

NAG Toolbox

nag_interp_nd_scat_shep_eval (e01zn)

1 Purpose

nag_interp_nd_scat_shep_eval (e01zn) evaluates the multidimensional interpolating function generated by nag_interp_nd_scat_shep (e01zm) and its first partial derivatives.

2 Syntax

```
[q, qx, ifail] = nag_interp_nd_scat_shep_eval(x, f, iq, rq, xe, 'd', d, 'm', m, 'n', n)
```

```
[q, qx, ifail] = e01zn(x, f, iq, rq, xe, 'd', d, 'm', m, 'n', n)
```

3 Description

nag_interp_nd_scat_shep_eval (e01zn) takes as input the interpolant $Q(\mathbf{x})$, $\mathbf{x} \in \mathbb{R}^d$ of a set of scattered data points (\mathbf{x}_r, f_r) , for $r = 1, 2, \dots, m$, as computed by nag_interp_nd_scat_shep (e01zm), and evaluates the interpolant and its first partial derivatives at the set of points \mathbf{x}_i , for $i = 1, 2, \dots, n$.

nag_interp_nd_scat_shep_eval (e01zn) must only be called after a call to nag_interp_nd_scat_shep (e01zm).

nag_interp_nd_scat_shep_eval (e01zn) is derived from the new implementation of QS3GRD described by Renka (1988). It uses the modification for high-dimensional interpolation described by Berry and Minser (1999).

4 References

Berry M W, Minser K S (1999) Algorithm 798: high-dimensional interpolation using the modified Shepard method *ACM Trans. Math. Software* **25** 353–366

Renka R J (1988) Algorithm 661: QSHEP3D: Quadratic Shepard method for trivariate interpolation of scattered data *ACM Trans. Math. Software* **14** 151–152

5 Parameters

5.1 Compulsory Input Parameters

1: $\mathbf{x}(\mathbf{d}, \mathbf{m})$ – REAL (KIND=nag_wp) array

Note: the i th ordinate of the point x_j is stored in $\mathbf{x}(i, j)$.

must be the same array supplied as argument \mathbf{x} in the preceding call to nag_interp_nd_scat_shep (e01zm). It **must** remain unchanged between calls.

2: $\mathbf{f}(\mathbf{m})$ – REAL (KIND=nag_wp) array

must be the same array supplied as argument \mathbf{f} in the preceding call to nag_interp_nd_scat_shep (e01zm). It **must** remain unchanged between calls.

3: $\mathbf{iq}(2 \times \mathbf{m} + 1)$ – INTEGER array

must be the same array returned as argument \mathbf{iq} in the preceding call to nag_interp_nd_scat_shep (e01zm). It **must** remain unchanged between calls.

4: **rq**(*) – REAL (KIND=nag_wp) array

The dimension of the array **rq** must be at least $((\mathbf{d} + 1) \times (\mathbf{d} + 2)/2) \times \mathbf{m} + 2 \times \mathbf{d} + 1$

must be the same array returned as argument **rq** in the preceding call to `nag_interp_nd_scat_shep` (e01zm). It **must** remain unchanged between calls.

5: **xe**(**d**, **n**) – REAL (KIND=nag_wp) array

Note: the i th ordinate of the point x_j is stored in **xe**(i, j).

xe(1 : **d**, j) must be set to the evaluation point \mathbf{x}_j , for $j = 1, 2, \dots, n$.

5.2 Optional Input Parameters

1: **d** – INTEGER

Default: the first dimension of the arrays **xe**, **x**. (An error is raised if these dimensions are not equal.)

must be the same value supplied for argument **d** in the preceding call to `nag_interp_nd_scat_shep` (e01zm).

Constraint: $\mathbf{d} \geq 2$.

2: **m** – INTEGER

Default: the dimension of the array **f** and the second dimension of the array **x**. (An error is raised if these dimensions are not equal.)

must be the same value supplied for argument **m** in the preceding call to `nag_interp_nd_scat_shep` (e01zm).

Constraint: $\mathbf{m} \geq (\mathbf{d} + 1) \times (\mathbf{d} + 2)/2 + 2$.

3: **n** – INTEGER

Default: the second dimension of the array **xe**.

n , the number of evaluation points.

Constraint: $\mathbf{n} \geq 1$.

5.3 Output Parameters

1: **q**(**n**) – REAL (KIND=nag_wp) array

q(i) contains the value of the interpolant, at \mathbf{x}_i , for $i = 1, 2, \dots, n$. If any of these evaluation points lie outside the region of definition of the interpolant the corresponding entries in **q** are set to the largest machine representable number (see `nag_machine_real_largest` (x02al)), and `nag_interp_nd_scat_shep_eval` (e01zn) returns with **ifail** = 3.

2: **qx**(**d**, **n**) – REAL (KIND=nag_wp) array

qx(i, j) contains the value of the partial derivatives with respect to the i th independent variable (dimension) of the interpolant $Q(\mathbf{x})$ at \mathbf{x}_j , for $j = 1, 2, \dots, n$, and for each of the partial derivatives $i = 1, 2, \dots, \mathbf{d}$. If any of these evaluation points lie outside the region of definition of the interpolant, the corresponding entries in **qx** are set to the largest machine representable number (see `nag_machine_real_largest` (x02al)), and `nag_interp_nd_scat_shep_eval` (e01zn) returns with **ifail** = 3.

3: **ifail** – INTEGER

ifail = 0 unless the function detects an error (see Section 5).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

Constraint: $\mathbf{d} \geq 2$.

Constraint: $\mathbf{m} \geq (\mathbf{d} + 1) \times (\mathbf{d} + 2)/2 + 2$.

Constraint: $\mathbf{n} \geq 1$.

On entry, $((\mathbf{d} + 1) \times (\mathbf{d} + 2)/2) \times \mathbf{m} + 2 \times \mathbf{d} + 1$ exceeds the largest machine integer.

ifail = 2

On entry, values in **iq** appear to be invalid. Check that **iq** has not been corrupted between calls to nag_interp_nd_scat_shep (e01zm) and nag_interp_nd_scat_shep_eval (e01zn).

On entry, values in **rq** appear to be invalid. Check that **rq** has not been corrupted between calls to nag_interp_nd_scat_shep (e01zm) and nag_interp_nd_scat_shep_eval (e01zn).

ifail = 3

On entry, at least one evaluation point lies outside the region of definition of the interpolant.

ifail = -99

An unexpected error has been triggered by this routine. Please contact NAG.

ifail = -399

Your licence key may have expired or may not have been installed correctly.

ifail = -999

Dynamic memory allocation failed.

7 Accuracy

Computational errors should be negligible in most practical situations.

8 Further Comments

The time taken for a call to nag_interp_nd_scat_shep_eval (e01zn) will depend in general on the distribution of the data points. If the data points are approximately uniformly distributed, then the time taken should be only $O(n)$. At worst $O(mn)$ time will be required.

9 Example

This program evaluates the function (in six variables)

$$f(x) = \frac{x_1 x_2 x_3}{1 + 2x_4 x_5 x_6}$$

at a set of randomly generated data points and calls nag_interp_nd_scat_shep (e01zm) to construct an interpolating function Q_x . It then calls nag_interp_nd_scat_shep_eval (e01zn) to evaluate the interpolant at a set of points on the line $x_i = x$, for $i = 1, 2, \dots, 6$. To reduce the time taken by this example, the number of data points is limited. Increasing this value to the suggested minimum of 4000 improves the interpolation accuracy at the expense of more time.

See also Section 10 in nag_interp_nd_scat_shep (e01zm).

9.1 Program Text

```
function e01zn_example

fprintf('e01zn example results\n\n');

genid = nag_int(1);
subid = nag_int(1);
seed = [nag_int(1762543)];
m = 120; % Number of data points
n = 9; % Number of evaluation points
d = 6; % Number of dimensions

% Initialize the generator to a repeatable sequence
[state, ifail] = g05kf(genid, subid, seed);

% Generate the data points X
[state, x, ifail] = g05sa(nag_int(d*m), state);

x = reshape(x, d, m);

% Evaluate f
f = x(1, :).*x(2, :).*x(3, :)./(1+2.*x(4, :).*x(5, :).*x(6, :));

% Generate the interpolant
[iq, rq, ifail] = e01zm(x, f);

% Generate a set of evaluation points lying on diagonal line.
xe = zeros(d, n);
for i = 1:n
    xe(:, i) = i/(n+1);
end

% Evaluate the interpolant
[q, qx, ifail] = e01zn(x, f, iq, rq, xe);

fprintf('\ni | f(i)      q(i)      | |f(i)-q(i)|\n');
fprintf('---|-----+-----\n');
for i=1:n
    fun = xe(1, i)*xe(2, i)*xe(3, i)/(1+2*xe(4, i)*xe(5, i)*xe(6, i));
    fprintf('%d %10.4f%10.4f %10.4f\n', i, fun, q(i), abs(fun-q(i)));
end
```

9.2 Program Results

e01zn example results

i	f(i)	q(i)	f(i)-q(i)
1	0.0010	0.0043	0.0033
2	0.0079	0.0040	0.0039
3	0.0256	0.0210	0.0046
4	0.0567	0.0536	0.0031
5	0.1000	0.0988	0.0012
6	0.1508	0.1526	0.0018
7	0.2034	0.2077	0.0043
8	0.2530	0.2570	0.0040
9	0.2966	0.2953	0.0013