

NAG Library Routine Document

G05ZTF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

G05ZTF produces realisations of a fractional Brownian motion, using the circulant embedding method. The square roots of the extended covariance matrix (or embedding matrix) need to be input, and can be calculated using G05ZMF or G05ZNF.

2 Specification

```
SUBROUTINE G05ZTF (NS, S, M, XMAX, H, LAM, RHO, STATE, Z, XX, IFAIL)
```

```
INTEGER NS, S, M, STATE(*), IFAIL
```

```
REAL (KIND=nag_wp) XMAX, H, LAM(M), RHO, Z(NS+1,S), XX(NS+1)
```

3 Description

The routines G05ZMF or G05ZNF and G05ZTF are used to simulate a fractional Brownian motion process with Hurst parameter H over an interval $[0, x_{\max}]$, using a set of equally spaced gridpoints. Fractional Brownian motion itself cannot be simulated directly using this method, since it is not a stationary Gaussian random field; however its increments can be simulated like a stationary Gaussian random field. The circulant embedding method is described in the documentation for G05ZMF or G05ZNF.

G05ZTF takes the square roots of the eigenvalues of the embedding matrix as returned by G05ZMF or G05ZNF, and its size M , as input and outputs S realisations of the fractional Brownian motion in Z .

One of the initialization routines G05KFF (for a repeatable sequence if computed sequentially) or G05KGF (for a non-repeatable sequence) must be called prior to the first call to G05ZTF.

4 References

Dietrich C R and Newsam G N (1997) Fast and exact simulation of stationary Gaussian processes through circulant embedding of the covariance matrix *SIAM J. Sci. Comput.* **18** 1088–1107

Schlather M (1999) Introduction to positive definite functions and to unconditional simulation of random fields *Technical Report ST 99–10* Lancaster University

Wood A T A and Chan G (1994) Simulation of stationary Gaussian processes in $[0, 1]^d$ *Journal of Computational and Graphical Statistics* **3(4)** 409–432

5 Parameters

1: NS – INTEGER *Input*

On entry: the number of sample points (grid points) to be generated in realisations of the increments of the fractional Brownian motion. This must be the same value as supplied to G05ZMF or G05ZNF when calculating the eigenvalues of the embedding matrix.

Constraint: $NS \geq 1$.

2: S – INTEGER *Input*

On entry: the number of realisations of the fractional Brownian motion to simulate.

Constraint: $S \geq 1$.

- 3: M – INTEGER *Input*
On entry: the size of the embedding matrix, as returned by G05ZMF or G05ZNF.
Constraint: $M \geq \max(1, 2(NS - 1))$.
- 4: XMAX – REAL (KIND=nag_wp) *Input*
On entry: the upper bound for the interval over which the fractional Brownian motion is to be simulated, as returned by G05ZMF or G05ZNF.
Constraint: XMAX > 0.0.
- 5: H – REAL (KIND=nag_wp) *Input*
On entry: the Hurst parameter for the fractional Brownian motion. This must be the same value as supplied to G05ZMF or G05ZNF when calculating the eigenvalues of the embedding matrix.
Constraint: $0.0 < H < 1.0$.
- 6: LAM(M) – REAL (KIND=nag_wp) array *Input*
On entry: contains the square roots of the eigenvalues of the embedding matrix, as returned by G05ZNF.
Constraint: $LAM(i) = 0, i = 1, 2, \dots, M$.
- 7: RHO – REAL (KIND=nag_wp) *Input*
On entry: indicates the scaling of the covariance matrix, as returned by G05ZMF or G05ZNF.
Constraint: $0.0 < RHO \leq 1.0$.
- 8: STATE(*) – INTEGER array *Communication Array*
Note: the actual argument supplied must be the array STATE supplied to the initialization routines G05KFF or G05KGF.
On entry: contains information on the selected base generator and its current state.
On exit: contains updated information on the state of the generator.
- 9: Z(NS + 1,S) – REAL (KIND=nag_wp) array *Output*
On exit: contains the realisations of the fractional Brownian motion. Each column of Z contains one realisation of the fractional Brownian motion, with $Z(i, j)$, for $j = 1, 2, \dots, S$, corresponding to the gridpoint $XX(i)$.
- 10: XX(NS + 1) – REAL (KIND=nag_wp) array *Output*
On exit: the gridpoints at which values of the fractional Brownian motion are output. The first gridpoint is always zero, and the subsequent NS gridpoints represent the equispaced steps towards the last gridpoint, XMAX. Note that in G05ZMF and G05ZNF, the returned NS sample points are the mid-points of the grid returned in XX here.
- 11: IFAIL – INTEGER *Input/Output*
On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.
 For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**
On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

6 Error Indicators and Warnings

If on entry $IFAIL = 0$ or -1 , explanatory error messages are output on the current error message unit (as defined by $X04AAF$).

Errors or warnings detected by the routine:

$IFAIL = 1$

On entry, $NS = \langle value \rangle$.
Constraint: $NS \geq 1$.

$IFAIL = 2$

On entry, $S = \langle value \rangle$.
Constraint: $S \geq 1$.

$IFAIL = 3$

On entry, $M = \langle value \rangle$, and $NS = \langle value \rangle$.
Constraint: $M \geq \max(1, 2(NS - 1))$.

$IFAIL = 4$

On entry, $XMAX = \langle value \rangle$.
Constraint: $XMAX > 0.0$.

$IFAIL = 5$

On entry, $H = \langle value \rangle$.
Constraint: $0.0 < H < 1.0$.

$IFAIL = 6$

On entry, at least one element of LAM was negative.
Constraint: all elements of LAM must be non-negative.

$IFAIL = 7$

On entry, $RHO = \langle value \rangle$.
Constraint: $0.0 < RHO \leq 1.0$.

$IFAIL = 8$

On entry, $STATE$ vector has been corrupted or not initialized.

7 Accuracy

Not applicable.

8 Further Comments

None.

9 Example

This example calls $G05ZTF$ to generate 5 realisations of a fractional Brownian motion over 10 steps from $x = 0.0$ to $x = 2.0$ using eigenvalues generated by $G05ZNF$ with $ICOV1 = 14$.

9.1 Program Text

```

! G05ZTF Example Program Text

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Program g05ztf

! G05ZTF Example Main Program

! .. Use Statements ..
Use nag_library, Only: g05znf, g05ztf, nag_wp
! .. Implicit None Statement ..
Implicit None
! .. Parameters ..
Integer, Parameter :: lenst = 17, nin = 5, nout = 6, &
                    npmax = 4
! .. Local Scalars ..
Real (Kind=nag_wp) :: h, rho, var, xmax, xmin
Integer :: approx, icorr, icount, icovl, &
          ifail, m, maxm, np, ns, pad, s
! .. Local Arrays ..
Real (Kind=nag_wp) :: eig(3), params(npmax)
Real (Kind=nag_wp), Allocatable :: lam(:), xx(:), yy(:), z(:, :)
Integer :: state(lenst)
! .. Executable Statements ..
Write (nout,*) 'G05ZTF Example Program Results'
Write (nout,*)

! Set fixed problem specifications for simulating fractional Brownian
! motion.
icovl = 14
np = 2
xmin = 0.0_nag_wp
var = 1.0_nag_wp

! Get other problem specifications from data file
Call read_input_data(params, xmax, ns, maxm, icorr, pad, s)

Allocate (lam(maxm), xx(ns))

! Get square roots of the eigenvalues of the embedding matrix
ifail = 0
Call g05znf(ns, xmin, xmax, maxm, var, icovl, np, params, pad, icorr, lam, xx, m, &
          approx, rho, icount, eig, ifail)

Call display_embedding_results(approx, m, rho, eig, icount)

! Initialize state array
Call initialize_state(state)

Allocate (yy(ns+1), z(ns+1, s))

! Compute s fractional Brownian Motion realisations.
h = params(1)
ifail = 0
Call g05ztf(ns, s, m, xmax, h, lam, rho, state, z, yy, ifail)

Call display_realizations(ns, s, yy, z)

Contains
Subroutine read_input_data(params, xmax, ns, maxm, icorr, pad, s)

! .. Implicit None Statement ..
Implicit None
! .. Scalar Arguments ..
Real (Kind=nag_wp), Intent (Out) :: xmax
Integer, Intent (Out) :: icorr, maxm, ns, pad, s
! .. Array Arguments ..
Real (Kind=nag_wp), Intent (Out) :: params(npmax)

```

```

!      .. Intrinsic Procedures ..
      Intrinsic                               :: real
!      .. Executable Statements ..
!      Skip heading in data file
      Read (nin,*)

!      Read in the Hurst parameter, H
      Read (nin,*) params(1)

!      Read in domain endpoint
      Read (nin,*) xmax

!      Read in number of sample points
      Read (nin,*) ns

      params(2) = xmax/(real(ns,kind=nag_wp))

!      Read in maximum size of embedding matrix
      Read (nin,*) maxm

!      Read in choice of scaling in case of approximation
      Read (nin,*) icorr

!      Read in choice of padding
      Read (nin,*) pad

!      Read in number of realization samples to be generated
      Read (nin,*) s

      Return

End Subroutine read_input_data

Subroutine display_embedding_results(approx,m,rho,eig,icount)

!      .. Implicit None Statement ..
      Implicit None
!      .. Scalar Arguments ..
      Real (Kind=nag_wp), Intent (In)       :: rho
      Integer, Intent (In)                  :: approx, icount, m
!      .. Array Arguments ..
      Real (Kind=nag_wp), Intent (In)       :: eig(3)
!      .. Executable Statements ..
!      Display size of embedding matrix
      Write (nout,*)
      Write (nout,99999) 'Size of embedding matrix = ', m

!      Display approximation information if approximation used
      Write (nout,*)
      If (approx==1) Then
        Write (nout,*) 'Approximation required'
        Write (nout,*)
        Write (nout,99998) 'RHO = ', rho
        Write (nout,99997) 'EIG = ', eig(1:3)
        Write (nout,99999) 'ICOUNT = ', icount
      Else
        Write (nout,*) 'Approximation not required'
      End If

      Return

99999  Format (1X,A,I7)
99998  Format (1X,A,F10.5)
99997  Format (1X,A,3(F10.5,1X))

End Subroutine display_embedding_results

Subroutine initialize_state(state)

!      .. Use Statements ..
      Use nag_library, Only: g05kff

```

```

!      .. Implicit None Statement ..
      Implicit None
!      .. Parameters ..
      Integer, Parameter          :: genid = 1, inseed = 14965,      &
                                   lseed = 1, subid = 1
!      .. Array Arguments ..
      Integer, Intent (Out)       :: state(lenst)
!      .. Local Scalars ..
      Integer                      :: ifail, lstate
!      .. Local Arrays ..
      Integer                      :: seed(lseed)
!      .. Executable Statements ..
!      Initialize the generator to a repeatable sequence
      lstate = lenst
      seed(1) = inseed
      ifail = 0
      Call g05kff(genid,subid,seed,lseed,state,lstate,ifail)

End Subroutine initialize_state

Subroutine display_realizations(ns,s,yy,z)

!      .. Use Statements ..
      Use nag_library, Only: x04cbf
!      .. Implicit None Statement ..
      Implicit None
!      .. Parameters ..
      Integer, Parameter          :: indent = 0, ncols = 80
      Character (1), Parameter    :: charlab = 'C', intlab = 'I',      &
                                   matrix = 'G', unit = 'n'
      Character (5), Parameter    :: form = 'F10.5'
!      .. Scalar Arguments ..
      Integer, Intent (In)        :: ns, s
!      .. Array Arguments ..
      Real (Kind=nag_wp), Intent (In) :: yy(ns+1), z(ns+1,s)
!      .. Local Scalars ..
      Integer                      :: i, ifail
      Character (61)               :: title
!      .. Local Arrays ..
      Character (1)                :: clabs(0)
      Character (6), Allocatable   :: rlabs(:)
!      .. Executable Statements ..
      Allocate (rlabs(ns+1))

!      Set row labels to mesh points (column label is realization number).
      Do i = 1, ns + 1
         Write (rlabs(i),99999) yy(i)
      End Do

!      Display random field results
      title = &
         'Fractional Brownian motion realisations (x coordinate first):'
      Write (nout,*)
      ifail = 0
      Call x04cbf(matrix,unit,ns+1,s,z,ns+1,form,title,charlab,rlabs,intlab, &
         clabs,ncols,indent,ifail)

99999  Format (F6.1)

End Subroutine display_realizations

End Program g05ztf

```

9.2 Program Data

```
G05ZTF Example Program Data
  0.35      : h
  2         : xmax
  10        : ns
  2048      : maxm
  2         : icorr
  1         : pad
  5         : s
```

9.3 Program Results

G05ZTF Example Program Results

Size of embedding matrix = 32

Approximation not required

Fractional Brownian motion realisations (x coordinate first):

	1	2	3	4	5
0.0	0.00000	0.00000	0.00000	0.00000	0.00000
0.2	-0.52650	-0.16159	-0.96224	-0.40096	0.65803
0.4	-1.81085	-0.85811	-1.43661	0.03947	0.99671
0.6	-1.65690	-0.74802	-0.61733	-0.34685	0.05141
0.8	-1.72240	-0.14958	0.14996	0.18134	0.26567
1.0	-2.20349	0.46219	0.70982	0.66405	0.40706
1.2	-2.38542	0.52085	0.36330	0.31831	0.81515
1.4	-3.13939	0.68433	0.79826	-0.35408	1.12296
1.6	-3.54602	0.64413	0.85751	-0.39303	1.14220
1.8	-4.09082	1.67048	0.06038	0.30181	1.30350
2.0	-2.97487	1.72275	-0.67253	-0.07439	1.57169
