Input

# **NAG Library Routine Document**

### F11MHF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

# 1 Purpose

F11MHF returns error bounds for the solution of a real sparse system of linear equations with multiple right-hand sides, AX = B or  $A^{T}X = B$ . It improves the solution by iterative refinement in standard precision, in order to reduce the backward error as much as possible.

# 2 Specification

```
SUBROUTINE F11MHF (TRANS, N, ICOLZP, IROWIX, A, IPRM, IL, LVAL, IU, UVAL, NRHS, B, LDB, X, LDX, FERR, BERR, IFAIL)

INTEGER

N, ICOLZP(*), IROWIX(*), IPRM(7*N), IL(*), IU(*), NRHS, LDB, LDX, IFAIL

REAL (KIND=nag_wp) A(*), LVAL(*), UVAL(*), B(LDB,*), X(LDX,*), FERR(NRHS), BERR(NRHS)

CHARACTER(1)

TRANS
```

## 3 Description

F11MHF returns the backward errors and estimated bounds on the forward errors for the solution of a real system of linear equations with multiple right-hand sides AX = B or  $A^{T}X = B$ . The routine handles each right-hand side vector (stored as a column of the matrix B) independently, so we describe the function of F11MHF in terms of a single right-hand side b and solution x.

Given a computed solution x, the routine computes the *component-wise backward error*  $\beta$ . This is the size of the smallest relative perturbation in each element of A and b such that if x is the exact solution of a perturbed system:

then 
$$(A + \delta A)x = b + \delta b$$
  
 $|\delta a_{ij}| \le \beta |a_{ij}|$  and  $|\delta b_i| \le \beta |b_i|$ .

Then the routine estimates a bound for the *component-wise forward error* in the computed solution, defined by:

$$\max_{i} |x_i - \hat{x}_i| / \max_{i} |x_i|$$

where  $\hat{x}$  is the true solution.

The routine uses the LU factorization  $P_rAP_c=LU$  computed by F11MEF and the solution computed by F11MFF.

#### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

# 5 Arguments

1: TRANS – CHARACTER(1)

On entry: specifies whether 
$$AX = B$$
 or  $A^{T}X = B$  is solved.

TRANS = 'N'

 $AX = B$  is solved.

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TRANS = 'T'

 $A^{\mathsf{T}}X = B$  is solved.

Constraint: TRANS = 'N' or 'T'.

2: N – INTEGER Input

On entry: n, the order of the matrix A.

Constraint:  $N \ge 0$ .

3: ICOLZP(\*) – INTEGER array

Input

**Note**: the dimension of the array ICOLZP must be at least N + 1.

On entry: ICOLZP(i) contains the index in A of the start of a new column. See Section 2.1.3 in the F11 Chapter Introduction.

4: IROWIX(\*) – INTEGER array

Input

**Note**: the dimension of the array IROWIX must be at least ICOLZP(N + 1) - 1, the number of nonzeros of the sparse matrix A.

On entry: the row index array of sparse matrix A.

5: A(\*) – REAL (KIND=nag wp) array

Input

**Note**: the dimension of the array A must be at least ICOLZP(N + 1) - 1, the number of nonzeros of the sparse matrix A.

On entry: the array of nonzero values in the sparse matrix A.

6:  $IPRM(7 \times N) - INTEGER$  array

Input

On entry: the column permutation which defines  $P_c$ , the row permutation which defines  $P_r$ , plus associated data structures as computed by F11MEF.

7: IL(\*) - INTEGER array

Input

**Note**: the dimension of the array IL must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records the sparsity pattern of matrix L as computed by F11MEF.

8: LVAL(\*) – REAL (KIND=nag\_wp) array

Input

**Note**: the dimension of the array LVAL must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records the nonzero values of matrix L and some nonzero values of matrix U as computed by F11MEF.

9: IU(\*) – INTEGER array

Input

**Note**: the dimension of the array IU must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records the sparsity pattern of matrix U as computed by F11MEF.

10: UVAL(\*) - REAL (KIND=nag\_wp) array

Input

**Note**: the dimension of the array UVAL must be at least as large as the dimension of the array of the same name in F11MEF.

On entry: records some nonzero values of matrix U as computed by F11MEF.

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#### 11: NRHS - INTEGER

Input

On entry: nrhs, the number of right-hand sides in B.

Constraint: NRHS  $\geq 0$ .

#### 12: B(LDB,\*) - REAL (KIND=nag wp) array

Input

Note: the second dimension of the array B must be at least max(1, NRHS).

On entry: the n by nrhs right-hand side matrix B.

#### 13: LDB – INTEGER

Input

On entry: the first dimension of the array B as declared in the (sub)program from which F11MHF is called.

*Constraint*: LDB  $\geq \max(1, N)$ .

### 14: X(LDX,\*) - REAL (KIND=nag wp) array

Input/Output

**Note**: the second dimension of the array X must be at least max(1, NRHS).

On entry: the n by nrhs solution matrix X, as returned by F11MFF.

On exit: the n by nrhs improved solution matrix X.

#### 15: LDX – INTEGER

Input

On entry: the first dimension of the array X as declared in the (sub)program from which F11MHF is called.

Constraint: LDX  $\geq \max(1, N)$ .

## 16: FERR(NRHS) - REAL (KIND=nag wp) array

Output

On exit: FERR(j) contains an estimated error bound for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., nrhs.

#### 17: BERR(NRHS) – REAL (KIND=nag wp) array

Output

On exit: BERR(j) contains the component-wise backward error bound  $\beta$  for the jth solution vector, that is, the jth column of X, for j = 1, 2, ..., nrhs.

### 18: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this argument you should refer to Section 3.4 in How to Use the NAG Library and its Documentation for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this argument, the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

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# 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
```

On entry, LDB =  $\langle value \rangle$  and N =  $\langle value \rangle$ .

Constraint: LDB  $\geq \max(1, N)$ .

On entry, LDX =  $\langle value \rangle$  and N =  $\langle value \rangle$ .

Constraint: LDX > max(1, N).

On entry,  $N = \langle value \rangle$ .

Constraint: N > 0.

On entry, NRHS =  $\langle value \rangle$ .

Constraint: NRHS  $\geq 0$ .

On entry, TRANS =  $\langle value \rangle$ .

Constraint: TRANS = 'N' or 'T'.

IFAIL = 2

Incorrect row permutations in array IPRM.

IFAIL = 3

Incorrect column permutations in array IPRM.

IFAIL = -99

An unexpected error has been triggered by this routine. Please contact NAG.

See Section 3.9 in How to Use the NAG Library and its Documentation for further information.

IFAIL = -399

Your licence key may have expired or may not have been installed correctly.

See Section 3.8 in How to Use the NAG Library and its Documentation for further information.

IFAIL = -999

Dynamic memory allocation failed.

See Section 3.7 in How to Use the NAG Library and its Documentation for further information.

# 7 Accuracy

The bounds returned in FERR are not rigorous, because they are estimated, not computed exactly; but in practice they almost always overestimate the actual error.

#### 8 Parallelism and Performance

F11MHF is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

F11MHF makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

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Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

#### **9** Further Comments

At most five steps of iterative refinement are performed, but usually only one or two steps are required. Estimating the forward error involves solving a number of systems of linear equations of the form Ax = b or  $A^{T}x = b$ ;

# 10 Example

This example solves the system of equations AX = B using iterative refinement and to compute the forward and backward error bounds, where

$$A = \begin{pmatrix} 2.00 & 1.00 & 0 & 0 & 0 \\ 0 & 0 & 1.00 & -1.00 & 0 \\ 4.00 & 0 & 1.00 & 0 & 1.00 \\ 0 & 0 & 0 & 1.00 & 2.00 \\ 0 & -2.00 & 0 & 0 & 3.00 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 1.56 & 3.12 \\ -0.25 & -0.50 \\ 3.60 & 7.20 \\ 1.33 & 2.66 \\ 0.52 & 1.04 \end{pmatrix}.$$

Here A is nonsymmetric and must first be factorized by F11MEF.

### 10.1 Program Text

```
Program f11mhfe
!
                 F11MHF Example Program Text
                 Mark 26 Release. NAG Copyright 2016.
1
                  .. Use Statements ..
                 Use nag_library, Only: f11mdf, f11mef, f11mff, f11mhf, nag_wp, x04caf,
                                                                                        x04cbf
!
                  .. Implicit None Statement ..
                 Implicit None
1
                  .. Parameters ..
                 Real (Kind=nag_wp), Parameter
Integer, Paramet
                  .. Local Scalars ..
                 Real (Kind=nag_wp)
                                                                                                                   :: flop, thresh
                                                                                                                   :: i, ifail, j, ldb, ldx, n, nnz, nnzl, &
                 Integer
                                                                                                                          nnzu, nrhs, nzlmx, nzlumx, nzumx
                 Character (1)
                                                                                                                     :: spec, trans
!
                  .. Local Arrays ..
                 Real (Kind=nag_wp), Allocatable :: a(:), b(:,:), berr(:), ferr(:),
                                                                                                                          lval(:), uval(:), x(:,:)
                                                                                                                      :: icolzp(:), il(:), iprm(:),
    irowix(:), iu(:)
                 Integer, Allocatable
                                                                                                                       :: clabs(1), rlabs(1)
                 Character (1)
                  .. Executable Statements ..
!
                 Write (nout,*) 'F11MHF Example Program Results'
                 Flush (nout)
                 Skip heading in data file
!
                 Read (nin,*)
                 Read order of matrix and number of right hand sides
!
                 Read (nin,*) n, nrhs
                  ldb = n
                 ldx = n
                 Allocate (b(ldb,nrhs),berr(nrhs),ferr(nrhs),x(ldx,nrhs),icolzp(n+1),
                        iprm(7*n)
```

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```
Read the matrix A
      Read (nin,*) icolzp(1:n+1)
      nnz = icolzp(n+1) - 1
      Allocate (a(nnz),lval(8*nnz),uval(8*nnz),il(7*n+8*nnz+4),irowix(nnz),
        iu(2*n+8*nnz+1))
      Do i = 1, nnz
       Read (nin,*) a(i), irowix(i)
      End Do
      Read the right hand sides
      Do j = 1, nrhs
        Read (nin,*) x(1:n,j)
        b(1:n,j) = x(1:n,j)
      End Do
!
      Calculate COLAMD permutation
      spec = 'M'
      ifail: behaviour on error exit
               =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
1
      ifail = 0
      Call f11mdf(spec,n,icolzp,irowix,iprm,ifail)
!
      Factorise
      thresh = one
      ifail = 0
      nzlmx = 8*nnz
      nzlumx = 8*nnz
      nzumx = 8*nnz
      Call f11mef(n,irowix,a,iprm,thresh,nzlmx,nzlmx,nzumx,i1,lval,iu,uval,
        nnzl, nnzu, flop, ifail)
      Compute solution in array X
      trans = 'N'
      ifail = 0
      Call f11mff(trans,n,iprm,il,lval,iu,uval,nrhs,x,ldx,ifail)
      Improve solution, and compute backward errors and estimated
!
      bounds on the forward errors
      Call f11mhf(trans,n,icolzp,irowix,a,iprm,il,lval,iu,uval,nrhs,b,ldb,x, &
        ldx,ferr,berr,ifail)
      Print solution
      Write (nout,*)
      Flush (nout)
      Call x04caf('G',' ',n,nrhs,x,ldx,'Solutions',ifail)
Call x04cbf('G','X',nrhs,1,ferr,nrhs,'1PE8.1','Estimated Forward Error', &
      'N',rlabs,'N',clabs,80,0,ifail)
Call x04cbf('G','X',nrhs,1,berr,nrhs,'1PE8.1','Backward Error','N',
        rlabs,'N',clabs,80,0,ifail)
    End Program f11mhfe
```

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# 10.2 Program Data

```
F11MHF Example Program Data
 5 2 N, NRHS
 3
 5
 9
 12
      ICOLZP(I) I=1,...,N+1
  2.
      1
  4.
       3
  1.
       1
 -2.
       5
 1.
 1.
       3
 -1.
       2
 1.
       4
  1.
  2.
       4
 3. 5 A(I), IROWIX(I) I=1,NNZ
1.56 -.25 3.6 1.33 .52
 3.12 -.50 7.2 2.66 1.04 X(I,J) J=1,NRHS I=1,N
```

### 10.3 Program Results

F11MHF Example Program Results

```
Solutions
            1
       0.7000
                1.4000
2
       0.1600
               0.3200
                 1.0400
3
      0.5200
      0.7700
                 1.5400
4
               0.5600
5
      0.2800
Estimated Forward Error
  5.0E-15
  5.0E-15
Backward Error
  3.6E - 17
  3.6E - 17
```

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