

NAG Toolbox

nag_linsys_real_gen_norm_rcomm (f04yd)

1 Purpose

nag_linsys_real_gen_norm_rcomm (f04yd) estimates the 1-norm of a real rectangular matrix without accessing the matrix explicitly. It uses reverse communication for evaluating matrix products. The function may be used for estimating condition numbers of square matrices.

2 Syntax

```
[irevcm, x, y, estnrm, work, iwork, ifail] = nag_linsys_real_gen_norm_rcomm
(irevcm, x, y, estnrm, seed, work, iwork, 'm', m, 'n', n, 't', t)

[irevcm, x, y, estnrm, work, iwork, ifail] = f04yd(irevcm, x, y, estnrm, seed,
work, iwork, 'm', m, 'n', n, 't', t)
```

3 Description

nag_linsys_real_gen_norm_rcomm (f04yd) computes an estimate (a lower bound) for the 1-norm

$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}| \quad (1)$$

of an m by n real matrix $A = (a_{ij})$. The function regards the matrix A as being defined by a user-supplied ‘Black Box’ which, given an $n \times t$ matrix X (with $t \ll n$) or an $m \times t$ matrix Y , can return AX or $A^T Y$. A reverse communication interface is used; thus control is returned to the calling program whenever a matrix product is required.

Note: this function is **not recommended** for use when the elements of A are known explicitly; it is then more efficient to compute the 1-norm directly from formula (1) above.

The **main use** of the function is for estimating $\|B^{-1}\|_1$ for a square matrix, B , and hence the **condition number** $\kappa_1(B) = \|B\|_1 \|B^{-1}\|_1$, without forming B^{-1} explicitly ($A = B^{-1}$ above).

If, for example, an LU factorization of B is available, the matrix products $B^{-1}X$ and $B^{-T}Y$ required by nag_linsys_real_gen_norm_rcomm (f04yd) may be computed by back- and forward-substitutions, without computing B^{-1} .

The function can also be used to estimate 1-norms of matrix products such as $A^{-1}B$ and ABC , without forming the products explicitly. Further applications are described by Higham (1988).

Since $\|A\|_\infty = \|A^T\|_1$, nag_linsys_real_gen_norm_rcomm (f04yd) can be used to estimate the ∞ -norm of A by working with A^T instead of A .

The algorithm used is described in Higham and Tisseur (2000).

4 References

Higham N J (1988) FORTRAN codes for estimating the one-norm of a real or complex matrix, with applications to condition estimation *ACM Trans. Math. Software* **14** 381–396

Higham N J and Tisseur F (2000) A block algorithm for matrix 1-norm estimation, with an application to 1-norm pseudospectra *SIAM J. Matrix. Anal. Appl.* **21** 1185–1201

5 Parameters

Note: this function uses **reverse communication**. Its use involves an initial entry, intermediate exits and re-entries, and a final exit, as indicated by the argument **irevcn**. Between intermediate exits and re-entries, **all arguments other than x and y must remain unchanged**.

5.1 Compulsory Input Parameters

1: **irevcn** – INTEGER

On initial entry: must be set to 0.

On intermediate re-entry: **irevcn** must be unchanged.

2: **x**(*ldx*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **x** must be at least **n**.

The second dimension of the array **x** must be at least $\max(1, \mathbf{t})$.

On initial entry: need not be set.

On intermediate re-entry: if **irevcn** = 2, must contain $A^T Y$.

3: **y**(*ldy*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **y** must be at least **m**.

The second dimension of the array **y** must be at least $\max(1, \mathbf{t})$.

On initial entry: need not be set.

On intermediate re-entry: if **irevcn** = 1, must contain AX .

4: **estnrm** – REAL (KIND=nag_wp)

On initial entry: need not be set.

On intermediate re-entry: must not be changed.

5: **seed** – INTEGER

The seed used for random number generation.

If **t** = 1, **seed** is not used.

Constraint: if **t** > 1, **seed** ≥ 1.

6: **work**(**m** × **t**) – REAL (KIND=nag_wp) array

7: **iwork**(**2** × **n** + **5** × **t** + **20**) – INTEGER array

On initial entry: need not be set.

On intermediate re-entry: must not be changed.

5.2 Optional Input Parameters

1: **m** – INTEGER

Default: the first dimension of the arrays **y**, **work**. (An error is raised if these dimensions are not equal.)

The number of rows of the matrix A .

Constraint: **m** ≥ 0.

2: **n** – INTEGER

Default: the first dimension of the array **x** and the dimension of the array **iwork**. (An error is raised if these dimensions are not equal.)

n, the number of columns of the matrix *A*.

Constraint: $n \geq 0$.

3: **t** – INTEGER

Suggested value: $t = 2$.

Default: $t = 2$

Default: the second dimension of the arrays **x**, **y**. (An error is raised if these dimensions are not equal.)

The number of columns *t* of the matrices *X* and *Y*. This is a argument that can be used to control the accuracy and reliability of the estimate and corresponds roughly to the number of columns of *A* that are visited during each iteration of the algorithm.

If $t \geq 2$ then a partly random starting matrix is used in the algorithm.

Constraint: $1 \leq t \leq m$.

5.3 Output Parameters

1: **irevcn** – INTEGER

On intermediate exit: **irevcn** = 1 or 2, and **x** contains the $n \times t$ matrix *X* and **y** contains the $m \times t$ matrix *Y*. The calling program must

- (a) if **irevcn** = 1, evaluate AX and store the result in **y**
or
if **irevcn** = 2, evaluate $A^T Y$ and store the result in **x**,

- (b) call nag_linsys_real_gen_norm_rcomm (f04yd) once again, with all the other arguments unchanged.

On final exit: **irevcn** = 0.

2: **x**(*ldx*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **x** will be **n**.

The second dimension of the array **x** will be $\max(1, t)$.

On intermediate exit: if **irevcn** = 1, contains the current matrix *X*.

On final exit: the array is undefined.

3: **y**(*ldy*,:) – REAL (KIND=nag_wp) array

The first dimension of the array **y** will be **m**.

The second dimension of the array **y** will be $\max(1, t)$.

On intermediate exit: if **irevcn** = 2, contains the current matrix *Y*.

On final exit: the array is undefined.

4: **estnrm** – REAL (KIND=nag_wp)

On final exit: an estimate (a lower bound) for $\|A\|_1$.

5: **work**($\mathbf{m} \times \mathbf{t}$) – REAL (KIND=nag_wp) array

6: **iwor**k($2 \times \mathbf{n} + 5 \times \mathbf{t} + 20$) – INTEGER array

7: **ifail** – INTEGER

On final exit: **ifail** = 0 unless the function detects an error (see Section 5).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

Internal error; please contact NAG.

ifail = -1

Constraint: **irevc**m = 0, 1 or 2.

On initial entry, **irevc**m = *value*.

Constraint: **irevc**m = 0.

ifail = -2

Constraint: **m** \geq 0.

ifail = -3

Constraint: **n** \geq 0.

ifail = -5

Constraint: *ldx* \geq **n**.

ifail = -7

Constraint: *ldy* \geq **m**.

ifail = -9

Constraint: $1 \leq \mathbf{t} \leq \mathbf{m}$.

ifail = -10

Constraint: if **t** > 1, **seed** \geq 1.

ifail = -99

An unexpected error has been triggered by this routine. Please contact NAG.

ifail = -399

Your licence key may have expired or may not have been installed correctly.

ifail = -999

Dynamic memory allocation failed.

7 Accuracy

In extensive tests on **random** matrices of size up to $m = n = 450$ the estimate **estnrm** has been found always to be within a factor two of $\|A\|_1$; often the estimate has many correct figures. However, matrices exist for which the estimate is smaller than $\|A\|_1$ by an arbitrary factor; such matrices are very unlikely to arise in practice. See Higham and Tisseur (2000) for further details.

8 Further Comments

8.1 Timing

For most problems the time taken during calls to `nag_linsys_real_gen_norm_rcomm` (f04yd) will be negligible compared with the time spent evaluating matrix products between calls to `nag_linsys_real_gen_norm_rcomm` (f04yd).

The number of matrix products required depends on the matrix A . At most six products of the form $Y = AX$ and five products of the form $X = A^T Y$ will be required. The number of iterations is independent of the choice of t .

8.2 Overflow

It is your responsibility to guard against potential overflows during evaluation of the matrix products. In particular, when estimating $\|B^{-1}\|_1$ using a triangular factorization of B , `nag_linsys_real_gen_norm_rcomm` (f04yd) should not be called if one of the factors is exactly singular – otherwise division by zero may occur in the substitutions.

8.3 Choice of t

The argument t controls the accuracy and reliability of the estimate. For $t = 1$, the algorithm behaves similarly to the LAPACK estimator xLACON. Increasing t typically improves the estimate, without increasing the number of iterations required.

For $t \geq 2$, random matrices are used in the algorithm, so for repeatable results the same value of `seed` should be used each time.

A value of $t = 2$ is recommended for new users.

8.4 Use in Conjunction with NAG Library Routines

To estimate the 1-norm of the inverse of a matrix A , the following skeleton code can normally be used:

```
... code to factorize A ...
if (A is not singular)
  icode = 0;
  [icode, x, estnrm, work, iwork, ifail] = f04yd(icode, x, estnrm, work,
iwork);
  while (icode /= 0)
    if (icode == 1)
      ... code to compute inv(A)*x ...
    else
      ... code to compute inv(transpose(A))*x ...
    end
  [icode, x, estnrm, work, iwork, ifail] = f04yd(icode, x, estnrm, work,
iwork);
end
end
```

To compute $A^{-1}X$ or $A^{-T}Y$, solve the equation $AY = X$ or $A^T X = Y$, storing the result in y or x respectively. The code will vary, depending on the type of the matrix A , and the NAG function used to factorize A .

The factorization will normally have been performed by a suitable function from Chapters F01, F03 or F07. Note also that many of the ‘Black Box’ functions in Chapter F04 for solving systems of equations also return a factorization of the matrix. The example program in Section 10 illustrates how `nag_linsys_real_gen_norm_rcomm` (f04yd) can be used in conjunction with NAG Toolbox functions for LU factorization of a real matrix `nag_lapack_dgetrf` (f07ad).

It is straightforward to use `nag_linsys_real_gen_norm_rcomm` (f04yd) for the following other types of matrix, using the named functions for factorization and solution:

nonsymmetric tridiagonal (nag_matop_real_gen_tridiag_lu (f01le) and nag_linsys_real_tridiag_fac_solve (f04le));

nonsymmetric almost block-diagonal (nag_matop_real_gen_blkdiag_lu (f01lh) and nag_linsys_real_blkdiag_fac_solve (f04lh));

nonsymmetric band (nag_lapack_dgbtrf (f07bd) and nag_lapack_dgbtrs (f07be));

symmetric positive definite (nag_lapack_dpotrf (f07fd) and nag_lapack_dpotsr (f07fe));

symmetric positive definite band (nag_lapack_dpbtrf (f07hd) and nag_lapack_dpbtrs (f07he));

symmetric positive definite tridiagonal (nag_lapack_dptsv (f07ja), nag_lapack_dpttrf (f07jd) and nag_lapack_dpttrs (f07je));

symmetric positive definite variable bandwidth (nag_matop_real_vband_posdef_fac (f01mc) and nag_linsys_real_posdef_vband_solve (f04mc));

symmetric positive definite sparse (nag_sparse_real_symm_precon_ichol (f11ja) and nag_sparse_real_symm_precon_ichol_solve (f11jb));

symmetric indefinite (nag_lapack_dsprtf (f07pd) and nag_lapack_dsptrs (f07pe));

nonsymmetric sparse (nag_sparse_direct_real_gen_lu (f11me) and nag_sparse_direct_real_gen_solve (f11mf); note that nag_sparse_direct_real_gen_cond (f11mg) can also be used here).

9 Example

For this function two examples are provided. There is a single example program for nag_linsys_real_gen_norm_rcomm (f04yd), with a main program and the code to solve the two example problems is given in Example 1 (EX1) and Example 2 (EX2).

Example 1 (EX1)

This example estimates the condition number $\|A\|_1 \|A^{-1}\|_1$ of the matrix A given by

$$A = \begin{pmatrix} 0.7 & -0.2 & 1.0 & 0.0 & 2.0 & 0.1 \\ 0.3 & 0.7 & 0.0 & 1.0 & 0.9 & 0.2 \\ 0.0 & 0.0 & 0.2 & 0.7 & 0.0 & -1.1 \\ 0.0 & 3.4 & -0.7 & 0.2 & 0.1 & 0.1 \\ 0.0 & -4.0 & 0.0 & 1.0 & 9.0 & 0.0 \\ 0.4 & 1.2 & 4.3 & 0.0 & 6.2 & 5.9 \end{pmatrix}.$$

Example 2 (EX2)

This example estimates the condition number of the sparse matrix A (stored in symmetric coordinate storage format) given by

$$A = \begin{pmatrix} 0.0 & 0.0 & 0.0 & 1.0 & 0.0 \\ 3.0 & 1.0 & 0.0 & 0.0 & 0.0 \\ 0.0 & 2.0 & 0.0 & 2.0 & 0.0 \\ 2.0 & 0.0 & 4.0 & 0.0 & 5.0 \\ 0.0 & 1.0 & 2.0 & 0.0 & 0.0 \end{pmatrix}.$$

9.1 Program Text

```
function f04yd_example

fprintf('f04yd example results\n\n');

% Example 1: Compute the condition number of a dense matrix
fprintf('\nExample 1\n');

a = [0.7, -0.2, 1.0, 0.0, 2.0, 0.1;
     0.3, 0.7, 0.0, 1.0, 0.9, 0.2;
     0.0, 0.0, 0.2, 0.7, 0.0, -1.1;
     0.0, 3.4, -0.7, 0.2, 0.1, 0.1;
     0.0, -4.0, 0.0, 1.0, 9.0, 0.0;
```

```

    0.4, 1.2, 4.3, 0.0, 6.2, 5.9];
t = nag_int(2);
m = 6;
n = 6;
x = zeros(n, t);
y = zeros(m, t);
estnrm = 0;
seed = nag_int(354);
irevcm = nag_int(0);
work = zeros(n*t, 1);
iwork = zeros(2*n+5*t+20, 1, nag_int_name);

nrma = norm(a, 1);
fprintf('\nThe norm of a is %6.2f\n', nrma);

% Estimate the norm of a(-1) without explicitly forming a(-1)

% Perform an LU factorization so that A=LU where L and U are lower and upper
% triangular.
[a, ipiv, info] = f07ad(a);

first = true;

while first || (irevcm ~= 0)
    first = false;

    [irevcm, x, y, estnrm, work, iwork, ifail] = ...
        f04yd( ...
            irevcm, x, y, estnrm, seed, work, iwork);

    switch irevcm
        case 1
            % Compute y = inv(a)*x
            [y, info] = f07ae('n', a, ipiv, x);
        case 2
            % Compute x = transpose(inv(a))*y
            [x, info] = f07ae('t', a, ipiv, y);
        otherwise
            end
    end
end

fprintf('The estimated norm of inverse(a) is: %6.2f\n', estnrm);
fprintf('\nEstimated condition number of a: %6.2f\n', estnrm*nrma);

% Example 2: Compute the condition number of a sparse matrix
% (stored in symmetric coordinate storage format)
fprintf('\nExample 2\n');

t = nag_int(2);
n = nag_int(5);
nz = nag_int(10);
a = zeros(4*nz, 1);
icn = zeros(4*nz, 1, nag_int_name);
irn = zeros(4*nz, 1, nag_int_name);
a(1:nz) = [3; 2; 1; 2; 1; 4; 2; 1; 2; 5];
irn(1:nz) = [2; 4; 2; 3; 5; 4; 5; 1; 3; 4];
icn(1:nz) = [1; 1; 2; 2; 2; 3; 3; 4; 4; 5];

x = zeros(n, t);
y = zeros(n, t);
estnrm = 0;
seed = nag_int(412);
irevcm = nag_int(0);
work = zeros(n*t, 1);
iwork = zeros(2*n+5*t+20, 1, nag_int_name);

% Compute 1-norm of a
nrma = 0;
for i = 1:n
    asum = 0;
    for j = 1:nz

```

```

        if (icn(j)==i)
            asum = asum + abs(a(j));
        end
    end
    nrma = max(nrma,asum);
end

fprintf('\nThe norm of a is %6.2f\n', nrma);

% Perform an LU factorization so that A=LU where L and U are lower and upper
% triangular.
abort = [true; true; false; false];
[a, irn, icn, ikeep, w, idisp, ifail] = ...
    f0lbr(n, nz, a, irn, icn, abort);

% Compute an estimate of the 1-norm of inv(a)

first = true;

while first || (irevcm ~= 0)
    first = false;

    [irevcm, x, y, estnrm, work, iwork, ifail] = ...
        f04yd( ...
            irevcm, x, y, estnrm, seed, work, iwork);

    switch irevcm
        case 1
            % Compute y = inv(a)*x
            for i=1:2
                [y(:, i), resid] = f04ax( ...
                    a, icn, ikeep, x(:, i), irevcm, idisp);
            end
        case 2
            % Compute x = transpose(inv(a))*y
            for i=1:2
                [x(:, i), resid] = f04ax( ...
                    a, icn, ikeep, y(:, i), irevcm, idisp);
            end
        otherwise
            end
    end
end

fprintf('The estimated norm of inverse(a) is: %6.2f\n', estnrm);
fprintf('\nEstimated condition number of a: %6.2f\n', estnrm*nrma);

```

9.2 Program Results

f04yd example results

Example 1

```

The norm of a is 18.20
The estimated norm of inverse(a) is: 2.97

Estimated condition number of a: 54.14

```

Example 2

```

The norm of a is 6.00
The estimated norm of inverse(a) is: 3.37

Estimated condition number of a: 20.20

```
