# NAG Library Function Document nag_zgghd3 (f08wtc) 

## 1 Purpose

nag_zgghd3 (f08wtc) reduces a pair of complex matrices $(A, B)$, where $B$ is upper triangular, to the generalized upper Hessenberg form using unitary transformations.

## 2 Specification

```
#include <nag.h>
#include <nagf08.h>
void nag_zgghd3 (Nag_OrderType order, Nag_ComputeQType compq,
    Nag_ComputeZType compz, Integer n, Integer ilo, Integer ihi,
    Complex a[], Integer pda, Complex b[], Integer pdb, Complex q[],
    Integer pdq, Complex z[], Integer pdz, NagError *fail)
```


## 3 Description

nag_zgghd3 (f08wtc) is usually the third step in the solution of the complex generalized eigenvalue problem

$$
A x=\lambda B x
$$

The (optional) first step balances the two matrices using nag_zggbal (f08wvc). In the second step, matrix $B$ is reduced to upper triangular form using the $Q R$ factorization function nag_zgeqrf (f08asc) and this unitary transformation $Q$ is applied to matrix $A$ by calling nag_zunmqr (f08auc). The driver, nag_zggev3 (f08wqc), solves the complex generalized eigenvalue problem by combining all the required steps including those just listed.
nag_zgghd3 (f08wtc) reduces a pair of complex matrices $(A, B)$, where $B$ is triangular, to the generalized upper Hessenberg form using unitary transformations. This two-sided transformation is of the form

$$
\begin{gathered}
Q^{\mathrm{H}} A Z=H, \\
Q^{\mathrm{H}} B Z=T
\end{gathered}
$$

where $H$ is an upper Hessenberg matrix, $T$ is an upper triangular matrix and $Q$ and $Z$ are unitary matrices determined as products of Givens rotations. They may either be formed explicitly, or they may be postmultiplied into input matrices $Q_{1}$ and $Z_{1}$, so that

$$
\begin{aligned}
Q_{1} A Z_{1}^{\mathrm{H}} & =\left(Q_{1} Q\right) H\left(Z_{1} Z\right)^{\mathrm{H}} \\
Q_{1} B Z_{1}^{\mathrm{H}} & =\left(Q_{1} Q\right) T\left(Z_{1} Z\right)^{\mathrm{H}} .
\end{aligned}
$$

## 4 References

Golub G H and Van Loan C F (2012) Matrix Computations (4th Edition) Johns Hopkins University Press, Baltimore
Moler C B and Stewart G W (1973) An algorithm for generalized matrix eigenproblems SIAM J. Numer. Anal. 10 241-256

## 5 Arguments

1: order - Nag_OrderType
Input
On entry: the order argument specifies the two-dimensional storage scheme being used, i.e., rowmajor ordering or column-major ordering. C language defined storage is specified by order $=$ Nag_RowMajor. See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument.
Constraint: order $=$ Nag_RowMajor or Nag_ColMajor.
2: compq - Nag_ComputeQType
Input
On entry: specifies the form of the computed unitary matrix $Q$.
$\boldsymbol{\operatorname { c o m p q }}=\mathrm{Nag}_{-}$NotQ
Do not compute $Q$.
$\boldsymbol{\operatorname { c o m p q }}=\mathrm{Nag}_{\text {_InitQ}}$
The unitary matrix $Q$ is returned.
$\boldsymbol{c o m p q}_{\mathbf{q}}=\mathrm{Nag}_{\_}$UpdateSchur
$\mathbf{q}$ must contain a unitary matrix $Q_{1}$, and the product $Q_{1} Q$ is returned.
Constraint: compq $=$ Nag_NotQ, Nag_InitQ or Nag_UpdateSchur.
3: compz - Nag_ComputeZType
Input
On entry: specifies the form of the computed unitary matrix $Z$.
$\boldsymbol{\operatorname { c o m p z }}=$ Nag_NotZ
Do not compute $Z$.
$\mathbf{c o m p z}=$ Nag_UpdateZ $^{\text {_ }}$
$\mathbf{z}$ must contain a unitary matrix $Z_{1}$, and the product $Z_{1} Z$ is returned.
$\boldsymbol{\operatorname { c o m p z }}=$ Nag_InitZ $^{\prime}$
The unitary matrix $Z$ is returned.
Constraint: $\mathbf{c o m p z}=$ Nag_NotZ, Nag_UpdateZ or Nag_InitZ.
n - Integer
Input
On entry: $n$, the order of the matrices $A$ and $B$.
Constraint: $\mathbf{n} \geq 0$.
ilo - Integer
Input
ihi - Integer Input

On entry: $i_{\text {lo }}$ and $i_{\text {hi }}$ as determined by a previous call to nag_zggbal (f08wve). Otherwise, they should be set to 1 and $n$, respectively.
Constraints:

$$
\begin{aligned}
& \text { if } \mathbf{n}>0,1 \leq \mathbf{i l o} \leq \mathbf{i h i} \leq \mathbf{n} ; \\
& \text { if } \mathbf{n}=0, \mathbf{i l o}=1 \text { and } \mathbf{i} \mathbf{h} \mathbf{i}=0 .
\end{aligned}
$$

$\mathbf{a}[$ dim $]$ - Complex
Input/Output
Note: the dimension, $\operatorname{dim}$, of the array a must be at least $\max (1, \mathbf{p d a} \times \mathbf{n})$.
The $(i, j)$ th element of the matrix $A$ is stored in

$$
\begin{aligned}
& \mathbf{a}[(j-1) \times \text { pda }+i-1] \text { when } \text { order }=\text { Nag_ColMajor; } \\
& \mathbf{a}[(i-1) \times \mathbf{p d a}+j-1] \text { when } \mathbf{o r d e r}=\text { Nag_RowMajor. } .
\end{aligned}
$$

On entry: the matrix $A$ of the matrix pair $(A, B)$. Usually, this is the matrix $A$ returned by nag_zunmqr (f08auc).

On exit: a is overwritten by the upper Hessenberg matrix $H$.
8: $\quad$ pda - Integer
Input
On entry: the stride separating row or column elements (depending on the value of order) in the array a.

Constraint: $\mathbf{p d a} \geq \max (1, \mathbf{n})$.
9: $\quad \mathbf{b}[\operatorname{dim}]-$ Complex
Input/Output
Note: the dimension, $\operatorname{dim}$, of the array $\mathbf{b}$ must be at least $\max (1, \mathbf{p d b} \times \mathbf{n})$.
The $(i, j)$ th element of the matrix $B$ is stored in
$\mathbf{b}[(j-1) \times \mathbf{p d b}+i-1]$ when order $=$ Nag_ColMajor;
$\mathbf{b}[(i-1) \times \mathbf{p d b}+j-1]$ when $\mathbf{o r d e r}=$ Nag_RowMajor.

On entry: the upper triangular matrix $B$ of the matrix pair $(A, B)$. Usually, this is the matrix $B$ returned by the $Q R$ factorization function nag_zgeqrf (f08asc).
On exit: $\mathbf{b}$ is overwritten by the upper triangular matrix $T$.

10: pdb - Integer
Input
On entry: the stride separating row or column elements (depending on the value of order) in the array $\mathbf{b}$.
Constraint: $\mathbf{p d b} \geq \max (1, \mathbf{n})$.
11: $\quad \mathbf{q}[\mathrm{dim}]$ - Complex
Input/Output
Note: the dimension, dim, of the array $\mathbf{q}$ must be at least
$\max (1, \mathbf{p d q} \times \mathbf{n})$ when compq $=$ Nag_InitQ or Nag_UpdateSchur;
1 when compq $=$ Nag_NotQ.
The $(i, j)$ th element of the matrix $Q$ is stored in
$\mathbf{q}[(j-1) \times \mathbf{p d q}+i-1]$ when order $=$ Nag_ColMajor;
$\mathbf{q}[(i-1) \times \mathbf{p d q}+j-1]$ when $\mathbf{o r d e r}=$ Nag_RowMajor.
On entry: if compq $=$ Nag_UpdateSchur, $\mathbf{q}$ must contain a unitary matrix $Q_{1}$.
If $\operatorname{compq}=$ Nag_NotQ, $\mathbf{q}$ is not referenced.
On exit: if compq = Nag_InitQ, $\mathbf{q}$ contains the unitary matrix $Q$.
Iif $\operatorname{compq}=$ Nag_UpdateSchur, $\mathbf{q}$ is overwritten by $Q_{1} Q$.
pdq - Integer
Input
On entry: the stride separating row or column elements (depending on the value of order) in the array $\mathbf{q}$.

## Constraints:

if compq $=$ Nag_InitQ or Nag_UpdateSchur, $_{\mathbf{p d q}}^{\mathbf{p d q}} \max (1, \mathbf{n})$;
if compq $=$ Nag_Not $Q, \mathbf{p d q} \geq 1$.
13: $\quad \mathbf{z}[\operatorname{dim}]-$ Complex
Input/Output
Note: the dimension, dim, of the array $\mathbf{z}$ must be at least
$\max (1, \mathbf{p d z} \times \mathbf{n})$ when compz $=$ Nag_UpdateZ or Nag_InitZ;
1 when $\mathbf{c o m p z}=$ Nag_NotZ.

The $(i, j)$ th element of the matrix $Z$ is stored in

$$
\begin{aligned}
& \mathbf{z}[(j-1) \times \mathbf{p d z}+i-1] \text { when order }=\text { Nag_ColMajor; } \\
& \mathbf{z}[(i-1) \times \mathbf{p d z}+j-1] \text { when } \mathbf{~ o r d e r}=\text { Nag_RowMajor. }
\end{aligned}
$$

On entry: if $\mathbf{c o m p z}=$ Nag_UpdateZ, $\mathbf{z}$ must contain a unitary matrix $Z_{1}$.
If compz $=$ Nag_NotZ, $\mathbf{z}$ is not referenced.
On exit: if $\mathbf{c o m p z}=$ Nag_InitZ, $\mathbf{z}$ contains the unitary matrix $Z$.
If $\mathbf{c o m p z}=$ Nag_UpdateZ, $\mathbf{z}$ is overwritten by $Z_{1} Z$.
14: pdz - Integer
Input
On entry: the stride separating row or column elements (depending on the value of order) in the array $\mathbf{z}$.
Constraints:

$$
\begin{aligned}
& \text { if } \mathbf{c o m p z}=\text { Nag_UpdateZ or Nag_InitZ, } \mathbf{p d z} \geq \max (1, \mathbf{n}) ; \\
& \text { if } \mathbf{c o m p z}=\text { Nag_NotZ, } \mathbf{p d z} \geq 1 .
\end{aligned}
$$

15: fail - NagError *
Input/Output
The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

## NE_ALLOC_FAIL

Dynamic memory allocation failed.
See Section 3.2.1.2 in How to Use the NAG Library and its Documentation for further information.

## NE_BAD_PARAM

On entry, argument $\langle$ value $\rangle$ had an illegal value.

## NE_ENUM_INT_2

On entry, compq $=\langle$ value $\rangle, \mathbf{p d q}=\langle$ value $\rangle$ and $\mathbf{n}=\langle$ value $\rangle$.
Constraint: if compq $=$ Nag_InitQ or Nag_UpdateSchur, $\mathbf{p d q} \geq \max (1, \mathbf{n})$;
if $\mathbf{c o m p q}=$ Nag_NotQ, $\mathbf{p d q} \geq 1$.
On entry, compz $=\langle$ value $\rangle, \mathbf{p d z}=\langle$ value $\rangle$ and $\mathbf{n}=\langle$ value $\rangle$.
Constraint: if compz $=$ Nag_UpdateZ or Nag_InitZ, $\mathbf{p d z} \geq \max (1, \mathbf{n})$;
if $\mathbf{c o m p z}=$ Nag_NotZ, $\mathbf{p d z} \geq 1$.

## NE_INT

On entry, $\mathbf{n}=\langle$ value $\rangle$.
Constraint: $\mathbf{n} \geq 0$.
On entry, pda $=\langle$ value $\rangle$.
Constraint: pda $>0$.
On entry, $\mathbf{p d b}=\langle$ value $\rangle$.
Constraint: $\mathbf{p d b}>0$.
On entry, $\mathbf{p d q}=\langle$ value $\rangle$.
Constraint: $\mathbf{p d q}>0$.
On entry, pdz $=\langle$ value $\rangle$.
Constraint: pdz $>0$.

## NE_INT_2

On entry, pda $=\langle$ value $\rangle$ and $\mathbf{n}=\langle$ value $\rangle$.
Constraint: pda $\geq \max (1, \mathbf{n})$.
On entry, pdb $=\langle$ value $\rangle$ and $\mathbf{n}=\langle$ value $\rangle$.
Constraint: $\mathbf{p d b} \geq \max (1, \mathbf{n})$.

## NE_INT_3

On entry, $\mathbf{n}=\langle$ value $\rangle, \mathbf{i l o}=\langle$ value $\rangle$ and $\mathbf{i h i}=\langle$ value $\rangle$.
Constraint: if $\mathbf{n}>0,1 \leq \mathbf{i l o} \leq \mathbf{i h i} \leq \mathbf{n}$;
if $\mathbf{n}=0$, $\mathbf{i l o}=1$ and $\mathbf{i h i}=0$.

## NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.
An unexpected error has been triggered by this function. Please contact NAG.
See Section 3.6.6 in How to Use the NAG Library and its Documentation for further information.

## NE_NO_LICENCE

Your licence key may have expired or may not have been installed correctly.
See Section 3.6.5 in How to Use the NAG Library and its Documentation for further information.

## 7 Accuracy

The reduction to the generalized Hessenberg form is implemented using unitary transformations which are backward stable.

## 8 Parallelism and Performance

nag_zgghd3 (f08wtc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Notefor your implementation for any additional implementation-specific information.

## 9 Further Comments

This function is usually followed by nag_zhgeqz (f08xsc) which implements the $Q Z$ algorithm for computing generalized eigenvalues of a reduced pair of matrices.
The real analogue of this function is nag_dgghd3 (f08wfc).

## 10 Example

See Section 10 in nag_zhgeqz (f08xsc) and nag_ztgevc (f08yxc).

