

## NAG Toolbox

### nag\_lapack\_zunmtr (f08fu)

#### 1 Purpose

nag\_lapack\_zunmtr (f08fu) multiplies an arbitrary complex matrix  $C$  by the complex unitary matrix  $Q$  which was determined by nag\_lapack\_zhetrd (f08fs) when reducing a complex Hermitian matrix to tridiagonal form.

#### 2 Syntax

```
[c, info] = nag_lapack_zunmtr(side, uplo, trans, a, tau, c, 'm', m, 'n', n)
```

```
[c, info] = f08fu(side, uplo, trans, a, tau, c, 'm', m, 'n', n)
```

#### 3 Description

nag\_lapack\_zunmtr (f08fu) is intended to be used after a call to nag\_lapack\_zhetrd (f08fs), which reduces a complex Hermitian matrix  $A$  to real symmetric tridiagonal form  $T$  by a unitary similarity transformation:  $A = QTQ^H$ . nag\_lapack\_zhetrd (f08fs) represents the unitary matrix  $Q$  as a product of elementary reflectors.

This function may be used to form one of the matrix products

$$QC, Q^H C, CQ \text{ or } CQ^H,$$

overwriting the result on  $C$  (which may be any complex rectangular matrix).

A common application of this function is to transform a matrix  $Z$  of eigenvectors of  $T$  to the matrix  $QZ$  of eigenvectors of  $A$ .

#### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

#### 5 Parameters

##### 5.1 Compulsory Input Parameters

1: **side** – CHARACTER(1)

Indicates how  $Q$  or  $Q^H$  is to be applied to  $C$ .

**side** = 'L'

$Q$  or  $Q^H$  is applied to  $C$  from the left.

**side** = 'R'

$Q$  or  $Q^H$  is applied to  $C$  from the right.

*Constraint:* **side** = 'L' or 'R'.

2: **uplo** – CHARACTER(1)

This **must** be the same argument **uplo** as supplied to nag\_lapack\_zhetrd (f08fs).

*Constraint:* **uplo** = 'U' or 'L'.

3: **trans** – CHARACTER(1)

Indicates whether  $Q$  or  $Q^H$  is to be applied to  $C$ .

**trans** = 'N'

$Q$  is applied to  $C$ .

**trans** = 'C'

$Q^H$  is applied to  $C$ .

*Constraint:* **trans** = 'N' or 'C'.

4: **a**(*lda*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension, *lda*, of the array **a** must satisfy

if **side** = 'L',  $lda \geq \max(1, \mathbf{m})$ ;

if **side** = 'R',  $lda \geq \max(1, \mathbf{n})$ .

The second dimension of the array **a** must be at least  $\max(1, \mathbf{m})$  if **side** = 'L' and at least  $\max(1, \mathbf{n})$  if **side** = 'R'.

Details of the vectors which define the elementary reflectors, as returned by nag\_lapack\_zhetrd (f08fs).

5: **tau**(:) – COMPLEX (KIND=nag\_wp) array

The dimension of the array **tau** must be at least  $\max(1, \mathbf{m} - 1)$  if **side** = 'L' and at least  $\max(1, \mathbf{n} - 1)$  if **side** = 'R'

Further details of the elementary reflectors, as returned by nag\_lapack\_zhetrd (f08fs).

6: **c**(*ldc*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **c** must be at least  $\max(1, \mathbf{m})$ .

The second dimension of the array **c** must be at least  $\max(1, \mathbf{n})$ .

The  $m$  by  $n$  matrix  $C$ .

## 5.2 Optional Input Parameters

1: **m** – INTEGER

*Default:* the first dimension of the array **c**.

$m$ , the number of rows of the matrix  $C$ ;  $m$  is also the order of  $Q$  if **side** = 'L'.

*Constraint:*  $\mathbf{m} \geq 0$ .

2: **n** – INTEGER

*Default:* the second dimension of the array **c**.

$n$ , the number of columns of the matrix  $C$ ;  $n$  is also the order of  $Q$  if **side** = 'R'.

*Constraint:*  $\mathbf{n} \geq 0$ .

## 5.3 Output Parameters

1: **c**(*ldc*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **c** will be  $\max(1, \mathbf{m})$ .

The second dimension of the array **c** will be  $\max(1, \mathbf{n})$ .

**c** stores  $QC$  or  $Q^H C$  or  $CQ$  or  $CQ^H$  as specified by **side** and **trans**.

- 2: **info** – INTEGER  
**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

**info** =  $-i$

If **info** =  $-i$ , parameter  $i$  had an illegal value on entry. The parameters are numbered as follows:

1: **side**, 2: **uplo**, 3: **trans**, 4: **m**, 5: **n**, 6: **a**, 7: **lda**, 8: **tau**, 9: **c**, 10: **ldc**, 11: **work**, 12: **lwork**, 13: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

## 7 Accuracy

The computed result differs from the exact result by a matrix  $E$  such that

$$\|E\|_2 = O(\epsilon)\|C\|_2,$$

where  $\epsilon$  is the *machine precision*.

## 8 Further Comments

The total number of real floating-point operations is approximately  $8m^2n$  if **side** = 'L' and  $8mn^2$  if **side** = 'R'.

The real analogue of this function is nag\_lapack\_dormtr (f08fg).

## 9 Example

This example computes the two smallest eigenvalues, and the associated eigenvectors, of the matrix  $A$ , where

$$A = \begin{pmatrix} -2.28 + 0.00i & 1.78 - 2.03i & 2.26 + 0.10i & -0.12 + 2.53i \\ 1.78 + 2.03i & -1.12 + 0.00i & 0.01 + 0.43i & -1.07 + 0.86i \\ 2.26 - 0.10i & 0.01 - 0.43i & -0.37 + 0.00i & 2.31 - 0.92i \\ -0.12 - 2.53i & -1.07 - 0.86i & 2.31 + 0.92i & -0.73 + 0.00i \end{pmatrix}.$$

Here  $A$  is Hermitian and must first be reduced to tridiagonal form  $T$  by nag\_lapack\_zhetrd (f08fs). The program then calls nag\_lapack\_dstebz (f08jj) to compute the requested eigenvalues and nag\_lapack\_zstein (f08jx) to compute the associated eigenvectors of  $T$ . Finally nag\_lapack\_zunmtr (f08fu) is called to transform the eigenvectors to those of  $A$ .

### 9.1 Program Text

```
function f08fu_example

fprintf('f08fu example results\n\n');

% Lower triangular part of Hermitian matrix A
uplo = 'L';
a = [-2.28 + 0.00i, 0.00 + 0i, 0 + 0i, 0 + 0i;
     1.78 + 2.03i, -1.12 + 0i, 0 + 0i, 0 + 0i;
     2.26 - 0.10i, 0.01 - 0.43i, -0.37 + 0i, 0 + 0i;
     -0.12 - 2.53i, -1.07 - 0.86i, 2.31 + 0.92i, -0.73 + 0i];

% Reduce A to tridiagonal form
[aq, d, e, tau, info] = f08fs( ...
    uplo, a);
```

```

% Calculate two smallest eigenvalues
range = 'Indices';
order = 'Block';
vl = 0;
vu = 0;
il = nag_int(1);
iu = nag_int(2);
abstol = 0;
[m, nsplit, w, iblock, isplit, info] = ...
    f08jj( ...
        range, order, vl, vu, il, iu, abstol, d, e);

% Corresponding eigenvectors of T
[tz, ifailv, info] = f08jx( ...
    d, e, m, w, iblock, isplit);

% Transform to eigenvalues of A (by premultiplying by Q)
trans = 'No transpose';
side = 'Left';
[z, info] = f08fu( ...
    side, uplo, trans, aq, tau, tz);

% Normalize vectors, largest element is real and positive.
for i = 1:m
    [~,k] = max(abs(real(z(:,i)))+abs(imag(z(:,i))));
    z(:,i) = z(:,i)*conj(z(k,i))/abs(z(k,i));
end

disp(' Selected eigenvalues of A:');
disp(w(1:m));
disp(' Corresponding eigenvectors:');
disp(z);

```

## 9.2 Program Results

f08fu example results

Selected eigenvalues of A:

```

-6.0002
-3.0030

```

Corresponding eigenvectors:

```

0.7299 + 0.0000i  -0.2120 + 0.1497i
-0.1663 - 0.2061i  0.7307 + 0.0000i
-0.4165 - 0.1417i  -0.3291 + 0.0479i
0.1743 + 0.4162i   0.5200 + 0.1329i

```

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