## **NAG Library Routine Document**

### E02BCF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

## 1 Purpose

E02BCF evaluates a cubic spline and its first three derivatives from its B-spline representation.

## 2 Specification

```
SUBROUTINE E02BCF (NCAP7, LAMDA, C, X, LEFT, S, IFAIL)

INTEGER NCAP7, LEFT, IFAIL

REAL (KIND=nag_wp) LAMDA(NCAP7), C(NCAP7), X, S(4)
```

## 3 Description

E02BCF evaluates the cubic spline s(x) and its first three derivatives at a prescribed argument x. It is assumed that s(x) is represented in terms of its B-spline coefficients  $c_i$ , for  $i=1,2,\ldots,\bar{n}+3$  and (augmented) ordered knot set  $\lambda_i$ , for  $i=1,2,\ldots,\bar{n}+7$ , (see E02BAF), i.e.,

$$s(x) = \sum_{i=1}^{q} c_i N_i(x).$$

Here  $q = \bar{n} + 3$ ,  $\bar{n}$  is the number of intervals of the spline and  $N_i(x)$  denotes the normalized B-spline of degree 3 (order 4) defined upon the knots  $\lambda_i, \lambda_{i+1}, \dots, \lambda_{i+4}$ . The prescribed argument x must satisfy

$$\lambda_4 \leq x \leq \lambda_{\bar{n}+4}$$
.

At a simple knot  $\lambda_i$  (i.e., one satisfying  $\lambda_{i-1} < \lambda_i < \lambda_{i+1}$ ), the third derivative of the spline is in general discontinuous. At a multiple knot (i.e., two or more knots with the same value), lower derivatives, and even the spline itself, may be discontinuous. Specifically, at a point x=u where (exactly) r knots coincide (such a point is termed a knot of multiplicity r), the values of the derivatives of order 4-j, for  $j=1,2,\ldots,r$ , are in general discontinuous. (Here  $1\leq r\leq 4;\ r>4$  is not meaningful.) You must specify whether the value at such a point is required to be the left- or right-hand derivative.

The method employed is based upon:

- (i) carrying out a binary search for the knot interval containing the argument x (see Cox (1978)),
- (ii) evaluating the nonzero B-splines of orders 1, 2, 3 and 4 by recurrence (see Cox (1972) and Cox (1978)),
- (iii) computing all derivatives of the B-splines of order 4 by applying a second recurrence to these computed B-spline values (see de Boor (1972)),
- (iv) multiplying the fourth-order B-spline values and their derivative by the appropriate B-spline coefficients, and summing, to yield the values of s(x) and its derivatives.

E02BCF can be used to compute the values and derivatives of cubic spline fits and interpolants produced by E02BAF.

If only values and not derivatives are required, E02BBF may be used instead of E02BCF, which takes about 50% longer than E02BBF.

Mark 24 E02BCF.1

E02BCF NAG Library Manual

#### 4 References

Cox M G (1972) The numerical evaluation of B-splines J. Inst. Math. Appl. 10 134-149

Cox M G (1978) The numerical evaluation of a spline from its B-spline representation *J. Inst. Math. Appl.* **21** 135–143

de Boor C (1972) On calculating with B-splines J. Approx. Theory 6 50-62

#### 5 Parameters

#### 1: NCAP7 – INTEGER

Input

On entry:  $\bar{n} + 7$ , where  $\bar{n}$  is the number of intervals of the spline (which is one greater than the number of interior knots, i.e., the knots strictly within the range  $\lambda_4$  to  $\lambda_{\bar{n}+4}$  over which the spline is defined).

*Constraint*: NCAP7  $\geq$  8.

#### 2: LAMDA(NCAP7) - REAL (KIND=nag wp) array

Input

On entry: LAMDA(j) must be set to the value of the jth member of the complete set of knots,  $\lambda_j$ , for  $j = 1, 2, ..., \bar{n} + 7$ .

Constraint: the LAMDA(j) must be in nondecreasing order with LAMDA(NCAP7 – 3) > LAMDA(4).

## 3: C(NCAP7) - REAL (KIND=nag\_wp) array

Input

On entry: the coefficient  $c_i$  of the B-spline  $N_i(x)$ , for  $i=1,2,\ldots,\bar{n}+3$ . The remaining elements of the array are not referenced.

## 4: $X - REAL (KIND=nag_wp)$

Input

On entry: the argument x at which the cubic spline and its derivatives are to be evaluated.

Constraint: LAMDA(4)  $\leq$  X  $\leq$  LAMDA(NCAP7 - 3).

#### 5: LEFT – INTEGER

Input

On entry: specifies whether left- or right-hand values of the spline and its derivatives are to be computed (see Section 3). Left- or right-hand values are formed according to whether LEFT is equal or not equal to 1.

If x does not coincide with a knot, the value of LEFT is immaterial.

If x = LAMDA(4), right-hand values are computed.

If x = LAMDA(NCAP7 - 3), left-hand values are formed, regardless of the value of LEFT.

## 6: $S(4) - REAL (KIND=nag_wp) array$

Output

On exit: S(j) contains the value of the (j-1)th derivative of the spline at the argument x, for j=1,2,3,4. Note that S(1) contains the value of the spline.

#### 7: IFAIL – INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

E02BCF.2 Mark 24

On exit: IFAIL = 0 unless the routine detects an error or a warning has been flagged (see Section 6).

## 6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

NCAP7 < 8, i.e., the number of intervals is not positive.

IFAIL = 2

Either LAMDA(4)  $\geq$  LAMDA(NCAP7 - 3), i.e., the range over which s(x) is defined is null or negative in length, or X is an invalid argument, i.e., X < LAMDA(4) or X > LAMDA(NCAP7 - 3).

## 7 Accuracy

The computed value of s(x) has negligible error in most practical situations. Specifically, this value has an **absolute** error bounded in modulus by  $18 \times c_{\max} \times \textit{machine precision}$ , where  $c_{\max}$  is the largest in modulus of  $c_j, c_{j+1}, c_{j+2}$  and  $c_{j+3}$ , and j is an integer such that  $\lambda_{j+3} \le x \le \lambda_{j+4}$ . If  $c_j, c_{j+1}, c_{j+2}$  and  $c_{j+3}$  are all of the same sign, then the computed value of s(x) has **relative** error bounded by  $20 \times \textit{machine precision}$ . For full details see Cox (1978).

No complete error analysis is available for the computation of the derivatives of s(x). However, for most practical purposes the absolute errors in the computed derivatives should be small.

### **8** Further Comments

The time taken is approximately linear in  $\log(\bar{n} + 7)$ .

**Note:** the routine does not test all the conditions on the knots given in the description of LAMDA in Section 5, since to do this would result in a computation time approximately linear in  $\bar{n} + 7$  instead of  $\log(\bar{n} + 7)$ . All the conditions are tested in E02BAF, however.

## 9 Example

Compute, at the 7 arguments x = 0, 1, 2, 3, 4, 5, 6, the left- and right-hand values and first 3 derivatives of the cubic spline defined over the interval  $0 \le x \le 6$  having the 6 interior knots x = 1, 3, 3, 3, 4, 4, the 8 additional knots 0, 0, 0, 0, 6, 6, 6, and the 10 B-spline coefficients 10, 12, 13, 15, 22, 26, 24, 18, 14, 12.

The input data items (using the notation of Section 5) comprise the following values in the order indicated:

$$ar{n}$$
  $m$  LAMDA $(j)$ , for  $j=1,2,\ldots,$  NCAP7  $C(j)$ , for  $j=1,2,\ldots,$  NCAP7  $X(i)$ , for  $i=1,2,\ldots,m$ 

This example program is written in a general form that will enable the values and derivatives of a cubic spline having an arbitrary number of knots to be evaluated at a set of arbitrary points. Any number of datasets may be supplied. The only changes required to the program relate to the dimensions of the arrays LAMDA and C.

Mark 24 E02BCF.3

#### 9.1 **Program Text**

```
Program e02bcfe
!
      E02BCF Example Program Text
1
      Mark 24 Release. NAG Copyright 2012.
      .. Use Statements ..
      Use nag_library, Only: e02bcf, nag_wp
!
      .. Implicit None Statement ..
     Implicit None
!
      .. Parameters ..
                                      :: nin = 5, nout = 6
      Integer, Parameter
      .. Local Scalars ..
      Real (Kind=nag_wp)
                                       :: X
                                       :: i, ifail, l, left, m, ncap, ncap7
      Integer
      .. Local Arrays ..
1
      Real (Kind=nag_wp), Allocatable :: c(:), lamda(:)
      Real (Kind=nag_wp)
                                       :: s(4)
      .. Executable Statements ..
      Write (nout,*) 'E02BCF Example Program Results'
!
      Skip heading in data file
      Read (nin,*)
      Read (nin,*) ncap, m
      ncap7 = ncap + 7
      Allocate (lamda(ncap7),c(ncap7))
      Read (nin,*) lamda(1:ncap7)
      Read (nin,*) c(1:(ncap+3))
      Do i = 1, m
       Read (nin,*) x
        Do left = 1, 2
          ifail = 0
          Call e02bcf(ncap7,lamda,c,x,left,s,ifail)
          If (left==1) Then
            If (i==1) Then
              Write (nout,*)
              Write (nout,*) '
                                                  Spline 1st &
               &deriv 2nd deriv 3rd deriv'
            End If
            Write (nout,*)
            Write (nout, 99999) x, ' LEFT', (s(1), l=1, 4)
            Write (nout, 99999) x, 'RIGHT', (s(1), 1=1, 4)
          End If
        End Do
      End Do
99999 Format (1X,E10.2,A,4E12.4)
    End Program e02bcfe
9.2 Program Data
```

```
E02BCF Example Program Data
  7 7
                    0.0 0.0 1.0 3.0
6.0 6.0 6.0 6.0
13.0 15.0 22.0 26.0
 0.0
           0.0
                   0.0
                                                          3.0
                                                                    3.0
 4.0
          4.0
 10.0
          12.0
                   13.0
                                                          24.0
                                                                    18.0
          12.0
14.0
```

E02BCF.4 Mark 24

- 0.0
- 1.0
- 2.0
- 4.0
- 5.0 6.0

# 9.3 Program Results

E02BCF Example Program Results

X	Spline	1st deriv	2nd deriv	3rd deriv
0.00E+00 LEFT	0.1000E+02		-0.1000E+02	0.1067E+02
0.00E+00 RIGHT	0.1000E+02		-0.1000E+02	0.1067E+02
0.10E+01 LEFT	0.1278E+02	0.1333E+01	0.6667E+00	0.1067E+02
0.10E+01 RIGHT	0.1278E+02	0.1333E+01	0.6667E+00	0.3917E+01
0.20E+01 LEFT	0.1510E+02	0.3958E+01	0.4583E+01	0.3917E+01
0.20E+01 RIGHT	0.1510E+02	0.3958E+01	0.4583E+01	0.3917E+01
0.30E+01 LEFT	0.2200E+02	0.1050E+02	0.8500E+01	0.3917E+01
0.30E+01 RIGHT	0.2200E+02	0.1200E+02	-0.3600E+02	0.3600E+02
0.40E+01 LEFT		-0.6000E+01	0.0000E+00	0.3600E+02
0.40E+01 RIGHT		-0.6000E+01	0.0000E+00	0.1500E+01
0.50E+01 LEFT		-0.5250E+01	0.1500E+01	0.1500E+01
0.50E+01 RIGHT		-0.5250E+01	0.1500E+01	0.1500E+01
0.60E+01 LEFT		-0.3000E+01	0.3000E+01	0.1500E+01
0.60E+01 RIGHT		-0.3000E+01	0.3000E+01	0.1500E+01

Mark 24 E02BCF.5 (last)