

# NAG Library Function Document

## nag\_1d\_quad\_vals (d01gac)

### 1 Purpose

nag\_1d\_quad\_vals (d01gac) integrates a function which is specified numerically at four or more points, over the whole of its specified range, using third-order finite difference formulae with error estimates, according to a method due to Gill and Miller (1972).

### 2 Specification

```
#include <nag.h>
#include <nagd01.h>
void nag_1d_quad_vals (Integer n, const double x[], const double y[],
double *ans, double *er, NagError *fail)
```

### 3 Description

nag\_1d\_quad\_vals (d01gac) evaluates the definite integral

$$I = \int_{x_1}^{x_n} y(x) dx,$$

where the function  $y$  is specified at the  $n$ -points  $x_1, x_2, \dots, x_n$ , which should be all distinct, and in either ascending or descending order. The integral between successive points is calculated by a four-point finite difference formula centred on the interval concerned, except in the case of the first and last intervals, where four-point forward and backward difference formulae respectively are employed. If  $n$  is less than 4, the function fails. An approximation to the truncation error is integrated and added to the result. It is also returned separately to give an estimate of the uncertainty in the result. The method is due to Gill and Miller (1972).

### 4 References

Gill P E and Miller G F (1972) An algorithm for the integration of unequally spaced data *Comput. J.* **15** 80–83

### 5 Arguments

- |    |  |               |
|----|--|---------------|
| 1: | <b>n</b> – Integer   | <i>Input</i>  |
|    | <i>On entry:</i> $n$ , the number of points.   |               |
|    | <i>Constraint:</i> $n \geq 4$ .  |               |
| 2: | <b>x[n]</b> – const double   | <i>Input</i>  |
|    | <i>On entry:</i> the values of the independent variable, i.e., the $x_1, x_2, \dots, x_n$ .                  |               |
|    | <i>Constraint:</i> either $x[0] < x[1] < \dots < x[n - 1]$ or $x[0] > x[1] > \dots > x[n - 1]$ .             |               |
| 3: | <b>y[n]</b> – const double   | <i>Input</i>  |
|    | <i>On entry:</i> the values of the dependent variable $y_i$ at the points $x_i$ , for $i = 1, 2, \dots, n$ . |               |
| 4: | <b>ans</b> – double *  | <i>Output</i> |
|    | <i>On exit:</i> the estimated value of the integral.   |               |

5: <b>er</b> – double *	<i>Output</i>
On exit: an estimate of the uncertainty in <b>ans</b> .	
6: <b>fail</b> – NagError *	<i>Input/Output</i>
The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).	

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_INT

On entry, **n** =  $\langle value \rangle$ .

Constraint:  $\mathbf{n} \geq 4$ .

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

### NE\_NO\_LICENCE

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

### NE\_NOT\_STRICTLY\_DECREASING

The sequence **x** is not strictly decreasing:  $\mathbf{x}[\langle value \rangle] = \langle value \rangle$  and  $\mathbf{x}[\langle value \rangle] = \langle value \rangle$ .

### NE\_NOT\_STRICTLY\_INCREASING

The sequence **x** is not strictly increasing:  $\mathbf{x}[\langle value \rangle] = \langle value \rangle$ ,  $\mathbf{x}[\langle value \rangle] = \langle value \rangle$ .

### NE\_QUAD\_FIRST\_TWO PTS\_EQL

The sequence **x** has first two points equal:  $\mathbf{x}[0] = \langle value \rangle$  and  $\mathbf{x}[1] = \langle value \rangle$ .

## 7 Accuracy

No accuracy level is specified by you before calling nag\_1d\_quad\_vals (d01gac) but on return the absolute value of **er** is an approximation to, but not necessarily a bound for,  $|I - \mathbf{ans}|$ . If on exit **fail.code** = NE\_INT, NE\_NOT\_STRICTLY\_DECREASING, NE\_NOT\_STRICTLY\_INCREASING or NE\_QUAD\_FIRST\_TWO PTS\_EQL, both **ans** and **er** are returned as zero.

## 8 Parallelism and Performance

nag\_1d\_quad\_vals (d01gac) is not threaded in any implementation.

## 9 Further Comments

The time taken by nag\_1d\_quad\_vals (d01gac) depends on the number of points supplied,  $n$ .

In their paper, Gill and Miller (1972) do not add the quantity **er** to **ans** before return. However, extensive tests have shown that a dramatic reduction in the error often results from such addition. In other cases, it does not make an improvement, but these tend to be cases of low accuracy in which the modified answer is not significantly inferior to the unmodified one. You have the option of recovering the Gill–Miller answer by subtracting **er** from **ans** on return from the function.

## 10 Example

This example evaluates the integral

$$\int_0^1 \frac{4}{1+x^2} dx = \pi$$

reading in the function values at 21 unequally spaced points.

### 10.1 Program Text

```
/* nag_1d_quad_vals (d01gac) Example Program.
*
* NAGPRODCODE Version.
*
* Copyright 2016 Numerical Algorithms Group.
*
* Mark 26, 2016.
*/
#include <nag.h>
#include <stdio.h>
#include <nag_stdl�.h>
#include <nagd01.h>

int main(void)
{
    Integer exit_status = 0, i, n;
    NagError fail;
    double ans, error, *x = 0, *y = 0;
    INIT_FAIL(fail);

    printf("nag_1d_quad_vals (d01gac) Example Program Results\n");
#ifndef _WIN32
    scanf_s("%*[^\n]"); /* Skip heading in data file */
#else
    scanf("%*[^\n]"); /* Skip heading in data file */
#endif
#ifndef _WIN32
    scanf_s("%" NAG_IFMT "", &n);
#else
    scanf("%" NAG_IFMT "", &n);
#endif
    if (n >= 4) {
        if (!(x = NAG_ALLOC(n, double)) || !(y = NAG_ALLOC(n, double)))
        {
            printf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
    }
    else {
        printf("Invalid n.\n");
        exit_status = 1;
        return exit_status;
    }
}

END:
    exit_status = 0;
    if (y != 0)
        NAG_FREE(y);
    if (x != 0)
        NAG_FREE(x);
}
```

```

    for (i = 0; i < n; ++i)
#define _WIN32
    scanf_s("%lf%lf", &x[i], &y[i]);
#else
    scanf("%lf%lf", &x[i], &y[i]);
#endif
/* nag_1d_quad_vals (d01gac).
 * One-dimensional integration of a function defined by data
 * values only
 */
nag_1d_quad_vals(n, x, y, &ans, &error, &fail);
if (fail.code == NE_NOERROR) {
    printf("Integral = %7.4f\n", ans);
    printf("Estimated error = %7.4f\n", error);
}
else {
    printf("Error from nag_1d_quad_vals (d01gac).\n%s\n", fail.message);
    printf("%s\n", fail.message);
    exit_status = 1;
}
END:
NAG_FREE(x);
NAG_FREE(y);
return exit_status;
}

```

## 10.2 Program Data

```
nag_1d_quad_vals (d01gac) Example Program Data
21
0.00    4.0000
0.04    3.9936
0.08    3.9746
0.12    3.9432
0.22    3.8153
0.26    3.7467
0.30    3.6697
0.38    3.4943
0.39    3.4719
0.42    3.4002
0.45    3.3264
0.46    3.3014
0.60    2.9412
0.68    2.7352
0.72    2.6344
0.73    2.6094
0.83    2.3684
0.85    2.3222
0.88    2.2543
0.90    2.2099
1.00    2.0000
```

## 10.3 Program Results

```
nag_1d_quad_vals (d01gac) Example Program Results
Integral = 3.1414
Estimated error = -0.0001
```

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