NAG Library Routine Document F08QLF (DTRSNA)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08QLF (DTRSNA) estimates condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix.

2 Specification

The routine may be called by its LAPACK name dtrsna.

3 Description

F08QLF (DTRSNA) estimates condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix T in canonical Schur form. These are the same as the condition numbers of the eigenvalues and right eigenvectors of an original matrix $A = ZTZ^T$ (with orthogonal Z), from which T may have been derived.

F08QLF (DTRSNA) computes the reciprocal of the condition number of an eigenvalue λ_i as

$$s_i = \frac{|v^{\mathsf{H}}u|}{\|u\|_E \|v\|_E},$$

where u and v are the right and left eigenvectors of T, respectively, corresponding to λ_i . This reciprocal condition number always lies between zero (i.e., ill-conditioned) and one (i.e., well-conditioned).

An approximate error estimate for a computed eigenvalue λ_i is then given by

$$\frac{\epsilon \|T\|}{s_i}$$

where ϵ is the *machine precision*.

To estimate the reciprocal of the condition number of the right eigenvector corresponding to λ_i , the routine first calls F08QFF (DTREXC) to reorder the eigenvalues so that λ_i is in the leading position:

$$T = Q \begin{pmatrix} \lambda_i & c^{\mathsf{T}} \\ 0 & T_{22} \end{pmatrix} Q^{\mathsf{T}}.$$

The reciprocal condition number of the eigenvector is then estimated as sep_i , the smallest singular value of the matrix $(T_{22} - \lambda_i I)$. This number ranges from zero (i.e., ill-conditioned) to very large (i.e., well-conditioned).

An approximate error estimate for a computed right eigenvector u corresponding to λ_i is then given by

$$\frac{\epsilon \|T\|}{sep_i}$$
.

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4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Arguments

1: JOB - CHARACTER(1)

Input

On entry: indicates whether condition numbers are required for eigenvalues and/or eigenvectors.

JOB = 'E'

Condition numbers for eigenvalues only are computed.

JOB = 'V'

Condition numbers for eigenvectors only are computed.

JOB = 'B'

Condition numbers for both eigenvalues and eigenvectors are computed.

Constraint: JOB = 'E', 'V' or 'B'.

2: HOWMNY - CHARACTER(1)

Input

On entry: indicates how many condition numbers are to be computed.

HOWMNY = 'A'

Condition numbers for all eigenpairs are computed.

HOWMNY = 'S'

Condition numbers for selected eigenpairs (as specified by SELECT) are computed.

Constraint: HOWMNY = 'A' or 'S'.

3: SELECT(*) – LOGICAL array

Input

Note: the dimension of the array SELECT must be at least max(1, N) if HOWMNY = 'S', and at least 1 otherwise.

On entry: specifies the eigenpairs for which condition numbers are to be computed if HOWMNY = 'S'. To select condition numbers for the eigenpair corresponding to the real eigenvalue λ_j , SELECT(j) must be set .TRUE.. To select condition numbers corresponding to a complex conjugate pair of eigenvalues λ_j and λ_{j+1} , SELECT(j) and/or SELECT(j+1) must be set to .TRUE..

If HOWMNY = 'A', SELECT is not referenced.

4: N – INTEGER

Input

On entry: n, the order of the matrix T.

Constraint: $N \ge 0$.

5: T(LDT, *) - REAL (KIND=nag wp) array

Input

Note: the second dimension of the array T must be at least max(1, N).

On entry: the n by n upper quasi-triangular matrix T in canonical Schur form, as returned by F08PEF (DHSEQR).

6: LDT – INTEGER

Input

On entry: the first dimension of the array T as declared in the (sub)program from which F08QLF (DTRSNA) is called.

Constraint: LDT $> \max(1, N)$.

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7: VL(LDVL,*) - REAL (KIND=nag wp) array

Input

Note: the second dimension of the array VL must be at least max(1, MM) if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.

On entry: if JOB = 'E' or 'B', VL must contain the left eigenvectors of T (or of any matrix QTQ^T with Q orthogonal) corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors **must** be stored in consecutive columns of VL, as returned by F08PKF (DHSEIN) or F08QKF (DTREVC).

If JOB = 'V', VL is not referenced.

8: LDVL – INTEGER

Input

On entry: the first dimension of the array VL as declared in the (sub)program from which F08QLF (DTRSNA) is called.

Constraints:

```
if JOB = 'E' or 'B', LDVL \ge max(1, N); if JOB = 'V', LDVL \ge 1.
```

9: VR(LDVR,*) - REAL (KIND=nag wp) array

Input

Note: the second dimension of the array VR must be at least max(1, MM) if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.

On entry: if JOB = 'E' or 'B', VR must contain the right eigenvectors of T (or of any matrix QTQ^T with Q orthogonal) corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors **must** be stored in consecutive columns of VR, as returned by F08PKF (DHSEIN) or F08QKF (DTREVC).

If JOB = 'V', VR is not referenced.

10: LDVR – INTEGER

Input

On entry: the first dimension of the array VR as declared in the (sub)program from which F08QLF (DTRSNA) is called.

Constraints:

```
if JOB = 'E' or 'B', LDVR \ge max(1, N); if JOB = 'V', LDVR \ge 1.
```

11: S(*) – REAL (KIND=nag wp) array

Output

Note: the dimension of the array S must be at least max(1, MM) if JOB = 'E' or 'B', and at least 1 otherwise.

On exit: the reciprocal condition numbers of the selected eigenvalues if JOB = 'E' or 'B', stored in consecutive elements of the array. Thus S(j), SEP(j) and the jth columns of VL and VR all correspond to the same eigenpair (but not in general the jth eigenpair unless all eigenpairs have been selected). For a complex conjugate pair of eigenvalues, two consecutive elements of S are set to the same value.

If JOB = 'V', S is not referenced.

12: SEP(*) - REAL (KIND=nag_wp) array

Output

Note: the dimension of the array SEP must be at least max(1, MM) if JOB = 'V' or 'B', and at least 1 otherwise.

On exit: the estimated reciprocal condition numbers of the selected right eigenvectors if JOB = 'V' or 'B', stored in consecutive elements of the array. For a complex eigenvector, two consecutive elements of SEP are set to the same value. If the eigenvalues cannot be reordered to compute SEP(j), then SEP(j) is set to zero; this can only occur when the true value would be very small anyway.

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If JOB = 'E', SEP is not referenced.

13: MM – INTEGER Input

On entry: the number of elements in the arrays S and SEP, and the number of columns in the arrays VL and VR (if used). The precise number required, m, is n if HOWMNY = 'A'; if HOWMNY = 'S', m is obtained by counting 1 for each selected real eigenvalue, and 2 for each selected complex conjugate pair of eigenvalues (see SELECT), in which case $0 \le m \le n$.

Constraint: $MM \ge M$.

14: M – INTEGER Output

On exit: m, the number of elements of S and/or SEP actually used to store the estimated condition numbers. If HOWMNY = 'A', M is set to n.

15: WORK(LDWORK,*) - REAL (KIND=nag wp) array

Workspace

Note: the second dimension of the array WORK must be at least max(1, N + 6) if JOB = 'V' or 'B' and at least 1 if JOB = 'E'.

If JOB = 'E', WORK is not referenced.

16: LDWORK – INTEGER

Input

On entry: the first dimension of the array WORK as declared in the (sub)program from which F08QLF (DTRSNA) is called.

Constraints:

```
if JOB = 'V' or 'B', LDWORK \ge max(1, N); if JOB = 'E', LDWORK \ge 1.
```

17: IWORK(*) – INTEGER array

Workspace

Note: the dimension of the array IWORK must be at least $max(1, 2 \times (N-1))$.

18: INFO – INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = -i, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed values sep_i may over estimate the true value, but seldom by a factor of more than 3.

8 Parallelism and Performance

F08QLF (DTRSNA) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

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9 Further Comments

For a description of canonical Schur form, see the document for F08PEF (DHSEQR).

The complex analogue of this routine is F08QYF (ZTRSNA).

10 Example

This example computes approximate error estimates for all the eigenvalues and right eigenvectors of the matrix T, where

$$T = \begin{pmatrix} 0.7995 & -0.1144 & 0.0060 & 0.0336 \\ 0.0000 & -0.0994 & 0.2478 & 0.3474 \\ 0.0000 & -0.6483 & -0.0994 & 0.2026 \\ 0.0000 & 0.0000 & 0.0000 & -0.1007 \end{pmatrix}$$

10.1 Program Text

```
Program f08qlfe
     FO8QLF Example Program Text
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!
!
      .. Use Statements ..
     Use nag_library, Only: dlange => f06raf, dtrevc, dtrsna, nag_wp, x02ajf
     .. Implicit None Statement ..
     Implicit None
!
      .. Parameters ..
                                       :: nin = 5, nout = 6
     Integer, Parameter
      .. Local Scalars ..
     Real (Kind=nag_wp)
                                        :: eps, tnorm
     Integer
                                        :: i, info, ldt, ldvl, ldvr, ldwork, m, &
     .. Local Arrays ..
!
     Real (Kind=nag_wp), Allocatable :: s(:), sep(:), t(:,:), vl(:,:),
                                           vr(:,:), work(:,:)
     Integer, Allocatable
                                        :: iwork(:)
                                        :: select(1)
     Logical
      .. Executable Statements ..
     Write (nout,*) 'F08QLF Example Program Results'
     Write (nout,*)
1
     Skip heading in data file
     Read (nin,*)
     Read (nin,*) n
     ldt = n
      ldvl = n
     ldvr = n
      ldwork = n
     Allocate (s(n), sep(n), t(ldt,n), vl(ldvl,n), vr(ldvr,n), work(ldwork,n+6),
        iwork(2*n-1))
     Read T from data file
     Read (nin,*)(t(i,1:n),i=1,n)
!
     Calculate the left and right eigenvectors of T
     The NAG name equivalent of dtrevc is f08qkf
!
     Call dtrevc('Both','All', select, n, t, ldt, vl, ldvl, vr, ldvr, n, m, work, info)
     Estimate condition numbers for all the eigenvalues and right
     eigenvectors of T
!
     The NAG name equivalent of dtrsna is f08qlf
     Call dtrsna('Both','All',select,n,t,ldt,vl,ldvl,vr,ldvr,s,sep,n,m,work, &
```

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ldwork,iwork,info)

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```
Print condition numbers of eigenvalues and right eigenvectors
     Write (nout,*) 'S'
Write (nout,99999) s(1:m)
     Write (nout,*)
      Write (nout,*) 'SEP'
     Write (nout, 99999) sep(1:m)
     Calculate approximate error estimates (using the 1-norm)
!
     eps = x02ajf()
     f06raf is the NAG name equivalent of the LAPACK auxiliary dlange
1
      tnorm = dlange('1-norm', n, n, t, ldt, work)
     Write (nout,*)
      Write (nout,*) 'Approximate error estimates for eigenvalues ',
        'of T (machine-dependent)'
     Write (nout, 99999) (eps*tnorm/s(i), i=1,m)
     Write (nout,*)
      Write (nout,*) 'Approximate error estimates for right ',
        'eigenvectors of T (machine-dependent)'
     Write (nout, 99999) (eps*tnorm/sep(i), i=1,m)
99999 Format ((3X,1P,7E11.1))
   End Program f08qlfe
10.2 Program Data
F08QLF Example Program Data
                                       :Value of N
 0.7995 -0.1144
                    0.0060 0.0336
 0.0000 -0.0994
                  0.2478 0.3474
 0.0000 -0.6483 -0.0994 0.2026
         0.0000
 0.0000
                   0.0000 -0.1007
                                       :End of matrix T
10.3 Program Results
```

```
FO8QLF Example Program Results
      9.9E-01
                 7.0E-01
                            7.0E-01
                                       5.7E-01
SEP
                 3.7E-01
      6.3E-01
                           3.7E-01
                                       3.1E-01
Approximate error estimates for eigenvalues of {\tt T} (machine-dependent)
      9.6E-17
                 1.4E-16
                            1.4E-16
                                       1.7E-16
Approximate error estimates for right eigenvectors of T (machine-dependent)
                 2.6E-16
                            2.6E-16
                                       3.1E-16
      1.5E-16
```

F08QLF.6 (last)

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