

NAG Toolbox

nag_matop_real_gen_blkdiag_lu (f01lh)

1 Purpose

nag_matop_real_gen_blkdiag_lu (f01lh) factorizes a real almost block diagonal matrix.

2 Syntax

```
[a, pivot, tol, kpivot, ifail] = nag_matop_real_gen_blkdiag_lu(n, blkstr, a,
tol, 'nbloks', nbloks, 'lena', lena)
```

```
[a, pivot, tol, kpivot, ifail] = f01lh(n, blkstr, a, tol, 'nbloks', nbloks,
'lena', lena)
```

3 Description

nag_matop_real_gen_blkdiag_lu (f01lh) factorizes a real almost block diagonal matrix, A , by row elimination with alternate row and column pivoting such that no ‘fill-in’ is produced. The code, which is derived from ARCECO described in Diaz *et al.* (1983), uses Level 1 and Level 2 BLAS. No three successive diagonal blocks may have columns in common and therefore the almost block diagonal matrix must have the form shown in the following diagram:

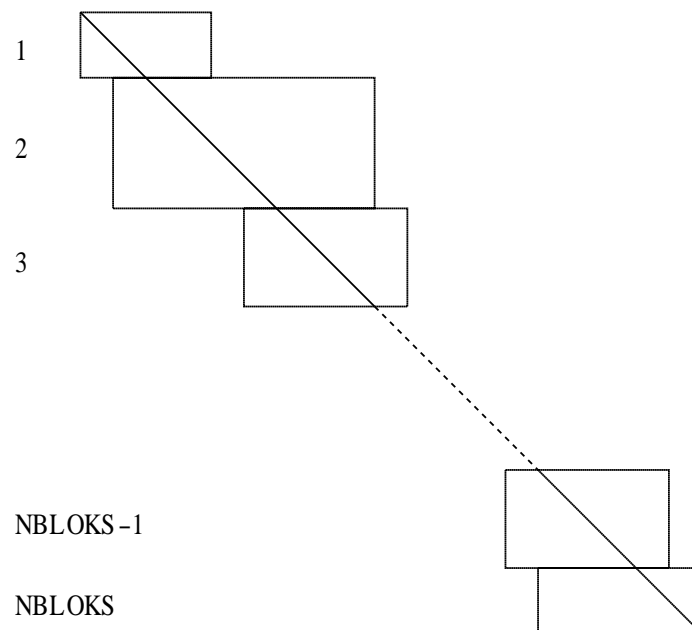


Figure 1

This function may be followed by nag_linsys_real_blkdiag_fac_solve (f04lh), which is designed to solve sets of linear equations $AX = B$ or $A^T X = B$.

4 References

Diaz J C, Fairweather G and Keast P (1983) Fortran packages for solving certain almost block diagonal linear systems by modified alternate row and column elimination *ACM Trans. Math. Software* **9** 358–375

5 Parameters

5.1 Compulsory Input Parameters

1: **n** – INTEGER

n , the order of the matrix A .

Constraint: $n > 0$.

2: **blkstr(3, nbloks)** – INTEGER array

Information which describes the block structure of A as follows:

blkstr(1, k) must contain the number of rows in the k th block, $k = 1, 2, \dots, \mathbf{nbloks}$;

blkstr(2, k) must contain the number of columns in the k th block, $k = 1, 2, \dots, \mathbf{nbloks}$;

blkstr(3, k) must contain the number of columns of overlap between the k th and $(k + 1)$ th blocks, $k = 1, 2, \dots, \mathbf{nbloks} - 1$. **blkstr(3, \mathbf{nbloks})** need not be set.

The following conditions delimit the structure of A :

blkstr(1, k), blkstr(2, k) > 0 , $k = 1, 2, \dots, \mathbf{nbloks}$,

blkstr(3, k) ≥ 0 , $k = 1, 2, \dots, \mathbf{nbloks} - 1$,

(there must be at least one column and one row in each block and a non-negative number of columns of overlap);

blkstr(3, $k - 1$) + blkstr(3, k) \leq **blkstr(2, k)**, $k = 2, 3, \dots, \mathbf{nbloks} - 1$,

(the total number of columns in overlaps in each block must not exceed the number of columns in that block);

blkstr(2, 1) \geq **blkstr(1, 1)**,

$$\mathbf{blkstr}(2, 1) + \sum_{k=2}^j [\mathbf{blkstr}(2, k) - \mathbf{blkstr}(3, k - 1)] \geq \sum_{k=1}^j \mathbf{blkstr}(1, k),$$

$j = 2, 3, \dots, \mathbf{nbloks} - 1$,

$$\sum_{k=1}^j [\mathbf{blkstr}(2, k) - \mathbf{blkstr}(3, k)] \leq \sum_{k=1}^j \mathbf{blkstr}(1, k), \quad j = 1, 2, \dots, \mathbf{nbloks} - 1,$$

(the index of the first column of the overlap between the j th and $(j + 1)$ th blocks must be \leq the index of the last row of the j th block, and the index of the last column of overlap must be \geq the index of the last row of the j th block);

$$\sum_{k=1}^{\mathbf{nbloks}} \mathbf{blkstr}(1, k) = n,$$

$$\mathbf{blkstr}(2, 1) + \sum_{k=2}^{\mathbf{nbloks}} [\mathbf{blkstr}(2, k) - \mathbf{blkstr}(3, k - 1)] = nk,$$

(both the number of rows and the number of columns of A must equal n).

3: **a(lena)** – REAL (KIND=nag_wp) array

The elements of the almost block diagonal matrix stored block by block, with each block stored column by column. The sizes of the blocks and the overlaps are defined by the argument **blkstr**.

If a_{rs} is the first element in the k th block, then an arbitrary element a_{ij} in the k th block must be stored in the array element:

$$\mathbf{a}(p_k + (j - r)m_k + (i - s) + 1)$$

where

$$p_k = \sum_{l=1}^{k-1} \mathbf{blkstr}(1, l) \times \mathbf{blkstr}(2, l)$$

is the base address of the k th block, and

$$m_k = \mathbf{blkstr}(1, k)$$

is the number of rows of the k th block.

See Section 9 for comments on scaling.

4: **tol** – REAL (KIND=nag_wp)

A relative tolerance to be used to indicate whether or not the matrix is singular. For a discussion on how **tol** is used see Section 9. If **tol** is non-positive, then **tol** is reset to 10ϵ , where ϵ is the *machine precision*.

5.2 Optional Input Parameters

1: **nbloks** – INTEGER

Default: the dimension of the array **blkstr**.

n , the total number of blocks of the matrix A .

Constraint: $0 < \mathbf{nbloks} \leq n$.

2: **lena** – INTEGER

Default: the dimension of the array **a**.

The dimension of the array **a**.

Constraint: $\mathbf{lena} \geq \sum_{k=1}^{\mathbf{nbloks}} [\mathbf{blkstr}(1, k) \times \mathbf{blkstr}(2, k)]$.

5.3 Output Parameters

1: **a(lena)** – REAL (KIND=nag_wp) array

The factorized form of the matrix.

2: **pivot(n)** – INTEGER array

Details of the interchanges.

3: **tol** – REAL (KIND=nag_wp)

Unchanged unless **tol** ≤ 0.0 on entry, in which case it is set to 10ϵ .

4: **kpivot** – INTEGER

If **ifail** = 2, **kpivot** contains the value k , where k is the first position on the diagonal of the matrix A where too small a pivot was detected. Otherwise **kpivot** is set to 0.

5: **ifail** – INTEGER

ifail = 0 unless the function detects an error (see Section 5).

$$b = \begin{pmatrix} -2.92 \\ -1.17 \\ -1.30 \\ -1.17 \\ -2.10 \\ -4.51 \\ -1.71 \\ -4.59 \\ -4.19 \\ -0.93 \\ -3.31 \\ 0.52 \\ -0.12 \\ -0.05 \\ -0.98 \\ -2.07 \\ -2.73 \\ -1.95 \end{pmatrix}$$

The exact solution is

$$x = (1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1)^T.$$

9.1 Program Text

```
function f01lh_example

fprintf('f01lh example results\n\n');

% Block structure of A
n = nag_int(18);
blkstr = [nag_int(2),4,5,3,4;
          4, 7,8,6,5;
          3, 4,2,3,0];

a1 = [-1.00 -0.98 -0.79 -0.15;
      -1.00  0.25 -0.87  0.35];
a2 = [ 0.78  0.31 -0.85  0.89 -0.69 -0.98 -0.76;
      -0.82  0.12 -0.01  0.75  0.32 -1.00 -0.53;
      -0.83 -0.98 -0.58  0.04  0.87  0.38 -1.00;
      -0.21 -0.93 -0.84  0.37 -0.94 -0.96 -1.00];
a3 = [-0.99 -0.91 -0.28  0.90  0.78 -0.93 -0.76  0.48;
      -0.87 -0.14 -1.00 -0.59 -0.99  0.21 -0.73 -0.48;
      -0.93 -0.91  0.10 -0.89 -0.68 -0.09 -0.58 -0.21;
      0.85 -0.39  0.79 -0.71  0.39 -0.99 -0.12 -0.75;
      0.17 -1.37  1.29 -1.59  1.10 -1.63 -1.01 -0.27];
a4 = [ 0.08  0.61  0.54 -0.41  0.16 -0.46;
      -0.67  0.56 -0.99  0.16 -0.16  0.98;
      -0.24 -0.41  0.40 -0.93  0.70  0.43];
a5 = [ 0.71 -0.97 -0.60 -0.30  0.18;
      -0.47 -0.98 -0.73  0.07  0.04;
      -0.25 -0.92 -0.52 -0.46 -0.58;
      0.89 -0.94 -0.54 -1.00 -0.36];

% Flatten A
a = [reshape(a1,[ 8,1]);
     reshape(a2,[28,1]);
     reshape(a3,[40,1]);
     reshape(a4,[18,1]);
     reshape(a5,[20,1])];

% Right hand side
b = [-2.92; -1.27; -1.30; -1.17; -2.10; -4.51; -1.71; -4.59;
     -4.19; -0.93; -3.31;  0.52; -0.12; -0.05; -0.98; -2.07;
     -2.73; -1.95];

% Factorize A
tol = 0;
[AF, pivot, tol, index, ifail] = ...
f01lh(n, blkstr, a, tol);

% Solve system
trans = 'N';
[x, ifail] = f04lh( ...
    trans, blkstr, AF, pivot, b);
disp('Component solution');
disp(x);
```

9.2 Program Results

f01lh example results

Component solution

```
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000  
1.0000
```
