NAG Library Routine Document

D01FDF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

D01FDF calculates an approximation to a definite integral in up to 30 dimensions, using the method of Sag and Szekeres (see Sag and Szekeres (1964)). The region of integration is an n-sphere, or by built-in transformation via the unit n-cube, any product region.

2 Specification

```
SUBROUTINE DO1FDF (NDIM, F, SIGMA, REGION, LIMIT, RO, U, RESULT, NCALLS, IFAIL)

INTEGER NDIM, LIMIT, NCALLS, IFAIL

REAL (KIND=nag_wp) F, SIGMA, RO, U, RESULT

EXTERNAL F, REGION
```

3 Description

D01FDF calculates an approximation to

$$\int\limits_{n\text{-sphere of radius }\sigma} f(x_1,x_2,\ldots,x_n) dx_1 dx_2 \cdots dx_n \tag{1}$$

or, more generally,

$$\int_{c_1}^{d_1} dx_1 \cdots \int_{c_n}^{d_n} dx_n f(x_1, \dots, x_n)$$
 (2)

where each c_i and d_i may be functions of x_i (j < i).

The routine uses the method of Sag and Szekeres (1964), which exploits a property of the shifted p-point trapezoidal rule, namely, that it integrates exactly all polynomials of degree < p (see Krylov (1962)). An attempt is made to induce periodicity in the integrand by making a parameterised transformation to the unit n-sphere. The Jacobian of the transformation and all its direct derivatives vanish rapidly towards the surface of the unit n-sphere, so that, except for functions which have strong singularities on the boundary, the resulting integrand will be pseudo-periodic. In addition, the variation in the integrand can be considerably reduced, causing the trapezoidal rule to perform well.

Integrals of the form (1) are transformed to the unit n-sphere by the change of variables:

$$x_i = y_i \frac{\sigma}{r} \tanh\left(\frac{ur}{1 - r^2}\right)$$

where $r^2 = \sum_{i=1}^{n} y_i^2$ and u is an adjustable parameter.

Integrals of the form (2) are first of all transformed to the n-cube $[-1,1]^n$ by a linear change of variables

$$x_i = ((d_i + c_i) + (d_i - c_i)y_i)/2$$

and then to the unit sphere by a further change of variables

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$$y_i = \tanh\left(\frac{uz_i}{1-r}\right)$$

where $r^2 = \sum_{i=1}^{n} z_i^2$ and u is again an adjustable parameter.

The parameter u in these transformations determines how the transformed integrand is distributed between the origin and the surface of the unit n-sphere. A typical value of u is 1.5. For larger u, the integrand is concentrated toward the centre of the unit n-sphere, while for smaller u it is concentrated toward the perimeter.

In performing the integration over the unit n-sphere by the trapezoidal rule, a displaced equidistant grid of size h is constructed. The points of the mesh lie on concentric layers of radius

$$r_i = \frac{h}{4}\sqrt{n+8(i-1)}, \qquad i = 1, 2, 3, \dots$$

The routine requires you to specify an approximate maximum number of points to be used, and then computes the largest number of whole layers to be used, subject to an upper limit of 400 layers.

In practice, the rapidly-decreasing Jacobian makes it unnecessary to include the whole unit n-sphere and the integration region is limited by a user-specified cut-off radius $r_0 < 1$. The grid-spacing h is determined by r_0 and the number of layers to be used. A typical value of r_0 is 0.8.

Some experimentation may be required with the choice of r_0 (which determines how much of the unit n-sphere is included) and u (which determines how the transformed integrand is distributed between the origin and surface of the unit n-sphere), to obtain best results for particular families of integrals. This matter is discussed further in Section 8.

4 References

Krylov V I (1962) Approximate Calculation of Integrals (trans A H Stroud) Macmillan

Sag T W and Szekeres G (1964) Numerical evaluation of high-dimensional integrals *Math. Comput.* **18** 245–253

5 Parameters

1: NDIM – INTEGER Input

On entry: n, the number of dimensions of the integral.

Constraint: $1 \le NDIM \le 30$.

2: F - REAL (KIND=nag_wp) FUNCTION, supplied by the user. External Procedure

F must return the value of the integrand f at a given point.

```
The specification of F is:
```

FUNCTION F (NDIM, X)

REAL (KIND=nag_wp) F
INTEGER NDIM
REAL (KIND=nag_wp) X(NDIM)

: NDIM – INTEGER Input

On entry: n, the number of dimensions of the integral.

2: X(NDIM) – REAL (KIND=nag wp) array Input

On entry: the coordinates of the point at which the integrand f must be evaluated.

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F must either be a module subprogram USEd by, or declared as EXTERNAL in, the (sub)program from which D01FDF is called. Parameters denoted as *Input* must **not** be changed by this procedure.

3: SIGMA – REAL (KIND=nag wp)

Input

On entry: indicates the region of integration.

 $SIGMA \ge 0.0$

The integration is carried out over the *n*-sphere of radius SIGMA, centred at the origin.

SIGMA < 0.0

The integration is carried out over the product region described by REGION.

4: REGION – SUBROUTINE, supplied by the NAG Library or the user. *External Procedure* If SIGMA < 0.0, REGION must evaluate the limits of integration in any dimension.

The specification of REGION is:

SUBROUTINE REGION (NDIM, X, J, C, D)

INTEGER NDIM, J
REAL (KIND=nag_wp) X(NDIM), C, D

1: NDIM – INTEGER

Input

On entry: n, the number of dimensions of the integral.

2: X(NDIM) - REAL (KIND=nag_wp) array

Input

On entry: X(1), ..., X(j-1) contain the current values of the first (j-1) variables, which may be used if necessary in calculating c_j and d_j .

3: J – INTEGER Input

On entry: the index j for which the limits of the range of integration are required.

4: C – REAL (KIND=nag wp)

Output

On exit: the lower limit c_i of the range of x_i .

5: D - REAL (KIND=nag wp)

Output

On exit: the upper limit d_i of the range of x_i .

REGION must either be a module subprogram USEd by, or declared as EXTERNAL in, the (sub)program from which D01FDF is called. Parameters denoted as *Input* must **not** be changed by this procedure.

If SIGMA \geq 0.0, REGION is not called by D01FDF, but a dummy routine must be supplied (D01FDV may be used).

5: LIMIT – INTEGER Input

On entry: the approximate maximum number of integrand evaluations to be used.

Constraint: LIMIT ≥ 100 .

6: R0 - REAL (KIND=nag wp)

Input

On entry: the cut-off radius on the unit n-sphere, which may be regarded as an adjustable parameter of the method.

Suggested value: a typical value is R0 = 0.8. (See also Section 8.)

Constraint: 0.0 < R0 < 1.0.

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7: $U - REAL (KIND=nag_wp)$

Input

On entry: must specify an adjustable parameter of the transformation to the unit n-sphere.

Suggested value: a typical value is U = 1.5. (See also Section 8.)

Constraint: U > 0.0.

8: RESULT – REAL (KIND=nag_wp)

Output

On exit: the approximation to the integral I.

9: NCALLS – INTEGER

Output

On exit: the actual number of integrand evaluations used. (See also Section 8.)

10: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

```
IFAIL = 1
```

On entry, NDIM < 1, or NDIM > 30.

IFAIL = 2

On entry, LIMIT < 100.

IFAIL = 3

On entry, $R0 \le 0.0$, or $R0 \ge 1.0$.

IFAIL = 4

On entry, $U \leq 0.0$.

7 Accuracy

No error estimate is returned, but results may be verified by repeating with an increased value of LIMIT (provided that this causes an increase in the returned value of NCALLS).

8 Further Comments

The time taken by D01FDF will be approximately proportional to the returned value of NCALLS, which, except in the circumstances outlined in (b) below, will be close to the given value of LIMIT.

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(a) Choice of r_0 and u

If the chosen combination of r_0 and u is too large in relation to the machine accuracy it is possible that some of the points generated in the original region of integration may transform into points in the unit n-sphere which lie too close to the boundary surface to be distinguished from it to machine accuracy (despite the fact that $r_0 < 1$). To be specific, the combination of r_0 and u is too large if

$$\frac{ur_0}{1-r_0^2} > 0.3465(t-1),$$
 if SIGMA ≥ 0.0 ,

or

$$\frac{ur_0}{1-r_0} > 0.3465(t-1),$$
 if SIGMA < 0.0,

where t is the number of bits in the mantissa of a real number.

The contribution of such points to the integral is neglected. This may be justified by appeal to the fact that the Jacobian of the transformation rapidly approaches zero towards the surface. Neglect of these points avoids the occurrence of overflow with integrands which are infinite on the boundary.

(b) Values of LIMIT and NCALLS

LIMIT is an approximate upper limit to the number of integrand evaluations, and may not be chosen less than 100. There are two circumstances when the returned value of NCALLS (the actual number of evaluations used) may be significantly less than LIMIT.

Firstly, as explained in (a), an unsuitably large combination of r_0 and u may result in some of the points being unusable. Such points are not included in the returned value of NCALLS.

Secondly, no more than 400 layers will ever be used, no matter how high LIMIT is set. This places an effective upper limit on NCALLS as follows:

n = 1: 56 n = 2: 1252 n = 3: 23690 n = 4: 394528 n = 5: 5956906

9 Example

This example calculates the integral

$$\int \int \int \frac{dx_1 dx_2 dx_3}{\sqrt{\sigma^2 - r^2}} = 22.2066$$

where s is the 3-sphere of radius σ , $r^2 = x_1^2 + x_2^2 + x_3^2$ and $\sigma = 1.5$. Both sphere-to-sphere and general product region transformations are used. For the former, we use $r_0 = 0.9$ and u = 1.5; for the latter, $r_0 = 0.8$ and u = 1.5.

9.1 Program Text

```
D01FDF Example Program Text
    Mark 24 Release. NAG Copyright 2012.
    Module d01fdfe_mod
      D01FDF Example Program Module:
1
1
             Parameters and User-defined Routines
!
      .. Use Statements ...
      Use nag_library, Only: nag_wp
      .. Implicit None Statement ..
!
      Implicit None
!
      .. Parameters ..
                                             :: nout = 6
      Integer, Parameter
    Contains
```

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```
Function f(ndim,x)
!
        .. Function Return Value ..
        Real (Kind=nag_wp)
                                                  :: f
         .. Scalar Arguments ..
1
        Integer, Intent (In)
                                                 :: ndim
        .. Array Arguments .. Real (Kind=nag_wp), Intent (In) :: x(ndim)
1
1
        .. Intrinsic Procedures ..
        Intrinsic
                                                 :: abs, sgrt, sum
!
        .. Executable Statements ..
        f = 1.0E0_nag_wp/sqrt(abs(2.25E0_nag_wp-sum(x(1:ndim)**2)))
        Return
      End Function f
      Subroutine region(ndim,x,j,c,d)
         .. Scalar Arguments ..
!
        Real (Kind=nag_wp), Intent (Out) :: c, d
        Integer, Intent (In)
                                                 :: j, ndim
        .. Array Arguments .. Real (Kind=nag_wp), Intent (In)
                                                 :: x(ndim)
        .. Intrinsic Procedures ..
!
        Intrinsic
                                                 :: abs, sqrt, sum
        .. Executable Statements ..
        If (j>1) Then
          d = sqrt(abs(2.25E0_nag_wp-sum(x(1:(j-1))**2)))
          c = -d
        Else
           c = -1.5E0_nag_wp
           d = 1.5E0_nag_wp
        End If
        Return
      End Subroutine region
    End Module d01fdfe_mod
    Program d01fdfe
      D01FDF Example Main Program
!
!
      .. Use Statements ..
      Use nag_library, Only: d01fdf, d01fdv, nag_wp
Use d01fdfe_mod, Only: f, nout, region
!
      .. Implicit None Statement ..
      Implicit None
!
      .. Local Scalars ..
                                                :: r0, result, sigma, u
      Real (Kind=nag_wp)
                                               :: ifail, limit, ncalls, ndim
      Integer
!
      .. Executable Statements ..
      Write (nout,*) 'D01FDF Example Program Results'
      ndim = 3
      limit = 8000
      u = 1.5E0_nag_wp
      sigma = 1.5E0_nag_wp
      r0 = 0.9E0_nag_wp
      ifail = 0
      Call d01fdf(ndim,f,sigma,d01fdv,limit,r0,u,result,ncalls,ifail)
      Write (nout,*)
      Write (nout,*) 'Sphere-to-sphere transformation'
      Write (nout,*)
      Write (nout,99999) 'Estimated value of the integral = ', result Write (nout,99998) 'Number of integrand evaluations = ', ncalls
      Write (nout,*)
      Write (nout,*) 'Product region transformation'
      sigma = -1.0E0_nag_wp
```

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```
r0 = 0.8E0_nag_wp

ifail = 0
   Call d01fdf(ndim,f,sigma,region,limit,r0,u,result,ncalls,ifail)

Write (nout,*)
   Write (nout,99999) 'Estimated value of the integral = ', result
   Write (nout,99998) 'Number of integrand evaluations = ', ncalls

99999 Format (1X,A,F9.3)
99998 Format (1X,A,I5)
   End Program d01fdfe
```

9.2 Program Data

None.

9.3 Program Results

```
DO1FDF Example Program Results

Sphere-to-sphere transformation

Estimated value of the integral = 22.168

Number of integrand evaluations = 8026

Product region transformation

Estimated value of the integral = 22.137

Number of integrand evaluations = 8026
```

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