

## NAG Toolbox

### nag\_lapack\_zporfs (f07fv)

#### 1 Purpose

nag\_lapack\_zporfs (f07fv) returns error bounds for the solution of a complex Hermitian positive definite system of linear equations with multiple right-hand sides,  $AX = B$ . It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

#### 2 Syntax

```
[x, ferr, berr, info] = nag_lapack_zporfs(uplo, a, af, b, x, 'n', n, 'nrhs_p', nrhs_p)
```

```
[x, ferr, berr, info] = f07fv(uplo, a, af, b, x, 'n', n, 'nrhs_p', nrhs_p)
```

#### 3 Description

nag\_lapack\_zporfs (f07fv) returns the backward errors and estimated bounds on the forward errors for the solution of a complex Hermitian positive definite system of linear equations with multiple right-hand sides  $AX = B$ . The function handles each right-hand side vector (stored as a column of the matrix  $B$ ) independently, so we describe the function of nag\_lapack\_zporfs (f07fv) in terms of a single right-hand side  $b$  and solution  $x$ .

Given a computed solution  $x$ , the function computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of  $A$  and  $b$  such that  $x$  is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where  $\hat{x}$  is the true solution.

For details of the method, see the F07 Chapter Introduction.

#### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

#### 5 Parameters

##### 5.1 Compulsory Input Parameters

1: **uplo** – CHARACTER(1)

Specifies whether the upper or lower triangular part of  $A$  is stored and how  $A$  is to be factorized.

**uplo** = 'U'

The upper triangular part of  $A$  is stored and  $A$  is factorized as  $U^H U$ , where  $U$  is upper triangular.

**uplo** = 'L'

The lower triangular part of  $A$  is stored and  $A$  is factorized as  $LL^H$ , where  $L$  is lower triangular.

*Constraint:* **uplo** = 'U' or 'L'.

2: **a**(*lda*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **a** must be at least  $\max(1, \mathbf{n})$ .

The second dimension of the array **a** must be at least  $\max(1, \mathbf{n})$ .

The  $n$  by  $n$  original Hermitian positive definite matrix  $A$  as supplied to nag\_lapack\_zpotrf (f07fr).

3: **af**(*ldaf*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **af** must be at least  $\max(1, \mathbf{n})$ .

The second dimension of the array **af** must be at least  $\max(1, \mathbf{n})$ .

The Cholesky factor of  $A$ , as returned by nag\_lapack\_zpotrf (f07fr).

4: **b**(*ldb*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$ .

The second dimension of the array **b** must be at least  $\max(1, \mathbf{nrhs\_p})$ .

The  $n$  by  $r$  right-hand side matrix  $B$ .

5: **x**(*ldx*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **x** must be at least  $\max(1, \mathbf{n})$ .

The second dimension of the array **x** must be at least  $\max(1, \mathbf{nrhs\_p})$ .

The  $n$  by  $r$  solution matrix  $X$ , as returned by nag\_lapack\_zpotrs (f07fs).

## 5.2 Optional Input Parameters

1: **n** – INTEGER

*Default:* the first dimension of the arrays **a**, **af**, **b**, **x** and the second dimension of the arrays **a**, **af**,  $n$ , the order of the matrix  $A$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

2: **nrhs\_p** – INTEGER

*Default:* the second dimension of the arrays **b**, **x**. (An error is raised if these dimensions are not equal.)

$r$ , the number of right-hand sides.

*Constraint:*  $\mathbf{nrhs\_p} \geq 0$ .

## 5.3 Output Parameters

1: **x**(*ldx*,:) – COMPLEX (KIND=nag\_wp) array

The first dimension of the array **x** will be  $\max(1, \mathbf{n})$ .

The second dimension of the array **x** will be  $\max(1, \mathbf{nrhs\_p})$ .

The improved solution matrix  $X$ .

- 2: **ferr**(nrhs\_p) – REAL (KIND=nag\_wp) array  
**ferr**(*j*) contains an estimated error bound for the *j*th solution vector, that is, the *j*th column of *X*, for  $j = 1, 2, \dots, r$ .
- 3: **berr**(nrhs\_p) – REAL (KIND=nag\_wp) array  
**berr**(*j*) contains the component-wise backward error bound  $\beta$  for the *j*th solution vector, that is, the *j*th column of *X*, for  $j = 1, 2, \dots, r$ .
- 4: **info** – INTEGER  
**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

**info** < 0

If **info** =  $-i$ , argument *i* had an illegal value. An explanatory message is output, and execution of the program is terminated.

## 7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

## 8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of  $16n^2$  real floating-point operations. Each step of iterative refinement involves an additional  $24n^2$  real operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form  $Ax = b$ ; the number is usually 5 and never more than 11. Each solution involves approximately  $8n^2$  real operations.

The real analogue of this function is nag\_lapack\_dporfs (f07fh).

## 9 Example

This example solves the system of equations  $AX = B$  using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 3.23 + 0.00i & 1.51 - 1.92i & 1.90 + 0.84i & 0.42 + 2.50i \\ 1.51 + 1.92i & 3.58 + 0.00i & -0.23 + 1.11i & -1.18 + 1.37i \\ 1.90 - 0.84i & -0.23 - 1.11i & 4.09 + 0.00i & 2.33 - 0.14i \\ 0.42 - 2.50i & -1.18 - 1.37i & 2.33 + 0.14i & 4.29 + 0.00i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 3.93 - 6.14i & 1.48 + 6.58i \\ 6.17 + 9.42i & 4.65 - 4.75i \\ -7.17 - 21.83i & -4.91 + 2.29i \\ 1.99 - 14.38i & 7.64 - 10.79i \end{pmatrix}.$$

Here *A* is Hermitian positive definite and must first be factorized by nag\_lapack\_zpotrf (f07fr).

## 9.1 Program Text

```
function f07fv_example

fprintf('f07fv example results\n\n');

% Lower triangular part of Hermitian matrix A
uplo = 'Lower';
a = [ 3.23 + 0i,      0 + 0i,      0 + 0i,      0 + 0i;
      1.51 + 1.92i,  3.58 + 0i,      0 + 0i,      0 + 0i;
      1.90 - 0.84i, -0.23 - 1.11i,  4.09 + 0i,      0 + 0i;
      0.42 - 2.50i, -1.18 - 1.37i,  2.33 + 0.14i,  4.29 + 0i];

[L, info] = f07fr( ...
                uplo, a);

% Rhs
b = [ 3.93 - 6.14i,  1.48 + 6.58i;
      6.17 + 9.42i,  4.65 - 4.75i;
      -7.17 - 21.83i, -4.91 + 2.29i;
      1.99 - 14.38i,  7.64 - 10.79i];

% Solve AX = B
[x, info] = f07fs( ...
                uplo, L, b);

% Refine
[x, ferr, berr, info] = f07fv( ...
                            uplo, a, L, b, x);

disp('Solution(s)');
disp(x);
fprintf('\nBackward errors (machine-dependent)\n  ')
fprintf('%11.1e', berr);
fprintf('\nEstimated forward error bounds (machine-dependent)\n  ')
fprintf('%11.1e', ferr);
fprintf('\n');
```

## 9.2 Program Results

```
f07fv example results

Solution(s)
  1.0000 - 1.0000i  -1.0000 + 2.0000i
 -0.0000 + 3.0000i   3.0000 - 4.0000i
 -4.0000 - 5.0000i  -2.0000 + 3.0000i
  2.0000 + 1.0000i   4.0000 - 5.0000i

Backward errors (machine-dependent)
  8.1e-17   7.4e-17
Estimated forward error bounds (machine-dependent)
  6.2e-14   7.7e-14
```

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