

NAG Toolbox

nag_lapack_dsygvd (f08sc)

1 Purpose

nag_lapack_dsygvd (f08sc) computes all the eigenvalues and, optionally, the eigenvectors of a real generalized symmetric-definite eigenproblem, of the form

$$Az = \lambda Bz, \quad ABz = \lambda z \quad \text{or} \quad BAz = \lambda z,$$

where A and B are symmetric and B is also positive definite. If eigenvectors are desired, it uses a divide-and-conquer algorithm.

2 Syntax

```
[a, b, w, info] = nag_lapack_dsygvd(itype, jobz, uplo, a, b, 'n', n)
[a, b, w, info] = f08sc(itype, jobz, uplo, a, b, 'n', n)
```

3 Description

nag_lapack_dsygvd (f08sc) first performs a Cholesky factorization of the matrix B as $B = U^T U$, when **uplo** = 'U' or $B = LL^T$, when **uplo** = 'L'. The generalized problem is then reduced to a standard symmetric eigenvalue problem

$$Cx = \lambda x,$$

which is solved for the eigenvalues and, optionally, the eigenvectors; the eigenvectors are then backtransformed to give the eigenvectors of the original problem.

For the problem $Az = \lambda Bz$, the eigenvectors are normalized so that the matrix of eigenvectors, z , satisfies

$$Z^T A Z = \Lambda \quad \text{and} \quad Z^T B Z = I,$$

where Λ is the diagonal matrix whose diagonal elements are the eigenvalues. For the problem $ABz = \lambda z$ we correspondingly have

$$Z^{-1} A Z^{-T} = \Lambda \quad \text{and} \quad Z^T B Z = I,$$

and for $BAz = \lambda z$ we have

$$Z^T A Z = \Lambda \quad \text{and} \quad Z^T B^{-1} Z = I.$$

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: **itype** – INTEGER

Specifies the problem type to be solved.

itype = 1
 $Az = \lambda Bz.$

itype = 2
 $ABz = \lambda z.$

itype = 3
 $BAz = \lambda z.$

Constraint: **itype** = 1, 2 or 3.

2: **jobz** – CHARACTER(1)

Indicates whether eigenvectors are computed.

jobz = 'N'
 Only eigenvalues are computed.

jobz = 'V'
 Eigenvalues and eigenvectors are computed.

Constraint: **jobz** = 'N' or 'V'.

3: **uplo** – CHARACTER(1)

If **uplo** = 'U', the upper triangles of A and B are stored.

If **uplo** = 'L', the lower triangles of A and B are stored.

Constraint: **uplo** = 'U' or 'L'.

4: **a**(lda,:) – REAL (KIND=nag_wp) array

The first dimension of the array **a** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **a** must be at least $\max(1, \mathbf{n})$.

The n by n symmetric matrix A .

If **uplo** = 'U', the upper triangular part of a must be stored and the elements of the array below the diagonal are not referenced.

If **uplo** = 'L', the lower triangular part of a must be stored and the elements of the array above the diagonal are not referenced.

5: **b**(ldb,:) – REAL (KIND=nag_wp) array

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **b** must be at least $\max(1, \mathbf{n})$.

The n by n symmetric matrix B .

If **uplo** = 'U', the upper triangular part of b must be stored and the elements of the array below the diagonal are not referenced.

If **uplo** = 'L', the lower triangular part of b must be stored and the elements of the array above the diagonal are not referenced.

5.2 Optional Input Parameters

1: **n** – INTEGER

Default: the first dimension of the arrays **a**, **b** and the second dimension of the arrays **a**, **b**. (An error is raised if these dimensions are not equal.)

n, the order of the matrices *A* and *B*.

Constraint: $n \geq 0$.

5.3 Output Parameters

1: **a**(*lda*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **a** will be $\max(1, n)$.

The second dimension of the array **a** will be $\max(1, n)$.

If **jobz** = 'V', **a** contains the matrix *Z* of eigenvectors. The eigenvectors are normalized as follows:

if **itype** = 1 or 2, $Z^T B Z = I$;

if **itype** = 3, $Z^T B^{-1} Z = I$.

If **jobz** = 'N', the upper triangle (if **uplo** = 'U') or the lower triangle (if **uplo** = 'L') of **a**, including the diagonal, is overwritten.

2: **b**(*ldb*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **b** will be $\max(1, n)$.

The second dimension of the array **b** will be $\max(1, n)$.

The triangular factor *U* or *L* from the Cholesky factorization $B = U^T U$ or $B = L L^T$.

3: **w**(**n**) – REAL (KIND=nag_wp) array

The eigenvalues in ascending order.

4: **info** – INTEGER

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

info = $-i$

If **info** = $-i$, parameter *i* had an illegal value on entry. The parameters are numbered as follows:

1: **itype**, 2: **jobz**, 3: **uplo**, 4: **n**, 5: **a**, 6: **lda**, 7: **b**, 8: **ldb**, 9: **w**, 10: **work**, 11: **lwork**, 12: **iwork**, 13: **liwork**, 14: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

info = 1 to **n**

If **info** = *i*, nag_lapack_dsyevd (f08fc) failed to converge; *i* *i* off-diagonal elements of an intermediate tridiagonal form did not converge to zero.

info > **n**

nag_lapack_dpotrf (f07fd) returned an error code; i.e., if **info** = **n** + *i*, for $1 \leq i \leq \mathbf{n}$, then the leading minor of order *i* of *B* is not positive definite. The factorization of *B* could not be completed and no eigenvalues or eigenvectors were computed.

7 Accuracy

If *B* is ill-conditioned with respect to inversion, then the error bounds for the computed eigenvalues and vectors may be large, although when the diagonal elements of *B* differ widely in magnitude the eigenvalues and eigenvectors may be less sensitive than the condition of *B* would suggest. See Section 4.10 of Anderson *et al.* (1999) for details of the error bounds.

The example program below illustrates the computation of approximate error bounds.

8 Further Comments

The total number of floating-point operations is proportional to n^3 .

The complex analogue of this function is nag_lapack_zhegvd (f08sq).

9 Example

This example finds all the eigenvalues and eigenvectors of the generalized symmetric eigenproblem $ABz = \lambda z$, where

$$A = \begin{pmatrix} 0.24 & 0.39 & 0.42 & -0.16 \\ 0.39 & -0.11 & 0.79 & 0.63 \\ 0.42 & 0.79 & -0.25 & 0.48 \\ -0.16 & 0.63 & 0.48 & -0.03 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 4.16 & -3.12 & 0.56 & -0.10 \\ -3.12 & 5.03 & -0.83 & 1.09 \\ 0.56 & -0.83 & 0.76 & 0.34 \\ -0.10 & 1.09 & 0.34 & 1.18 \end{pmatrix},$$

together with an estimate of the condition number of *B*, and approximate error bounds for the computed eigenvalues and eigenvectors.

The example program for nag_lapack_dsygv (f08sa) illustrates solving a generalized symmetric eigenproblem of the form $Az = \lambda Bz$.

9.1 Program Text

```
function f08sc_example

fprintf('f08sc example results\n\n');

% Upper triangular parts of symmetric matrix A and symmetric definite matrix B
uplo = 'Upper';
n = 4;
a = [0.24, 0.39, 0.42, -0.16;
     0, -0.11, 0.79, 0.63;
     0, 0, -0.25, 0.48;
     0, 0, 0, -0.03];
b = [4.16, -3.12, 0.56, -0.10;
     0, 5.03, -0.83, 1.09;
     0, 0, 0.76, 0.34;
     0, 0, 0, 1.18];

% Generalized eigenvalues and eigenvectors for problem ABz = lambda z
itype = nag_int(2);
jobz = 'Vectors';
[Z, U, w, info] = f08sc(...
    itype, jobz, uplo, a, b);

% Normalize eigenvectors: largest element positive (with z'Bz = I)
for j = 1:n
    [~,k] = max(abs(Z(:,j)));
    if Z(k,j) < 0
```

```
        z(:,j) = -z(:,j);  
    end  
end  
  
disp('Eigenvalues');  
disp(w');  
disp('Eigenvectors');  
disp(Z);
```

9.2 Program Results

f08sc example results

```
Eigenvalues  
-3.5411   -0.3347    0.2983    2.2544  
  
Eigenvectors  
-0.0356  -0.1039  -0.7459   0.1909  
 0.3809   0.4322  -0.7845   0.3540  
-0.2943   1.5644  -0.7144   0.5665  
-0.3186  -1.0647   1.1184   0.3859
```
