

NAG Toolbox

nag_opt_lsq_uncon_covariance (e04yc)

1 Purpose

nag_opt_lsq_uncon_covariance (e04yc) returns estimates of elements of the variance-covariance matrix of the estimated regression coefficients for a nonlinear least squares problem. The estimates are derived from the Jacobian of the function $f(x)$ at the solution.

This function may be used following any one of the nonlinear least squares functions nag_opt_lsq_uncon_mod_func_comp (e04fc), nag_opt_lsq_uncon_mod_func_easy (e04fy), nag_opt_lsq_uncon_quasi_deriv_comp (e04gb), nag_opt_lsq_uncon_mod_deriv_comp (e04gd), nag_opt_lsq_uncon_quasi_deriv_easy (e04gy), nag_opt_lsq_uncon_mod_deriv_easy (e04gz), nag_opt_lsq_uncon_mod_deriv2_comp (e04he) or nag_opt_lsq_uncon_mod_deriv2_easy (e04hy).

2 Syntax

```
[v, cj, ifail] = nag_opt_lsq_uncon_covariance(job, m, fsumsq, s, v, 'n', n)
```

```
[v, cj, ifail] = e04yc(job, m, fsumsq, s, v, 'n', n)
```

3 Description

nag_opt_lsq_uncon_covariance (e04yc) is intended for use when the nonlinear least squares function, $F(x) = f^T(x)f(x)$, represents the goodness-of-fit of a nonlinear model to observed data. The function assumes that the Hessian of $F(x)$, at the solution, can be adequately approximated by $2J^T J$, where J is the Jacobian of $f(x)$ at the solution. The estimated variance-covariance matrix C is then given by

$$C = \sigma^2 (J^T J)^{-1}, \quad J^T J \text{ nonsingular,}$$

where σ^2 is the estimated variance of the residual at the solution, \bar{x} , given by

$$\sigma^2 = \frac{F(\bar{x})}{m - n},$$

m being the number of observations and n the number of variables.

The diagonal elements of C are estimates of the variances of the estimated regression coefficients. See the E04 Chapter Introduction, Bard (1974) and Wolberg (1967) for further information on the use of C .

When $J^T J$ is singular then C is taken to be

$$C = \sigma^2 (J^T J)^\dagger,$$

where $(J^T J)^\dagger$ is the pseudo-inverse of $J^T J$, and

$$\sigma^2 = \frac{F(\bar{x})}{m - k}, \quad k = \text{rank}(J)$$

but in this case the argument **ifail** is returned as nonzero as a warning to you that J has linear dependencies in its columns. The assumed rank of J can be obtained from **ifail**.

The function can be used to find either the diagonal elements of C , or the elements of the j th column of C , or the whole of C .

nag_opt_lsq_uncon_covariance (e04yc) must be preceded by one of the nonlinear least squares functions mentioned in Section 1, and requires the arguments **fsumsq**, **s** and **v** to be supplied by those functions (e.g., see nag_opt_lsq_uncon_mod_func_comp (e04fc)). **fsumsq** is the residual sum of squares $F(\bar{x})$ and **s** and **v** contain the singular values and right singular vectors respectively in the singular value decomposition of J . **s** and **v** are returned directly by the comprehensive functions

nag_opt_lsq_uncon_mod_func_comp (e04fc), nag_opt_lsq_uncon_quasi_deriv_comp (e04gb), nag_opt_lsq_uncon_mod_deriv_comp (e04gd) and nag_opt_lsq_uncon_mod_deriv2_comp (e04he), but are returned as part of the workspace argument **w** (from one of the easy-to-use functions). In the case of nag_opt_lsq_uncon_mod_func_easy (e04fy), **s** starts at **w**(*ns*), where

$$ns = 6 \times n + 2 \times m + m \times n + 1 + \max(1, n \times (n - 1)/2)$$

and in the cases of the remaining easy-to-use functions, **s** starts at **w**(*ns*), where

$$ns = 7 \times n + 2 \times m + m \times n + n \times (n + 1)/2 + 1 + \max(1, n \times (n - 1)/2).$$

The argument **v** starts immediately following the elements of **s**, so that **v** starts at **w**(*nv*), where

$$nv = ns + n.$$

For all the easy-to-use functions the argument *ldv* must be supplied as **n**. Thus a call to nag_opt_lsq_uncon_covariance (e04yc) following nag_opt_lsq_uncon_mod_func_easy (e04fy) can be illustrated as

```
.
.
[x, fsumsq, user, ifail] = e04fy(m, lsfun1, x);
.
.
ns = 6*n + 2*m + m*n + 1 + max((1, (n*(n-1))/2));
nv = ns + n;
[v, cj, ifail] = e04yc(job, m, fsumsq, w(ns:nv-1), w(nv:numel(w)));
```

where the arguments **m**, **n**, **fsumsq** and the $(n + n^2)$ elements **w**(*ns*), **w**(*ns* + 1), ..., **w**(*nv* + n^2 - 1) must not be altered between the calls to nag_opt_lsq_uncon_mod_func_easy (e04fy) and nag_opt_lsq_uncon_covariance (e04yc). The above illustration also holds for a call to nag_opt_lsq_uncon_covariance (e04yc) following a call to one of nag_opt_lsq_uncon_quasi_deriv_easy (e04gy), nag_opt_lsq_uncon_mod_deriv_easy (e04gz) or nag_opt_lsq_uncon_mod_deriv2_easy (e04hy), except that *ns* must be computed as

$$ns = 7 \times n + 2 \times m + m \times n + (n \times (n + 1))/2 + 1 + \max((1, n \times (n - 1))/2).$$

4 References

Bard Y (1974) *Nonlinear Parameter Estimation* Academic Press

Wolberg J R (1967) *Prediction Analysis* Van Nostrand

5 Parameters

5.1 Compulsory Input Parameters

1: **job** – INTEGER

Which elements of *C* are returned as follows:

job = -1

The *n* by *n* symmetric matrix *C* is returned.

job = 0

The diagonal elements of *C* are returned.

job > 0

The elements of column **job** of *C* are returned.

Constraint: $-1 \leq \mathbf{job} \leq n$.

2: **m** – INTEGER

The number m of observations (residuals $f_i(x)$).

Constraint: $\mathbf{m} \geq \mathbf{n}$.

3: **fsumsq** – REAL (KIND=nag_wp)

The sum of squares of the residuals, $F(\bar{x})$, at the solution \bar{x} , as returned by the nonlinear least squares function.

Constraint: **fsumsq** \geq 0.0.

4: **s(n)** – REAL (KIND=nag_wp) array

The n singular values of the Jacobian as returned by the nonlinear least squares function. See Section 3 for information on supplying **s** following one of the easy-to-use functions.

5: **v(ldv, n)** – REAL (KIND=nag_wp) array

ldv , the first dimension of the array, must satisfy the constraint if **job** = -1, $ldv \geq \mathbf{n}$.

The n by n right-hand orthogonal matrix (the right singular vectors) of J as returned by the nonlinear least squares function. See Section 3 for information on supplying **v** following one of the easy-to-use functions.

5.2 Optional Input Parameters

1: **n** – INTEGER

Default: the dimension of the array **s** and the second dimension of the array **v**. (An error is raised if these dimensions are not equal.)

The number n of variables (x_j).

Constraint: $1 \leq \mathbf{n} \leq \mathbf{m}$.

5.3 Output Parameters

1: **v(ldv, n)** – REAL (KIND=nag_wp) array

If **job** \geq 0, **v** is unchanged.

If **job** = -1, the leading n by n part of **v** stores the n by n matrix C . When nag_opt_lsq_uncon_covariance (e04yc) is called with **job** = -1 following an easy-to-use function this means that C is returned, column by column, in the n^2 elements of **w** given by **w(nv)**, **w(nv + 1)**, ..., **w(nv + n² - 1)**. (See Section 3 for the definition of nv .)

2: **cj(n)** – REAL (KIND=nag_wp) array

If **job** = 0, **cj** returns the n diagonal elements of C .

If **job** = $j > 0$, **cj** returns the n elements of the j th column of C .

If **job** = -1, **cj** is not referenced.

3: **ifail** – INTEGER

ifail = 0 unless the function detects an error (see Section 5).

6 Error Indicators and Warnings

Note: nag_opt_lsq_uncon_covariance (e04yc) may return useful information for one or more of the following detected errors or warnings.

Errors or warnings detected by the function:

ifail = 1

On entry, **job** < -1,
 or **job** > **n**,
 or **n** < 1,
 or **m** < **n**,
 or **fsumsq** < 0.0,
 or *ldv* < **n**.

ifail = 2 (*warning*)

The singular values are all zero, so that at the solution the Jacobian matrix J has rank 0.

ifail > 2 (*warning*)

At the solution the Jacobian matrix contains linear, or near linear, dependencies amongst its columns. In this case the required elements of C have still been computed based upon J having an assumed rank given by **ifail** - 2. The rank is computed by regarding singular values $SV(j)$ that are not larger than $10\epsilon \times SV(1)$ as zero, where ϵ is the *machine precision* (see `nag_machine_precision` (x02aj)). If you expect near linear dependencies at the solution and are happy with this tolerance in determining rank you should call `nag_opt_lsq_uncon_covariance` (e04yc) with **ifail** = 1 in order to prevent termination. It is then essential to test the value of **ifail** on exit from `nag_opt_lsq_uncon_covariance` (e04yc).

Overflow

If overflow occurs then either an element of C is very large, or the singular values or singular vectors have been incorrectly supplied.

ifail = -99

An unexpected error has been triggered by this routine. Please contact NAG.

ifail = -399

Your licence key may have expired or may not have been installed correctly.

ifail = -999

Dynamic memory allocation failed.

7 Accuracy

The computed elements of C will be the exact covariances corresponding to a closely neighbouring Jacobian matrix J .

8 Further Comments

When **job** = -1 the time taken by `nag_opt_lsq_uncon_covariance` (e04yc) is approximately proportional to n^3 . When **job** \geq 0 the time taken by the function is approximately proportional to n^2 .

9 Example

This example estimates the variance-covariance matrix C for the least squares estimates of x_1 , x_2 and x_3 in the model

$$y = x_1 + \frac{t_1}{x_2 t_2 + x_3 t_3}$$

using the 15 sets of data given in the following table:

y	t_1	t_2	t_3
0.14	1.0	15.0	1.0
0.18	2.0	14.0	2.0
0.22	3.0	13.0	3.0
0.25	4.0	12.0	4.0
0.29	5.0	11.0	5.0
0.32	6.0	10.0	6.0
0.35	7.0	9.0	7.0
0.39	8.0	8.0	8.0
0.37	9.0	7.0	7.0
0.58	10.0	6.0	6.0
0.73	11.0	5.0	5.0
0.96	12.0	4.0	4.0
1.34	13.0	3.0	3.0
2.10	14.0	2.0	2.0
4.39	15.0	1.0	1.0

The program uses (0.5, 1.0, 1.5) as the initial guess at the position of the minimum and computes the least squares solution using `nag_opt_lsq_uncon_mod_func_easy` (e04fy). See the function document `nag_opt_lsq_uncon_mod_func_easy` (e04fy) for further information.

9.1 Program Text

```
function e04yc_example

fprintf('e04yc example results\n\n');

global y t;

% Fit data
n = 3;
m = nag_int(15);
y = [0.14, 0.18, 0.22, 0.25, 0.29, 0.32, 0.35, 0.39, 0.37, ...
     0.58, 0.73, 0.96, 1.34, 2.10, 4.39];

t = [1.0, 15.0, 1.0;
     2.0, 14.0, 2.0;
     3.0, 13.0, 3.0;
     4.0, 12.0, 4.0;
     5.0, 11.0, 5.0;
     6.0, 10.0, 6.0;
     7.0,  9.0, 7.0;
     8.0,  8.0, 8.0;
     9.0,  7.0, 7.0;
    10.0,  6.0, 6.0;
    11.0,  5.0, 5.0;
    12.0,  4.0, 4.0;
    13.0,  3.0, 3.0;
    14.0,  2.0, 2.0;
    15.0,  1.0, 1.0];

% Initial guess
x = [0.5; 1; 1.5];

% Minimize
[x, fsumsq, fvec, fjac, s, v, niter, nf, user, ifail] = ...
e04fc( ...
     m, @lsqfun, @lsqmon, x);

fprintf('The sum of squares is %12.4f\n', fsumsq)
fprintf('at the point\n');
fprintf('%12.4f', x);
fprintf('\n\n');

job = nag_int(0);
```

```
[~, cj, ifail] = e04yc(...
    job, m, fsumsq, s, v);

fprintf('Estimated variances of the sample regression coefficients are:\n');
fprintf('%12.4f', cj);
fprintf('\n');

function [iflag,fvecc, user] = lsqfun(iflag, m, n, xc, user)

    global y t;

    fvecc = zeros(m,1);
    for i=1:double(m)
        fvecc(i) = xc(1) + t(i,1)/(xc(2)*t(i,2)+xc(3)*t(i,3)) - y(i);
    end

function [user] = lsqmon(m, n, xc, fvecc, fjacc, ljc, ...
    s, igrade, niter, nf, user)
```

9.2 Program Results

e04yc example results

The sum of squares is 0.0082
at the point
 0.0824 1.1330 2.3437

Estimated variances of the sample regression coefficients are:
 0.0002 0.0948 0.0878
