

NAG Library Routine Document

F08XQF (ZGGES3)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F08XQF (ZGGES3) computes the generalized eigenvalues, the generalized Schur form (S, T) and, optionally, the left and/or right generalized Schur vectors for a pair of n by n complex nonsymmetric matrices (A, B) .

2 Specification

```

SUBROUTINE F08XQF (JOBVSL, JOBVSR, SORT, SELCTG, N, A, LDA, B, LDB,      &
                  SDIM, ALPHA, BETA, VSL, LDVSL, VSR, LDVSR, WORK,      &
                  LWORK, RWORK, BWORK, INFO)
INTEGER                N, LDA, LDB, SDIM, LDVSL, LDVSR, LWORK, INFO
REAL (KIND=nag_wp)    RWORK(max(1,8*N))
COMPLEX (KIND=nag_wp) A(LDA,*), B(LDB,*), ALPHA(N), BETA(N),          &
                    VSL(LDVSL,*), VSR(LDVSR,*), WORK(max(1,LWORK))
LOGICAL                SELCTG, BWORK(*)
CHARACTER(1)          JOBVSL, JOBVSR, SORT
EXTERNAL               SELCTG

```

The routine may be called by its LAPACK name *zggges3*.

3 Description

The generalized Schur factorization for a pair of complex matrices (A, B) is given by

$$A = QSZ^H, \quad B = QTZ^H,$$

where Q and Z are unitary, T and S are upper triangular. The generalized eigenvalues, λ , of (A, B) are computed from the diagonals of T and S and satisfy

$$Az = \lambda Bz,$$

where z is the corresponding generalized eigenvector. λ is actually returned as the pair (α, β) such that

$$\lambda = \alpha/\beta$$

since β , or even both α and β can be zero. The columns of Q and Z are the left and right generalized Schur vectors of (A, B) .

Optionally, F08XQF (ZGGES3) can order the generalized eigenvalues on the diagonals of (S, T) so that selected eigenvalues are at the top left. The leading columns of Q and Z then form an orthonormal basis for the corresponding eigenspaces, the deflating subspaces.

F08XQF (ZGGES3) computes T to have real non-negative diagonal entries. The generalized Schur factorization, before reordering, is computed by the QZ algorithm.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F (2012) *Matrix Computations* (4th Edition) Johns Hopkins University Press, Baltimore

5 Arguments

- 1: JOBVSL – CHARACTER(1) *Input*
On entry: if JOBVSL = 'N', do not compute the left Schur vectors.
 If JOBVSL = 'V', compute the left Schur vectors.
Constraint: JOBVSL = 'N' or 'V'.
- 2: JOBVSR – CHARACTER(1) *Input*
On entry: if JOBVSR = 'N', do not compute the right Schur vectors.
 If JOBVSR = 'V', compute the right Schur vectors.
Constraint: JOBVSR = 'N' or 'V'.
- 3: SORT – CHARACTER(1) *Input*
On entry: specifies whether or not to order the eigenvalues on the diagonal of the generalized Schur form.
 SORT = 'N'
 Eigenvalues are not ordered.
 SORT = 'S'
 Eigenvalues are ordered (see SELCTG).
Constraint: SORT = 'N' or 'S'.
- 4: SELCTG – LOGICAL FUNCTION, supplied by the user. *External Procedure*
 If SORT = 'S', SELCTG is used to select generalized eigenvalues to be moved to the top left of the generalized Schur form.
 If SORT = 'N', SELCTG is not referenced by F08XQF (ZGGES3), and may be called with the dummy function F08XNZ.

The specification of SELCTG is:

```
FUNCTION SELCTG (A, B)
  LOGICAL SELCTG
  COMPLEX (KIND=nag_wp) A, B
```

1: A – COMPLEX (KIND=nag_wp) *Input*

2: B – COMPLEX (KIND=nag_wp) *Input*

On entry: an eigenvalue $A(j)/B(j)$ is selected if $\text{SELCTG}(A(j), B(j))$ is .TRUE..

Note that in the ill-conditioned case, a selected generalized eigenvalue may no longer satisfy $\text{SELCTG}(A(j), B(j)) = \text{.TRUE.}$ after ordering. INFO = N + 2 in this case.

SELCTG must either be a module subprogram USEd by, or declared as EXTERNAL in, the (sub) program from which F08XQF (ZGGES3) is called. Arguments denoted as *Input* must **not** be changed by this procedure.

- 5: N – INTEGER *Input*
On entry: n , the order of the matrices A and B .
Constraint: $N \geq 0$.
- 6: A(LDA,*) – COMPLEX (KIND=nag_wp) array *Input/Output*
Note: the second dimension of the array A must be at least $\max(1, N)$.
On entry: the first of the pair of matrices, A .

On exit: A has been overwritten by its generalized Schur form S .

- 7: LDA – INTEGER *Input*
On entry: the first dimension of the array A as declared in the (sub)program from which F08XQF (ZGGES3) is called.
Constraint: $LDA \geq \max(1, N)$.
- 8: B(LDB, *) – COMPLEX (KIND=nag_wp) array *Input/Output*
Note: the second dimension of the array B must be at least $\max(1, N)$.
On entry: the second of the pair of matrices, B .
On exit: B has been overwritten by its generalized Schur form T .
- 9: LDB – INTEGER *Input*
On entry: the first dimension of the array B as declared in the (sub)program from which F08XQF (ZGGES3) is called.
Constraint: $LDB \geq \max(1, N)$.
- 10: SDIM – INTEGER *Output*
On exit: if SORT = 'N', SDIM = 0.
 If SORT = 'S', SDIM = number of eigenvalues (after sorting) for which SELCTG is .TRUE..
- 11: ALPHA(N) – COMPLEX (KIND=nag_wp) array *Output*
On exit: see the description of BETA.
- 12: BETA(N) – COMPLEX (KIND=nag_wp) array *Output*
On exit: ALPHA(j)/BETA(j), for $j = 1, 2, \dots, N$, will be the generalized eigenvalues. ALPHA(j), for $j = 1, 2, \dots, N$ and BETA(j), for $j = 1, 2, \dots, N$, are the diagonals of the complex Schur form (A, B) output by F08XQF (ZGGES3). The BETA(j) will be non-negative real.
Note: the quotients ALPHA(j)/BETA(j) may easily overflow or underflow, and BETA(j) may even be zero. Thus, you should avoid naively computing the ratio α/β . However, ALPHA will always be less than and usually comparable with $\|A\|_2$ in magnitude, and BETA will always be less than and usually comparable with $\|B\|_2$.
- 13: VSL(LDVSL, *) – COMPLEX (KIND=nag_wp) array *Output*
Note: the second dimension of the array VSL must be at least $\max(1, N)$ if JOBVSL = 'V', and at least 1 otherwise.
On exit: if JOBVSL = 'V', VSL will contain the left Schur vectors, Q .
 If JOBVSL = 'N', VSL is not referenced.
- 14: LDVSL – INTEGER *Input*
On entry: the first dimension of the array VSL as declared in the (sub)program from which F08XQF (ZGGES3) is called.
Constraints:
 if JOBVSL = 'V', $LDVSL \geq \max(1, N)$;
 otherwise $LDVSL \geq 1$.

- 15: VSR(LDVSR,*) – COMPLEX (KIND=nag_wp) array Output
Note: the second dimension of the array VSR must be at least $\max(1, N)$ if $\text{JOBVSR} = 'V'$, and at least 1 otherwise.
On exit: if $\text{JOBVSR} = 'V'$, VSR will contain the right Schur vectors, Z .
 If $\text{JOBVSR} = 'N'$, VSR is not referenced.
- 16: LDVSR – INTEGER Input
On entry: the first dimension of the array VSR as declared in the (sub)program from which F08XQF (ZGGES3) is called.
Constraints:
 if $\text{JOBVSR} = 'V'$, $\text{LDVSR} \geq \max(1, N)$;
 otherwise $\text{LDVSR} \geq 1$.
- 17: WORK($\max(1, \text{LWORK})$) – COMPLEX (KIND=nag_wp) array Workspace
On exit: if $\text{INFO} = 0$, the real part of $\text{WORK}(1)$ contains the minimum value of LWORK required for optimal performance.
- 18: LWORK – INTEGER Input
On entry: the dimension of the array WORK as declared in the (sub)program from which F08XQF (ZGGES3) is called.
 If $\text{LWORK} = -1$, a workspace query is assumed; the routine only calculates the optimal size of the WORK array, returns this value as the first entry of the WORK array, and no error message related to LWORK is issued.
Suggested value: for optimal performance, LWORK must generally be larger than the minimum, say $2 \times N + nb \times (N \times 6)$, where nb is the optimal **block size** for F08WTF (ZGGHD3).
Constraint: $\text{LWORK} \geq \max(1, 2 \times N)$.
- 19: RWORK($\max(1, 8 \times N)$) – REAL (KIND=nag_wp) array Workspace
- 20: BWORK(*) – LOGICAL array Workspace
Note: the dimension of the array BWORK must be at least 1 if $\text{SORT} = 'N'$, and at least $\max(1, N)$ otherwise.
 If $\text{SORT} = 'N'$, BWORK is not referenced.
- 21: INFO – INTEGER Output
On exit: $\text{INFO} = 0$ unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If $\text{INFO} = -i$, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO = 1 to N

The QZ iteration did not converge and the matrix pair (A, B) is not in the generalized Schur form. The computed α_i and β_i should be correct for $i = \langle \text{value} \rangle, \dots, \langle \text{value} \rangle$.

INFO = N + 1

The QZ iteration failed with an unexpected error, please contact NAG.

INFO = N + 2

After reordering, roundoff changed values of some complex eigenvalues so that leading eigenvalues in the generalized Schur form no longer satisfy SELCTG = .TRUE.. This could also be caused by underflow due to scaling.

INFO = N + 3

The eigenvalues could not be reordered because some eigenvalues were too close to separate (the problem is very ill-conditioned).

7 Accuracy

The computed generalized Schur factorization satisfies

$$A + E = QSZ^H, \quad B + F = QTZ^H,$$

where

$$\|(E, F)\|_F = O(\epsilon)\|(A, B)\|_F$$

and ϵ is the *machine precision*. See Section 4.11 of Anderson *et al.* (1999) for further details.

8 Parallelism and Performance

F08XQF (ZGGES3) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

F08XQF (ZGGES3) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The total number of floating-point operations is proportional to n^3 .

The real analogue of this routine is F08XCF (DGGES3).

10 Example

This example finds the generalized Schur factorization of the matrix pair (A, B) , where

$$A = \begin{pmatrix} -21.10 - 22.50i & 53.50 - 50.50i & -34.50 + 127.50i & 7.50 + 0.50i \\ -0.46 - 7.78i & -3.50 - 37.50i & -15.50 + 58.50i & -10.50 - 1.50i \\ 4.30 - 5.50i & 39.70 - 17.10i & -68.50 + 12.50i & -7.50 - 3.50i \\ 5.50 + 4.40i & 14.40 + 43.30i & -32.50 - 46.00i & -19.00 - 32.50i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1.00 - 5.00i & 1.60 + 1.20i & -3.00 + 0.00i & 0.00 - 1.00i \\ 0.80 - 0.60i & 3.00 - 5.00i & -4.00 + 3.00i & -2.40 - 3.20i \\ 1.00 + 0.00i & 2.40 + 1.80i & -4.00 - 5.00i & 0.00 - 3.00i \\ 0.00 + 1.00i & -1.80 + 2.40i & 0.00 - 4.00i & 4.00 - 5.00i \end{pmatrix}.$$

10.1 Program Text

```

Program f08xqfe

!      F08XQF Example Program Text

!      Mark 26 Release. NAG Copyright 2016.

!      .. Use Statements ..
Use nag_library, Only: f08xznz, nag_wp, x02ajf, x04dbf, zgemm, zgges3,      &
                        zlange => f06uaf
!      .. Implicit None Statement ..
Implicit None
!      .. Parameters ..
Integer, Parameter      :: nb = 64, nin = 5, nout = 6
!      .. Local Scalars ..
Complex (Kind=nag_wp)   :: alph, bet
Real (Kind=nag_wp)     :: normd, norme
Integer                 :: i, ifail, info, lda, ldb, ldc, ldd,      &
                        lde, ldvsl, ldvsr, lwork, n, sdim
!      .. Local Arrays ..
Complex (Kind=nag_wp), Allocatable :: a(:,,:), alpha(:), b(:,:), beta(:), &
                        c(:,:), d(:,:), e(:,:), vsl(:,:),      &
                        vsr(:,:), work(:)
Complex (Kind=nag_wp)   :: wdum(1)
Real (Kind=nag_wp), Allocatable :: rwork(:)
Logical, Allocatable    :: bwork(:)
Character (1)           :: clabs(1), rlabs(1)
!      .. Intrinsic Procedures ..
Intrinsic                :: cmplx, max, nint, real
!      .. Executable Statements ..
Write (nout,*) 'F08XQF Example Program Results'
Write (nout,*)
Flush (nout)
!      Skip heading in data file
Read (nin,*)
Read (nin,*) n
lda = n
ldb = n
ldc = n
ldd = n
lde = n
ldvsl = n
ldvsr = n
Allocate (a(lda,n),alpha(n),b(ldb,n),beta(n),c(ldc,n),d(ddd,n),e(lde,n), &
          vsl(ldvsl,n),vsr(ldvsr,n),rwork(8*n),bwork(n))

!      Use routine workspace query to get optimal workspace.
lwork = -1
!      The NAG name equivalent of zgges3 is f08xqf
Call zgges3('Vectors (left)', 'Vectors (right)', 'No sort', f08xznz, n, a, lda, &
           b, ldb, sdim, alpha, beta, vsl, ldvsl, vsr, ldvsr, wdum, lwork, rwork, bwork, info)

!      Make sure that there is enough workspace for block size nb.
lwork = max((nb+1)*n, nint(real(wdum(1))))
Allocate (work(lwork))

!      Read in the matrices A and B
Read (nin,*) (a(i,1:n), i=1, n)
Read (nin,*) (b(i,1:n), i=1, n)

!      Copy A and B into D and E respectively
d(1:n,1:n) = a(1:n,1:n)
e(1:n,1:n) = b(1:n,1:n)

!      Print matrices A and B
!      ifail: behaviour on error exit
!              =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
ifail = 0
Call x04dbf('General', ' ', n, n, a, lda, 'Bracketed', 'F8.4', 'Matrix A',      &
           'Integer', rlabs, 'Integer', clabs, 80, 0, ifail)

```

```

Write (nout,*)
Flush (nout)

ifail = 0
Call x04dbf('General',' ',n,n,b,ldb,'Bracketed','F8.4','Matrix B',      &
'Integer',rlabs,'Integer',clabs,80,0,ifail)
Write (nout,*)
Flush (nout)

! Find the generalized Schur form
! The NAG name equivalent of zgges3 is f08xqf
Call zgges3('Vectors (left)','Vectors (right)','No sort',f08xzn,n,a,lda, &
b,ldb,sdim,alpha,beta,vsl,ldvsl,vsr,ldvsr,work,lwork,rwork,bwork,info)

If (info>0) Then
Write (nout,99999) 'Failure in ZGGES3. INFO =', info
Else

! Compute A - Q*S*Z`H from the factorization of (A,B) and store in
! matrix D
! The NAG name equivalent of zgemm is f06zaf
alph = cmplx(1,kind=nag_wp)
bet = cmplx(0,kind=nag_wp)
Call zgemm('N','N',n,n,n,alph,vsl,ldvsl,a,lda,bet,c,ldc)
alph = cmplx(-1,kind=nag_wp)
bet = cmplx(1,kind=nag_wp)
Call zgemm('N','C',n,n,n,alph,c,ldc,vsr,ldvsr,bet,d,ldd)

! Compute B - Q*T*Z`H from the factorization of (A,B) and store in
! matrix E
alph = cmplx(1,kind=nag_wp)
bet = cmplx(0,kind=nag_wp)
Call zgemm('N','N',n,n,n,alph,vsl,ldvsl,b,ldb,bet,c,ldc)
alph = cmplx(-1,kind=nag_wp)
bet = cmplx(1,kind=nag_wp)
Call zgemm('N','C',n,n,n,alph,c,ldc,vsr,ldvsr,bet,e,lde)

! Find norms of matrices D and E and warn if either is too large
! f06uaf is the NAG name equivalent of the LAPACK auxiliary zlange
normd = zlange('O',ldd,n,d,ldd,rwork)
norme = zlange('O',lde,n,e,lde,rwork)
If (normd>x02ajf())**0.75_nag_wp .Or. norme>x02ajf())**0.75_nag_wp) Then
Write (nout,*)
'Norm of A-(Q*S*Z`H) or norm of B-(Q*T*Z`H) is much greater than 0.' &
Write (nout,*) 'Schur factorization has failed.'
Else
! Print generalized eigenvalues
Write (nout,*) 'Generalized Eigenvalues'

Do i = 1, n
If (beta(i)/=0.0_nag_wp) Then
Write (nout,99998) i, alpha(i)/beta(i)
Else
Write (nout,99997) i
End If
End Do
End If
End If

99999 Format (1X,A,I4)
99998 Format (1X,I2,1X,('( ',1P,E11.4,' ',',',E11.4,')')')
99997 Format (1X,I4,'Eigenvalue is infinite')
End Program f08xqfe

```

10.2 Program Data

F08XQF Example Program Data

```

4
(-21.10,-22.50) ( 53.50,-50.50) (-34.50,127.50) ( 7.50, 0.50) : Value of N
(-0.46, -7.78) (-3.50,-37.50) (-15.50, 58.50) (-10.50, -1.50)
( 4.30, -5.50) ( 39.70,-17.10) (-68.50, 12.50) (-7.50, -3.50)
( 5.50, 4.40) ( 14.40, 43.30) (-32.50,-46.00) (-19.00,-32.50) : End of A
( 1.00, -5.00) ( 1.60, 1.20) (-3.00, 0.00) ( 0.00, -1.00)
( 0.80, -0.60) ( 3.00, -5.00) (-4.00, 3.00) (-2.40, -3.20)
( 1.00, 0.00) ( 2.40, 1.80) (-4.00, -5.00) ( 0.00, -3.00)
( 0.00, 1.00) (-1.80, 2.40) ( 0.00, -4.00) ( 4.00, -5.00) : End of B

```

10.3 Program Results

F08XQF Example Program Results

Matrix A

```

1 2 3
1 (-21.1000,-22.5000) ( 53.5000,-50.5000) (-34.5000,127.5000)
2 (-0.4600, -7.7800) (-3.5000,-37.5000) (-15.5000, 58.5000)
3 ( 4.3000, -5.5000) ( 39.7000,-17.1000) (-68.5000, 12.5000)
4 ( 5.5000, 4.4000) ( 14.4000, 43.3000) (-32.5000,-46.0000)

4
1 ( 7.5000, 0.5000)
2 (-10.5000, -1.5000)
3 (-7.5000, -3.5000)
4 (-19.0000,-32.5000)

```

Matrix B

```

1 2 3
1 ( 1.0000, -5.0000) ( 1.6000, 1.2000) (-3.0000, 0.0000)
2 ( 0.8000, -0.6000) ( 3.0000, -5.0000) (-4.0000, 3.0000)
3 ( 1.0000, 0.0000) ( 2.4000, 1.8000) (-4.0000, -5.0000)
4 ( 0.0000, 1.0000) (-1.8000, 2.4000) ( 0.0000, -4.0000)

4
1 ( 0.0000, -1.0000)
2 (-2.4000, -3.2000)
3 ( 0.0000, -3.0000)
4 ( 4.0000, -5.0000)

```

Generalized Eigenvalues

```

1 ( 3.0000E+00,-9.0000E+00)
2 ( 2.0000E+00,-5.0000E+00)
3 ( 3.0000E+00,-1.0000E+00)
4 ( 4.0000E+00,-5.0000E+00)

```
