

# NAG Library Function Document

## nag\_dstein (f08jkc)

### 1 Purpose

nag\_dstein (f08jkc) computes the eigenvectors of a real symmetric tridiagonal matrix corresponding to specified eigenvalues, by inverse iteration.

### 2 Specification

```
#include <nag.h>
#include <nagf08.h>

void nag_dstein (Nag_OrderType order, Integer n, const double d[],
                const double e[], Integer m, const double w[], const Integer iblock[],
                const Integer isplit[], double z[], Integer pdz, Integer ifailv[],
                NagError *fail)
```

### 3 Description

nag\_dstein (f08jkc) computes the eigenvectors of a real symmetric tridiagonal matrix  $T$  corresponding to specified eigenvalues, by inverse iteration (see Jessup and Ipsen (1992)). It is designed to be used in particular after the specified eigenvalues have been computed by nag\_dstebz (f08jjc) with **rank** = Nag\_ByBlock, but may also be used when the eigenvalues have been computed by other functions in Chapters f02 or f08.

If  $T$  has been formed by reduction of a full real symmetric matrix  $A$  to tridiagonal form, then eigenvectors of  $T$  may be transformed to eigenvectors of  $A$  by a call to nag\_dormtr (f08fgc) or nag\_dopmtr (f08ggc).

nag\_dstebz (f08jjc) determines whether the matrix  $T$  splits into block diagonal form:

$$T = \begin{pmatrix} T_1 & & & & \\ & T_2 & & & \\ & & \cdot & & \\ & & & \cdot & \\ & & & & T_p \end{pmatrix}$$

and passes details of the block structure to this function in the arrays **iblock** and **isplit**. This function can then take advantage of the block structure by performing inverse iteration on each block  $T_i$  separately, which is more efficient than using the whole matrix.

### 4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Jessup E and Ipsen I C F (1992) Improving the accuracy of inverse iteration *SIAM J. Sci. Statist. Comput.* **13** 550–572

### 5 Arguments

- 1: **order** – Nag\_OrderType *Input*  
*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by

**order** = Nag\_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

- 2: **n** – Integer *Input*  
*On entry:*  $n$ , the order of the matrix  $T$ .  
*Constraint:*  $n \geq 0$ .
- 3: **d**[ $dim$ ] – const double *Input*  
**Note:** the dimension,  $dim$ , of the array **d** must be at least  $\max(1, n)$ .  
*On entry:* the diagonal elements of the tridiagonal matrix  $T$ .
- 4: **e**[ $dim$ ] – const double *Input*  
**Note:** the dimension,  $dim$ , of the array **e** must be at least  $\max(1, n - 1)$ .  
*On entry:* the off-diagonal elements of the tridiagonal matrix  $T$ .
- 5: **m** – Integer *Input*  
*On entry:*  $m$ , the number of eigenvectors to be returned.  
*Constraint:*  $0 \leq m \leq n$ .
- 6: **w**[ $dim$ ] – const double *Input*  
**Note:** the dimension,  $dim$ , of the array **w** must be at least  $\max(1, n)$ .  
*On entry:* the eigenvalues of the tridiagonal matrix  $T$  stored in **w**[0] to **w**[ $m - 1$ ], as returned by nag\_dstebz (f08jjc) with **rank** = Nag\_ByBlock. Eigenvalues associated with the first sub-matrix must be supplied first, in nondecreasing order; then those associated with the second sub-matrix, again in nondecreasing order; and so on.  
*Constraint:* if **iblock**[ $i$ ] = **iblock**[ $i + 1$ ],  $w[i] \leq w[i + 1]$ , for  $i = 0, 1, \dots, m - 2$ .
- 7: **iblock**[ $dim$ ] – const Integer *Input*  
**Note:** the dimension,  $dim$ , of the array **iblock** must be at least  $\max(1, n)$ .  
*On entry:* the first  $m$  elements must contain the sub-matrix indices associated with the specified eigenvalues, as returned by nag\_dstebz (f08jjc) with **rank** = Nag\_ByBlock. If the eigenvalues were not computed by nag\_dstebz (f08jjc) with **rank** = Nag\_ByBlock, set **iblock**[ $i - 1$ ] to 1, for  $i = 1, 2, \dots, m$ .  
*Constraint:* **iblock**[ $i$ ]  $\leq$  **iblock**[ $i + 1$ ], for  $i = 0, 1, \dots, m - 2$ .
- 8: **isplit**[ $dim$ ] – const Integer *Input*  
**Note:** the dimension,  $dim$ , of the array **isplit** must be at least  $\max(1, n)$ .  
*On entry:* the points at which  $T$  breaks up into sub-matrices, as returned by nag\_dstebz (f08jjc) with **rank** = Nag\_ByBlock. If the eigenvalues were not computed by nag\_dstebz (f08jjc) with **rank** = Nag\_ByBlock, set **isplit**[0] to **n**.
- 9: **z**[ $dim$ ] – double *Output*  
**Note:** the dimension,  $dim$ , of the array **z** must be at least  
 $\max(1, pdz \times m)$  when **order** = Nag\_ColMajor;  
 $\max(1, n \times pdz)$  when **order** = Nag\_RowMajor.

The  $(i, j)$ th element of the matrix  $Z$  is stored in

$$\begin{aligned} & \mathbf{z}[(j-1) \times \mathbf{pdz} + i - 1] \text{ when } \mathbf{order} = \text{Nag\_ColMajor}; \\ & \mathbf{z}[(i-1) \times \mathbf{pdz} + j - 1] \text{ when } \mathbf{order} = \text{Nag\_RowMajor}. \end{aligned}$$

*On exit:* the  $m$  eigenvectors, stored as columns of  $Z$ ; the  $i$ th column corresponds to the  $i$ th specified eigenvalue, unless **fail.code** = NE\_CONVERGENCE (in which case see Section 6).

10: **pdz** – Integer *Input*

*On entry:* the stride separating row or column elements (depending on the value of **order**) in the array **z**.

*Constraints:*

$$\begin{aligned} & \text{if } \mathbf{order} = \text{Nag\_ColMajor}, \mathbf{pdz} \geq \max(1, \mathbf{n}); \\ & \text{if } \mathbf{order} = \text{Nag\_RowMajor}, \mathbf{pdz} \geq \max(1, \mathbf{m}). \end{aligned}$$

11: **ifailv[m]** – Integer *Output*

*On exit:* if **fail.errnum** =  $i > 0$ , the first  $i$  elements of **ifailv** contain the indices of any eigenvectors which have failed to converge. The rest of the first  $\mathbf{m}$  elements of **ifailv** are set to 0.

12: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 2.3.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle \text{value} \rangle$  had an illegal value.

### NE\_CONSTRAINT

On entry,  $\mathbf{m} = \langle \text{value} \rangle$ ,  $\mathbf{iblock}[i]\mathbf{iblock}[i+1] = \langle \text{value} \rangle$  and  $\mathbf{w}[i]\mathbf{w}[i+1] = \langle \text{value} \rangle$ .  
Constraint: , for  $i = 0, 1, \dots, \mathbf{m} - 2$

### NE\_CONVERGENCE

$\langle \text{value} \rangle$  eigenvectors (as indicated by argument **ifailv**) each failed to converge in five iterations. The current iterate after five iterations is stored in the corresponding column of **z**.

### NE\_INT

On entry,  $\mathbf{n} = \langle \text{value} \rangle$ .  
Constraint:  $\mathbf{n} \geq 0$ .

On entry,  $\mathbf{pdz} = \langle \text{value} \rangle$ .  
Constraint:  $\mathbf{pdz} > 0$ .

### NE\_INT\_2

On entry,  $\mathbf{m} = \langle \text{value} \rangle$  and  $\mathbf{n} = \langle \text{value} \rangle$ .  
Constraint:  $0 \leq \mathbf{m} \leq \mathbf{n}$ .

On entry,  $\mathbf{pdz} = \langle \text{value} \rangle$  and  $\mathbf{m} = \langle \text{value} \rangle$ .  
Constraint:  $\mathbf{pdz} \geq \max(1, \mathbf{m})$ .

On entry, **pdz** =  $\langle value \rangle$  and **n** =  $\langle value \rangle$ .  
 Constraint: **pdz**  $\geq \max(1, \mathbf{n})$ .

#### NE\_INT\_ARRAY

On entry, **m** =  $\langle value \rangle$  and **iblock**[*i*]**iblock**[*i* + 1] =  $\langle value \rangle$ .  
 Constraint: **iblock**[*i*]  $\leq$  **iblock**[*i* + 1], for  $i = 0, 1, \dots, \mathbf{m} - 2$

#### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG.  
 See Section 2.7.6 in How to Use the NAG Library and its Documentation for further information.

#### NE\_NO\_LICENCE

Your licence key may have expired or may not have been installed correctly.  
 See Section 2.7.5 in How to Use the NAG Library and its Documentation for further information.

## 7 Accuracy

Each computed eigenvector  $z_i$  is the exact eigenvector of a nearby matrix  $A + E_i$ , such that

$$\|E_i\| = O(\epsilon)\|A\|,$$

where  $\epsilon$  is the *machine precision*. Hence the residual is small:

$$\|Az_i - \lambda_i z_i\| = O(\epsilon)\|A\|.$$

However, a set of eigenvectors computed by this function may not be orthogonal to so high a degree of accuracy as those computed by nag\_dsteqr (f08jec).

## 8 Parallelism and Performance

nag\_dstein (f08jkc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_dstein (f08jkc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The complex analogue of this function is nag\_zstein (f08jxc).

## 10 Example

See Section 10 in nag\_dormtr (f08fgc).

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