NAG Library Routine Document F08OHF (DTRSYL)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08QHF (DTRSYL) solves the real quasi-triangular Sylvester matrix equation.

2 Specification

```
SUBROUTINE FO8QHF (TRANA, TRANB, ISGN, M, N, A, LDA, B, LDB, C, LDC, SCALE, INFO)

INTEGER ISGN, M, N, LDA, LDB, LDC, INFO

REAL (KIND=nag_wp) A(LDA,*), B(LDB,*), C(LDC,*), SCALE

CHARACTER(1) TRANA, TRANB
```

The routine may be called by its LAPACK name dtrsyl.

3 Description

F08QHF (DTRSYL) solves the real Sylvester matrix equation

$$op(A)X \pm X op(B) = \alpha C$$
,

where op(A) = A or A^T , and the matrices A and B are upper quasi-triangular matrices in canonical Schur form (as returned by F08PEF (DHSEQR)); α is a scale factor (\leq 1) determined by the routine to avoid overflow in X; A is m by m and B is n by n while the right-hand side matrix C and the solution matrix X are both m by n. The matrix X is obtained by a straightforward process of back-substitution (see Golub and Van Loan (1996)).

Note that the equation has a unique solution if and only if $\alpha_i \pm \beta_j \neq 0$, where $\{\alpha_i\}$ and $\{\beta_j\}$ are the eigenvalues of A and B respectively and the sign (+ or -) is the same as that used in the equation to be solved.

4 References

Golub G H and Van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (1992) Perturbation theory and backward error for AX - XB = C Numerical Analysis Report University of Manchester

5 Parameters

1: TRANA - CHARACTER(1)

On entry: specifies the option op(A).

TRANA = 'N'

Input

$$op(A) = A.$$

$$TRANA = 'T' \text{ or 'C'}$$

$$op(A) = A^{T}.$$

Constraint: TRANA = 'N', 'T' or 'C'.

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2: TRANB - CHARACTER(1)

Input

On entry: specifies the option op(B).

$$TRANB = 'N'$$

$$op(B) = B$$
.

$$TRANB = 'T' \text{ or } 'C'$$

$$op(B) = B^{T}$$
.

Constraint: TRANB = 'N', 'T' or 'C'.

3: ISGN – INTEGER

Input

On entry: indicates the form of the Sylvester equation.

$$ISGN = +1$$

The equation is of the form $op(A)X + X op(B) = \alpha C$.

ISGN = -1

The equation is of the form $op(A)X - X op(B) = \alpha C$.

Constraint: ISGN = +1 or -1.

4: M - INTEGER

Input

On entry: m, the order of the matrix A, and the number of rows in the matrices X and C.

Constraint: $M \ge 0$.

5: N – INTEGER

Input

On entry: n, the order of the matrix B, and the number of columns in the matrices X and C.

Constraint: $N \geq 0$.

6: $A(LDA,*) - REAL (KIND=nag_wp) array$

Input

Note: the second dimension of the array A must be at least max(1, M).

On entry: the m by m upper quasi-triangular matrix A in canonical Schur form, as returned by F08PEF (DHSEQR).

7: LDA – INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08QHF (DTRSYL) is called.

Constraint: LDA $\geq \max(1, M)$.

8: B(LDB,*) - REAL (KIND=nag wp) array

Input

Note: the second dimension of the array B must be at least max(1, N).

On entry: the n by n upper quasi-triangular matrix B in canonical Schur form, as returned by F08PEF (DHSEQR).

9: LDB – INTEGER

Input

On entry: the first dimension of the array B as declared in the (sub)program from which F08QHF (DTRSYL) is called.

Constraint: LDB $\geq \max(1, N)$.

10: C(LDC,*) - REAL (KIND=nag wp) array

Input/Output

Note: the second dimension of the array C must be at least max(1, N).

On entry: the m by n right-hand side matrix C.

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On exit: C is overwritten by the solution matrix X.

11: LDC – INTEGER Input

On entry: the first dimension of the array C as declared in the (sub)program from which F08QHF (DTRSYL) is called.

Constraint: LDC $\geq \max(1, M)$.

12: SCALE - REAL (KIND=nag wp)

Output

On exit: the value of the scale factor α .

13: INFO – INTEGER Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = -i, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO = 1

A and B have common or close eigenvalues, perturbed values of which were used to solve the equation.

7 Accuracy

Consider the equation AX - XB = C. (To apply the remarks to the equation AX + XB = C, simply replace B by -B.)

Let \ddot{X} be the computed solution and R the residual matrix:

$$R = C - (A\tilde{X} - \tilde{X}B).$$

Then the residual is always small:

$$||R||_F = O(\epsilon) (||A||_F + ||B||_F) ||\tilde{X}||_F.$$

However, \tilde{X} is **not** necessarily the exact solution of a slightly perturbed equation; in other words, the solution is not backwards stable.

For the forward error, the following bound holds:

$$\left\|\tilde{X} - X\right\|_F \le \frac{\|R\|_F}{sep(A, B)}$$

but this may be a considerable over estimate. See Golub and Van Loan (1996) for a definition of sep(A, B), and Higham (1992) for further details.

These remarks also apply to the solution of a general Sylvester equation, as described in Section 8.

8 Further Comments

The total number of floating point operations is approximately mn(m+n).

To solve the general real Sylvester equation

$$AX \pm XB = C$$

where A and B are general nonsymmetric matrices, A and B must first be reduced to Schur form (by calling F08PAF (DGEES), for example):

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$$A = Q_1 \tilde{A} Q_1^{\mathsf{T}}$$
 and $B = Q_2 \tilde{B} Q_2^{\mathsf{T}}$

where \tilde{A} and \tilde{B} are upper quasi-triangular and Q_1 and Q_2 are orthogonal. The original equation may then be transformed to:

$$\tilde{A}\tilde{X} \pm \tilde{X}\tilde{B} = \tilde{C}$$

where $\tilde{X} = Q_1^T X Q_2$ and $\tilde{C} = Q_1^T C Q_2$. \tilde{C} may be computed by matrix multiplication; F08QHF (DTRSYL) may be used to solve the transformed equation; and the solution to the original equation can be obtained as $X = Q_1 \tilde{X} Q_2^T$.

The complex analogue of this routine is F08QVF (ZTRSYL).

9 Example

This example solves the Sylvester equation AX + XB = C, where

$$A = \begin{pmatrix} 0.10 & 0.50 & 0.68 & -0.21 \\ -0.50 & 0.10 & -0.24 & 0.67 \\ 0.00 & 0.00 & 0.19 & -0.35 \\ 0.00 & 0.00 & 0.00 & -0.72 \end{pmatrix},$$

$$B = \begin{pmatrix} -0.99 & -0.17 & 0.39 & 0.58 \\ 0.00 & 0.48 & -0.84 & -0.15 \\ 0.00 & 0.00 & 0.75 & 0.25 \\ 0.00 & 0.00 & -0.25 & 0.75 \end{pmatrix}$$

and

$$C = \begin{pmatrix} 0.63 & -0.56 & 0.08 & -0.23 \\ -0.45 & -0.31 & 0.27 & 1.21 \\ 0.20 & -0.35 & 0.41 & 0.84 \\ 0.49 & -0.05 & -0.52 & -0.08 \end{pmatrix}.$$

9.1 Program Text

Program f08qhfe

```
!
      FO8QHF Example Program Text
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!
      .. Use Statements ..
     Use nag_library, Only: dtrsyl, nag_wp, x04caf
      .. Implicit None Statement ..
      Implicit None
      .. Parameters ..
                                      :: nin = 5, nout = 6
      Integer, Parameter
     .. Local Scalars ..
Real (Kind=nag_wp)
                                        :: i, ifail, info, lda, ldb, ldc, m, n, &
     Integer
      .. Local Arrays ..
!
     Real (Kind=nag_wp), Allocatable :: a(:,:), b(:,:), c(:,:)
      .. Executable Statements ..
     Write (nout,*) 'F08QHF Example Program Results'
     Write (nout,*)
      Flush (nout)
     Skip heading in data file
!
     Read (nin,*)
      Read (nin,*) m, n
      lda = m
      ldb = n
```

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```
1dc = m
      sign = 1
     Allocate (a(lda,m),b(ldb,n),c(ldc,n))
     Read A, B and C from data file
     Read (nin,*)(a(i,1:m),i=1,m)
     Read (nin,*)(b(i,1:n),i=1,n)
     Read (nin,*)(c(i,1:n),i=1,m)
!
     Solve the Sylvester equation A*X + X*B = C for X
1
     The NAG name equivalent of dtrsyl is f08qhf
      Call dtrsyl('No transpose','No transpose',sign,m,n,a,lda,b,ldb,c,ldc, &
       scale, info)
      If (info==1) Then
       Write (nout,99999)
        Write (nout,*)
     End If
     Flush (nout)
!
     Print X
     ifail: behaviour on error exit
!
              =0 for hard exit, =1 for quiet-soft, =-1 for noisy-soft
      ifail = 0
     Call x04caf('General',' ',m,n,c,ldc,'Solution Matrix',ifail)
99999 Format (/' A and B have common or very close eigenvalues.'/' Pe', &
        'rturbed values were used to solve the equations')
    End Program f08qhfe
```

9.2 Program Data

```
FO8QHF Example Program Data
                            :Values of M and N
 4 4
 0.10
        0.50
              0.68 -0.21
       0.10
                    0.67
-0.50
             -0.24
        0.00
              0.19
                    -0.35
 0.00
       0.00
              0.00 -0.72
                            :End of matrix A
 0.00
 -0.99 -0.17
             0.39
                    0.58
 0.00
      0.48 -0.84 -0.15
 0.00
       0.00
              0.75
                     0.25
 0.00
        0.00
             -0.25
                     0.75
                            :End of matrix B
      -0.56
             0.08
                   -0.23
 0.63
-0.45
       -0.31
             0.27
                     1.21
       -0.35
              0.41
 0.20
                     0.84
       -0.05 -0.52
 0.49
                    -0.08
                            :End of matrix C
```

9.3 Program Results

F08QHF Example Program Results

```
Solution Matrix

1 2 3 4

1 -0.4209 0.1764 0.2438 -0.9577

2 0.5600 -0.8337 -0.7221 0.5386

3 -0.1246 -0.3392 0.6221 0.8691

4 -0.2865 0.4113 0.5535 0.3174
```

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