

# NAG Toolbox

## nag\_lapack\_zptsv (f07jn)

### 1 Purpose

nag\_lapack\_zptsv (f07jn) computes the solution to a complex system of linear equations

$$AX = B,$$

where  $A$  is an  $n$  by  $n$  Hermitian positive definite tridiagonal matrix, and  $X$  and  $B$  are  $n$  by  $r$  matrices.

### 2 Syntax

```
[d, e, b, info] = nag_lapack_zptsv(d, e, b, 'n', n, 'nrhs_p', nrhs_p)
[d, e, b, info] = f07jn(d, e, b, 'n', n, 'nrhs_p', nrhs_p)
```

### 3 Description

nag\_lapack\_zptsv (f07jn) factors  $A$  as  $A = LDL^H$ . The factored form of  $A$  is then used to solve the system of equations.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

### 5 Parameters

#### 5.1 Compulsory Input Parameters

- 1: **d**(:) – REAL (KIND=nag\_wp) array  
The dimension of the array **d** must be at least  $\max(1, \mathbf{n})$   
The  $n$  diagonal elements of the tridiagonal matrix  $A$ .
- 2: **e**(:) – COMPLEX (KIND=nag\_wp) array  
The dimension of the array **e** must be at least  $\max(1, \mathbf{n} - 1)$   
The  $(n - 1)$  subdiagonal elements of the tridiagonal matrix  $A$ .
- 3: **b**(ldb,:) – COMPLEX (KIND=nag\_wp) array  
The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$ .  
The second dimension of the array **b** must be at least  $\max(1, \mathbf{nrhs\_p})$ .  
The  $n$  by  $r$  right-hand side matrix  $B$ .

#### 5.2 Optional Input Parameters

- 1: **n** – INTEGER  
*Default:* the first dimension of the array **b** and the dimension of the array **d**.

$n$ , the order of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

2: **nrhs\_p** – INTEGER

*Default:* the second dimension of the array **b**.

$r$ , the number of right-hand sides, i.e., the number of columns of the matrix  $B$ .

*Constraint:* **nrhs\_p**  $\geq 0$ .

### 5.3 Output Parameters

1: **d**(:) – REAL (KIND=nag\_wp) array

The dimension of the array **d** will be  $\max(1, \mathbf{n})$

The  $n$  diagonal elements of the diagonal matrix  $D$  from the factorization  $A = LDL^H$ .

2: **e**(:) – COMPLEX (KIND=nag\_wp) array

The dimension of the array **e** will be  $\max(1, \mathbf{n} - 1)$

The  $(n - 1)$  subdiagonal elements of the unit bidiagonal factor  $L$  from the  $LDL^H$  factorization of  $A$ . (**e** can also be regarded as the superdiagonal of the unit bidiagonal factor  $U$  from the  $U^H DU$  factorization of  $A$ .)

3: **b**(ldb,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **b** will be  $\max(1, \mathbf{n})$ .

The second dimension of the array **b** will be  $\max(1, \mathbf{nrhs\_p})$ .

If **info** = 0, the  $n$  by  $r$  solution matrix  $X$ .

4: **info** – INTEGER

**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

**info** < 0

If **info** =  $-i$ , argument  $i$  had an illegal value. An explanatory message is output, and execution of the program is terminated.

**info** > 0

The leading minor of order  $\langle value \rangle$  is not positive definite, and the solution has not been computed.

## 7 Accuracy

The computed solution for a single right-hand side,  $\hat{x}$ , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and  $\epsilon$  is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where  $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$ , the condition number of  $A$  with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

nag\_lapack\_zptsvx (f07jp) is a comprehensive LAPACK driver that returns forward and backward error bounds and an estimate of the condition number. Alternatively, nag\_linsys\_complex\_posdef\_tridiag\_solve (f04cg) solves  $Ax = b$  and returns a forward error bound and condition estimate. nag\_linsys\_complex\_posdef\_tridiag\_solve (f04cg) calls nag\_lapack\_zptsv (f07jn) to solve the equations.

## 8 Further Comments

The number of floating-point operations required for the factorization of  $A$  is proportional to  $n$ , and the number of floating-point operations required for the solution of the equations is proportional to  $nr$ , where  $r$  is the number of right-hand sides.

The real analogue of this function is nag\_lapack\_dptsv (f07ja).

## 9 Example

This example solves the equations

$$Ax = b,$$

where  $A$  is the Hermitian positive definite tridiagonal matrix

$$A = \begin{pmatrix} 16.0 & 16.0 - 16.0i & 0 & 0 \\ 16.0 + 16.0i & 41.0 & 18.0 + 9.0i & 0 \\ 0 & 18.0 - 9.0i & 46.0 & 1.0 + 4.0i \\ 0 & 0 & 1.0 - 4.0i & 21.0 \end{pmatrix}$$

and

$$b = \begin{pmatrix} 64.0 + 16.0i \\ 93.0 + 62.0i \\ 78.0 - 80.0i \\ 14.0 - 27.0i \end{pmatrix}.$$

Details of the  $LDL^H$  factorization of  $A$  are also output.

### 9.1 Program Text

```
function f07jn_example
fprintf('f07jn example results\n\n');

% Hermitian tridiagonal A stored as two diagonals
d = [ 16          41          46          21];
e = [ 16 + 16i    18 - 9i     1 - 4i     ];

%RHS
b = [ 64 + 16i;
      93 + 62i;
      78 - 80i;
      14 - 27i];

%Solve
[df, ef, x, info] = f07jn( ...
                      d, e, b);

disp('Solution');
disp(x);
disp('Diagonal elements of the diagonal matrix D');
disp(df);
disp('Sub-diagonal elements of the Cholesky factor L');
disp(ef);
```

## 9.2 Program Results

f07jn example results

Solution

```
2.0000 + 1.0000i
1.0000 + 1.0000i
1.0000 - 2.0000i
1.0000 - 1.0000i
```

Diagonal elements of the diagonal matrix D

```
16      9      1      4
```

Sub-diagonal elements of the Cholesky factor L

```
1.0000 + 1.0000i  2.0000 - 1.0000i  1.0000 - 4.0000i
```

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