NAG Library Routine Document

D06BAF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1   Purpose

D06BAF generates a boundary mesh on a closed connected subdomain Ω of $\mathbb{R}^2$.

2   Specification

```
SUBROUTINE D06BAF (NLINES, COORCH, LINED, FBND, CRUS, SDCRUS, RATE, NCOMP,    &
                   NLCOMP, LCOMP, NVMAX, NEDMX, NVB, COOR, NEDGE, EDGE,       &
                   ITRACE, RUSER, IUSER, RWORK, LRWORK, IWORK, LIWORK,        &
                   IFAIL)

INTEGER           NLINES, LINED(4,NLINES), SDCRUS, NCOMP, NLCOMP(NCOMP),      &
                  LCOMP(NLINES), NVMAX, NEDMX, NVB, NEDGE, EDGE(3,NEDMX),     &
                  ITRACE, IUSER(*), LRWORK, IWORK(LIWORK), LIWORK, IFAIL
REAL (KIND=nag_wp) COORCH(2,NLINES), FBND, CRUS(2,SDCRUS), RATE(NLINES),      &
                  COOR(2,NVMAX), RUSER(*), RWORK(LRWORK)
EXTERNAL          FBND
```

3   Description

Given a closed connected subdomain Ω of $\mathbb{R}^2$, whose boundary $\partial\Omega$ is divided by characteristic points into m distinct line segments, D06BAF generates a boundary mesh on $\partial\Omega$. Each line segment may be a straight line, a curve defined by the equation $f(x, y) = 0$, or a polygonal curve defined by a set of given boundary mesh points.

This routine is primarily designed for use with either D06AAF (a simple incremental method) or D06ABF (Delaunay–Voronoi method) or D06ACF (Advancing Front method) to triangulate the interior of the domain Ω. For more details about the boundary and interior mesh generation, consult the D06 Chapter Introduction as well as George and Borouchaki (1998).

This routine is derived from material in the MODULEF package from INRIA (Institut National de Recherche en Informatique et Automatique).

4   References

George P L and Borouchaki H (1998) *Delaunay Triangulation and Meshing: Application to Finite Elements* Editions HERMES, Paris

5   Parameters

1:    NLINES – INTEGER   *Input*

On entry: m, the number of lines that define the boundary of the closed connected subdomain (this equals the number of characteristic points which separate the entire boundary $\partial\Omega$ into lines).

Constraint: NLINES ≥ 1.

2:    COORCH(2,NLINES) – REAL (KIND=nag_wp) array   *Input*

On entry: COORCH$(1, i)$ contains the x coordinate of the ith characteristic point, for $i = 1, 2, \ldots,$ NLINES; while COORCH$(2, i)$ contains the corresponding y coordinate.

3:      LINED(4,NLINES) – INTEGER array   *Input*

On entry: the description of the lines that define the boundary domain.   The line i, for $i = 1, 2, \ldots, m$, is defined as follows:

LINED$(1, i)$
    The number of points on the line, including two end points.

LINED$(2, i)$
    The first end point of the line. If LINED$(2, i) = j$, then the coordinates of the first end point are those stored in COORCH$(:, j)$.

LINED$(3, i)$
    The second end point of the line. If LINED$(3, i) = k$, then the coordinates of the second end point are those stored in COORCH$(:, k)$.

LINED$(4, i)$
    This defines the type of line segment connecting the end points. Additional information is conveyed by the numerical value of LINED$(4, i)$ as follows:

    (i)   LINED$(4, i) > 0$, the line is described in FBND with LINED$(4, i)$ as the index. In this case, the line must be described in the trigonometric (anticlockwise) direction;

    (ii) LINED$(4, i) = 0$, the line is a straight line;

    (iii) if LINED$(4, i) < 0$, say $(-p)$, then the line is a polygonal arc joining the end points and interior points specified in CRUS. In this case the line contains the points whose coordinates are stored in
          COORCH$(:, j)$,
          CRUS$(:, p)$,
          CRUS$(:, p + 1), \ldots,$ CRUS$(:, p + r - 3)$,
          COORCH$(:, k)$,
          where $z \in \{1, 2\}$, $r = $ LINED$(1, i)$, $j = $ LINED$(2, i)$ and $k = $ LINED$(3, i)$.

Constraints:

    $2 \leq$ LINED$(1, i)$;
    $1 \leq$ LINED$(2, i) \leq$ NLINES;
    $1 \leq$ LINED$(3, i) \leq$ NLINES;
    LINED$(2, i) \neq$ LINED$(3, i)$, for $i = 1, 2, \ldots,$ NLINES.

For each line described by FBND (lines with LINED$(4, i) > 0$, for $i = 1, 2, \ldots,$ NLINES) the two end points (LINED$(2, i)$ and LINED$(3, i)$) lie on the curve defined by index LINED$(4, i)$ in FBND, i.e.,

FBND(LINED$(4, i)$, COORCH$(1,$ LINED$(2, i))$, COORCH$(2,$ LINED$(2, i))$, RUSER, IUSER$) = 0$;

FBND(LINED$(4, i)$, COORCH$(1,$ LINED$(3, i))$, COORCH$(2,$ LINED$(3, i))$, RUSER, IUSER$) = 0$, for $i = 1, 2, \ldots,$ NLINES.

For all lines described as polygonal arcs (lines with LINED$(4, i) < 0$, for $i = 1, 2, \ldots,$ NLINES) the sets of intermediate points (i.e.,$[-$LINED$(4, i) : -$LINED$(4, i) + $LINED$(1, i) - 3]$ for all i such that LINED$(4, i) < 0$) are not overlapping. This can be expressed as:

$$-\text{LINED}(4, i) + \text{LINED}(1, i) - 3 = \sum_{\{i, \text{LINED}(4,i) < 0\}} \{\text{LINED}(1, i) - 2\}$$

or

$$-\text{LINED}(4, i) + \text{LINED}(1, i) - 2 = -\text{LINED}(4, j),$$

for a j such that $j = 1, 2, \ldots,$ NLINES, $j \neq i$ and LINED$(4, j) < 0$.

4:      FBND – REAL (KIND=nag_wp) FUNCTION, supplied by the user.   *External Procedure*

FBND must be supplied to calculate the value of the function which describes the curve $\{(x, y) \in \mathbb{R}^2;$ such that $f(x, y) = 0\}$ on segments of the boundary for which LINED$(4, i) > 0$. If

there are no boundaries for which $\text{LINED}(4, i) > 0$ FBND will never be referenced by D06BAF and FBND may be the dummy function D06BAD. (D06BAD is included in the NAG Library.)

The specification of FBND is:

```
FUNCTION FBND (I, X, Y, RUSER, IUSER)
REAL (KIND=nag_wp) FBND
INTEGER            I, IUSER(*)
REAL (KIND=nag_wp) X, Y, RUSER(*)
```

1:     I – INTEGER   *Input*

   On entry: $\text{LINED}(4, i)$, the reference index of the line (portion of the contour) i described.

2:     X – REAL (KIND=nag_wp)   *Input*
3:     Y – REAL (KIND=nag_wp)   *Input*

   On entry: the values of x and y at which $f(x, y)$ is to be evaluated.

4:     RUSER($*$) – REAL (KIND=nag_wp) array   *User Workspace*
5:     IUSER($*$) – INTEGER array   *User Workspace*

   FBND is called with the parameters RUSER and IUSER as supplied to D06BAF. You are free to use the arrays RUSER and IUSER to supply information to FBND as an alternative to using COMMON global variables.

FBND must either be a module subprogram USEd by, or declared as EXTERNAL in, the (sub)program from which D06BAF is called. Parameters denoted as *Input* must **not** be changed by this procedure.

5:     CRUS(2,SDCRUS) – REAL (KIND=nag_wp) array   *Input*

On entry: the coordinates of the intermediate points for polygonal arc lines. For a line i defined as a polygonal arc (i.e., $\text{LINED}(4, i) < 0$), if $p = -\text{LINED}(4, i)$, then $\text{CRUS}(1, k)$, for $k = p, \ldots, p + \text{LINED}(1, i) - 3$, must contain the x coordinate of the consecutive intermediate points for this line. Similarly $\text{CRUS}(2, k)$, for $k = p, \ldots, p + \text{LINED}(1, i) - 3$, must contain the corresponding y coordinate.

6:     SDCRUS – INTEGER   *Input*

On entry: the second dimension of the array CRUS as declared in the (sub)program from which D06BAF is called.

Constraint: $\text{SDCRUS} \geq \sum_{\{i, \text{LINED}(4,i) < 0\}} \{\text{LINED}(1, i) - 2\}$.

7:     RATE(NLINES) – REAL (KIND=nag_wp) array   *Input*

On entry: $\text{RATE}(i)$ is the geometric progression ratio between the points to be generated on the line i, for $i = 1, 2, \ldots, m$ and $\text{LINED}(4, i) \geq 0$.

If $\text{LINED}(4, i) < 0$, $\text{RATE}(i)$ is not referenced.

Constraint: if $\text{LINED}(4, i) \geq 0$, $\text{RATE}(i) > 0.0$, for $i = 1, 2, \ldots, \text{NLINES}$.

8:     NCOMP – INTEGER   *Input*

On entry: n, the number of separately connected components of the boundary.

Constraint: $\text{NCOMP} \geq 1$.

9: NLCOMP(NCOMP) – INTEGER array *Input*

On entry: $|\text{NLCOMP}(k)|$ is the number of line segments in component k of the contour. The line i of component k runs in the direction $\text{LINED}(2,i)$ to $\text{LINED}(3,i)$ if $\text{NLCOMP}(k) > 0$, and in the opposite direction otherwise; for $k = 1, 2, \ldots, n$.

Constraints:

$$1 \leq |\text{NLCOMP}(k)| \leq \text{NLINES}, \text{ for } k = 1, 2, \ldots, \text{NCOMP};$$

$$\sum_{k=1}^{n} |\text{NLCOMP}(k)| = \text{NLINES}.$$

10: LCOMP(NLINES) – INTEGER array *Input*

On entry: $\text{LCOMP}(l1 : l2)$, where $l2 = \sum_{i=1}^{k} |\text{NLCOMP}(i)|$ and $l1 = l2 + 1 - |\text{NLCOMP}(k)|$ is the list of line numbers for the kth components of the boundary, for $k = 1, 2, \ldots, \text{NCOMP}$.

Constraint: LCOMP must hold a valid permutation of the integers $[1, \text{NLINES}]$.

11: NVMAX – INTEGER *Input*

On entry: the maximum number of the boundary mesh vertices to be generated.

Constraint: $\text{NVMAX} \geq \text{NLINES}$.

12: NEDMX – INTEGER *Input*

On entry: the maximum number of boundary edges in the boundary mesh to be generated.

Constraint: $\text{NEDMX} \geq 1$.

13: NVB – INTEGER *Output*

On exit: the total number of boundary mesh vertices generated.

14: COOR(2,NVMAX) – REAL (KIND=nag_wp) array *Output*

On exit: $\text{COOR}(1,i)$ will contain the x coordinate of the ith boundary mesh vertex generated, for $i = 1, 2, \ldots, \text{NVB}$; while $\text{COOR}(2,i)$ will contain the corresponding y coordinate.

15: NEDGE – INTEGER *Output*

On exit: the total number of boundary edges in the boundary mesh.

16: EDGE(3,NEDMX) – INTEGER array *Output*

On exit: the specification of the boundary edges. $\text{EDGE}(1,j)$ and $\text{EDGE}(2,j)$ will contain the vertex numbers of the two end points of the jth boundary edge. $\text{EDGE}(3,j)$ is a reference number for the jth boundary edge and

$\text{EDGE}(3,j) = \text{LINED}(4,i)$, where i and j are such that the jth edges is part of the ith line of the boundary and $\text{LINED}(4,i) \geq 0$;

$\text{EDGE}(3,j) = 100 + |\text{LINED}(4,i)|$, where i and j are such that the jth edges is part of the ith line of the boundary and $\text{LINED}(4,i) < 0$.

17: ITRACE – INTEGER *Input*

On entry: the level of trace information required from D06BAF.

$\text{ITRACE} = 0$ or $\text{ITRACE} < -1$
    No output is generated.

ITRACE $= 1$

Output from the boundary mesh generator is printed on the current advisory message unit (see X04ABF). This output contains the input information of each line and each connected component of the boundary.

ITRACE $= -1$

An analysis of the output boundary mesh is printed on the current advisory message unit. This analysis includes the orientation (clockwise or anticlockwise) of each connected component of the boundary. This information could be of interest to you, especially if an interior meshing is carried out using the output of this routine, calling either D06AAF, D06ABF or D06ACF.

ITRACE > 1

The output is similar to that produced when ITRACE $= 1$, but the coordinates of the generated vertices on the boundary are also output.

You are advised to set ITRACE $= 0$, unless you are experienced with finite element mesh generation.

18: RUSER($*$) – REAL (KIND=nag_wp) array   *User Workspace*
19: IUSER($*$) – INTEGER array   *User Workspace*

RUSER and IUSER are not used by D06BAF, but are passed directly to FBND and may be used to pass information to this routine as an alternative to using COMMON global variables.

20: RWORK(LRWORK) – REAL (KIND=nag_wp) array   *Workspace*
21: LRWORK – INTEGER   *Input*

On entry: the dimension of the array RWORK as declared in the (sub)program from which D06BAF is called.

Constraint: $\text{LRWORK} \geq 2 \times (\text{NLINES} + \text{SDCRUS}) + 2 \times \max_{i=1,2,\ldots,m}\{\text{LINED}(1,i)\} \times \text{NLINES}$.

22: IWORK(LIWORK) – INTEGER array   *Workspace*
23: LIWORK – INTEGER   *Input*

On entry: the dimension of the array IWORK as declared in the (sub)program from which D06BAF is called.

Constraint:
$$\text{LIWORK} \geq \sum_{\{i,\text{LINED}(4,i)<0\}} \{\text{LINED}(1,i) - 2\} + 8 \times \text{NLINES} + \text{NVMAX} + 3 \times \text{NEDMX} + 2 \times \text{SDCRUS}.$$

24: IFAIL – INTEGER   *Input/Output*

On entry: IFAIL must be set to 0, -1 or 1. If you are unfamiliar with this parameter you should refer to Section 3.3 in the Essential Introduction for details.

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, if you are not familiar with this parameter, the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

On exit: IFAIL $= 0$ unless the routine detects an error or a warning has been flagged (see Section 6).

6   Error Indicators and Warnings

If on entry $IFAIL = 0$ or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

$IFAIL = 1$

    On entry, NLINES < 1;

    or   NVMAX $<$ NLINES;

    or   NEDMX < 1;

    or   NCOMP < 1;

    or   LRWORK $< 2 \times (\text{NLINES} + \text{SDCRUS}) + 2 \times \max_{i=1,2,\ldots,m} \{\text{LINED}(1, i)\} \times \text{NLINES}$;

    or $\text{LIWORK} < \sum\limits_{\{i,\text{LINED}(4,i)<0\}} \{\text{LINED}(1, i) - 2\} + 8 \times \text{NLINES} + \text{NVMAX} + 3 \times$
                $\text{NEDMX} + 2 \times \text{SDCRUS}$;

    or $\text{SDCRUS} < \sum\limits_{\{i,\text{LINED}(4,i)<0\}} \{\text{LINED}(1, i) - 2\}$;

    or $\text{RATE}(i) < 0.0$ for some $i = 1, 2, \ldots, \text{NLINES}$ with $\text{LINED}(4, i) \geq 0$;

    or $\text{LINED}(1, i) < 2$ for some $i = 1, 2, \ldots, \text{NLINES}$;

    or $\text{LINED}(2, i) < 1$ or $\text{LINED}(2, i) > \text{NLINES}$ for some $i = 1, 2, \ldots, \text{NLINES}$;

    or $\text{LINED}(3, i) < 1$ or $\text{LINED}(3, i) > \text{NLINES}$ for some $i = 1, 2, \ldots, \text{NLINES}$;

    or $\text{LINED}(2, i) = \text{LINED}(3, i)$ for some $i = 1, 2, \ldots, \text{NLINES}$;

    or $\text{NLCOMP}(k) = 0$, or $|\text{NLCOMP}(k)| > \text{NLINES}$ for a $k = 1, 2, \ldots, \text{NCOMP}$;

    or $\sum\limits_{k=1}^{n} |\text{NLCOMP}(k)| \neq \text{NLINES}$;

    or   LCOMP does not represent a valid permutation of the integers in $[1, \text{NLINES}]$;

    or   one of the end points for a line i described by the user-supplied function (lines with $\text{LINED}(4, i) > 0$, for $i = 1, 2, \ldots, \text{NLINES}$) does not belong to the corresponding curve in FBND;

    or   the intermediate points for the lines described as polygonal arcs (lines with $\text{LINED}(i) < 0$, for $i = 1, 2, \ldots, \text{NLINES}$) are overlapping.

$IFAIL = 2$

    An error has occurred during the generation of the boundary mesh. It appears that NEDMX is not large enough, so you are advised to increase the value of NEDMX.

$IFAIL = 3$

    An error has occurred during the generation of the boundary mesh. It appears that NVMAX is not large enough, so you are advised to increase the value of NVMAX.

$IFAIL = 4$

    An error has occurred during the generation of the boundary mesh. Check the definition of each line (the parameter LINED) and each connected component of the boundary (the arguments NLCOMP, and LCOMP, as well as the coordinates of the characteristic points. Setting $ITRACE > 0$ may provide more details.

7   Accuracy

Not applicable.

8   Further Comments

The boundary mesh generation technique in this routine has a 'tree' structure. The boundary should be partitioned into geometrically simple segments (straight lines or curves) delimited by characteristic points. Then, the lines should be assembled into connected components of the boundary domain.

Using this strategy, the inputs to that routine can be built up, following the requirements stated in Section 5:

> the characteristic and the user-supplied intermediate points:
>
> > NLINES, SDCRUS, COORCH and CRUS;
>
> the characteristic lines:
>
> > LINED, FBND, RATE;
>
> finally the assembly of lines into the connected components of the boundary:
>
> > NCOMP, and
> >
> > NLCOMP, LCOMP.

The example below details the use of this strategy.

9 Example

The NAG logo is taken as an example of a geometry with holes. The boundary has been partitioned in 40 lines characteristic points; including 4 for the exterior boundary and 36 for the logo itself. All line geometry specifications have been considered, see the description of LINED, including 4 lines defined as polygonal arc, 4 defined by FBND and all the others are straight lines.

9.1 Program Text

```
!   D06BAF Example Program Text
!   Mark 24 Release. NAG Copyright 2012.
    Module d06bafe_mod

!     D06BAF Example Program Module:
!            Parameters and User-defined Routines

!     .. Use Statements ..
      Use nag_library, Only: nag_wp
!     .. Implicit None Statement ..
      Implicit None
!     .. Parameters ..
      Integer, Parameter                :: nin = 5, nout = 6
    Contains
      Function fbnd(i,x,y,ruser,iuser)

!       .. Function Return Value ..
        Real (Kind=nag_wp)                :: fbnd
!       .. Scalar Arguments ..
        Real (Kind=nag_wp), Intent (In)    :: x, y
        Integer, Intent (In)              :: i
!       .. Array Arguments ..
        Real (Kind=nag_wp), Intent (Inout)  :: ruser(*)
        Integer, Intent (Inout)           :: iuser(*)
!       .. Local Scalars ..
        Real (Kind=nag_wp)                :: radius2, x0, xa, xb, y0
!       .. Executable Statements ..
        xa = ruser(1)
        xb = ruser(2)
        x0 = ruser(3)
        y0 = ruser(4)

        fbnd = 0.0_nag_wp

        Select Case (i)
        Case (1)

!         line 1,2,3, and 4: ellipse centred in (X0,Y0) with
!         XA and XB as coefficients

          fbnd = ((x-x0)/xa)**2 + ((y-y0)/xb)**2 - 1.0_nag_wp
        Case (2)
```

```
!          line 7, lower arc on letter n, is a circle centred in (X0,Y0)
!          with radius SQRT(RADIUS2)

           x0 = 0.5_nag_wp
           y0 = 6.25_nag_wp
           radius2 = 20.3125_nag_wp
           fbnd = (x-x0)**2 + (y-y0)**2 - radius2
         Case (3)

!          line 11, upper arc on letter n, is a circle centred in (X0,Y0)
!          with radius SQRT(RADIUS2)

           x0 = 1.0_nag_wp
           y0 = 4.0_nag_wp
           radius2 = 9.0_nag_wp + (11.0_nag_wp-y0)**2
           fbnd = (x-x0)**2 + (y-y0)**2 - radius2
         Case (4)

!          line 15, upper arc on letter a, is a circle centred in (X0,Y0)
!          with radius SQRT(RADIUS2) touching point (5,11).

           x0 = 8.5_nag_wp
           y0 = 2.75_nag_wp
           radius2 = (x0-5.0_nag_wp)**2 + (11.0_nag_wp-y0)**2
           fbnd = (x-x0)**2 + (y-y0)**2 - radius2
         Case (5)

!          line 25, lower arc on hat of 'a', is a circle centred in (X0,Y0)
!          with radius SQRT(RADIUS2) touching point (11,10).

           x0 = 8.5_nag_wp
           y0 = 4.0_nag_wp
           radius2 = 2.5_nag_wp**2 + (10.0_nag_wp-y0)**2
           fbnd = (x-x0)**2 + (y-y0)**2 - radius2
         Case (6)

!          lines 20, 21 and 22, belly of letter a, is an ellipse centered
!          in (X0, Y0) with semi-axes 3.5 and 2.75.

           x0 = 8.5_nag_wp
           y0 = 5.75_nag_wp
           fbnd = ((x-x0)/3.5_nag_wp)**2 + ((y-y0)/2.75_nag_wp)**2 - 1.0_nag_wp
         Case (7)

!          lines 43, 44 and 45, outer curve on bottom of 'g', is an ellipse
!          centered in (X0, Y0) with semi-axes 3.5 and 2.5.

           x0 = 17.5_nag_wp
           y0 = 2.5_nag_wp
           fbnd = ((x-x0)/3.5_nag_wp)**2 + ((y-y0)/2.5_nag_wp)**2 - 1.0_nag_wp
         Case (8)

!          lines 28, 29 and 30, inner curve on bottom of 'g', is an ellipse
!          centered in (X0, Y0) with semi-axes 2.0 and 1.5.

           x0 = 17.5_nag_wp
           y0 = 2.5_nag_wp
           fbnd = ((x-x0)/2.0_nag_wp)**2 + ((y-y0)/1.5_nag_wp)**2 - 1.0_nag_wp
         Case (9)

!          line 42, inner curve on lower middle of 'g', is an ellipse
!          centered in (X0, Y0) with semi-axes 1.5 and 0.5.

           x0 = 17.5_nag_wp
           y0 = 5.5_nag_wp
           fbnd = ((x-x0)/1.5_nag_wp)**2 + ((y-y0)/0.5_nag_wp)**2 - 1.0_nag_wp
         Case (10)

!          line 31, outer curve on lower middle of 'g', is an ellipse
!          centered in (X0, Y0) with semi-axes 2.0 and 1.5.
```

```
          x0 = 17.5_nag_wp
          y0 = 5.5_nag_wp
          fbnd = ((x-x0)/3.0_nag_wp)**2 + ((y-y0)/1.5_nag_wp)**2 - 1.0_nag_wp
        Case (11)

!         line 41, inner curve on upper middle of 'g', is an ellipse
!         centered in (X0, Y0) with semi-axes 1.0 and 1.0.

          x0 = 17.0_nag_wp
          y0 = 5.5_nag_wp
          fbnd = ((x-x0)/1.0_nag_wp)**2 + ((y-y0)/1.0_nag_wp)**2 - 1.0_nag_wp
        Case (12)

!         line 32, outer curve on upper middle of 'g', is an ellipse
!         centered in (X0, Y0) with semi-axes 1.5 and 1.1573.

          x0 = 16.0_nag_wp
          y0 = 5.5_nag_wp
          fbnd = ((x-x0)/1.5_nag_wp)**2 + ((y-y0)/1.1573_nag_wp)**2 - &
            1.0_nag_wp
        Case (13)

!         lines 33, 33, 34, 39 and 40, upper portion of 'g', is an ellipse
!         centered in (X0, Y0) with semi-axes 3.0 and 2.75.
          x0 = 17.0_nag_wp
          y0 = 9.25_nag_wp
          fbnd = ((x-x0)/3.0_nag_wp)**2 + ((y-y0)/2.75_nag_wp)**2 - 1.0_nag_wp
        End Select

        Return

      End Function fbnd
    End Module d06bafe_mod
    Program d06bafe

!     D06BAF Example Main Program

!     .. Use Statements ..
      Use nag_library, Only: d06abf, d06acf, d06baf, f16dnf, nag_wp
      Use d06bafe_mod, Only: fbnd, nin, nout
!     .. Implicit None Statement ..
      Implicit None
!     .. Local Scalars ..
      Real (Kind=nag_wp)                   :: x0, xa, xb, xmax, xmin, y0,    &
                                              ymax, ymin
      Integer                              :: i, ifail, itrace, j, k, liwork, &
                                              lrwork, maxind, maxval, ncomp,  &
                                              nedge, nedmx, nelt, nlines,     &
                                              npropa, nv, nvb, nvint, nvmax,  &
                                              reftk, sdcrus
      Character (1)                        :: pmesh
!     .. Local Arrays ..
      Real (Kind=nag_wp), Allocatable      :: coor(:,:), coorch(:,:),        &
                                              crus(:,:), rate(:), rwork(:),   &
                                              weight(:)
      Real (Kind=nag_wp)                   :: ruser(4)
      Integer, Allocatable                 :: conn(:,:), edge(:,:), iwork(:), &
                                              lcomp(:), lined(:,:), nlcomp(:)
      Integer                              :: iuser(1)
!     .. Intrinsic Procedures ..
      Intrinsic                            :: abs
!     .. Executable Statements ..
      Write (nout,*) 'D06BAF Example Program Results'
      Flush (nout)

!     Skip heading in data file
      Read (nin,*)

!     Initialise boundary mesh inputs:
!     the number of line and of the characteristic points of
```

```
!     the boundary mesh

      Read (nin,*) nlines, nvmax, nedmx
      Allocate (coor(2,nvmax),coorch(2,nlines),rate(nlines),edge(3,nedmx), &
        lcomp(nlines),lined(4,nlines))

!     The Lines of the boundary mesh

      Read (nin,*)(lined(1:4,j),rate(j),j=1,nlines)

      sdcrus = 0

      Do i = 1, nlines

        If (lined(4,i)<0) Then
          sdcrus = sdcrus + lined(1,i) - 2
        End If

      End Do

      liwork = 8*nlines + nvmax + 3*nedmx + 3*sdcrus

!     Get max(LINED(1,:)) for computing LRWORK

      Call f16dnf(nlines,lined,4,maxind,maxval)

      lrwork = 2*(nlines+sdcrus) + 2*maxval*nlines

      Allocate (crus(2,sdcrus),iwork(liwork),rwork(lrwork))

!     The ellipse boundary which envelops the NAg Logo
!     the N, the A and the G

      Read (nin,*) coorch(1,1:nlines)
      Read (nin,*) coorch(2,1:nlines)

      Read (nin,*) crus(1,1:sdcrus)
      Read (nin,*) crus(2,1:sdcrus)

!     The number of connected components to the boundary
!     and their informations

      Read (nin,*) ncomp
      Allocate (nlcomp(ncomp))

      j = 1

      Do i = 1, ncomp
        Read (nin,*) nlcomp(i)
        k = j + abs(nlcomp(i)) - 1
        Read (nin,*) lcomp(j:k)
        j = k + 1
      End Do

!     Data passed to the user-supplied function

      xmin = coorch(1,4)
      xmax = coorch(1,2)
      ymin = coorch(2,1)
      ymax = coorch(2,3)

      xa = (xmax-xmin)/2.0_nag_wp
      xb = (ymax-ymin)/2.0_nag_wp

      x0 = (xmin+xmax)/2.0_nag_wp
      y0 = (ymin+ymax)/2.0_nag_wp

      ruser(1:4) = (/xa,xb,x0,y0/)
      iuser(1) = 0

      itrace = -1
```

```
      Write (nout,*)
      Flush (nout)

!     Call to the boundary mesh generator

      ifail = 0
      Call d06baf(nlines,coorch,lined,fbnd,crus,sdcrus,rate,ncomp,nlcomp, &
        lcomp,nvmax,nedmx,nvb,coor,nedge,edge,itrace,ruser,iuser,rwork,lrwork, &
        iwork,liwork,ifail)

      Read (nin,*) pmesh

      Select Case (pmesh)
      Case ('N')
        Write (nout,*) 'Boundary mesh characteristics'
        Write (nout,99999) 'NVB   =', nvb
        Write (nout,99999) 'NEDGE =', nedge
      Case ('Y')

!       Output the mesh

        Write (nout,99998) nvb, nedge

        Do i = 1, nvb
          Write (nout,99997) i, coor(1:2,i)
        End Do

        Do i = 1, nedge
          Write (nout,99996) i, edge(1:3,i)
        End Do

        Flush (nout)

      Case Default
        Write (nout,*) 'Problem with the printing option Y or N'
        Go To 100
      End Select

      Deallocate (rwork,iwork)

!     Initialise mesh control parameters

      itrace = 0
      npropa = 1
      nvint = 0
      lrwork = 12*nvmax + 15
      liwork = 6*nedge + 32*nvmax + 2*nvb + 78
      Allocate (weight(nvint),rwork(lrwork),iwork(liwork),conn(3,2*nvmax+5))

!     Call to the 2D Delaunay-Voronoi mesh generator

      ifail = 0
      Call d06abf(nvb,nvint,nvmax,nedge,edge,nv,nelt,coor,conn,weight,npropa, &
        itrace,rwork,lrwork,iwork,liwork,ifail)

      Select Case (pmesh)
      Case ('N')
        Write (nout,*) 'Complete mesh (via the 2D Delaunay-Voronoi'
        Write (nout,*) 'mesh generator) characteristics'
        Write (nout,99999) 'NV   =', nv
        Write (nout,99999) 'NELT =', nelt
      Case ('Y')

!       Output the mesh

        Write (nout,99998) nv, nelt

        Do i = 1, nv
          Write (nout,99995) coor(1:2,i)
        End Do
```

```
          reftk = 0

          Do k = 1, nelt
            Write (nout,99994) conn(1:3,k), reftk
          End Do

          Flush (nout)

       End Select

       Deallocate (rwork,iwork)
       lrwork = 12*nvmax + 30015
       liwork = 8*nedge + 53*nvmax + 2*nvb + 10078
       Allocate (rwork(lrwork),iwork(liwork))

!      Call to the 2D Advancing front mesh generator

       ifail = 0
       Call d06acf(nvb,nvint,nvmax,nedge,edge,nv,nelt,coor,conn,weight,itrace, &
         rwork,lrwork,iwork,liwork,ifail)

       Select Case (pmesh)
       Case ('N')
         Write (nout,*) 'Complete mesh (via the 2D Advancing front mesh'
         Write (nout,*) 'generator) characteristics'
         Write (nout,99999) 'NV   =', nv
         Write (nout,99999) 'NELT =', nelt
       Case ('Y')

!        Output the mesh

         Write (nout,99998) nv, nelt

         Do i = 1, nv
           Write (nout,99995) coor(1:2,i)
         End Do

         reftk = 0

         Do k = 1, nelt
           Write (nout,99994) conn(1:3,k), reftk
         End Do

       End Select

100    Continue

99999 Format (1X,A,I6)
99998 Format (1X,2I10)
99997 Format (2X,I4,2(2X,E13.6))
99996 Format (1X,4I4)
99995 Format (2(2X,E13.6))
99994 Format (1X,4I10)
    End Program d06bafe
```

9.2 Program Data

```
D06BAF Example Program Data
45  5000  1000                                              :NLINES (m), NVMAX, NEDMX
15  1  2  1   0.9500    15  2  3  1   1.0500
15  3  4  1   0.9500    15  4  1  1   1.0500
 4  6  5 -1   1.0000    10 10  6  0   1.0000
10 14 10  2   1.0000    10  7 14  0   1.0000
 4  8  7  0   1.0000    10 13  8  0   1.0000
10 13  9  3   1.0000    10 12  9  0   1.0000
 4 11 12  0   1.0000    15  5 11  0   1.0000
15 26 15  4   1.0000    10 26 25  0   1.0000
 4 25 24  0   1.0000     4 24 23  0   1.0000
 4 23 22  0   1.0000    10 21 22  6   1.0000
```

```
10 20 21  6    1.0000   10 19 20  6    1.0000
 4 19 18  0    1.0000    5 18 17  0    1.0000
15 17 16  5    1.0000    4 16 15  0    1.0000
 4 27 28  0    1.0000    7 28 30  8    1.0000
 7 30 32  8    1.0000    7 32 34  8    1.0000
 6 36 34 10    1.0000    6 38 36 12    1.0000
10 40 38 13    1.0000   10 42 40 13    1.0000
 8 44 42 13    1.0000    4 44 45  0    1.0000
 4 45 43  0    1.0000    4 43 41  0    1.0000
 6 39 41 13    1.0000   10 37 39 13    1.0000
 6 37 35 11    1.0000    6 35 33  9    1.0000
10 31 33  7    1.0000   10 29 31  7    1.0000
10 27 29  7    1.0000                          :(LINE(:,j),RATE(j),j=1,m)
 9.5000   33.0000    9.5000 -14.0000
-4.0000   -2.0000    2.0000   4.0000  -2.0000  -2.0000  -4.0000
-2.0000    4.0000    2.0000
 5.0000    6.0000   11.0000   11.0000   8.5000   5.0000   8.5000
11.5000   13.0000   14.0000   13.0000  13.0000
14.0000   15.5000   17.5000   17.5000  21.0000  19.5000  17.5000
17.5000   16.0000   14.5000   17.0000  16.0000  20.0000  14.0000
19.3142   17.0000   20.5000   18.7249  19.5000           : End of X coords
-3.0000    6.5000   16.0000    6.5000
 3.0000    3.0000    3.0000    3.0000  11.0000  10.0000  11.5000
12.0000   11.0000   10.5000
11.0000   10.0000   10.0000    8.5000   8.5000   5.7500   3.0000
 4.3335    3.0000    3.7500    4.7500  10.5000
 2.5000    2.5000    0.0000    1.0000   2.5000   2.5000   5.0000
 4.0000    5.5000    5.5000    6.5000   6.6573   9.2500   9.2500
11.0000   12.000    11.5000   11.5000  12.0000           : End of Y coords
-2.6667   -3.3333    3.3333    2.6667                     :(Poly (X))
 3.0000    3.0000    3.0000    3.0000                     :(Poly (Y))
 4                                       :NCOMP (n, number of contours)
 4                                       :number of lines in contour 1
 1  2  3  4                              :lines of contour 1    (Ellipse)
10                                       :number of lines in contour 2
14 13 12 11 10  9  8  7  6  5            :lines of contour 2   (Letter N)
12                                       :number of lines in contour 3
18 19 20 21 22 23 24 25 26 15 16 17      :lines of contour 3   (Letter A)
19                                       :number of lines in contour 4
27 28 29 30 31 32 33 34 35 36 37 38
39 40 41 42 43 44 45                     :lines of contour 4   (Letter G)
'N'                                        :Printing option 'Y' or 'N'
```

9.3 Program Results

```
D06BAF Example Program Results

ANALYSIS OF THE BOUNDARY CREATED:
THE BOUNDARY MESH CONTAINS     332 VERTEX AND     332 EDGES
THERE ARE        4 COMPONENTS CONNECTED THE BOUNDARY
THE  1-st COMPONENT CONTAINS      4 LINES IN ANTICLOCKWISE ORIENTATION
THE  2-nd COMPONENT CONTAINS     10 LINES IN CLOCKWISE ORIENTATION
THE  3-rd COMPONENT CONTAINS     12 LINES IN ANTICLOCKWISE ORIENTATION
THE  4-th COMPONENT CONTAINS     19 LINES IN CLOCKWISE ORIENTATION
Boundary mesh characteristics
NVB  =    332
NEDGE =   332
Complete mesh (via the 2D Delaunay-Voronoi
mesh generator) characteristics
NV   =    903
NELT =   1478
Complete mesh (via the 2D Advancing front mesh
generator) characteristics
NV   =    924
NELT =   1520
```

Example Program
Boundary Mesh of the NAG Logo with 259 Nodes and 259 Edges
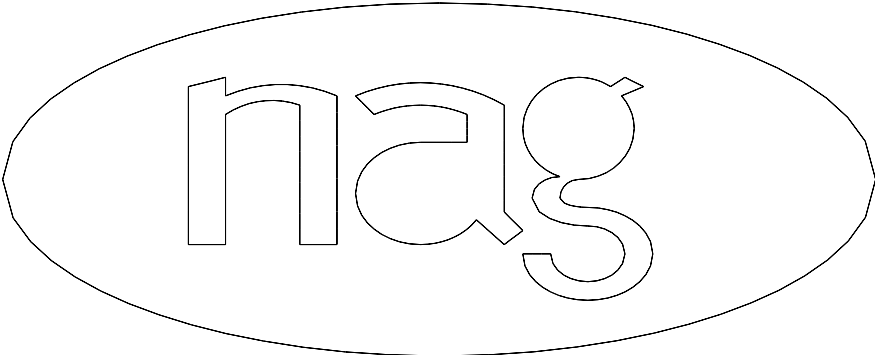
Final Mesh Built Using the Delaunay-Voronoi Method
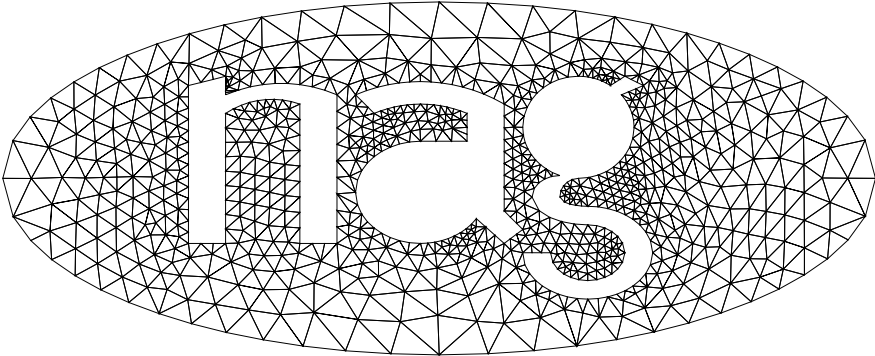
Final Mesh Built Using the Advancing Front Method