

# NAG Library Routine Document

## F08QLF (DTRSNA)

**Note:** before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

### 1 Purpose

F08QLF (DTRSNA) estimates condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix.

### 2 Specification

```

SUBROUTINE F08QLF (JOB, HOWMNY, SELECT, N, T, LDT, VL, LDVL, VR, LDVR, S,      &
                  SEP, MM, M, WORK, LDWORK, IWORK, INFO)

INTEGER          N, LDT, LDVL, LDVR, MM, M, LDWORK, IWORK(*), INFO
REAL (KIND=nag_wp) T(LDT,*), VL(LDVL,*), VR(LDVR,*), S(*), SEP(*),      &
                  WORK(LDWORK,*)
LOGICAL          SELECT(*)
CHARACTER(1)     JOB, HOWMNY

```

The routine may be called by its LAPACK name *dtrsna*.

### 3 Description

F08QLF (DTRSNA) estimates condition numbers for specified eigenvalues and/or right eigenvectors of a real upper quasi-triangular matrix  $T$  in canonical Schur form. These are the same as the condition numbers of the eigenvalues and right eigenvectors of an original matrix  $A = ZTZ^T$  (with orthogonal  $Z$ ), from which  $T$  may have been derived.

F08QLF (DTRSNA) computes the reciprocal of the condition number of an eigenvalue  $\lambda_i$  as

$$s_i = \frac{|v^H u|}{\|u\|_E \|v\|_E},$$

where  $u$  and  $v$  are the right and left eigenvectors of  $T$ , respectively, corresponding to  $\lambda_i$ . This reciprocal condition number always lies between zero (i.e., ill-conditioned) and one (i.e., well-conditioned).

An approximate error estimate for a computed eigenvalue  $\lambda_i$  is then given by

$$\frac{\epsilon \|T\|}{s_i},$$

where  $\epsilon$  is the *machine precision*.

To estimate the reciprocal of the condition number of the right eigenvector corresponding to  $\lambda_i$ , the routine first calls F08QFF (DTREXC) to reorder the eigenvalues so that  $\lambda_i$  is in the leading position:

$$T = Q \begin{pmatrix} \lambda_i & c^T \\ 0 & T_{22} \end{pmatrix} Q^T.$$

The reciprocal condition number of the eigenvector is then estimated as  $sep_i$ , the smallest singular value of the matrix  $(T_{22} - \lambda_i I)$ . This number ranges from zero (i.e., ill-conditioned) to very large (i.e., well-conditioned).

An approximate error estimate for a computed right eigenvector  $u$  corresponding to  $\lambda_i$  is then given by

$$\frac{\epsilon \|T\|}{sep_i}.$$

## 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

## 5 Parameters

- 1: JOB – CHARACTER(1) *Input*  
*On entry:* indicates whether condition numbers are required for eigenvalues and/or eigenvectors.  
 JOB = 'E'  
     Condition numbers for eigenvalues only are computed.  
 JOB = 'V'  
     Condition numbers for eigenvectors only are computed.  
 JOB = 'B'  
     Condition numbers for both eigenvalues and eigenvectors are computed.  
*Constraint:* JOB = 'E', 'V' or 'B'.
- 2: HOWMNY – CHARACTER(1) *Input*  
*On entry:* indicates how many condition numbers are to be computed.  
 HOWMNY = 'A'  
     Condition numbers for all eigenpairs are computed.  
 HOWMNY = 'S'  
     Condition numbers for selected eigenpairs (as specified by SELECT) are computed.  
*Constraint:* HOWMNY = 'A' or 'S'.
- 3: SELECT(\*) – LOGICAL array *Input*  
**Note:** the dimension of the array SELECT must be at least  $\max(1, N)$  if HOWMNY = 'S', and at least 1 otherwise.  
*On entry:* specifies the eigenpairs for which condition numbers are to be computed if HOWMNY = 'S'. To select condition numbers for the eigenpair corresponding to the real eigenvalue  $\lambda_j$ , SELECT(*j*) must be set .TRUE.. To select condition numbers corresponding to a complex conjugate pair of eigenvalues  $\lambda_j$  and  $\lambda_{j+1}$ , SELECT(*j*) and/or SELECT(*j* + 1) must be set to .TRUE..  
 If HOWMNY = 'A', SELECT is not referenced.
- 4: N – INTEGER *Input*  
*On entry:* *n*, the order of the matrix *T*.  
*Constraint:*  $N \geq 0$ .
- 5: T(LDT,\*) – REAL (KIND=nag\_wp) array *Input*  
**Note:** the second dimension of the array T must be at least  $\max(1, N)$ .  
*On entry:* the *n* by *n* upper quasi-triangular matrix *T* in canonical Schur form, as returned by F08PEF (DHSEQR).
- 6: LDT – INTEGER *Input*  
*On entry:* the first dimension of the array T as declared in the (sub)program from which F08QLF (DTRSNA) is called.  
*Constraint:*  $LDT \geq \max(1, N)$ .

- 7: VL(LDVL,\*) – REAL (KIND=nag\_wp) array Input
- Note:** the second dimension of the array VL must be at least  $\max(1, MM)$  if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.
- On entry:* if JOB = 'E' or 'B', VL must contain the left eigenvectors of  $T$  (or of any matrix  $QTQ^T$  with  $Q$  orthogonal) corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors **must** be stored in consecutive columns of VL, as returned by F08PKF (DHSEIN) or F08QKF (DTREVC).
- If JOB = 'V', VL is not referenced.
- 8: LDVL – INTEGER Input
- On entry:* the first dimension of the array VL as declared in the (sub)program from which F08QLF (DTRSNA) is called.
- Constraints:*
- if JOB = 'E' or 'B',  $LDVL \geq \max(1, N)$ ;  
if JOB = 'V',  $LDVL \geq 1$ .
- 9: VR(LDVR,\*) – REAL (KIND=nag\_wp) array Input
- Note:** the second dimension of the array VR must be at least  $\max(1, MM)$  if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.
- On entry:* if JOB = 'E' or 'B', VR must contain the right eigenvectors of  $T$  (or of any matrix  $QTQ^T$  with  $Q$  orthogonal) corresponding to the eigenpairs specified by HOWMNY and SELECT. The eigenvectors **must** be stored in consecutive columns of VR, as returned by F08PKF (DHSEIN) or F08QKF (DTREVC).
- If JOB = 'V', VR is not referenced.
- 10: LDVR – INTEGER Input
- On entry:* the first dimension of the array VR as declared in the (sub)program from which F08QLF (DTRSNA) is called.
- Constraints:*
- if JOB = 'E' or 'B',  $LDVR \geq \max(1, N)$ ;  
if JOB = 'V',  $LDVR \geq 1$ .
- 11: S(\*) – REAL (KIND=nag\_wp) array Output
- Note:** the dimension of the array S must be at least  $\max(1, MM)$  if JOB = 'E' or 'B' and at least 1 if JOB = 'V'.
- On exit:* the reciprocal condition numbers of the selected eigenvalues if JOB = 'E' or 'B', stored in consecutive elements of the array. Thus  $S(j)$ ,  $SEP(j)$  and the  $j$ th columns of VL and VR all correspond to the same eigenpair (but not in general the  $j$ th eigenpair unless all eigenpairs have been selected). For a complex conjugate pair of eigenvalues, two consecutive elements of S are set to the same value.
- S is not referenced if JOB = 'V'.
- 12: SEP(\*) – REAL (KIND=nag\_wp) array Output
- Note:** the dimension of the array SEP must be at least  $\max(1, MM)$  if JOB = 'V' or 'B' and at least 1 if JOB = 'E'.
- On exit:* the estimated reciprocal condition numbers of the selected right eigenvectors if JOB = 'V' or 'B', stored in consecutive elements of the array. For a complex eigenvector, two consecutive elements of SEP are set to the same value. If the eigenvalues cannot be reordered to compute  $SEP(j)$ , then  $SEP(j)$  is set to zero; this can only occur when the true value would be very small anyway.

If JOB = 'E', SEP is not referenced.

- 13: MM – INTEGER *Input*  
*On entry:* the number of elements in the arrays S and SEP, and the number of columns in the arrays VL and VR (if used). The precise number required,  $m$ , is  $n$  if HOWMNY = 'A'; if HOWMNY = 'S',  $m$  is obtained by counting 1 for each selected real eigenvalue, and 2 for each selected complex conjugate pair of eigenvalues (see SELECT), in which case  $0 \leq m \leq n$ .  
*Constraint:*  $MM \geq M$ .
- 14: M – INTEGER *Output*  
*On exit:*  $m$ , the number of elements of S and/or SEP actually used to store the estimated condition numbers. If HOWMNY = 'A', M is set to  $n$ .
- 15: WORK(LDWORK,\*) – REAL (KIND=nag\_wp) array *Workspace*  
**Note:** the second dimension of the array WORK must be at least  $\max(1, N + 6)$  if JOB = 'V' or 'B' and at least 1 if JOB = 'E'.  
 If JOB = 'E', WORK is not referenced.
- 16: LDWORK – INTEGER *Input*  
*On entry:* the first dimension of the array WORK as declared in the (sub)program from which F08QLF (DTRSNA) is called.  
*Constraints:*  
     if JOB = 'V' or 'B',  $LDWORK \geq \max(1, N)$ ;  
     if JOB = 'E',  $LDWORK \geq 1$ .
- 17: IWORK(\*) – INTEGER array *Workspace*  
**Note:** the dimension of the array IWORK must be at least  $\max(1, 2 \times (N - 1))$ .
- 18: INFO – INTEGER *Output*  
*On exit:* INFO = 0 unless the routine detects an error (see Section 6).

## 6 Error Indicators and Warnings

INFO < 0

If INFO =  $-i$ , argument  $i$  had an illegal value. An explanatory message is output, and execution of the program is terminated.

## 7 Accuracy

The computed values  $sep_i$  may over estimate the true value, but seldom by a factor of more than 3.

## 8 Further Comments

For a description of canonical Schur form, see the document for F08PEF (DHSEQR).

The complex analogue of this routine is F08QYF (ZTRSNA).

## 9 Example

This example computes approximate error estimates for all the eigenvalues and right eigenvectors of the matrix  $T$ , where

$$T = \begin{pmatrix} 0.7995 & -0.1144 & 0.0060 & 0.0336 \\ 0.0000 & -0.0994 & 0.2478 & 0.3474 \\ 0.0000 & -0.6483 & -0.0994 & 0.2026 \\ 0.0000 & 0.0000 & 0.0000 & -0.1007 \end{pmatrix}.$$

## 9.1 Program Text

```

Program f08qlfe

!      F08QLF Example Program Text

!      Mark 24 Release. NAG Copyright 2012.

!      .. Use Statements ..
Use nag_library, Only: dlange => f06raf, dtrevc, dtrsna, nag_wp, x02ajf
!      .. Implicit None Statement ..
Implicit None
!      .. Parameters ..
Integer, Parameter          :: nin = 5, nout = 6
!      .. Local Scalars ..
Real (Kind=nag_wp)         :: eps, tnorm
Integer                    :: i, info, ldt, ldvl, ldvr, ldwork, m, n
!      .. Local Arrays ..
Real (Kind=nag_wp), Allocatable :: s(:), sep(:), t(:,,:), vl(:,,:),      &
                                vr(:,,:), work(:,:)
Integer, Allocatable        :: iwork(:)
Logical                    :: select(1)
!      .. Executable Statements ..
Write (nout,*) 'F08QLF Example Program Results'
Write (nout,*)
!      Skip heading in data file
Read (nin,*)
Read (nin,*) n
ldt = n
ldvl = n
ldvr = n
ldwork = n
Allocate (s(n),sep(n),t(ldt,n),vl(ldvl,n),vr(ldvr,n),work(ldwork,n+6), &
         iwork(2*n-1))

!      Read T from data file

Read (nin,*)(t(i,1:n),i=1,n)

!      Calculate the left and right eigenvectors of T

!      The NAG name equivalent of dtrevc is f08qkf
Call dtrevc('Both','All',select,n,t,ldt,vl,ldvl,vr,ldvr,n,m,work,info)

!      Estimate condition numbers for all the eigenvalues and right
!      eigenvectors of T

!      The NAG name equivalent of dtrsna is f08qlf
Call dtrsna('Both','All',select,n,t,ldt,vl,ldvl,vr,ldvr,s,sep,n,m,work, &
         ldwork,iwork,info)

!      Print condition numbers of eigenvalues and right eigenvectors

Write (nout,*) 'S'
Write (nout,99999) s(1:m)
Write (nout,*)
Write (nout,*) 'SEP'
Write (nout,99999) sep(1:m)

!      Calculate approximate error estimates (using the 1-norm)

eps = x02ajf()

```

```

!      f06raf is the NAG name equivalent of the LAPACK auxiliary dlange
      tnorm = dlange('1-norm',n,n,t,ldt,work)
      Write (nout,*)
      Write (nout,*) 'Approximate error estimates for eigenvalues ', &
        'of T (machine-dependent)'
      Write (nout,99999)(eps*tnorm/s(i),i=1,m)
      Write (nout,*)
      Write (nout,*) 'Approximate error estimates for right ', &
        'eigenvectors of T (machine-dependent)'
      Write (nout,99999)(eps*tnorm/sep(i),i=1,m)

99999 Format ((3X,1P,7E11.1))
      End Program f08qlfe

```

## 9.2 Program Data

```

F08QLF Example Program Data
4                                     :Value of N
0.7995  -0.1144  0.0060  0.0336
0.0000  -0.0994  0.2478  0.3474
0.0000  -0.6483  -0.0994  0.2026
0.0000   0.0000  0.0000  -0.1007  :End of matrix T

```

## 9.3 Program Results

```

F08QLF Example Program Results

S
    9.9E-01    7.0E-01    7.0E-01    5.7E-01

SEP
    6.3E-01    3.7E-01    3.7E-01    3.1E-01

Approximate error estimates for eigenvalues of T (machine-dependent)
    9.6E-17    1.4E-16    1.4E-16    1.7E-16

Approximate error estimates for right eigenvectors of T (machine-dependent)
    1.5E-16    2.6E-16    2.6E-16    3.1E-16

```

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