

## NAG Library Function Document

### nag\_zgghd3 (f08wtc)

#### 1 Purpose

nag\_zgghd3 (f08wtc) reduces a pair of complex matrices  $(A, B)$ , where  $B$  is upper triangular, to the generalized upper Hessenberg form using unitary transformations.

#### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_zgghd3 (Nag_OrderType order, Nag_ComputeQType compq,
                Nag_ComputeZType compz, Integer n, Integer ilo, Integer ihi,
                Complex a[], Integer pda, Complex b[], Integer pdb, Complex q[],
                Integer pdq, Complex z[], Integer pdz, NagError *fail)
```

#### 3 Description

nag\_zgghd3 (f08wtc) is usually the third step in the solution of the complex generalized eigenvalue problem

$$Ax = \lambda Bx.$$

The (optional) first step balances the two matrices using nag\_zggbal (f08wvc). In the second step, matrix  $B$  is reduced to upper triangular form using the  $QR$  factorization function nag\_zgeqrf (f08asc) and this unitary transformation  $Q$  is applied to matrix  $A$  by calling nag\_zunmqr (f08auc). The driver, nag\_zgge3 (f08wqc), solves the complex generalized eigenvalue problem by combining all the required steps including those just listed.

nag\_zgghd3 (f08wtc) reduces a pair of complex matrices  $(A, B)$ , where  $B$  is triangular, to the generalized upper Hessenberg form using unitary transformations. This two-sided transformation is of the form

$$\begin{aligned} Q^H A Z &= H, \\ Q^H B Z &= T \end{aligned}$$

where  $H$  is an upper Hessenberg matrix,  $T$  is an upper triangular matrix and  $Q$  and  $Z$  are unitary matrices determined as products of Givens rotations. They may either be formed explicitly, or they may be postmultiplied into input matrices  $Q_1$  and  $Z_1$ , so that

$$\begin{aligned} Q_1 A Z_1^H &= (Q_1 Q) H (Z_1 Z)^H, \\ Q_1 B Z_1^H &= (Q_1 Q) T (Z_1 Z)^H. \end{aligned}$$

#### 4 References

Golub G H and Van Loan C F (2012) *Matrix Computations* (4th Edition) Johns Hopkins University Press, Baltimore

Moler C B and Stewart G W (1973) An algorithm for generalized matrix eigenproblems *SIAM J. Numer. Anal.* **10** 241–256

## 5 Arguments

- 1: **order** – Nag\_OrderType *Input*  
*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.  
*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.
- 2: **compq** – Nag\_ComputeQType *Input*  
*On entry:* specifies the form of the computed unitary matrix  $Q$ .  
**compq** = Nag\_NotQ  
 Do not compute  $Q$ .  
**compq** = Nag\_InitQ  
 The unitary matrix  $Q$  is returned.  
**compq** = Nag\_UpdateSchur  
**q** must contain a unitary matrix  $Q_1$ , and the product  $Q_1Q$  is returned.  
*Constraint:* **compq** = Nag\_NotQ, Nag\_InitQ or Nag\_UpdateSchur.
- 3: **compz** – Nag\_ComputeZType *Input*  
*On entry:* specifies the form of the computed unitary matrix  $Z$ .  
**compz** = Nag\_NotZ  
 Do not compute  $Z$ .  
**compz** = Nag\_UpdateZ  
**z** must contain a unitary matrix  $Z_1$ , and the product  $Z_1Z$  is returned.  
**compz** = Nag\_InitZ  
 The unitary matrix  $Z$  is returned.  
*Constraint:* **compz** = Nag\_NotZ, Nag\_UpdateZ or Nag\_InitZ.
- 4: **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrices  $A$  and  $B$ .  
*Constraint:*  $n \geq 0$ .
- 5: **ilo** – Integer *Input*  
 6: **ihi** – Integer *Input*  
*On entry:*  $i_{lo}$  and  $i_{hi}$  as determined by a previous call to nag\_zggbal (f08wvc). Otherwise, they should be set to 1 and  $n$ , respectively.  
*Constraints:*  
 if  $n > 0$ ,  $1 \leq ilo \leq ihi \leq n$ ;  
 if  $n = 0$ ,  $ilo = 1$  and  $ihi = 0$ .
- 7: **a**[*dim*] – Complex *Input/Output*  
**Note:** the dimension, *dim*, of the array **a** must be at least  $\max(1, pda \times n)$ .  
 The ( $i, j$ )th element of the matrix  $A$  is stored in  
 $a[(j-1) \times pda + i - 1]$  when **order** = Nag\_ColMajor;  
 $a[(i-1) \times pda + j - 1]$  when **order** = Nag\_RowMajor.  
*On entry:* the matrix  $A$  of the matrix pair  $(A, B)$ . Usually, this is the matrix  $A$  returned by nag\_zunmqr (f08auc).

*On exit:* **a** is overwritten by the upper Hessenberg matrix  $H$ .

8: **pda** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **a**.

*Constraint:*  $\mathbf{pda} \geq \max(1, \mathbf{n})$ .

9: **b**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **b** must be at least  $\max(1, \mathbf{pdb} \times \mathbf{n})$ .

The (*i*, *j*)th element of the matrix  $B$  is stored in

$$\begin{aligned} & \mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ & \mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On entry:* the upper triangular matrix  $B$  of the matrix pair  $(A, B)$ . Usually, this is the matrix  $B$  returned by the  $QR$  factorization function nag\_zgeqrf (f08asc).

*On exit:* **b** is overwritten by the upper triangular matrix  $T$ .

10: **pdb** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **b**.

*Constraint:*  $\mathbf{pdb} \geq \max(1, \mathbf{n})$ .

11: **q**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **q** must be at least

$$\begin{aligned} & \max(1, \mathbf{pdq} \times \mathbf{n}) \text{ when } \mathbf{compq} = \text{Nag\_InitQ} \text{ or } \text{Nag\_UpdateSchur}; \\ & 1 \text{ when } \mathbf{compq} = \text{Nag\_NotQ}. \end{aligned}$$

The (*i*, *j*)th element of the matrix  $Q$  is stored in

$$\begin{aligned} & \mathbf{q}[(j-1) \times \mathbf{pdq} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ & \mathbf{q}[(i-1) \times \mathbf{pdq} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On entry:* if  $\mathbf{compq} = \text{Nag\_UpdateSchur}$ , **q** must contain a unitary matrix  $Q_1$ .

If  $\mathbf{compq} = \text{Nag\_NotQ}$ , **q** is not referenced.

*On exit:* if  $\mathbf{compq} = \text{Nag\_InitQ}$ , **q** contains the unitary matrix  $Q$ .

If  $\mathbf{compq} = \text{Nag\_UpdateSchur}$ , **q** is overwritten by  $Q_1 Q$ .

12: **pdq** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **q**.

*Constraints:*

$$\begin{aligned} & \text{if } \mathbf{compq} = \text{Nag\_InitQ} \text{ or } \text{Nag\_UpdateSchur}, \mathbf{pdq} \geq \max(1, \mathbf{n}); \\ & \text{if } \mathbf{compq} = \text{Nag\_NotQ}, \mathbf{pdq} \geq 1. \end{aligned}$$

13: **z**[*dim*] – Complex *Input/Output*

**Note:** the dimension, *dim*, of the array **z** must be at least

$$\begin{aligned} & \max(1, \mathbf{pdz} \times \mathbf{n}) \text{ when } \mathbf{compz} = \text{Nag\_UpdateZ} \text{ or } \text{Nag\_InitZ}; \\ & 1 \text{ when } \mathbf{compz} = \text{Nag\_NotZ}. \end{aligned}$$

The  $(i, j)$ th element of the matrix  $Z$  is stored in

$$\begin{aligned} & \mathbf{z}[(j-1) \times \mathbf{pdz} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ & \mathbf{z}[(i-1) \times \mathbf{pdz} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On entry:* if **compz** = Nag\_UpdateZ,  $\mathbf{z}$  must contain a unitary matrix  $Z_1$ .

If **compz** = Nag\_NotZ,  $\mathbf{z}$  is not referenced.

*On exit:* if **compz** = Nag\_InitZ,  $\mathbf{z}$  contains the unitary matrix  $Z$ .

If **compz** = Nag\_UpdateZ,  $\mathbf{z}$  is overwritten by  $Z_1 Z$ .

14: **pdz** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array  $\mathbf{z}$ .

*Constraints:*

$$\begin{aligned} & \text{if } \mathbf{compz} = \text{Nag\_UpdateZ} \text{ or } \text{Nag\_InitZ}, \mathbf{pdz} \geq \max(1, \mathbf{n}); \\ & \text{if } \mathbf{compz} = \text{Nag\_NotZ}, \mathbf{pdz} \geq 1. \end{aligned}$$

15: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle \text{value} \rangle$  had an illegal value.

### NE\_ENUM\_INT\_2

On entry, **compq** =  $\langle \text{value} \rangle$ , **pdq** =  $\langle \text{value} \rangle$  and **n** =  $\langle \text{value} \rangle$ .

Constraint: if **compq** = Nag\_InitQ or Nag\_UpdateSchur, **pdq**  $\geq \max(1, \mathbf{n})$ ;  
if **compq** = Nag\_NotQ, **pdq**  $\geq 1$ .

On entry, **compz** =  $\langle \text{value} \rangle$ , **pdz** =  $\langle \text{value} \rangle$  and **n** =  $\langle \text{value} \rangle$ .

Constraint: if **compz** = Nag\_UpdateZ or Nag\_InitZ, **pdz**  $\geq \max(1, \mathbf{n})$ ;  
if **compz** = Nag\_NotZ, **pdz**  $\geq 1$ .

### NE\_INT

On entry, **n** =  $\langle \text{value} \rangle$ .

Constraint: **n**  $\geq 0$ .

On entry, **pda** =  $\langle \text{value} \rangle$ .

Constraint: **pda**  $> 0$ .

On entry, **pdb** =  $\langle \text{value} \rangle$ .

Constraint: **pdb**  $> 0$ .

On entry, **pdq** =  $\langle \text{value} \rangle$ .

Constraint: **pdq**  $> 0$ .

On entry, **pdz** =  $\langle \text{value} \rangle$ .

Constraint: **pdz**  $> 0$ .

**NE\_INT\_2**

On entry, **pda** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pda**  $\geq$   $\max(1, \mathbf{n})$ .

On entry, **pdb** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pdb**  $\geq$   $\max(1, \mathbf{n})$ .

**NE\_INT\_3**

On entry, **n** =  $\langle value \rangle$ , **ilo** =  $\langle value \rangle$  and **ihi** =  $\langle value \rangle$ .  
 Constraint: if **n** > 0,  $1 \leq \mathbf{ilo} \leq \mathbf{ihi} \leq \mathbf{n}$ ;  
 if **n** = 0, **ilo** = 1 and **ihi** = 0.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.  
 See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

**NE\_NO\_LICENCE**

Your licence key may have expired or may not have been installed correctly.  
 See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

**7 Accuracy**

The reduction to the generalized Hessenberg form is implemented using unitary transformations which are backward stable.

**8 Parallelism and Performance**

nag\_zgghd3 (f08wtc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

**9 Further Comments**

This function is usually followed by nag\_zhgeqz (f08xsc) which implements the *QZ* algorithm for computing generalized eigenvalues of a reduced pair of matrices.

The real analogue of this function is nag\_dgghd3 (f08wfc).

**10 Example**

See Section 10 in nag\_zhgeqz (f08xsc) and nag\_ztgevc (f08yxc).

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