

NAG Toolbox

nag_opt_lsq_uncon_mod_func_easy (e04fy)

1 Purpose

nag_opt_lsq_uncon_mod_func_easy (e04fy) is an easy-to-use algorithm for finding an unconstrained minimum of a sum of squares of m nonlinear functions in n variables ($m \geq n$). No derivatives are required.

It is intended for functions which are continuous and which have continuous first and second derivatives (although it will usually work even if the derivatives have occasional discontinuities).

2 Syntax

```
[x, fsumsq, user, ifail] = nag_opt_lsq_uncon_mod_func_easy(m, lsfun1, x, 'n', n,
'user', user)
[x, fsumsq, user, ifail] = e04fy(m, lsfun1, x, 'n', n, 'user', user)
```

3 Description

nag_opt_lsq_uncon_mod_func_easy (e04fy) is essentially identical to the function LSNDN1 in the NPL Algorithms Library. It is applicable to problems of the form

$$\text{Minimize } F(x) = \sum_{i=1}^m [f_i(x)]^2$$

where $x = (x_1, x_2, \dots, x_n)^T$ and $m \geq n$. (The functions $f_i(x)$ are often referred to as ‘residuals’.)

You must supply a function to evaluate functions $f_i(x)$ at any point x .

From a starting point supplied by you, a sequence of points is generated which is intended to converge to a local minimum of the sum of squares. These points are generated using estimates of the curvature of $F(x)$.

4 References

Gill P E and Murray W (1978) Algorithms for the solution of the nonlinear least squares problem *SIAM J. Numer. Anal.* **15** 977–992

5 Parameters

5.1 Compulsory Input Parameters

1: **m** – INTEGER

The number m of residuals, $f_i(x)$, and the number n of variables, x_j .

Constraint: $1 \leq n \leq m$.

2: **lsfun1** – SUBROUTINE, supplied by the user.

You must supply this function to calculate the vector of values $f_i(x)$ at any point x . It should be tested separately before being used in conjunction with nag_opt_lsq_uncon_mod_func_easy (e04fy) (see the E04 Chapter Introduction).

```
[fvec, user] = lsfun1(m, n, xc, user)
```

Input Parameters

- 1: **m** – INTEGER
m, the numbers of residuals.
- 2: **n** – INTEGER
n, the numbers of variables.
- 3: **xc(n)** – REAL (KIND=nag_wp) array
The point *x* at which the values of the f_i are required.
- 4: **user** – INTEGER array
lsfun1 is called from `nag_opt_lsq_uncon_mod_func_easy` (e04fy) with the object supplied to `nag_opt_lsq_uncon_mod_func_easy` (e04fy).

Output Parameters

- 1: **fvec(m)** – REAL (KIND=nag_wp) array
fvec(i) must contain the value of f_i at the point *x*, for $i = 1, 2, \dots, m$.
- 2: **user** – INTEGER array

- 3: **x(n)** – REAL (KIND=nag_wp) array
x(j) must be set to a guess at the *j*th component of the position of the minimum, for $j = 1, 2, \dots, n$.

5.2 Optional Input Parameters

- 1: **n** – INTEGER
Default: the dimension of the array **x**.
The number *m* of residuals, $f_i(x)$, and the number *n* of variables, x_j .
Constraint: $1 \leq \mathbf{n} \leq \mathbf{m}$.
- 2: **user** – INTEGER array
user is not used by `nag_opt_lsq_uncon_mod_func_easy` (e04fy), but is passed to **lsfun1**. Note that for large objects it may be more efficient to use a global variable which is accessible from the m-files than to use **user**.

5.3 Output Parameters

- 1: **x(n)** – REAL (KIND=nag_wp) array
The lowest point found during the calculations. Thus, if **ifail** = 0 on exit, **x(j)** is the *j*th component of the position of the minimum.
- 2: **fsumsq** – REAL (KIND=nag_wp)
The value of the sum of squares, $F(x)$, corresponding to the final point stored in **x**.
- 3: **user** – INTEGER array

4: **ifail** – INTEGER

ifail = 0 unless the function detects an error (see Section 5).

6 Error Indicators and Warnings

Note: `nag_opt_lsq_uncon_mod_func_easy` (e04fy) may return useful information for one or more of the following detected errors or warnings.

Errors or warnings detected by the function:

ifail = 1

On entry, $\mathbf{n} < 1$,

or $\mathbf{m} < \mathbf{n}$,

or $lw < 7 \times \mathbf{n} + \mathbf{n} \times \mathbf{n} + 2 \times \mathbf{m} \times \mathbf{n} + 3 \times \mathbf{m} + \mathbf{n} \times (\mathbf{n} - 1)/2$, when $\mathbf{n} > 1$,

or $lw < 9 + 5 \times \mathbf{m}$, when $\mathbf{n} = 1$.

ifail = 2

There have been $400 \times n$ calls of `lsfun1`, yet the algorithm does not seem to have converged. This may be due to an awkward function or to a poor starting point, so it is worth restarting `nag_opt_lsq_uncon_mod_func_easy` (e04fy) from the final point held in \mathbf{x} .

ifail = 3 (*warning*)

The final point does not satisfy the conditions for acceptance as a minimum, but no lower point could be found.

ifail = 4

An auxiliary function has been unable to complete a singular value decomposition in a reasonable number of sub-iterations.

ifail = 5 (*warning*)

ifail = 6 (*warning*)

ifail = 7 (*warning*)

ifail = 8 (*warning*)

There is some doubt about whether the point \mathbf{x}_x found by `nag_opt_lsq_uncon_mod_func_easy` (e04fy) is a minimum of $F(x)$. The degree of confidence in the result decreases as **ifail** increases. Thus, when **ifail** = 5, it is probable that the final x gives a good estimate of the position of a minimum, but when **ifail** = 8 it is very unlikely that the function has found a minimum.

ifail = -99

An unexpected error has been triggered by this routine. Please contact NAG.

ifail = -399

Your licence key may have expired or may not have been installed correctly.

ifail = -999

Dynamic memory allocation failed.

If you are not satisfied with the result (e.g., because **ifail** lies between 3 and 8), it is worth restarting the calculations from a different starting point (not the point at which the failure occurred) in order to avoid the region which caused the failure. Repeated failure may indicate some defect in the formulation of the problem.

7 Accuracy

If the problem is reasonably well scaled and a successful exit is made, then, for a computer with a mantissa of t decimals, one would expect to get about $t/2 - 1$ decimals accuracy in the components of x and between $t - 1$ (if $F(x)$ is of order 1 at the minimum) and $2t - 2$ (if $F(x)$ is close to zero at the minimum) decimals accuracy in $F(x)$.

8 Further Comments

The number of iterations required depends on the number of variables, the number of residuals and their behaviour, and the distance of the starting point from the solution. The number of multiplications performed per iteration of `nag_opt_lsq_uncon_mod_func_easy` (e04fy) varies, but for $m \gg n$ is approximately $n \times m^2 + O(n^3)$. In addition, each iteration makes at least $n + 1$ calls of `lsfun1`. So, unless the residuals can be evaluated very quickly, the run time will be dominated by the time spent in `lsfun1`.

Ideally, the problem should be scaled so that the minimum value of the sum of squares is in the range $(0, +1)$, and so that at points a unit distance away from the solution the sum of squares is approximately a unit value greater than at the minimum. It is unlikely that you will be able to follow these recommendations very closely, but it is worth trying (by guesswork), as sensible scaling will reduce the difficulty of the minimization problem, so that `nag_opt_lsq_uncon_mod_func_easy` (e04fy) will take less computer time.

When the sum of squares represents the goodness-of-fit of a nonlinear model to observed data, elements of the variance-covariance matrix of the estimated regression coefficients can be computed by a subsequent call to `nag_opt_lsq_uncon_covariance` (e04yc), using information returned in segments of the workspace array w . See `nag_opt_lsq_uncon_covariance` (e04yc) for further details.

9 Example

This example finds least squares estimates of x_1 , x_2 and x_3 in the model

$$y = x_1 + \frac{t_1}{x_2 t_2 + x_3 t_3}$$

using the 15 sets of data given in the following table.

y	t_1	t_2	t_3
0.14	1.0	15.0	1.0
0.18	2.0	14.0	2.0
0.22	3.0	13.0	3.0
0.25	4.0	12.0	4.0
0.29	5.0	11.0	5.0
0.32	6.0	10.0	6.0
0.35	7.0	9.0	7.0
0.39	8.0	8.0	8.0
0.37	9.0	7.0	7.0
0.58	10.0	6.0	6.0
0.73	11.0	5.0	5.0
0.96	12.0	4.0	4.0
1.34	13.0	3.0	3.0
2.10	14.0	2.0	2.0
4.39	15.0	1.0	1.0

The program uses $(0.5, 1.0, 1.5)$ as the initial guess at the position of the minimum.

9.1 Program Text

```

function e04fy_example

fprintf('e04fy example results\n\n');

global y t;

% Model fitting data.
m = nag_int(15);
y = [ 0.14, 0.18, 0.22, 0.25, 0.29,...
      0.32, 0.35, 0.39, 0.37, 0.58,...
      0.73, 0.96, 1.34, 2.10, 4.39];
t = [ 1.0 15.0 1.0;
      2.0 14.0 2.0;
      3.0 13.0 3.0;
      4.0 12.0 4.0;
      5.0 11.0 5.0;
      6.0 10.0 6.0;
      7.0  9.0 7.0;
      8.0  8.0 8.0;
      9.0  7.0 7.0;
     10.0  6.0 6.0;
     11.0  5.0 5.0;
     12.0  4.0 4.0;
     13.0  3.0 3.0;
     14.0  2.0 2.0;
     15.0  1.0 1.0];

% Initial guess
n = 3;
x = [0.5; 1; 1.5];

% Minimize
[x, fsumsq, user, ifail] = e04fy(m, @lsfun1, x);

fprintf('Best fit model parameters are:\n');
for i = 1:n
    fprintf('      x_%d = %10.3f\n',i,x(i));
end
fprintf('\nSum of squares of residuals = %7.4f\n',fsumsq);

function [fvecc, user] = lsfun1(m, n, xc, user)

global y t;

fvecc=zeros(m,1);
for i = 1:double(m)
    fvecc(i) = xc(1) + t(i,1)/(xc(2)*t(i,2)+xc(3)*t(i,3)) - y(i);
end

```

9.2 Program Results

```

e04fy example results

Best fit model parameters are:
      x_1 =      0.082
      x_2 =      1.133
      x_3 =      2.344

Sum of squares of residuals =  0.0082

```
