

## NAG Library Function Document

### nag\_bessel\_i1\_vector (s18atc)

#### 1 Purpose

nag\_bessel\_i1\_vector (s18atc) returns an array of values for the modified Bessel function  $I_1(x)$ .

#### 2 Specification

```
#include <nag.h>
#include <nags.h>
void nag_bessel_i1_vector (Integer n, const double x[], double f[],
                          Integer ivalid[], NagError *fail)
```

#### 3 Description

nag\_bessel\_i1\_vector (s18atc) evaluates an approximation to the modified Bessel function of the first kind  $I_1(x_i)$  for an array of arguments  $x_i$ , for  $i = 1, 2, \dots, n$ .

**Note:**  $I_1(-x) = -I_1(x)$ , so the approximation need only consider  $x \geq 0$ .

The function is based on three Chebyshev expansions:

For  $0 < x \leq 4$ ,

$$I_1(x) = x \sum_{r=0} a_r T_r(t), \quad \text{where } t = 2\left(\frac{x}{4}\right)^2 - 1;$$

For  $4 < x \leq 12$ ,

$$I_1(x) = e^x \sum_{r=0} b_r T_r(t), \quad \text{where } t = \frac{x-8}{4};$$

For  $x > 12$ ,

$$I_1(x) = \frac{e^x}{\sqrt{x}} \sum_{r=0} c_r T_r(t), \quad \text{where } t = 2\left(\frac{12}{x}\right) - 1.$$

For small  $x$ ,  $I_1(x) \simeq x$ . This approximation is used when  $x$  is sufficiently small for the result to be correct to **machine precision**.

For large  $x$ , the function must fail because  $I_1(x)$  cannot be represented without overflow.

#### 4 References

Abramowitz M and Stegun I A (1972) *Handbook of Mathematical Functions* (3rd Edition) Dover Publications

#### 5 Arguments

- 1: **n** – Integer Input  
*On entry:*  $n$ , the number of points.  
*Constraint:*  $n \geq 0$ .
- 2: **x[n]** – const double Input  
*On entry:* the argument  $x_i$  of the function, for  $i = 1, 2, \dots, n$ .

- 3: **f[n]** – double *Output*  
*On exit:*  $I_1(x_i)$ , the function values.
- 4: **ivalid[n]** – Integer *Output*  
*On exit:* **ivalid**[ $i - 1$ ] contains the error code for  $x_i$ , for  $i = 1, 2, \dots, \mathbf{n}$ .  
**ivalid**[ $i - 1$ ] = 0  
 No error.  
**ivalid**[ $i - 1$ ] = 1  
 $x_i$  is too large. **f**[ $i - 1$ ] contains the approximate value of  $I_1(x_i)$  at the nearest valid argument. The threshold value is the same as for **fail.code** = NE\_REAL\_ARG\_GT in nag\_bessel\_i1 (s18afc), as defined in the Users' Note for your implementation.
- 5: **fail** – NagError \* *Input/Output*  
 The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_INT

On entry,  $\mathbf{n} = \langle value \rangle$ .

Constraint:  $\mathbf{n} \geq 0$ .

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.

See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

### NE\_NO\_LICENCE

Your licence key may have expired or may not have been installed correctly.

See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

### NW\_INVALID

On entry, at least one value of  $\mathbf{x}$  was invalid.

Check **ivalid** for more information.

## 7 Accuracy

Let  $\delta$  and  $\epsilon$  be the relative errors in the argument and result respectively.

If  $\delta$  is somewhat larger than the *machine precision* (i.e., if  $\delta$  is due to data errors etc.), then  $\epsilon$  and  $\delta$  are approximately related by:

$$\epsilon \simeq \left| \frac{xI_0(x) - I_1(x)}{I_1(x)} \right| \delta.$$

Figure 1 shows the behaviour of the error amplification factor

$$\left| \frac{xI_0(x) - I_1(x)}{I_1(x)} \right|.$$

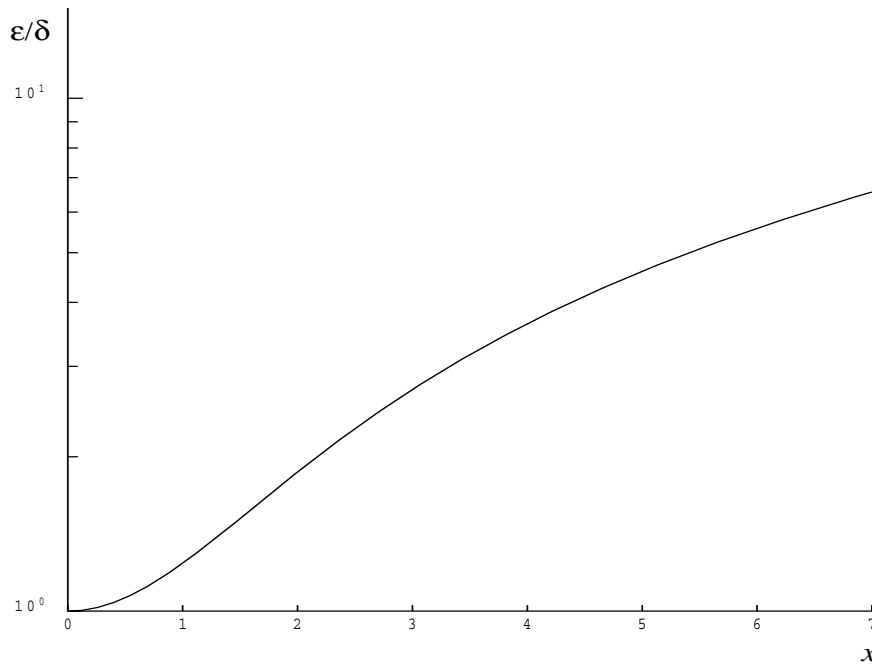


Figure 1

However, if  $\delta$  is of the same order as *machine precision*, then rounding errors could make  $\epsilon$  slightly larger than the above relation predicts.

For small  $x$ ,  $\epsilon \simeq \delta$  and there is no amplification of errors.

For large  $x$ ,  $\epsilon \simeq x\delta$  and we have strong amplification of errors. However, for quite moderate values of  $x$  ( $x > \hat{x}$ , the threshold value), the function must fail because  $I_1(x)$  would overflow; hence in practice the loss of accuracy for  $x$  close to  $\hat{x}$  is not excessive and the errors will be dominated by those of the standard function `exp`.

## 8 Parallelism and Performance

`nag_bessel_i1_vector` (s18atc) is not threaded in any implementation.

## 9 Further Comments

None.

## 10 Example

This example reads values of  $x$  from a file, evaluates the function at each value of  $x_i$  and prints the results.

## 10.1 Program Text

```

/* nag_bessel_il_vector (s18atc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */
#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nags.h>

int main(void)
{
    Integer exit_status = 0;
    Integer i, n;
    double *f = 0, *x = 0;
    Integer *ivalid = 0;
    NagError fail;

    INIT_FAIL(fail);

    /* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

    printf("nag_bessel_il_vector (s18atc) Example Program Results\n");
    printf("\n");
    printf("      x          f          ivalid\n");
    printf("\n");
#ifdef _WIN32
    scanf_s("%" NAG_IFMT " ", &n);
#else
    scanf("%" NAG_IFMT " ", &n);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

    /* Allocate memory */
    if (!(x = NAG_ALLOC(n, double)) ||
        !(f = NAG_ALLOC(n, double)) || !(ivalid = NAG_ALLOC(n, Integer)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    for (i = 0; i < n; i++)
#ifdef _WIN32
        scanf_s("%lf", &x[i]);
#else
        scanf("%lf", &x[i]);
#endif
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif

    /* nag_bessel_il_vector (s18atc).
     * modified Bessel Function I1(x)
     */

```

```

nag_bessel_il_vector(n, x, f, ivalid, &fail);
if (fail.code != NE_NOERROR && fail.code != NW_INVALID) {
    printf("Error from nag_bessel_il_vector (s18atc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

for (i = 0; i < n; i++)
    printf(" %11.3e %11.3e %4" NAG_IFMT "\n", x[i], f[i], ivalid[i]);

END:
NAG_FREE(f);
NAG_FREE(x);
NAG_FREE(ivalid);

return exit_status;
}

```

## 10.2 Program Data

nag\_bessel\_il\_vector (s18atc) Example Program Data

10

0.0 0.5 1.0 3.0 6.0 8.0 10.0 15.0 20.0 -1.0

## 10.3 Program Results

nag\_bessel\_il\_vector (s18atc) Example Program Results

x	f	ivalid
0.000e+00	0.000e+00	0
5.000e-01	2.579e-01	0
1.000e+00	5.652e-01	0
3.000e+00	3.953e+00	0
6.000e+00	6.134e+01	0
8.000e+00	3.999e+02	0
1.000e+01	2.671e+03	0
1.500e+01	3.281e+05	0
2.000e+01	4.245e+07	0
-1.000e+00	-5.652e-01	0

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