NAG Library Routine Document

D01ALF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

D01ALF is a general purpose integrator which calculates an approximation to the integral of a function f(x) over a finite interval [a,b]:

$$I = \int_{a}^{b} f(x) \, dx$$

where the integrand may have local singular behaviour at a finite number of points within the integration interval.

2 Specification

```
SUBROUTINE DO1ALF (F, A, B, NPTS, POINTS, EPSABS, EPSREL, RESULT, ABSERR, W, LW, IW, LIW, IFAIL)

INTEGER
REAL (KIND=nag_wp) F, A, B, POINTS(*), EPSABS, EPSREL, RESULT, ABSERR, W(LW)

EXTERNAL

F
```

3 Description

D01ALF is based on the QUADPACK routine QAGP (see Piessens *et al.* (1983)). It is very similar to D01AJF, but allows you to supply 'break-points', points at which the integrand is known to be difficult. It employs an adaptive algorithm, using the Gauss 10-point and Kronrod 21-point rules. The algorithm, described in de Doncker (1978), incorporates a global acceptance criterion (as defined by Malcolm and Simpson (1976)) together with the ϵ -algorithm (see Wynn (1956)) to perform extrapolation. The user-supplied 'break-points' always occur as the end points of some sub-interval during the adaptive process. The local error estimation is described in Piessens *et al.* (1983).

4 References

de Doncker E (1978) An adaptive extrapolation algorithm for automatic integration *ACM SIGNUM Newsl.* **13(2)** 12–18

Malcolm M A and Simpson R B (1976) Local versus global strategies for adaptive quadrature ACM Trans. Math. Software 1 129–146

Piessens R, de Doncker-Kapenga E, Ûberhuber C and Kahaner D (1983) *QUADPACK, A Subroutine Package for Automatic Integration* Springer-Verlag

Wynn P (1956) On a device for computing the $e_m(S_n)$ transformation Math. Tables Aids Comput. 10 91–96

5 Arguments

1: F - REAL (KIND=nag_wp) FUNCTION, supplied by the user. External Procedure

F must return the value of the integrand f at a given point.

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The specification of F is:

FUNCTION F (X)
REAL (KIND=nag_wp) F
REAL (KIND=nag_wp) X

1: $X - REAL (KIND=nag_wp)$

Input

On entry: the point at which the integrand f must be evaluated.

F must either be a module subprogram USEd by, or declared as EXTERNAL in, the (sub) program from which D01ALF is called. Arguments denoted as *Input* must **not** be changed by this procedure.

2: $A - REAL (KIND=nag_wp)$

Input

On entry: a, the lower limit of integration.

3: $B - REAL (KIND=nag_wp)$

Input

On entry: b, the upper limit of integration. It is not necessary that a < b.

4: NPTS – INTEGER

Input

On entry: the number of user-supplied break-points within the integration interval.

Constraint: NPTS ≥ 0 and NPTS $< \min((LW - 2 \times NPTS - 4)/4, (LIW - NPTS - 2)/2)$.

5: POINTS(*) - REAL (KIND=nag wp) array

Input

Note: the dimension of the array POINTS must be at least max(1, NPTS).

On entry: the user-specified break-points.

Constraint: the break-points must all lie within the interval of integration (but may be supplied in any order).

6: EPSABS – REAL (KIND=nag wp)

Input

On entry: the absolute accuracy required. If EPSABS is negative, the absolute value is used. See Section 7.

7: EPSREL – REAL (KIND=nag wp)

Input

On entry: the relative accuracy required. If EPSREL is negative, the absolute value is used. See Section 7.

8: RESULT – REAL (KIND=nag wp)

Output

On exit: the approximation to the integral I.

9: ABSERR – REAL (KIND=nag wp)

Output

On exit: an estimate of the modulus of the absolute error, which should be an upper bound for |I - RESULT|.

10: W(LW) - REAL (KIND=nag wp) array

Output

On exit: details of the computation see Section 9 for more information.

11: LW – INTEGER

Input

On entry: the dimension of the array W as declared in the (sub)program from which D01ALF is called. The value of LW (together with that of LIW) imposes a bound on the number of sub-intervals into which the interval of integration may be divided by the routine. The number of sub-

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intervals cannot exceed $(LW - 2 \times NPTS - 4)/4$. The more difficult the integrand, the larger LW should be

Suggested value: a value in the range 800 to 2000 is adequate for most problems.

Constraint: LW $\geq 2 \times NPTS + 8$.

12: IW(LIW) – INTEGER array

Output

On exit: IW(1) contains the actual number of sub-intervals used. The rest of the array is used as workspace.

13: LIW – INTEGER

Input

On entry: the dimension of the array IW as declared in the (sub)program from which D01ALF is called. The number of sub-intervals into which the interval of integration may be divided cannot exceed (LIW - NPTS - 2)/2.

Suggested value: LIW = LW/2.

Constraint: LIW \geq NPTS + 4.

14: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this argument you should refer to Section 3.4 in How to Use the NAG Library and its Documentation for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, because for this routine the values of the output arguments may be useful even if IFAIL $\neq 0$ on exit, the recommended value is -1. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Note: D01ALF may return useful information for one or more of the following detected errors or warnings.

Errors or warnings detected by the routine:

IFAIL = 1

The maximum number of subdivisions allowed with the given workspace has been reached without the accuracy requirements being achieved. Look at the integrand in order to determine the integration difficulties. If the position of a local difficulty within the interval can be determined (e.g., a singularity of the integrand or its derivative, a peak, a discontinuity, etc.) it should be supplied to the routine as an element of the vector POINTS. If necessary, another integrator, which is designed for handling the type of difficulty involved, must be used. Alternatively, consider relaxing the accuracy requirements specified by EPSABS and EPSREL, or increasing the amount of workspace.

IFAIL = 2

Round-off error prevents the requested tolerance from being achieved. Consider requesting less accuracy.

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IFAIL = 3

Extremely bad local integrand behaviour causes a very strong subdivision around one (or more) points of the interval. The same advice applies as in the case of IFAIL = 1.

IFAIL = 4

The requested tolerance cannot be achieved because the extrapolation does not increase the accuracy satisfactorily; the returned result is the best which can be obtained. The same advice applies as in the case of IFAIL = 1.

IFAIL = 5

The integral is probably divergent, or slowly convergent. Please note that divergence can occur with any nonzero value of IFAIL.

IFAIL = 6

The input is invalid: break-points are specified outside the integration range, NPTS $> \min\left((LW-2\times NPTS-4)/4,(LIW-NPTS-2)/2\right)$ or NPTS < 0. RESULT and ABSERR are set to zero.

$$IFAIL = 7$$

On entry, LW
$$< 2 \times NPTS + 8$$
, or LIW $< NPTS + 4$.

$$IFAIL = -99$$

An unexpected error has been triggered by this routine. Please contact NAG.

See Section 3.9 in How to Use the NAG Library and its Documentation for further information.

$$IFAIL = -399$$

Your licence key may have expired or may not have been installed correctly.

See Section 3.8 in How to Use the NAG Library and its Documentation for further information.

$$IFAIL = -999$$

Dynamic memory allocation failed.

See Section 3.7 in How to Use the NAG Library and its Documentation for further information.

7 Accuracy

D01ALF cannot guarantee, but in practice usually achieves, the following accuracy:

$$|I - RESULT| \le tol$$
,

where

$$tol = \max\{|EPSABS|, |EPSREL| \times |I|\},\$$

and EPSABS and EPSREL are user-specified absolute and relative error tolerances. Moreover, it returns the quantity ABSERR which, in normal circumstances, satisfies

$$|I - RESULT| \le ABSERR \le tol.$$

8 Parallelism and Performance

D01ALF is not threaded in any implementation.

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9 Further Comments

The time taken by D01ALF depends on the integrand and the accuracy required.

If IFAIL $\neq 0$ on exit, then you may wish to examine the contents of the array W, which contains the end points of the sub-intervals used by D01ALF along with the integral contributions and error estimates over these sub-intervals.

Specifically, for i = 1, 2, ..., n, let r_i denote the approximation to the value of the integral over the subinterval $[a_i, b_i]$ in the partition of [a, b] and e_i be the corresponding absolute error estimate. Then,

$$\int_{a_i}^{b_i} f(x) dx \simeq r_i$$
 and RESULT $= \sum_{i=1}^n r_i$ unless D01ALF terminates while testing for divergence of the

integral (see Section 3.4.3 of Piessens *et al.* (1983)). In this case, RESULT (and ABSERR) are taken to be the values returned from the extrapolation process. The value of n is returned in IW(1), and the values a_i , b_i , e_i and r_i are stored consecutively in the array W, that is:

$$a_i = \mathrm{W}(i),$$
 $b_i = \mathrm{W}(n+i),$ $e_i = \mathrm{W}(2n+i)$ and $r_i = \mathrm{W}(3n+i).$

10 Example

This example computes

$$\int_0^1 \frac{1}{\sqrt{|x-1/7|}} \, dx.$$

A break-point is specified at x = 1/7, at which point the integrand is infinite. (For definiteness the function FST returns the value 0.0 at this point.)

10.1 Program Text

```
D01ALF Example Program Text
   Mark 26 Release. NAG Copyright 2016.
!
    Module d01alfe_mod
1
     D01ALF Example Program Module:
!
             Parameters and User-defined Routines
1
      .. Use Statements ..
     Use nag_library, Only: nag_wp
      .. Implicit None Statement ..
!
     Implicit None
      .. Accessibility Statements ..
!
     Private
                                        :: f
     Public
      .. Parameters ..
     Integer, Parameter, Public
                                        :: lw = 800, nout = 6, npts = 1
     Integer, Parameter, Public
                                        :: liw = lw/2
    Contains
     Function f(x)
!
        .. Function Return Value ..
        Real (Kind=nag_wp)
        .. Scalar Arguments ..
!
        Real (Kind=nag_wp), Intent (In) :: x
!
        .. Local Scalars ..
        Real (Kind=nag_wp)
                                        :: a
1
        .. Intrinsic Procedures ..
        Intrinsic
                                        :: abs
!
        .. Executable Statements ..
        a = abs(x-1.0E0_nag_wp/7.0E0_nag_wp)
```

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```
If (a/=0.0E0_nag_wp) Then
             f = a**(-0.5E0_nag_wp)
           Else
            f = 0.0E0_nag_wp
           End If
           Return
        End Function f
     End Module d01alfe_mod
     Program d01alfe
        D01ALF Example Main Program
!
1
        .. Use Statements ..
        Use nag_library, Only: d01alf, nag_wp
Use d01alfe_mod, Only: f, liw, lw, nout, npts
1
        .. Implicit None Statement ..
        Implicit None
        .. Local Scalars ..
!
        Real (Kind=nag_wp)
                                                     :: a, abserr, b, epsabs, epsrel, result
                                                     :: ifail
        Integer
        .. Local Arrays ..
        Real (Kind=nag_wp), Allocatable :: points(:), w(:)
                                                   :: iw(:)
        Integer, Allocatable
        .. Executable Statements ..
        Write (nout,*) 'DO1ALF Example Program Results'
        Allocate (points(npts),w(lw),iw(liw))
        epsabs = 0.0E0_nag_wp
        epsrel = 1.0E-03_nag_wp
        a = 0.0E0_nag_wp
        b = 1.0E0_nag_wp
        points(1) = 1.0E0_nag_wp/7.0E0_nag_wp
        ifail = -1
        Call d01alf(f,a,b,npts,points,epsabs,epsrel,result,abserr,w,lw,iw,liw,
           ifail)
        If (ifail>=0) Then
           Write (nout,*)
          Write (nout,99999) 'A ', 'lower limit of integration', a
Write (nout,99999) 'B ', 'upper limit of integration', b
Write (nout,99998) 'EPSABS', 'absolute accuracy requested', epsabs
Write (nout,99998) 'EPSREL', 'relative accuracy requested', epsrel
          Write (nout,99995) 'POINTS(1)', 'given break-point', points(1)
        End If
        If (ifail>=0 .And. ifail<=5) Then</pre>
           Write (nout,*)
          Write (nout,99997) 'RESULT', 'approximation to the integral', result Write (nout,99998) 'ABSERR', 'estimate of the absolute error', abserr Write (nout,99996) 'IW(1)', 'number of subintervals used', iw(1)
        End If
                              - ',A32,' = ',F10.4)
- ',A32,' = ',E9.2)
99999 Format (1X,A6,'
99998 Format (1X,A6,'
                              - ',A32,' = ',F9.5)
- ',A32,' = ',I4)
99997 Format (1X,A6,'
99996 Format (1X,A6,' - ',A32,' = ',I4)
99995 Format (1X,A9,' - ',A32,' = ',F10.4)
     End Program d01alfe
```

10.2 Program Data

None.

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10.3 Program Results

D01ALF Example Program Results

```
A - lower limit of integration = 0.0000
B - upper limit of integration = 1.0000
EPSABS - absolute accuracy requested = 0.00E+00
EPSREL - relative accuracy requested = 0.10E-02
POINTS(1) - given break-point = 0.1429

RESULT - approximation to the integral = 2.60757
ABSERR - estimate of the absolute error = 0.62E-13
IW(1) - number of subintervals used = 12
```

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