

# NAG Library Routine Document

## D01GCF

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

### 1 Purpose

D01GCF calculates an approximation to a definite integral in up to 20 dimensions, using the Korobov–Conroy number theoretic method.

### 2 Specification

```
SUBROUTINE D01GCF (NDIM, F, REGION, NPTS, VK, NRAND, ITRANS, RES, ERR,      &
                  IFAIL)
INTEGER          NDIM, NPTS, NRAND, ITRANS, IFAIL
REAL (KIND=nag_wp) F, VK(NDIM), RES, ERR
EXTERNAL        F, REGION
```

### 3 Description

D01GCF calculates an approximation to the integral

$$I = \int_{c_1}^{d_1} dx_1, \dots, \int_{c_n}^{d_n} dx_n f(x_1, x_2, \dots, x_n) \quad (1)$$

using the Korobov–Conroy number theoretic method (see Korobov (1957), Korobov (1963) and Conroy (1967)). The region of integration defined in (1) is such that generally  $c_i$  and  $d_i$  may be functions of  $x_1, x_2, \dots, x_{i-1}$ , for  $i = 2, 3, \dots, n$ , with  $c_1$  and  $d_1$  constants. The integral is first of all transformed to an integral over the  $n$ -cube  $[0, 1]^n$  by the change of variables

$$x_i = c_i + (d_i - c_i)y_i, \quad i = 1, 2, \dots, n.$$

The method then uses as its basis the number theoretic formula for the  $n$ -cube,  $[0, 1]^n$ :

$$\int_0^1 dx_1 \cdots \int_0^1 dx_n g(x_1, x_2, \dots, x_n) = \frac{1}{p} \sum_{k=1}^p g\left(\left\{\frac{ka_1}{p}\right\}, \dots, \left\{\frac{ka_n}{p}\right\}\right) - E \quad (2)$$

where  $\{x\}$  denotes the fractional part of  $x$ ,  $a_1, a_2, \dots, a_n$  are the so-called optimal coefficients,  $E$  is the error, and  $p$  is a prime integer. (It is strictly only necessary that  $p$  be relatively prime to all  $a_1, a_2, \dots, a_n$  and is in fact chosen to be even for some cases in Conroy (1967).) The method makes use of properties of the Fourier expansion of  $g(x_1, x_2, \dots, x_n)$  which is assumed to have some degree of periodicity. Depending on the choice of  $a_1, a_2, \dots, a_n$  the contributions from certain groups of Fourier coefficients are eliminated from the error,  $E$ . Korobov shows that  $a_1, a_2, \dots, a_n$  can be chosen so that the error satisfies

$$E \leq CKp^{-\alpha} \ln^{\alpha\beta} p \quad (3)$$

where  $\alpha$  and  $C$  are real numbers depending on the convergence rate of the Fourier series,  $\beta$  is a constant depending on  $n$ , and  $K$  is a constant depending on  $\alpha$  and  $n$ . There are a number of procedures for calculating these optimal coefficients. Korobov imposes the constraint that

$$a_1 = 1 \quad \text{and} \quad a_i = a^{i-1} \pmod{p} \quad (4)$$

and gives a procedure for calculating the argument,  $a$ , to satisfy the optimal conditions.

In this routine the periodisation is achieved by the simple transformation

$$x_i = y_i^2(3 - 2y_i), \quad i = 1, 2, \dots, n.$$

More sophisticated periodisation procedures are available but in practice the degree of periodisation does not appear to be a critical requirement of the method.

An easily calculable error estimate is not available apart from repetition with an increasing sequence of values of  $p$  which can yield erratic results. The difficulties have been studied by Cranley and Patterson (1976) who have proposed a Monte–Carlo error estimate arising from converting (2) into a stochastic integration rule by the inclusion of a random origin shift which leaves the form of the error (3) unchanged; i.e., in the formula (2),  $\left\{k\frac{a_i}{p}\right\}$  is replaced by  $\left\{\alpha_i + k\frac{a_i}{p}\right\}$ , for  $i = 1, 2, \dots, n$ , where each  $\alpha_i$ , is uniformly distributed over  $[0, 1]$ . Computing the integral for each of a sequence of random vectors  $\alpha$  allows a ‘standard error’ to be estimated.

This routine provides built-in sets of optimal coefficients, corresponding to six different values of  $p$ . Alternatively, the optimal coefficients may be supplied by you. Routines D01GYF and D01GZF compute the optimal coefficients for the cases where  $p$  is a prime number or  $p$  is a product of two primes, respectively.

## 4 References

Conroy H (1967) Molecular Shroedinger equation VIII. A new method for evaluating multi-dimensional integrals *J. Chem. Phys.* **47** 5307–5318

Cranley R and Patterson T N L (1976) Randomisation of number theoretic methods for mulitple integration *SIAM J. Numer. Anal.* **13** 904–914

Korobov N M (1957) The approximate calculation of multiple integrals using number theoretic methods *Dokl. Acad. Nauk SSSR* **115** 1062–1065

Korobov N M (1963) *Number Theoretic Methods in Approximate Analysis* Fizmatgiz, Moscow

## 5 Arguments

- 1: NDIM – INTEGER *Input*  
*On entry:*  $n$ , the number of dimensions of the integral.  
*Constraint:*  $1 \leq \text{NDIM} \leq 20$ .
- 2: F – REAL (KIND=nag\_wp) FUNCTION, supplied by the user. *External Procedure*  
 F must return the value of the integrand  $f$  at a given point.

The specification of F is:

```
FUNCTION F (NDIM, X)
REAL (KIND=nag_wp) F
INTEGER NDIM
REAL (KIND=nag_wp) X(NDIM)
```

- 1: NDIM – INTEGER *Input*  
*On entry:*  $n$ , the number of dimensions of the integral.
- 2: X(NDIM) – REAL (KIND=nag\_wp) array *Input*  
*On entry:* the coordinates of the point at which the integrand  $f$  must be evaluated.

F must either be a module subprogram USED by, or declared as EXTERNAL in, the (sub) program from which D01GCF is called. Arguments denoted as *Input* must **not** be changed by this procedure.

- 3: REGION – SUBROUTINE, supplied by the user. *External Procedure*  
 REGION must evaluate the limits of integration in any dimension.

The specification of REGION is:

```
SUBROUTINE REGION (NDIM, X, J, C, D)
```

```
INTEGER NDIM, J
```

```
REAL (KIND=nag_wp) X(NDIM), C, D
```

- |    |   |               |
|----|---|---------------|
| 1: | NDIM – INTEGER  | <i>Input</i>  |
|    | <i>On entry:</i> $n$ , the number of dimensions of the integral.  |               |
| 2: | X(NDIM) – REAL (KIND=nag_wp) array  | <i>Input</i>  |
|    | <i>On entry:</i> $X(1), \dots, X(j-1)$ contain the current values of the first $(j-1)$ variables, which may be used if necessary in calculating $c_j$ and $d_j$ . |               |
| 3: | J – INTEGER   | <i>Input</i>  |
|    | <i>On entry:</i> the index $j$ for which the limits of the range of integration are required.   |               |
| 4: | C – REAL (KIND=nag_wp)  | <i>Output</i> |
|    | <i>On exit:</i> the lower limit $c_j$ of the range of $x_j$ .   |               |
| 5: | D – REAL (KIND=nag_wp)  | <i>Output</i> |
|    | <i>On exit:</i> the upper limit $d_j$ of the range of $x_j$ .   |               |

REGION must either be a module subprogram USED by, or declared as EXTERNAL in, the (sub) program from which D01GCF is called. Arguments denoted as *Input* must **not** be changed by this procedure.

- |    |   |                     |
|----|---|---------------------|
| 4: | NPTS – INTEGER  | <i>Input</i>        |
|    | <i>On entry:</i> the Korobov rule to be used. There are two alternatives depending on the value of NPTS.  |                     |
|    | (i) $1 \leq \text{NPTS} \leq 6$ .   |                     |
|    | In this case one of six preset rules is chosen using 2129, 5003, 10007, 20011, 40009 or 80021 points depending on the respective value of NPTS being 1, 2, 3, 4, 5 or 6.  |                     |
|    | (ii) $\text{NPTS} > 6$ .  |                     |
|    | NPTS is the number of actual points to be used with corresponding optimal coefficients supplied in the array VK.  |                     |
|    | <i>Constraint:</i> $\text{NPTS} \geq 1$ .   |                     |
| 5: | VK(NDIM) – REAL (KIND=nag_wp) array   | <i>Input/Output</i> |
|    | <i>On entry:</i> if $\text{NPTS} > 6$ , VK must contain the $n$ optimal coefficients (which may be calculated using D01GYF or D01GZF).  |                     |
|    | If $\text{NPTS} \leq 6$ , VK need not be set.   |                     |
|    | <i>On exit:</i> if $\text{NPTS} > 6$ , VK is unchanged.   |                     |
|    | If $\text{NPTS} \leq 6$ , VK contains the $n$ optimal coefficients used by the preset rule.   |                     |
| 6: | NRAND – INTEGER   | <i>Input</i>        |
|    | <i>On entry:</i> the number of random samples to be generated in the error estimation (generally a small value, say 3 to 5, is sufficient). The total number of integrand evaluations will be $\text{NRAND} \times \text{NPTS}$ . |                     |
|    | <i>Constraint:</i> $\text{NRAND} \geq 1$ .  |                     |

- 7: ITRANS – INTEGER *Input*  
*On entry:* indicates whether the periodising transformation is to be used.  
 ITRANS = '0'  
     The transformation is to be used.  
 ITRANS  $\neq$  '0'  
     The transformation is to be suppressed (to cover cases where the integrand may already be periodic or where you want to specify a particular transformation in the definition of F).  
*Suggested value:* ITRANS = '0'.
- 8: RES – REAL (KIND=nag\_wp) *Output*  
*On exit:* the approximation to the integral  $I$ .
- 9: ERR – REAL (KIND=nag\_wp) *Output*  
*On exit:* the standard error as computed from NRAND sample values. If NRAND = 1, then ERR contains zero.
- 10: IFAIL – INTEGER *Input/Output*  
*On entry:* IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this argument you should refer to Section 3.4 in How to Use the NAG Library and its Documentation for details.  
 For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this argument, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**  
*On exit:* IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

## 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, NDIM < 1,  
 or NDIM > 20.

IFAIL = 2

On entry, NPTS < 1.

IFAIL = 3

On entry, NRAND < 1.

IFAIL = -99

An unexpected error has been triggered by this routine. Please contact NAG.

See Section 3.9 in How to Use the NAG Library and its Documentation for further information.

IFAIL = -399

Your licence key may have expired or may not have been installed correctly.

See Section 3.8 in How to Use the NAG Library and its Documentation for further information.

IFAIL = -999

Dynamic memory allocation failed.

See Section 3.7 in How to Use the NAG Library and its Documentation for further information.

## 7 Accuracy

An estimate of the absolute standard error is given by the value, on exit, of ERR.

## 8 Parallelism and Performance

D01GCF is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

Please consult the X06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this routine. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The time taken by D01GCF will be approximately proportional to  $\text{NRAND} \times p$ , where  $p$  is the number of points used.

The exact values of RES and ERR on return will depend (within statistical limits) on the sequence of random numbers generated within D01GCF by calls to G05SAF. Separate runs will produce identical answers.

## 10 Example

This example calculates the integral

$$\int_0^1 \int_0^1 \int_0^1 \int_0^1 \cos(0.5 + 2(x_1 + x_2 + x_3 + x_4) - 4) dx_1 dx_2 dx_3 dx_4.$$

### 10.1 Program Text

```
! D01GCF Example Program Text
! Mark 26 Release. NAG Copyright 2016.

Module d01gcfe_mod

! D01GCF Example Program Module:
! Parameters and User-defined Routines

! .. Use Statements ..
Use nag_library, Only: nag_wp
! .. Implicit None Statement ..
Implicit None
! .. Accessibility Statements ..
Private
Public :: f, region
! .. Parameters ..
Integer, Parameter, Public :: ndim = 4, nout = 6
Contains
Subroutine region(ndim,x,j,c,d)

! .. Scalar Arguments ..
Real (Kind=nag_wp), Intent (Out) :: c, d
Integer, Intent (In) :: j, ndim
! .. Array Arguments ..
Real (Kind=nag_wp), Intent (In) :: x(ndim)
! .. Executable Statements ..
c = 0.0E0_nag_wp
d = 1.0E0_nag_wp
```

```

    Return

End Subroutine region
Function f(ndim,x)

!     .. Function Return Value ..
!     Real (Kind=nag_wp)           :: f
!     .. Scalar Arguments ..
!     Integer, Intent (In)         :: ndim
!     .. Array Arguments ..
!     Real (Kind=nag_wp), Intent (In) :: x(ndim)
!     .. Intrinsic Procedures ..
!     Intrinsic                    :: cos, real, sum
!     .. Executable Statements ..
    f = cos(0.5E0_nag_wp+2.0E0_nag_wp*sum(x(1:ndim))-real(ndim,kind=nag_wp &
    ))

    Return

End Function f
End Module d01gcfe_mod
Program d01gcfe

!     D01GCF Example Main Program

!     .. Use Statements ..
!     Use nag_library, Only: d01gcf, nag_wp
!     Use d01gcfe_mod, Only: f, ndim, nout, region
!     .. Implicit None Statement ..
!     Implicit None
!     .. Local Scalars ..
!     Real (Kind=nag_wp)           :: err, res
!     Integer                      :: ifail, itrans, npts, nrand
!     .. Local Arrays ..
!     Real (Kind=nag_wp)           :: vk(ndim)
!     .. Executable Statements ..
!     Write (nout,*) 'D01GCF Example Program Results'

    npts = 2
    itrans = 0
    nrand = 4

    ifail = 0
    Call d01gcf(ndim,f,region,npts,vk,nrand,itrans,res,err,ifail)

    Write (nout,*)
    Write (nout,99999) 'Result =', res, ' Standard error =', err

99999 Format (1X,A,F13.5,A,E10.2)
End Program d01gcfe

```

## 10.2 Program Data

None.

## 10.3 Program Results

D01GCF Example Program Results

Result =           0.43999 Standard error = 0.19E-05

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