

NAG Toolbox

nag_univar_robust_lvar_ci (g07ea)

1 Purpose

`nag_univar_robust_lvar_ci (g07ea)` computes a rank based (nonparametric) estimate and confidence interval for the location argument of a single population.

2 Syntax

```
[theta, thetal, thetau, estc1, wlower, wupper, ifail] =
nag_univar_robust_lvar_ci(method, x, clevel, 'n', n)

[theta, thetal, thetau, estc1, wlower, wupper, ifail] = g07ea(method, x,
clevel, 'n', n)
```

3 Description

Consider a vector of independent observations, $x = (x_1, x_2, \dots, x_n)^T$ with unknown common symmetric density $f(x_i - \theta)$. `nag_univar_robust_lvar_ci (g07ea)` computes the Hodges–Lehmann location estimator (see Lehmann (1975)) of the centre of symmetry θ , together with an associated confidence interval. The Hodges–Lehmann estimate is defined as

$$\hat{\theta} = \text{median}\left\{\frac{x_i + x_j}{2}, 1 \leq i \leq j \leq n\right\}.$$

Let $m = (n(n+1))/2$ and let a_k , for $k = 1, 2, \dots, m$ denote the m ordered averages $(x_i + x_j)/2$ for $1 \leq i \leq j \leq n$. Then

if m is odd, $\hat{\theta} = a_k$ where $k = (m+1)/2$;

if m is even, $\hat{\theta} = (a_k + a_{k+1})/2$ where $k = m/2$.

This estimator arises from inverting the one-sample Wilcoxon signed-rank test statistic, $W(x - \theta_0)$, for testing the hypothesis that $\theta = \theta_0$. Effectively $W(x - \theta_0)$ is a monotonically decreasing step function of θ_0 with

$$\text{mean}(W) = \mu = \frac{n(n+1)}{4},$$

$$\text{var}(W) = \sigma^2 = \frac{n(n+1)(2n+1)}{24}.$$

The estimate $\hat{\theta}$ is the solution to the equation $W(x - \hat{\theta}) = \mu$; two methods are available for solving this equation. These methods avoid the computation of all the ordered averages a_k ; this is because for large n both the storage requirements and the computation time would be excessive.

The first is an exact method based on a set partitioning procedure on the set of all ordered averages $(x_i + x_j)/2$ for $i \leq j$. This is based on the algorithm proposed by Monahan (1984).

The second is an iterative algorithm, based on the Illinois method which is a modification of the *regula falsi* method, see McKean and Ryan (1977). This algorithm has proved suitable for the function $W(x - \theta_0)$ which is asymptotically linear as a function of θ_0 .

The confidence interval limits are also based on the inversion of the Wilcoxon test statistic.

Given a desired percentage for the confidence interval, $1 - \alpha$, expressed as a proportion between 0 and 1, initial estimates for the lower and upper confidence limits of the Wilcoxon statistic are found from

$$W_l = \mu - 0.5 + (\sigma\Phi^{-1}(\alpha/2))$$

and

$$W_u = \mu + 0.5 + (\sigma\Phi^{-1}(1 - \alpha/2)),$$

where Φ^{-1} is the inverse cumulative Normal distribution function.

W_l and W_u are rounded to the nearest integer values. These estimates are then refined using an exact method if $n \leq 80$, and a Normal approximation otherwise, to find W_l and W_u satisfying

$$\begin{aligned} P(W \leq W_l) &\leq \alpha/2 \\ P(W \leq W_l + 1) &> \alpha/2 \end{aligned}$$

and

$$\begin{aligned} P(W \geq W_u) &\leq \alpha/2 \\ P(W \geq W_u - 1) &> \alpha/2. \end{aligned}$$

Let $W_u = m - k$; then $\theta_l = a_{k+1}$. This is the largest value θ_l such that $W(x - \theta_l) = W_u$.

Let $W_l = k$; then $\theta_u = a_{m-k}$. This is the smallest value θ_u such that $W(x - \theta_u) = W_l$.

As in the case of $\hat{\theta}$, these equations may be solved using either the exact or the iterative methods to find the values θ_l and θ_u .

Then (θ_l, θ_u) is the confidence interval for θ . The confidence interval is thus defined by those values of θ_0 such that the null hypothesis, $\theta = \theta_0$, is not rejected by the Wilcoxon signed-rank test at the $(100 \times \alpha)\%$ level.

4 References

- Lehmann E L (1975) *Nonparametrics: Statistical Methods Based on Ranks* Holden-Day
- Marazzi A (1987) Subroutines for robust estimation of location and scale in ROBETH *Cah. Rech. Doc. IUMSP, No. 3 ROB 1* Institut Universitaire de Médecine Sociale et Préventive, Lausanne
- McKean J W and Ryan T A (1977) Algorithm 516: An algorithm for obtaining confidence intervals and point estimates based on ranks in the two-sample location problem *ACM Trans. Math. Software* **10** 183–185
- Monahan J F (1984) Algorithm 616: Fast computation of the Hodges–Lehman location estimator *ACM Trans. Math. Software* **10** 265–270

5 Parameters

5.1 Compulsory Input Parameters

- 1: **method** – CHARACTER(1)
Specifies the method to be used.
method = 'E'
The exact algorithm is used.
method = 'A'
The iterative algorithm is used.
Constraint: **method** = 'E' or 'A'.
- 2: **x(n)** – REAL (KIND=nag_wp) array
The sample observations, x_i , for $i = 1, 2, \dots, n$.

- 3: **clevel** – REAL (KIND=nag_wp)
 The confidence interval desired.
 For example, for a 95% confidence interval set **clevel** = 0.95.
Constraint: $0.0 < \mathbf{clevel} < 1.0$.

5.2 Optional Input Parameters

- 1: **n** – INTEGER
Default: the dimension of the array **x**.
 n , the sample size.
Constraint: $\mathbf{n} \geq 2$.

5.3 Output Parameters

- 1: **theta** – REAL (KIND=nag_wp)
 The estimate of the location, $\hat{\theta}$.
- 2: **thetal** – REAL (KIND=nag_wp)
 The estimate of the lower limit of the confidence interval, θ_l .
- 3: **thetau** – REAL (KIND=nag_wp)
 The estimate of the upper limit of the confidence interval, θ_u .
- 4: **estcl** – REAL (KIND=nag_wp)
 An estimate of the actual percentage confidence of the interval found, as a proportion between (0.0, 1.0).
- 5: **wlower** – REAL (KIND=nag_wp)
 The upper value of the Wilcoxon test statistic, W_u , corresponding to the lower limit of the confidence interval.
- 6: **wupper** – REAL (KIND=nag_wp)
 The lower value of the Wilcoxon test statistic, W_l , corresponding to the upper limit of the confidence interval.
- 7: **ifail** – INTEGER
ifail = 0 unless the function detects an error (see Section 5).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **method** \neq 'E' or 'A',
 or **n** < 2,
 or **clevel** \leq 0.0,
 or **clevel** \geq 1.0.

ifail = 2

There is not enough information to compute a confidence interval since the whole sample consists of identical values.

ifail = 3

For at least one of the estimates $\hat{\theta}$, θ_l and θ_u , the underlying iterative algorithm (when **method** = 'A') failed to converge. This is an unlikely exit but the estimate should still be a reasonable approximation.

ifail = -99

An unexpected error has been triggered by this routine. Please contact NAG.

ifail = -399

Your licence key may have expired or may not have been installed correctly.

ifail = -999

Dynamic memory allocation failed.

7 Accuracy

nag_univar_robust_lvar_ci (g07ea) should produce results accurate to five significant figures in the width of the confidence interval; that is the error for any one of the three estimates should be less than $0.00001 \times (\text{thetau} - \text{thetal})$.

8 Further Comments

The time taken increases with the sample size n .

9 Example

The following program calculates a 95% confidence interval for θ , a measure of symmetry of the sample of 50 observations.

9.1 Program Text

```
function g07ea_example

fprintf('g07ea example results\n\n');

x = [-0.23; 0.35; -0.77; 0.35; 0.27; -0.72; 0.08; -0.40; -0.76; 0.45;
      0.73; 0.74; 0.83; -0.87; 0.21; 0.29; -0.91; -0.04; 0.82; -0.38;
      -0.31; 0.24; -0.47; -0.68; -0.77; -0.86; -0.59; 0.73; 0.39; -0.44;
      0.63; -0.22; -0.07; -0.43; -0.21; -0.31; 0.64; -1.00; -0.86; -0.73];

method = 'Exact';
clevel = 0.95;

[theta, thetal, thetau, estcl, wlower, wupper, ifail] = ...
    g07ea(method, x, clevel);

fprintf(' Location estimator      Confidence Interval\n\n');
fprintf('%13.4f%12s%7.4f,%7.4f )\n\n', theta, '( ', thetal, thetau);
fprintf(' Corresponding Wilcoxon statistics\n\n');
fprintf(' Lower : %8.2f\n', wlower);
fprintf(' Upper : %8.2f\n', wupper);
```

9.2 Program Results

g07ea example results

Location estimator	Confidence Interval
-0.1300	(-0.3300, 0.0350)

Corresponding Wilcoxon statistics

Lower :	556.00
Upper :	264.00
