NAG Library Function Document

nag_dggevx (f08wbc)

1 Purpose

nag_dggevx (f08wbc) computes for a pair of n by n real nonsymmetric matrices (A, B) the generalized eigenvalues and, optionally, the left and/or right generalized eigenvectors using the QZ algorithm.

Optionally it also computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors, reciprocal condition numbers for the eigenvalues, and reciprocal condition numbers for the right eigenvectors.

2 Specification

```
#include <nag.h>
#include <nagf08.h>
void nag_dggevx (Nag_OrderType order, Nag_BalanceType balanc,
     Nag_LeftVecsType jobvl, Nag_RightVecsType jobvr, Nag_RCondType sense,
     Integer n, double a[], Integer pda, double b[], Integer pdb,
     double alphar[], double alphai[], double beta[], double vl[],
     Integer pdvl, double vr[], Integer pdvr, Integer *ilo, Integer *ihi,
     double lscale[], double rscale[], double *abnrm, double *bbnrm,
     double rconde[], double rcondv[], NagError *fail)
```

3 Description

A generalized eigenvalue for a pair of matrices (A, B) is a scalar λ or a ratio $\alpha/\beta = \lambda$, such that $A - \lambda B$ is singular. It is usually represented as the pair (α, β), as there is a reasonable interpretation for $\beta = 0$, and even for both being zero.

The right eigenvector v_j corresponding to the eigenvalue λ_j of (A, B) satisfies

$$Av_j = \lambda_j Bv_j.$$

The left eigenvector u_j corresponding to the eigenvalue λ_j of (A, B) satisfies

$$u_j^{\mathrm{H}} A = \lambda_j u_j^{\mathrm{H}} B,$$

where u_j^{H} is the conjugate-transpose of u_j.

All the eigenvalues and, if required, all the eigenvectors of the generalized eigenproblem $Ax = \lambda Bx$, where A and B are real, square matrices, are determined using the QZ algorithm. The QZ algorithm consists of four stages:

1. A is reduced to upper Hessenberg form and at the same time B is reduced to upper triangular form.
2. A is further reduced to quasi-triangular form while the triangular form of B is maintained. This is the real generalized Schur form of the pair (A, B).
3. The quasi-triangular form of A is reduced to triangular form and the eigenvalues extracted. This function does not actually produce the eigenvalues λ_j, but instead returns α_j and β_j such that

   $$\lambda_j = \alpha_j/\beta_j, \quad j = 1, 2, \ldots, n.$$

   The division by β_j becomes your responsibility, since β_j may be zero, indicating an infinite eigenvalue. Pairs of complex eigenvalues occur with α_j/β_j and α_{j+1}/β_{j+1} complex conjugates, even though α_j and α_{j+1} are not conjugate.
4. If the eigenvectors are required they are obtained from the triangular matrices and then transformed back into the original coordinate system.

For details of the balancing option, see Section 3 in nag_dggbal (f08whc).

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (2012) *Matrix Computations* (4th Edition) Johns Hopkins University Press, Baltimore

Wilkinson J H (1979) Kronecker's canonical form and the QZ algorithm *Linear Algebra Appl.* **28** 285–303

5 Arguments

1: **order** – Nag_OrderType *Input*

On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

Constraint: **order** = Nag_RowMajor or Nag_ColMajor.

2: **balanc** – Nag_BalanceType *Input*

On entry: specifies the balance option to be performed.

balanc = Nag_NoBalancing
Do not diagonally scale or permute.

balanc = Nag_BalancePermute
Permute only.

balanc = Nag_BalanceScale
Scale only.

balanc = Nag_BalanceBoth
Both permute and scale.

Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does. In the absence of other information, **balanc** = Nag_BalanceBoth is recommended.

Constraint: **balanc** = Nag_NoBalancing, Nag_BalancePermute, Nag_BalanceScale or Nag_BalanceBoth.

3: **jobvl** – Nag_LeftVecsType *Input*

On entry: if **jobvl** = Nag_NotLeftVecs, do not compute the left generalized eigenvectors.

If **jobvl** = Nag_LeftVecs, compute the left generalized eigenvectors.

Constraint: **jobvl** = Nag_NotLeftVecs or Nag_LeftVecs.

4: **jobvr** – Nag_RightVecsType *Input*

On entry: if **jobvr** = Nag_NotRightVecs, do not compute the right generalized eigenvectors.

If **jobvr** = Nag_RightVecs, compute the right generalized eigenvectors.

Constraint: **jobvr** = Nag_NotRightVecs or Nag_RightVecs.

5: **sense** – Nag_RCondType *Input*

On entry: determines which reciprocal condition numbers are computed.

sense = Nag_NotRCond
None are computed.

sense = Nag_RCondEigVals
Computed for eigenvalues only.

sense = Nag_RCondEigVecs
Computed for eigenvectors only.

sense = Nag_RCondBoth
Computed for eigenvalues and eigenvectors.

Constraint: **sense** = Nag_NotRCond, Nag_RCondEigVals, Nag_RCondEigVecs or Nag_RCondBoth.

6: **n** – Integer *Input*

On entry: n, the order of the matrices A and B.

Constraint: $\mathbf{n} \geq 0$.

7: **a**[dim] – double *Input/Output*

Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.

Where $\mathbf{A}(i,j)$ appears in this document, it refers to the array element

$\mathbf{a}[(j-1) \times \mathbf{pda} + i - 1]$ when **order** = Nag_ColMajor;
$\mathbf{a}[(i-1) \times \mathbf{pda} + j - 1]$ when **order** = Nag_RowMajor.

On entry: the matrix A in the pair (A, B).

On exit: **a** has been overwritten. If **jobvl** = Nag_LeftVecs or **jobvr** = Nag_RightVecs or both, then A contains the first part of the real Schur form of the 'balanced' versions of the input A and B.

8: **pda** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **a**.

Constraint: $\mathbf{pda} \geq \max(1, \mathbf{n})$.

9: **b**[dim] – double *Input/Output*

Note: the dimension, *dim*, of the array **b** must be at least $\max(1, \mathbf{pdb} \times \mathbf{n})$.

Where $\mathbf{B}(i,j)$ appears in this document, it refers to the array element

$\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1]$ when **order** = Nag_ColMajor;
$\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1]$ when **order** = Nag_RowMajor.

On entry: the matrix B in the pair (A, B).

On exit: **b** has been overwritten.

10: **pdb** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **b**.

Constraint: $\mathbf{pdb} \geq \max(1, \mathbf{n})$.

11: **alphar**[**n**] – double *Output*

On exit: the element $\mathbf{alphar}[j-1]$ contains the real part of α_j.

12: **alphai**[**n**] – double *Output*

On exit: the element **alphai**$[j-1]$ contains the imaginary part of α_j.

13: **beta**[**n**] – double *Output*

On exit: (**alphar**$[j-1]$ + **alphai**$[j-1] \times i$)/**beta**$[j-1]$, for $j = 1, 2, \ldots,$ **n**, will be the generalized eigenvalues.

If **alphai**$[j-1]$ is zero, then the jth eigenvalue is real; if positive, then the jth and $(j+1)$st eigenvalues are a complex conjugate pair, with **alphai**$[j]$ negative.

Note: the quotients **alphar**$[j-1]$/**beta**$[j-1]$ and **alphai**$[j-1]$/**beta**$[j-1]$ may easily overflow or underflow, and **beta**$[j-1]$ may even be zero. Thus, you should avoid naively computing the ratio α_j/β_j. However, $\max\left(\left|\alpha_j\right|\right)$ will always be less than and usually comparable with $\|A\|_2$ in magnitude, and $\max\left(\left|\beta_j\right|\right)$ will always be less than and usually comparable with $\|B\|_2$.

14: **vl**[dim] – double *Output*

Note: the dimension, *dim*, of the array **vl** must be at least

$\max(1, \textbf{pdvl} \times \textbf{n})$ when **jobvl** = Nag_LeftVecs;
1 otherwise.

The (i,j)th element of the matrix is stored in

vl$[(j-1) \times$ **pdvl** $+ i - 1]$ when **order** = Nag_ColMajor;
vl$[(i-1) \times$ **pdvl** $+ j - 1]$ when **order** = Nag_RowMajor.

On exit: if **jobvl** = Nag_LeftVecs, the left generalized eigenvectors u_j are stored one after another in the columns of **vl**, in the same order as the corresponding eigenvalues. Each eigenvector will be scaled so the largest component will have |real part| + |imag. part| = 1.

If **jobvl** = Nag_NotLeftVecs, **vl** is not referenced.

15: **pdvl** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **vl**.

Constraints:

if **jobvl** = Nag_LeftVecs, **pdvl** $\geq \max(1, \textbf{n})$;
otherwise **pdvl** ≥ 1.

16: **vr**[dim] – double *Output*

Note: the dimension, *dim*, of the array **vr** must be at least

$\max(1, \textbf{pdvr} \times \textbf{n})$ when **jobvr** = Nag_RightVecs;
1 otherwise.

The (i,j)th element of the matrix is stored in

vr$[(j-1) \times$ **pdvr** $+ i - 1]$ when **order** = Nag_ColMajor;
vr$[(i-1) \times$ **pdvr** $+ j - 1]$ when **order** = Nag_RowMajor.

On exit: if **jobvr** = Nag_RightVecs, the right generalized eigenvectors v_j are stored one after another in the columns of **vr**, in the same order as the corresponding eigenvalues. Each eigenvector will be scaled so the largest component will have |real part| + |imag. part| = 1.

If **jobvr** = Nag_NotRightVecs, **vr** is not referenced.

17: **pdvr** – Integer *Input*

On entry: the stride separating row or column elements (depending on the value of **order**) in the array **vr**.

Constraints:

if **jobvr** = Nag_RightVecs, **pdvr** $\geq \max(1, \mathbf{n})$;
otherwise **pdvr** ≥ 1.

18: **ilo** – Integer * *Output*

19: **ihi** – Integer * *Output*

On exit: **ilo** and **ihi** are integer values such that $\mathbf{A}(i,j) = 0$ and $\mathbf{B}(i,j) = 0$ if $i > j$ and $j = 1, 2, \ldots, \mathbf{ilo} - 1$ or $i = \mathbf{ihi} + 1, \ldots, \mathbf{n}$.

If **balanc** = Nag_NoBalancing or Nag_BalanceScale, **ilo** $= 1$ and **ihi** $= \mathbf{n}$.

20: **lscale**[**n**] – double *Output*

On exit: details of the permutations and scaling factors applied to the left side of A and B.

If pl_j is the index of the row interchanged with row j, and dl_j is the scaling factor applied to row j, then:

lscale$[j-1] = pl_j$, for $j = 1, 2, \ldots, \mathbf{ilo} - 1$;

lscale $= dl_j$, for $j = \mathbf{ilo}, \ldots, \mathbf{ihi}$;

lscale $= pl_j$, for $j = \mathbf{ihi} + 1, \ldots, \mathbf{n}$.

The order in which the interchanges are made is **n** to **ihi** $+ 1$, then 1 to **ilo** $- 1$.

21: **rscale**[**n**] – double *Output*

On exit: details of the permutations and scaling factors applied to the right side of A and B.

If pr_j is the index of the column interchanged with column j, and dr_j is the scaling factor applied to column j, then:

rscale$[j-1] = pr_j$, for $j = 1, 2, \ldots, \mathbf{ilo} - 1$;

if **rscale** $= dr_j$, for $j = \mathbf{ilo}, \ldots, \mathbf{ihi}$;

if **rscale** $= pr_j$, for $j = \mathbf{ihi} + 1, \ldots, \mathbf{n}$.

The order in which the interchanges are made is **n** to **ihi** $+ 1$, then 1 to **ilo** $- 1$.

22: **abnrm** – double * *Output*

On exit: the 1-norm of the balanced matrix A.

23: **bbnrm** – double * *Output*

On exit: the 1-norm of the balanced matrix B.

24: **rconde**[dim] – double *Output*

Note: the dimension, *dim*, of the array **rconde** must be at least $\max(1, \mathbf{n})$.

On exit: if **sense** = Nag_RCondEigVals or Nag_RCondBoth, the reciprocal condition numbers of the eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of **rconde** are set to the same value. Thus **rconde**$[j-1]$, **rcondv**$[j-1]$, and the jth columns of **vl** and **vr** all correspond to the jth eigenpair.

If **sense** = Nag_RCondEigVecs, **rconde** is not referenced.

25: **rcondv**[dim] – double *Output*

Note: the dimension, *dim*, of the array **rcondv** must be at least $\max(1, \mathbf{n})$.

On exit: if **sense** = Nag_RCondEigVecs or Nag_RCondBoth, the estimated reciprocal condition numbers of the eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of **rcondv** are set to the same value.

If **sense** = Nag_RCondEigVals, **rcondv** is not referenced.

26: **fail** – NagError * *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.
See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

NE_BAD_PARAM

On entry, argument ⟨*value*⟩ had an illegal value.

NE_EIGENVECTORS

A failure occurred in nag_dtgevc (f08ykc) while computing generalized eigenvectors.

NE_ENUM_INT_2

On entry, **jobvl** = ⟨*value*⟩, **pdvl** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: if **jobvl** = Nag_LeftVecs, **pdvl** $\geq \max(1, \mathbf{n})$;
otherwise **pdvl** ≥ 1.

On entry, **jobvr** = ⟨*value*⟩, **pdvr** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: if **jobvr** = Nag_RightVecs, **pdvr** $\geq \max(1, \mathbf{n})$;
otherwise **pdvr** ≥ 1.

NE_INT

On entry, **n** = ⟨*value*⟩.
Constraint: **n** ≥ 0.

On entry, **pda** = ⟨*value*⟩.
Constraint: **pda** > 0.

On entry, **pdb** = ⟨*value*⟩.
Constraint: **pdb** > 0.

On entry, **pdvl** = ⟨*value*⟩.
Constraint: **pdvl** > 0.

On entry, **pdvr** = ⟨*value*⟩.
Constraint: **pdvr** > 0.

NE_INT_2

On entry, **pda** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pda** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = ⟨*value*⟩ and **n** = ⟨*value*⟩.
Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.
See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

NE_ITERATION_QZ

The QZ iteration failed. No eigenvectors have been calculated but **alphar**$[j]$, **alphai**$[j]$ and **beta**$[j]$ should be correct from element $\langle value \rangle$.

The QZ iteration failed with an unexpected error, please contact NAG.

NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly.
See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

7 Accuracy

The computed eigenvalues and eigenvectors are exact for nearby matrices $(A + E)$ and $(B + F)$, where

$$\|(E, F)\|_F = O(\epsilon)\|(A, B)\|_F,$$

and ϵ is the ***machine precision***.

An approximate error bound on the chordal distance between the ith computed generalized eigenvalue w and the corresponding exact eigenvalue λ is

$$\epsilon \times \|\mathbf{abnrm}, \mathbf{bbnrm}\|_2 / \mathbf{rconde}[i-1].$$

An approximate error bound for the angle between the ith computed eigenvector u_j or v_j is given by

$$\epsilon \times \|\mathbf{abnrm}, \mathbf{bbnrm}\|_2 / \mathbf{rcondv}[i-1].$$

For further explanation of the reciprocal condition numbers **rconde** and **rcondv**, see Section 4.11 of Anderson *et al.* (1999).

Note: interpretation of results obtained with the QZ algorithm often requires a clear understanding of the effects of small changes in the original data. These effects are reviewed in Wilkinson (1979), in relation to the significance of small values of α_j and β_j. It should be noted that if α_j and β_j are **both** small for any j, it may be that no reliance can be placed on **any** of the computed eigenvalues $\lambda_i = \alpha_i/\beta_i$. You are recommended to study Wilkinson (1979) and, if in difficulty, to seek expert advice on determining the sensitivity of the eigenvalues to perturbations in the data.

8 Parallelism and Performance

nag_dggevx (f08wbc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag_dggevx (f08wbc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

9 Further Comments

The total number of floating-point operations is proportional to n^3.

The complex analogue of this function is nag_zggevx (f08wpc).

10 Example

This example finds all the eigenvalues and right eigenvectors of the matrix pair (A, B), where

$$A = \begin{pmatrix} 3.9 & 12.5 & -34.5 & -0.5 \\ 4.3 & 21.5 & -47.5 & 7.5 \\ 4.3 & 21.5 & -43.5 & 3.5 \\ 4.4 & 26.0 & -46.0 & 6.0 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 1.0 & 2.0 & -3.0 & 1.0 \\ 1.0 & 3.0 & -5.0 & 4.0 \\ 1.0 & 3.0 & -4.0 & 3.0 \\ 1.0 & 3.0 & -4.0 & 4.0 \end{pmatrix},$$

together with estimates of the condition number and forward error bounds for each eigenvalue and eigenvector. The option to balance the matrix pair is used.

10.1 Program Text

```
/* nag_dggevx (f08wbc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <math.h>
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf08.h>
#include <nagx02.h>
#include <naga02.h>
int main(void)
{
  /* Scalars */
  Complex eig, eigl, eigr;
  double abnorm, abnrm, bbnrm, eps, sign, small, tol;
  Integer i, ihi, ilo, j, k, n, pda, pdb, pdvl, pdvr;
  Integer exit_status = 0;

  /* Arrays */
  double *a = 0, *alphai = 0, *alphar = 0, *b = 0, *beta = 0;
  double *lscale = 0, *rconde = 0, *rcondv = 0, *rscale = 0;
  double *vl = 0, *vr = 0;
  char nag_enum_arg[40];

  /* Nag Types */
  NagError fail;
  Nag_OrderType order;
  Nag_LeftVecsType jobvl;
  Nag_RightVecsType jobvr;
  Nag_RCondType sense;

#ifdef NAG_COLUMN_MAJOR
#define A(I, J)  a[(J-1)*pda + I - 1]
#define B(I, J)  b[(J-1)*pdb + I - 1]
#define VL(I, J) vl[(J-1)*pdvl + I - 1]
#define VR(I, J) vr[(J-1)*pdvr + I - 1]
  order = Nag_ColMajor;
#else
#define A(I, J)  a[(I-1)*pda + J - 1]
#define B(I, J)  b[(I-1)*pdb + J - 1]
#define VL(I, J) vl[(I-1)*pdvl + J - 1]
#define VR(I, J) vr[(I-1)*pdvr + J - 1]
  order = Nag_RowMajor;
#endif

  INIT_FAIL(fail);

  printf("nag_dggevx (f08wbc) Example Program Results\n");
```

```
  /* Skip heading in data file */
#ifdef _WIN32
  scanf_s("%*[^\n]");
#else
  scanf("%*[^\n]");
#endif
#ifdef _WIN32
  scanf_s("%" NAG_IFMT "%*[^\n]", &n);
#else
  scanf("%" NAG_IFMT "%*[^\n]", &n);
#endif
  if (n < 0) {
    printf("Invalid n\n");
    exit_status = 1;
    goto END;
  }
#ifdef _WIN32
  scanf_s(" %39s%*[^\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
  scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
  /* nag_enum_name_to_value (x04nac).
   * Converts NAG enum member name to value
   */
  jobvl = (Nag_LeftVecsType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
  scanf_s(" %39s%*[^\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
  scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
  jobvr = (Nag_RightVecsType) nag_enum_name_to_value(nag_enum_arg);
#ifdef _WIN32
  scanf_s(" %39s%*[^\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
  scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
  sense = (Nag_RCondType) nag_enum_name_to_value(nag_enum_arg);

  pda = n;
  pdb = n;
  pdvl = (jobvl == Nag_LeftVecs ? n : 1);
  pdvr = (jobvr == Nag_RightVecs ? n : 1);

  /* Allocate memory */
  if (!(a = NAG_ALLOC(n * n, double)) ||
      !(alphai = NAG_ALLOC(n, double)) ||
      !(alphar = NAG_ALLOC(n, double)) ||
      !(b = NAG_ALLOC(n * n, double)) ||
      !(beta = NAG_ALLOC(n, double)) ||
      !(lscale = NAG_ALLOC(n, double)) ||
      !(rconde = NAG_ALLOC(n, double)) ||
      !(rcondv = NAG_ALLOC(n, double)) ||
      !(rscale = NAG_ALLOC(n, double)) ||
      !(vl = NAG_ALLOC(pdvl * pdvl, double)) ||
      !(vr = NAG_ALLOC(pdvr * pdvr, double)))
  {
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
  }

  /* Read in the matrices A and B */
  for (i = 1; i <= n; ++i)
#ifdef _WIN32
    for (j = 1; j <= n; ++j)
      scanf_s("%lf", &A(i, j));
#else
    for (j = 1; j <= n; ++j)
      scanf("%lf", &A(i, j));
#endif
#ifdef _WIN32
```

```
  scanf_s("%*[^\n]");
#else
  scanf("%*[^\n]");
#endif
  for (i = 1; i <= n; ++i)
#ifdef _WIN32
    for (j = 1; j <= n; ++j)
      scanf_s("%lf", &B(i, j));
#else
    for (j = 1; j <= n; ++j)
      scanf("%lf", &B(i, j));
#endif
#ifdef _WIN32
  scanf_s("%*[^\n]");
#else
  scanf("%*[^\n]");
#endif

  /* Solve the generalized eigenvalue problem using nag_dggevx (f08wbc). */
  nag_dggevx(order, Nag_BalanceBoth, jobvl, jobvr, sense, n, a, pda, b, pdb,
             alphar, alphai, beta, vl, pdvl, vr, pdvr, &ilo, &ihi, lscale,
             rscale, &abnrm, &bbnrm, rconde, rcondv, &fail);
  if (fail.code != NE_NOERROR) {
    printf("Error from nag_dggevx (f08wbc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
  }

  /* nag_real_safe_small_number (x02amc), nag_machine_precision (x02ajc) */
  eps = nag_machine_precision;
  small = nag_real_safe_small_number;
  if (abnrm == 0.0)
    abnorm = ABS(bbnrm);
  else if (bbnrm == 0.0)
    abnorm = ABS(abnrm);
  else if (ABS(abnrm) >= ABS(bbnrm))
    abnorm = ABS(abnrm) * sqrt(1.0 + (bbnrm / abnrm) * (bbnrm / abnrm));
  else
    abnorm = ABS(bbnrm) * sqrt(1.0 + (abnrm / bbnrm) * (abnrm / bbnrm));

  tol = eps * abnorm;

  /* Print out eigenvalues and vectors and associated condition
   * number and bounds.
   */
  for (j = 0; j < n; ++j) {
    /* Print out information on the j-th eigenvalue */
    printf("\n");
    if ((fabs(alphar[j]) + fabs(alphai[j])) * small >= fabs(beta[j])) {
      printf("Eigenvalue %2" NAG_IFMT " is numerically infinite or "
             "undetermined\n", j + 1);
      printf("alpha = (%13.4e, %13.4e), beta = %13.4e\n", alphar[j],
             alphai[j], beta[j]);
    }
    else if (alphai[j] == 0.0) {
      printf("Eigenvalue %2" NAG_IFMT " = %13.4e\n", j + 1,
             alphar[j] / beta[j]);
    }
    else {
      eig.re = alphar[j] / beta[j], eig.im = alphai[j] / beta[j];
      printf("Eigenvalue %2" NAG_IFMT " = (%13.4e, %13.4e)\n", j + 1, eig.re,
             eig.im);
    }
    if (sense == Nag_RCondEigVals || sense == Nag_RCondBoth) {
      printf("\n Reciprocal condition number = %10.1e\n", rconde[j]);

      if (rconde[j] > 0.0)
        printf(" Error bound                 = %10.1e\n", tol / rconde[j]);
      else
        printf(" Error bound is infinite\n");
    }
```

```
    printf("\n\n");
    /* Normalize and print out information on the j-th eigenvector(s) */
    if (jobvl == Nag_LeftVecs)
      printf("%21s%8s", "Left Eigenvector", "");
    if (jobvr == Nag_RightVecs)
      printf("%21s", "Right Eigenvector");
    printf(" %2" NAG_IFMT "\n", j + 1);
    if (alphai[j] == 0.0)
      for (i = 1; i <= n; ++i) {
        if (jobvl == Nag_LeftVecs)
          printf("%7s%13.4e%12s", "", VL(i, j + 1) / VL(n, j + 1), "");
        if (jobvr == Nag_RightVecs)
          printf("%7s%13.4e", "", VR(i, j + 1) / VR(n, j + 1));
        printf("\n");
      }
    else {
      k = (alphai[j] > 0.0 ? j + 1 : j);
      sign = (alphai[j] > 0.0 ? 1.0 : -1.0);
      if (jobvl == Nag_LeftVecs)
        eigl = nag_complex(VL(n, k), VL(n, k + 1));
      if (jobvr == Nag_RightVecs)
        eigr = nag_complex(VR(n, k), VR(n, k + 1));
      for (i = 1; i <= n; ++i) {
        if (jobvl == Nag_LeftVecs) {
          eig = nag_complex_divide(nag_complex(VL(i, k), VL(i, k + 1)), eigl);
          printf(" (%13.4e,%13.4e) ", eig.re, sign * eig.im);
        }
        if (jobvr == Nag_RightVecs) {
          eig = nag_complex_divide(nag_complex(VR(i, k), VR(i, k + 1)), eigr);
          printf(" (%13.4e,%13.4e)", eig.re, sign * eig.im);
        }
        printf("\n");
      }
    }

    if (sense == Nag_RCondEigVecs || sense == Nag_RCondBoth) {
      printf("\n Reciprocal condition number = %10.1e\n", rcondv[j]);

      if (rcondv[j] > 0.0)
        printf(" Error bound                 = %10.1e\n\n", tol / rcondv[j]);
      else
        printf(" Error bound is infinite\n\n");
    }
  }

END:
  NAG_FREE(a);
  NAG_FREE(alphai);
  NAG_FREE(alphar);
  NAG_FREE(b);
  NAG_FREE(beta);
  NAG_FREE(lscale);
  NAG_FREE(rconde);
  NAG_FREE(rcondv);
  NAG_FREE(rscale);
  NAG_FREE(vl);
  NAG_FREE(vr);

  return exit_status;
}
```

10.2 Program Data

```
nag_dggevx (f08wbc) Example Program Data
   4                    : n

   Nag_NotLeftVecs      : jobvl
   Nag_RightVecs        : jobvr
   Nag_RCondBoth        : sense
```

```
   3.9  12.5 -34.5  -0.5
   4.3  21.5 -47.5   7.5
   4.3  21.5 -43.5   3.5
   4.4  26.0 -46.0   6.0 : matrix A

   1.0   2.0  -3.0   1.0
   1.0   3.0  -5.0   4.0
   1.0   3.0  -4.0   3.0
   1.0   3.0  -4.0   4.0 : matrix B
```

10.3 Program Results

```
nag_dggevx (f08wbc) Example Program Results

Eigenvalue  1 =    2.0000e+00

 Reciprocal condition number =    9.5e-02
 Error bound                =    2.5e-14


    Right Eigenvector  1
          1.5909e+01
          9.0909e-02
          1.0000e+00
          1.0000e+00

 Reciprocal condition number =    1.3e-01
 Error bound                =    1.9e-14


Eigenvalue  2 = (   3.0000e+00,    4.0000e+00)

 Reciprocal condition number =    1.7e-01
 Error bound                =    1.4e-14


    Right Eigenvector  2
 (   3.0000e+00,   4.0000e+00)
 (   6.0000e-01,   8.0000e-01)
 (   1.0000e+00,   3.9126e-16)
 (   1.0000e+00,  -0.0000e+00)

 Reciprocal condition number =    3.8e-02
 Error bound                =    6.2e-14


Eigenvalue  3 = (   3.0000e+00,   -4.0000e+00)

 Reciprocal condition number =    1.7e-01
 Error bound                =    1.4e-14


    Right Eigenvector  3
 (   3.0000e+00,  -4.0000e+00)
 (   6.0000e-01,  -8.0000e-01)
 (   1.0000e+00,  -3.9126e-16)
 (   1.0000e+00,   0.0000e+00)

 Reciprocal condition number =    3.8e-02
 Error bound                =    6.2e-14


Eigenvalue  4 =    4.0000e+00

 Reciprocal condition number =    5.1e-01
 Error bound                =    4.6e-15


    Right Eigenvector  4
          6.4286e+00
```

```
          7.1429e-02
         -2.1429e-01
          1.0000e+00

 Reciprocal condition number =    7.1e-02
 Error bound                =    3.3e-14
```
