

NAG Toolbox

nag_lapack_dporfs (f07fh)

1 Purpose

nag_lapack_dporfs (f07fh) returns error bounds for the solution of a real symmetric positive definite system of linear equations with multiple right-hand sides, $AX = B$. It improves the solution by iterative refinement, in order to reduce the backward error as much as possible.

2 Syntax

```
[x, ferr, berr, info] = nag_lapack_dporfs(uplo, a, af, b, x, 'n', n, 'nrhs_p',
nrhs_p)
[x, ferr, berr, info] = f07fh(uplo, a, af, b, x, 'n', n, 'nrhs_p', nrhs_p)
```

3 Description

nag_lapack_dporfs (f07fh) returns the backward errors and estimated bounds on the forward errors for the solution of a real symmetric positive definite system of linear equations with multiple right-hand sides $AX = B$. The function handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of nag_lapack_dporfs (f07fh) in terms of a single right-hand side b and solution x .

Given a computed solution x , the function computes the *component-wise backward error* β . This is the size of the smallest relative perturbation in each element of A and b such that x is the exact solution of a perturbed system

$$(A + \delta A)x = b + \delta b$$

$$|\delta a_{ij}| \leq \beta |a_{ij}| \quad \text{and} \quad |\delta b_i| \leq \beta |b_i|.$$

Then the function estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_i |x_i - \hat{x}_i| / \max_i |x_i|$$

where \hat{x} is the true solution.

For details of the method, see the F07 Chapter Introduction.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: **uplo** – CHARACTER(1)

Specifies whether the upper or lower triangular part of A is stored and how A is to be factorized.

uplo = 'U'

The upper triangular part of A is stored and A is factorized as $U^T U$, where U is upper triangular.

uplo = 'L'

The lower triangular part of A is stored and A is factorized as LL^T , where L is lower triangular.

Constraint: **uplo** = 'U' or 'L'.

2: **a**(*lda*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **a** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **a** must be at least $\max(1, \mathbf{n})$.

The n by n original symmetric positive definite matrix A as supplied to nag_lapack_dpotrf (f07fd).

3: **af**(*ldaf*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **af** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **af** must be at least $\max(1, \mathbf{n})$.

The Cholesky factor of A , as returned by nag_lapack_dpotrf (f07fd).

4: **b**(*ldb*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **b** must be at least $\max(1, \mathbf{nrhs_p})$.

The n by r right-hand side matrix B .

5: **x**(*ldx*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **x** must be at least $\max(1, \mathbf{n})$.

The second dimension of the array **x** must be at least $\max(1, \mathbf{nrhs_p})$.

The n by r solution matrix X , as returned by nag_lapack_dpotsr (f07fe).

5.2 Optional Input Parameters

1: **n** – INTEGER

Default: the first dimension of the arrays **a**, **af**, **b**, **x** and the second dimension of the arrays **a**, **af**, n , the order of the matrix A .

Constraint: $\mathbf{n} \geq 0$.

2: **nrhs_p** – INTEGER

Default: the second dimension of the arrays **b**, **x**. (An error is raised if these dimensions are not equal.)

r , the number of right-hand sides.

Constraint: $\mathbf{nrhs_p} \geq 0$.

5.3 Output Parameters

1: **x**(*ldx*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **x** will be $\max(1, \mathbf{n})$.

The second dimension of the array **x** will be $\max(1, \mathbf{nrhs_p})$.

The improved solution matrix X .

- 2: **ferr(nrhs_p)** – REAL (KIND=nag_wp) array
ferr(j) contains an estimated error bound for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.
- 3: **berr(nrhs_p)** – REAL (KIND=nag_wp) array
berr(j) contains the component-wise backward error bound β for the j th solution vector, that is, the j th column of X , for $j = 1, 2, \dots, r$.
- 4: **info** – INTEGER
info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

info < 0

If **info** = $-i$, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The bounds returned in **ferr** are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

8 Further Comments

For each right-hand side, computation of the backward error involves a minimum of $4n^2$ floating-point operations. Each step of iterative refinement involves an additional $6n^2$ operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required.

Estimating the forward error involves solving a number of systems of linear equations of the form $Ax = b$; the number is usually 4 or 5 and never more than 11. Each solution involves approximately $2n^2$ operations.

The complex analogue of this function is nag_lapack_zporfs (f07fv).

9 Example

This example solves the system of equations $AX = B$ using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 4.16 & -3.12 & 0.56 & -0.10 \\ -3.12 & 5.03 & -0.83 & 1.18 \\ 0.56 & -0.83 & 0.76 & 0.34 \\ -0.10 & 1.18 & 0.34 & 1.18 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 8.70 & 8.30 \\ -13.35 & 2.13 \\ 1.89 & 1.61 \\ -4.14 & 5.00 \end{pmatrix}.$$

Here A is symmetric positive definite and must first be factorized by nag_lapack_dpotrf (f07fd).

9.1 Program Text

```
function f07fh_example
    fprintf('f07fh example results\n\n');

    % Lower triangular part of symmetric matrix A
    uplo = 'Lower';
    a = [ 4.16, 0, 0, 0;
         -3.12, 5.03, 0, 0;
          0.56, -0.83, 0.76, 0;
         -0.10, 1.18, 0.34, 1.18];
```

```

[L, info] = f07fd( ...
                uplo, a);

% Rhs
b = [ 8.70, 8.30;
     -13.35, 2.13;
       1.89, 1.61;
     -4.14, 5.00];

% Solve
[x, info] = f07fe( ...
                uplo, L, b);

% Refine
[x, ferr, berr, info] = f07fh( ...
                            uplo, a, L, b, x);

[ifail] = x04ca( ...
                'General', 'N', x, 'Solution(s)');

fprintf('\nBackward errors (machine-dependent)\n  ')
fprintf('%11.1e', berr);
fprintf('\nEstimated forward error bounds (machine-dependent)\n  ')
fprintf('%11.1e', ferr);
fprintf('\n');

```

9.2 Program Results

f07fh example results

Solution(s)		
	1	2
1	1.0000	4.0000
2	-1.0000	3.0000
3	2.0000	2.0000
4	-3.0000	1.0000

Backward errors (machine-dependent)		
	1.0e-16	5.0e-17
Estimated forward error bounds (machine-dependent)		
	2.3e-14	2.3e-14
