

## NAG Toolbox

### nag\_roots\_sys\_deriv\_easy (c05rb)

#### 1 Purpose

nag\_roots\_sys\_deriv\_easy (c05rb) is an easy-to-use function that finds a solution of a system of nonlinear equations by a modification of the Powell hybrid method. You must provide the Jacobian.

#### 2 Syntax

```
[x, fvec, fjac, user, ifail] = nag_roots_sys_deriv_easy(fcn, x, 'n', n, 'xtol',
xtol, 'user', user)
```

```
[x, fvec, fjac, user, ifail] = c05rb(fcn, x, 'n', n, 'xtol', xtol, 'user', user)
```

#### 3 Description

The system of equations is defined as:

$$f_i(x_1, x_2, \dots, x_n) = 0, \quad i = 1, 2, \dots, n.$$

nag\_roots\_sys\_deriv\_easy (c05rb) is based on the MINPACK routine HYBRJ1 (see Moré *et al.* (1980)). It chooses the correction at each step as a convex combination of the Newton and scaled gradient directions. The Jacobian is updated by the rank-1 method of Broyden. At the starting point, the Jacobian is requested, but it is not asked for again until the rank-1 method fails to produce satisfactory progress. For more details see Powell (1970).

#### 4 References

Moré J J, Garbow B S and Hillstom K E (1980) User guide for MINPACK-1 *Technical Report ANL-80-74* Argonne National Laboratory

Powell M J D (1970) A hybrid method for nonlinear algebraic equations *Numerical Methods for Nonlinear Algebraic Equations* (ed P Rabinowitz) Gordon and Breach

#### 5 Parameters

##### 5.1 Compulsory Input Parameters

1: **fcn** – SUBROUTINE, supplied by the user.

Depending upon the value of **iflag**, **fcn** must either return the values of the functions  $f_i$  at a point  $x$  or return the Jacobian at  $x$ .

```
[fvec, fjac, user, iflag] = fcn(n, x, fvec, fjac, user, iflag)
```

##### **Input Parameters**

1: **n** – INTEGER

$n$ , the number of equations.

2: **x(n)** – REAL (KIND=nag\_wp) array

The components of the point  $x$  at which the functions or the Jacobian must be evaluated.

- 3: **fvec**(**n**) – REAL (KIND=nag\_wp) array  
If **iflag** = 2, **fvec** contains the function values  $f_i(x)$  and must not be changed.
- 4: **fjac**(**n**, **n**) – REAL (KIND=nag\_wp) array  
If **iflag** = 1, **fjac** contains the value of  $\frac{\partial f_i}{\partial x_j}$  at the point  $x$ , for  $i = 1, 2, \dots, n$  and  $j = 1, 2, \dots, n$ , and must not be changed.
- 5: **user** – INTEGER array  
**fcn** is called from nag\_roots\_sys\_deriv\_easy (c05rb) with the object supplied to nag\_roots\_sys\_deriv\_easy (c05rb).
- 6: **iflag** – INTEGER  
**iflag** = 1 or 2.  
**iflag** = 1  
    **fvec** is to be updated.  
**iflag** = 2  
    **fjac** is to be updated.

#### Output Parameters

- 1: **fvec**(**n**) – REAL (KIND=nag\_wp) array  
If **iflag** = 1 on entry, **fvec** must contain the function values  $f_i(x)$  (unless **iflag** is set to a negative value by **fcn**).
- 2: **fjac**(**n**, **n**) – REAL (KIND=nag\_wp) array  
If **iflag** = 2 on entry, **fjac**( $i, j$ ) must contain the value of  $\frac{\partial f_i}{\partial x_j}$  at the point  $x$ , for  $i = 1, 2, \dots, n$  and  $j = 1, 2, \dots, n$ , (unless **iflag** is set to a negative value by **fcn**).
- 3: **user** – INTEGER array
- 4: **iflag** – INTEGER  
In general, **iflag** should not be reset by **fcn**. If, however, you wish to terminate execution (perhaps because some illegal point  $x$  has been reached), then **iflag** should be set to a negative integer.

- 2: **x**(**n**) – REAL (KIND=nag\_wp) array  
An initial guess at the solution vector.

## 5.2 Optional Input Parameters

- 1: **n** – INTEGER  
*Default:* the dimension of the array **x**.  
 $n$ , the number of equations.  
*Constraint:* **n** > 0.
- 2: **xtol** – REAL (KIND=nag\_wp)  
*Suggested value:*  $\sqrt{\epsilon}$ , where  $\epsilon$  is the *machine precision* returned by nag\_machine\_precision (x02aj).

*Default:*  $\sqrt{\text{machine precision}}$

The accuracy in  $\mathbf{x}$  to which the solution is required.

*Constraint:*  $\mathbf{xtol} \geq 0.0$ .

3: **user** – INTEGER array

**user** is not used by nag\_roots\_sys\_deriv\_easy (c05rb), but is passed to **fcn**. Note that for large objects it may be more efficient to use a global variable which is accessible from the m-files than to use **user**.

### 5.3 Output Parameters

1: **x(n)** – REAL (KIND=nag\_wp) array

The final estimate of the solution vector.

2: **fvec(n)** – REAL (KIND=nag\_wp) array

The function values at the final point returned in  $\mathbf{x}$ .

3: **fjac(n, n)** – REAL (KIND=nag\_wp) array

The orthogonal matrix  $Q$  produced by the  $QR$  factorization of the final approximate Jacobian.

4: **user** – INTEGER array

5: **ifail** – INTEGER

**ifail** = 0 unless the function detects an error (see Section 5).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = 2 (*warning*)

There have been at least  $100 \times (\mathbf{n} + 1)$  calls to **fcn**. Consider restarting the calculation from the point held in  $\mathbf{x}$ .

**ifail** = 3 (*warning*)

No further improvement in the solution is possible.

**ifail** = 4 (*warning*)

The iteration is not making good progress. This failure exit may indicate that the system does not have a zero, or that the solution is very close to the origin (see Section 7). Otherwise, rerunning nag\_roots\_sys\_deriv\_easy (c05rb) from a different starting point may avoid the region of difficulty.

**ifail** = 5 (*warning*)

**iflag** was set negative in **fcn**.

**ifail** = 11

Constraint:  $\mathbf{n} > 0$ .

**ifail** = 12

Constraint:  $\mathbf{xtol} \geq 0.0$ .

**ifail** = -99

An unexpected error has been triggered by this routine. Please contact NAG.

**ifail** = -399

Your licence key may have expired or may not have been installed correctly.

**ifail** = -999

Dynamic memory allocation failed.

## 7 Accuracy

If  $\hat{x}$  is the true solution, nag\_roots\_sys\_deriv\_easy (c05rb) tries to ensure that

$$\|x - \hat{x}\|_2 \leq \mathbf{xtol} \times \|\hat{x}\|_2.$$

If this condition is satisfied with  $\mathbf{xtol} = 10^{-k}$ , then the larger components of  $x$  have  $k$  significant decimal digits. There is a danger that the smaller components of  $x$  may have large relative errors, but the fast rate of convergence of nag\_roots\_sys\_deriv\_easy (c05rb) usually obviates this possibility.

If  $\mathbf{xtol}$  is less than *machine precision* and the above test is satisfied with the *machine precision* in place of  $\mathbf{xtol}$ , then the function exits with **ifail** = 3.

**Note:** this convergence test is based purely on relative error, and may not indicate convergence if the solution is very close to the origin.

The convergence test assumes that the functions and the Jacobian are coded consistently and that the functions are reasonably well behaved. If these conditions are not satisfied, then nag\_roots\_sys\_deriv\_easy (c05rb) may incorrectly indicate convergence. The coding of the Jacobian can be checked using nag\_roots\_sys\_deriv\_check (c05zd). If the Jacobian is coded correctly, then the validity of the answer can be checked by rerunning nag\_roots\_sys\_deriv\_easy (c05rb) with a lower value for  $\mathbf{xtol}$ .

## 8 Further Comments

Local workspace arrays of fixed lengths are allocated internally by nag\_roots\_sys\_deriv\_easy (c05rb). The total size of these arrays amounts to  $n \times (n + 13)/2$  double elements.

The time required by nag\_roots\_sys\_deriv\_easy (c05rb) to solve a given problem depends on  $n$ , the behaviour of the functions, the accuracy requested and the starting point. The number of arithmetic operations executed by nag\_roots\_sys\_deriv\_easy (c05rb) is approximately  $11.5 \times n^2$  to process each evaluation of the functions and approximately  $1.3 \times n^3$  to process each evaluation of the Jacobian. The timing of nag\_roots\_sys\_deriv\_easy (c05rb) is strongly influenced by the time spent evaluating the functions.

Ideally the problem should be scaled so that, at the solution, the function values are of comparable magnitude.

## 9 Example

This example determines the values  $x_1, \dots, x_9$  which satisfy the tridiagonal equations:

$$\begin{aligned} (3 - 2x_1)x_1 - 2x_2 &= -1, \\ -x_{i-1} + (3 - 2x_i)x_i - 2x_{i+1} &= -1, \quad i = 2, 3, \dots, 8 \\ -x_8 + (3 - 2x_9)x_9 &= -1. \end{aligned}$$

## 9.1 Program Text

```

function c05rb_example

fprintf('c05rb example results\n\n');

% The following starting values provide a rough solution.
x = -ones(9, 1);
[xOut, fvec, fjac, user, ifail] = c05rb(@fcfn, x);
switch ifail
  case {0}
    fprintf('\nFinal 2-norm of the residuals = %12.4e\n', norm(fvec));
    fprintf('\nFinal approximate solution\n');
    disp(xOut);
  case {2, 3, 4}
    fprintf('\nApproximate solution\n');
    disp(xOut);
end

function [fvec, fjac, user, iflag] = fcfn(n, x, fvec, fjac, user, iflag)
  coeff = [-1, 3, -2, -2, -1];
  nd = double(n); % Can't use 64 bit integers in loops
  if (iflag ~= 2)
    fvec(1:nd) = (coeff(2)+coeff(3)*x(1:nd)).*x(1:nd) - coeff(5);
    fvec(2:nd) = fvec(2:nd) + coeff(1)*x(1:(nd-1));
    fvec(1:(nd-1)) = fvec(1:(nd-1)) + coeff(4)*x(2:nd);
  else
    fjac = zeros(nd, nd);

    fjac(1,1) = coeff(2) + 2*coeff(3)*x(1);
    fjac(1,2) = coeff(4);
    for k = 2:nd-1
      fjac(k,k-1) = coeff(1);
      fjac(k,k) = coeff(2) + 2*coeff(3)*x(k);
      fjac(k,k+1) = coeff(4);
    end
    fjac(nd,nd-1) = coeff(1);
    fjac(nd,nd) = coeff(2) + 2*coeff(3)*x(nd);
  end
end

```

## 9.2 Program Results

```

c05rb example results

Final 2-norm of the residuals = 1.1926e-08

Final approximate solution
-0.5707
-0.6816
-0.7017
-0.7042
-0.7014
-0.6919
-0.6658
-0.5960
-0.4164

```

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