

5 Arguments

- 1: **n** – Integer *Input*
On entry: the actual state dimension, n , i.e., the order of the matrix A .
Constraint: $n \geq 1$.
- 2: **p** – Integer *Input*
On entry: the actual output dimension, p .
Constraint: $p \geq 1$.
- 3: **reduceto** – Nag_ObserverForm *Input*
On entry: indicates whether the matrix pair (A, C) is to be reduced to upper or lower observer Hessenberg form
reduceto = Nag_UH_Observer
 Upper observer Hessenberg form).
reduceto = Nag_LH_Observer
 Lower observer Hessenberg form).
Constraint: **reduceto** = Nag_UH_Observer or Nag_LH_Observer.
- 4: **a**[$n \times tda$] – double *Input/Output*
Note: the (i, j) th element of the matrix A is stored in **a**[($i - 1$) \times **tda** + $j - 1$].
On entry: the leading n by n part of this array must contain the state transition matrix A to be transformed.
On exit: the leading n by n part of this array contains the transformed state transition matrix UAU^T .
- 5: **tda** – Integer *Input*
On entry: the stride separating matrix column elements in the array **a**.
Constraint: **tda** $\geq n$.
- 6: **c**[$p \times tdc$] – double *Input/Output*
Note: the (i, j) th element of the matrix C is stored in **c**[($i - 1$) \times **tdc** + $j - 1$].
On entry: the leading p by n part of this array must contain the output matrix C to be transformed.
On exit: the leading p by n part of this array contains the transformed output matrix CU^T .
- 7: **tdc** – Integer *Input*
On entry: the stride separating matrix column elements in the array **c**.
Constraint: **tdc** $\geq n$.
- 8: **u**[$n \times tdu$] – double *Input/Output*
Note: the (i, j) th element of the matrix U is stored in **u**[($i - 1$) \times **tdu** + $j - 1$].
On entry: if **u** is not **NULL**, then the leading n by n part of this array must contain either a transformation matrix (e.g., from a previous call to this function) or be initialized as the identity matrix. If this information is not to be input then **u** must be set to **NULL**.

On exit: if **u** is not **NULL**, then the leading n by n part of this array contains the product of the input matrix U and the state-space transformation matrix which reduces the given pair to observer Hessenberg form.

9: **tdu** – Integer *Input*

On entry: the stride separating matrix column elements in the array **u**.

Constraint: **tdu** \geq **n** if **u** is defined.

10: **fail** – NagError * *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

6 Error Indicators and Warnings

NE_2_INT_ARG_LT

On entry, **tda** = $\langle value \rangle$ while **n** = $\langle value \rangle$. These arguments must satisfy **tda** \geq **n**.

On entry **tdc** = $\langle value \rangle$ while **n** = $\langle value \rangle$. These arguments must satisfy **tdc** \geq **n**.

On entry **tdu** = $\langle value \rangle$ while **n** = $\langle value \rangle$. These arguments must satisfy **tdu** \geq **n**.

NE_BAD_PARAM

On entry, argument **reduceto** had an illegal value.

NE_INT_ARG_LT

On entry, **n** = $\langle value \rangle$.

Constraint: **n** \geq 1.

On entry, **p** = $\langle value \rangle$.

Constraint: **p** \geq 1.

7 Accuracy

The algorithm is backward stable.

8 Parallelism and Performance

nag_trans_hessenberg_observer (g13ewc) is not threaded in any implementation.

9 Further Comments

The algorithm requires $O((n+m)n^2)$ operations (see van Dooren and Verhaegen (1985)).

10 Example

To reduce the matrix pair (A, C) to upper observer Hessenberg form.

10.1 Program Text

```
/* nag_trans_hessenberg_observer (g13ewc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group
 *
 * Mark 26, 2016.
 */
```

```

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <naggl3.h>

#define A(I, J) a[(I) *tda + J]
#define C(I, J) c[(I) *tdc + J]
#define U(I, J) u[(I) *tdu + J]
int main(void)
{
    Integer exit_status = 0, i, j, n, p, tda, tdc, tdu;
    double *a = 0, *c = 0, one = 1.0, *u = 0, zero = 0.0;
    Nag_ObserverForm reduceto;
    NagError fail;

    INIT_FAIL(fail);

    printf("nag_trans_hessenberg_observer (g13ewc) Example Program Results\n");

    /* Skip the heading in the data file and read the data. */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "", &n, &p);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "", &n, &p);
#endif
    if (n >= 1 || p >= 1) {
        if (!(a = NAG_ALLOC(n * n, double)) ||
            !(c = NAG_ALLOC(p * n, double)) || !(u = NAG_ALLOC(n * n, double)))
        {
            printf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
        tda = n;
        tdc = n;
        tdu = n;
    }
    else {
        printf("Invalid n or p.\n");
        exit_status = 1;
        return exit_status;
    }

    reduceto = Nag_UH_Observer;

    for (j = 0; j < n; ++j)
        for (i = 0; i < n; ++i)
#ifdef _WIN32
            scanf_s("%lf", &A(i, j));
#else
            scanf("%lf", &A(i, j));
#endif
    for (i = 0; i < p; ++i)
        for (j = 0; j < n; ++j)
#ifdef _WIN32
            scanf_s("%lf", &C(i, j));
#else
            scanf("%lf", &C(i, j));
#endif

    if (u) /* Initialize U as the identity matrix. */
        for (i = 0; i < n; ++i) {
            for (j = 0; j < n; ++j)
                U(i, j) = zero;
            U(i, i) = one;
        }
}

```

```

    }

/* Reduce the pair (A,C) to reduced observer Hessenberg form. */
/* nag_trans_hessenberg_observer (g13ewc).
 * Unitary state-space transformation to reduce (AC) to
 * lower or upper observer Hessenberg form
 */
nag_trans_hessenberg_observer(n, p, reduceto, a, tda, c, tdc, u, tdu,
                             &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_trans_hessenberg_observer (g13ewc).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
}

printf("\nThe transformed state transition matrix is \n\n");
for (i = 0; i < n; ++i) {
    for (j = 0; j < n; ++j)
        printf("%8.4f ", A(i, j));
    printf("\n");
}
printf("\nThe transformed input matrix is \n\n");
for (i = 0; i < p; ++i) {
    for (j = 0; j < n; ++j)
        printf("%8.4f ", C(i, j));
    printf("\n");
}
if (u) {
    printf("\nThe transformation matrix that reduces (A,C) "
           "to observer Hessenberg form is \n\n");
    for (i = 0; i < n; ++i) {
        for (j = 0; j < n; ++j)
            printf("%8.4f ", U(i, j));
        printf("\n");
    }
}
END:
NAG_FREE(a);
NAG_FREE(c);
NAG_FREE(u);
return exit_status;
}

```

10.2 Program Data

nag_trans_hessenberg_observer (g13ewc) Example Program Data

```

5      3
15.0  21.0  -3.0   3.0   9.0
20.0   1.0   2.0   8.0   9.0
 4.0   1.0   7.0  13.0  14.0
 5.0   6.0  12.0  13.0  -6.0
 5.0  11.0  17.0  -7.0  -1.0
 7.0  -1.0   3.0  -6.0  -3.0
 4.0   5.0   6.0  -2.0  -3.0
 9.0   8.0   5.0   2.0   1.0

```

10.3 Program Results

nag_trans_hessenberg_observer (g13ewc) Example Program Results

The transformed state transition matrix is

```

 7.1637  -0.9691 -16.5046   0.2869   0.9205
 -2.3285  11.5431  -8.7471   3.4122  -3.7118
-10.5440  -7.6032  -0.3215   3.6571  -0.4335
 -3.6845   5.6449   0.5906 -15.6996  17.4267
 0.0000  -6.4260   1.5591  14.4317  32.3143

```

The transformed input matrix is

0.0000	0.0000	7.6585	5.2973	-4.1576
0.0000	0.0000	0.0000	5.8305	-7.4837
0.0000	0.0000	0.0000	0.0000	-13.2288

The transformation matrix that reduces (A,C) to observer Hessenberg form is

0.1863	-0.4823	0.2645	0.6648	-0.4698
-0.1137	-0.3601	0.6748	-0.0512	0.6320
0.6742	-0.5151	-0.1897	-0.4940	-0.0097
-0.1872	0.0813	0.5439	-0.5371	-0.6116
-0.6803	-0.6047	-0.3780	-0.1512	-0.0756
