# NAG Library Routine Document <br> E01BAF 

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

## 1 Purpose

E01BAF determines a cubic spline interpolant to a given set of data.

## 2 Specification

```
SUBROUTINE EO1BAF (M, X, Y, LAMDA, C, LCK, WRK, LWRK, IFAIL)
INTEGER M, LCK, LWRK, IFAIL
REAL (KIND=nag_wp) X (M), Y(M), LAMDA(LCK), C(LCK), WRK(LWRK)
```


## 3 Description

E01BAF determines a cubic spline $s(x)$, defined in the range $x_{1} \leq x \leq x_{m}$, which interpolates (passes exactly through) the set of data points $\left(x_{i}, y_{i}\right)$, for $i=1,2, \ldots, m$, where $m \geq 4$ and $x_{1}<x_{2}<\cdots<x_{m}$. Unlike some other spline interpolation algorithms, derivative end conditions are not imposed. The spline interpolant chosen has $m-4$ interior knots $\lambda_{5}, \lambda_{6}, \ldots, \lambda_{m}$, which are set to the values of $x_{3}, x_{4}, \ldots, x_{m-2}$ respectively. This spline is represented in its B-spline form (see Cox (1975)):

$$
s(x)=\sum_{i=1}^{m} c_{i} N_{i}(x)
$$

where $N_{i}(x)$ denotes the normalized B-spline of degree 3 , defined upon the knots $\lambda_{i}, \lambda_{i+1}, \ldots, \lambda_{i+4}$, and $c_{i}$ denotes its coefficient, whose value is to be determined by the routine.
The use of B-splines requires eight additional knots $\lambda_{1}, \lambda_{2}, \lambda_{3}, \lambda_{4}, \lambda_{m+1}, \lambda_{m+2}, \lambda_{m+3}$ and $\lambda_{m+4}$ to be specified; E01BAF sets the first four of these to $x_{1}$ and the last four to $x_{m}$.

The algorithm for determining the coefficients is as described in Cox (1975) except that $Q R$ factorization is used instead of $L U$ decomposition. The implementation of the algorithm involves setting up appropriate information for the related routine E02BAF followed by a call of that routine. (See E02BAF for further details.)

Values of the spline interpolant, or of its derivatives or definite integral, can subsequently be computed as detailed in Section 9.

## 4 References

Cox M G (1975) An algorithm for spline interpolation J. Inst. Math. Appl. 15 95-108
Cox M G (1977) A survey of numerical methods for data and function approximation The State of the Art in Numerical Analysis (ed D A H Jacobs) 627-668 Academic Press

## 5 Parameters

1: M - INTEGER Input
On entry: $m$, the number of data points.
Constraint: $\mathrm{M} \geq 4$.

2: $\quad \mathrm{X}(\mathrm{M})-\mathrm{REAL}(\mathrm{KIND}=$ nag_wp $)$ array
Input
On entry: $\mathrm{X}(i)$ must be set to $x_{i}$, the $i$ th data value of the independent variable $x$, for $i=1,2, \ldots, m$.
Constraint: $\mathrm{X}(i)<\mathrm{X}(i+1)$, for $i=1,2, \ldots, \mathrm{M}-1$.
3: $\quad \mathrm{Y}(\mathrm{M})-$ REAL (KIND=nag_wp) array
Input
On entry: $\mathrm{Y}(i)$ must be set to $y_{i}$, the $i$ th data value of the dependent variable $y$, for $i=1,2, \ldots, m$.

4: LAMDA(LCK) - REAL (KIND=nag_wp) array
Output
On exit: the value of $\lambda_{i}$, the $i$ th knot, for $i=1,2, \ldots, m+4$.
5: $\quad \mathrm{C}(\mathrm{LCK})-$ REAL (KIND=nag_wp) array
Output
On exit: the coefficient $c_{i}$ of the B-spline $N_{i}(x)$, for $i=1,2, \ldots, m$. The remaining elements of the array are not used.

6: LCK - INTEGER Input
On entry: the dimension of the arrays LAMDA and C as declared in the (sub)program from which E01BAF is called.
Constraint: $\mathrm{LCK} \geq \mathrm{M}+4$.
WRK(LWRK) - REAL (KIND=nag_wp) array Workspace
LWRK - INTEGER
Input
On entry: the dimension of the array WRK as declared in the (sub)program from which E01BAF is called.

Constraint: LWRK $\geq 6 \times \mathrm{M}+16$.
9: IFAIL - INTEGER
Input/Output
On entry: IFAIL must be set to $0,-1$ or 1 . If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0 . When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

On exit: IFAIL $=0$ unless the routine detects an error or a warning has been flagged (see Section 6).

## 6 Error Indicators and Warnings

If on entry IFAIL $=0$ or -1 , explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:
IFAIL $=1$
On entry, $\mathrm{M}<4$,
or $\quad \mathrm{LCK}<\mathrm{M}+4$,
or $\quad$ LWRK $<6 \times M+16$.

IFAIL $=2$
The X -values fail to satisfy the condition
$\mathrm{X}(1)<\mathrm{X}(2)<\mathrm{X}(3)<\cdots<\mathrm{X}(\mathrm{M})$.
IFAIL $=-99$
An unexpected error has been triggered by this routine. Please contact NAG.
See Section 3.8 in the Essential Introduction for further information.
IFAIL $=-399$
Your licence key may have expired or may not have been installed correctly.
See Section 3.7 in the Essential Introduction for further information.
IFAIL $=-999$
Dynamic memory allocation failed.
See Section 3.6 in the Essential Introduction for further information.

## $7 \quad$ Accuracy

The rounding errors incurred are such that the computed spline is an exact interpolant for a slightly perturbed set of ordinates $y_{i}+\delta y_{i}$. The ratio of the root-mean-square value of the $\delta y_{i}$ to that of the $y_{i}$ is no greater than a small multiple of the relative machine precision.

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

The time taken by E01BAF is approximately proportional to $m$.
All the $x_{i}$ are used as knot positions except $x_{2}$ and $x_{m-1}$. This choice of knots (see Cox (1977)) means that $s(x)$ is composed of $m-3$ cubic arcs as follows. If $m=4$, there is just a single arc space spanning the whole interval $x_{1}$ to $x_{4}$. If $m \geq 5$, the first and last arcs span the intervals $x_{1}$ to $x_{3}$ and $x_{m-2}$ to $x_{m}$ respectively. Additionally if $m \geq 6$, the $i$ th arc, for $i=2,3, \ldots, m-4$, spans the interval $x_{i+1}$ to $x_{i+2}$.
After the call
CALL EO1BAF (M, X, Y, LAMDA, C, LCK, WRK, LWRK, IFAIL)
the following operations may be carried out on the interpolant $s(x)$.
The value of $s(x)$ at $x=\mathrm{X}$ can be provided in the real variable S by the call

```
CALL EO2BBF (M+4, LAMDA, C, X, S, IFAIL)
```

(see E02BBF).
The values of $s(x)$ and its first three derivatives at $x=\mathrm{X}$ can be provided in the real array S of dimension 4 , by the call

CALL EO2BCF (M+4, LAMDA, C, X, LEFT, S, IFAIL)
(see E02BCF).
Here LEFT must specify whether the left- or right-hand value of the third derivative is required (see E02BCF for details).
The value of the integral of $s(x)$ over the range $x_{1}$ to $x_{m}$ can be provided in the real variable DINT by
CALL E02BDF ( $\mathrm{M}+4$, LAMDA, C , DINT, IFAIL)
(see E02BDF).

## 10 Example

This example sets up data from 7 values of the exponential function in the interval 0 to 1 . E01BAF is then called to compute a spline interpolant to these data.

The spline is evaluated by E02BBF, at the data points and at points halfway between each adjacent pair of data points, and the spline values and the values of $e^{x}$ are printed out.

### 10.1 Program Text

```
Program e01bafe
    EO1BAF Example Program Text
    Mark 25 Release. NAG Copyright 2014.
    .. Use Statements ..
    Use nag_library, Only: e01baf, e02bbf, nag_wp
    .. Implicit None Statement ..
    Implicit None
! .. Parameters ..
    Integer, Parameter :: m = 7, nout = 6
    Integer, Parameter :: lck = m + 4
    Integer, Parameter :: lwrk = 6*m + 16
    Real (Kind=nag_wp), Parameter : : x(m) = (/O.0E0_nag_wp,0.2E0_nag_wp, &
        0.4E0_nag_wp,0.6E0_nag_wp,0.75E0_nag_wp,0.9E0_nag_wp,1.0E0_nag_wp/)
        .. Local Scalars ..
        Real (Kind=nag_wp) :: fit, xarg
        Integer :: ifail, j, r
        Real (Kind=nag_wp) :: c(lck), lamda(lck), wrk(lwrk), y(m)
! .. Intrinsic Procedures ..
        Intrinsic :: exp
        .. Executable Statements ..
        Write (nout,*) 'EO1BAF Example Program Results'
        y(1:m) = exp(x(1:m))
        ifail = 0
        Call e01baf(m,x,y,lamda,c,lck,wrk,lwrk,ifail)
        Write (nout,*)
        Write (nout,*) , J Knot LAMDA(J+2) B-spline coeff C(J)'
        Write (nout,*)
        j = 1
        Write (nout,99998) j, c(1)
        Do j = 2,m - 1
        Write (nout,99999) j, lamda(j+2), c(j)
End Do
Write (nout,99998) m, c(m)
Write (nout,*)
Write (nout,*) &
    ' R Abscissa Ordinate Spline'
Write (nout,*)
Do r = 1,m
    ifail = 0
    Call e02bbf(m+4,lamda,c,x(r),fit,ifail)
    Write (nout,99999) r, x(r), y(r), fit
    If (r<m) Then
        xarg = 0.5E0_nag_wp*(x (r)+x(r+1))
        ifail = 0
```

```
    Call e02bbf(m+4,lamda,c,xarg,fit,ifail)
    Write (nout,99997) xarg, fit
        End If
        End Do
99999 Format (1X,I4,F15.4,2F20.4)
99998 Format (1X,I4,F35.4)
99997 Format (1X,F19.4,F40.4)
    End Program e01bafe
```


### 10.2 Program Data

None.

### 10.3 Program Results

| J | Knot LAMDA (J+2) | B-spline coeff C(J) |  |
| :---: | :---: | :---: | :---: |
| 1 |  | 1.0000 |  |
| 2 | 0.0000 | 1.1336 |  |
| 3 | 0.4000 | 1.3726 |  |
| 4 | 0.6000 | 1.7827 |  |
| 5 | 0.7500 | 2.1744 |  |
| 6 | 1.0000 | 2.4918 |  |
| 7 |  | 2.7183 |  |
| R | Abscissa | Ordinate | Spline |
| 1 | 0.0000 | 1.0000 | 1.0000 |
|  | 0.1000 |  | 1.1052 |
| 2 | 0.2000 | 1.2214 | 1.2214 |
|  | 0.3000 |  | 1.3498 |
| 3 | 0.4000 | 1.4918 | 1.4918 |
|  | 0.5000 |  | 1.6487 |
| 4 | 0.6000 | 1.8221 | 1.8221 |
|  | 0.6750 |  | 1.9640 |
| 5 | 0.7500 | 2.1170 | 2.1170 |
|  | 0.8250 |  | 2.2819 |
| 6 | 0.9000 | 2.4596 | 2.4596 |
|  | 0.9500 |  | 2.5857 |
| 7 | 1.0000 | 2.7183 | 2.7183 |

