation.)
 Final approximate solution

-0.5707	-0.6816	-0.7017
-0.7042	-0.7014	-0.6919
-0.6658	-0.5960	-0.4164
